

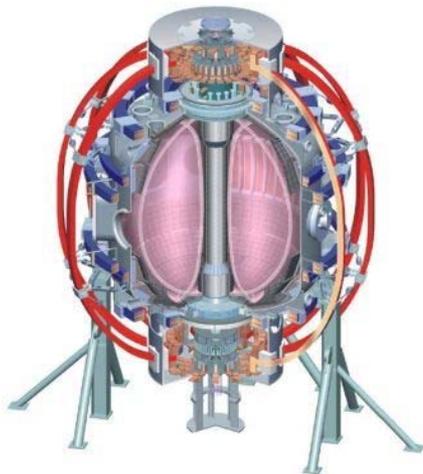
Intrinsic Rotation Generation in NSTX Ohmic H-mode Plasmas

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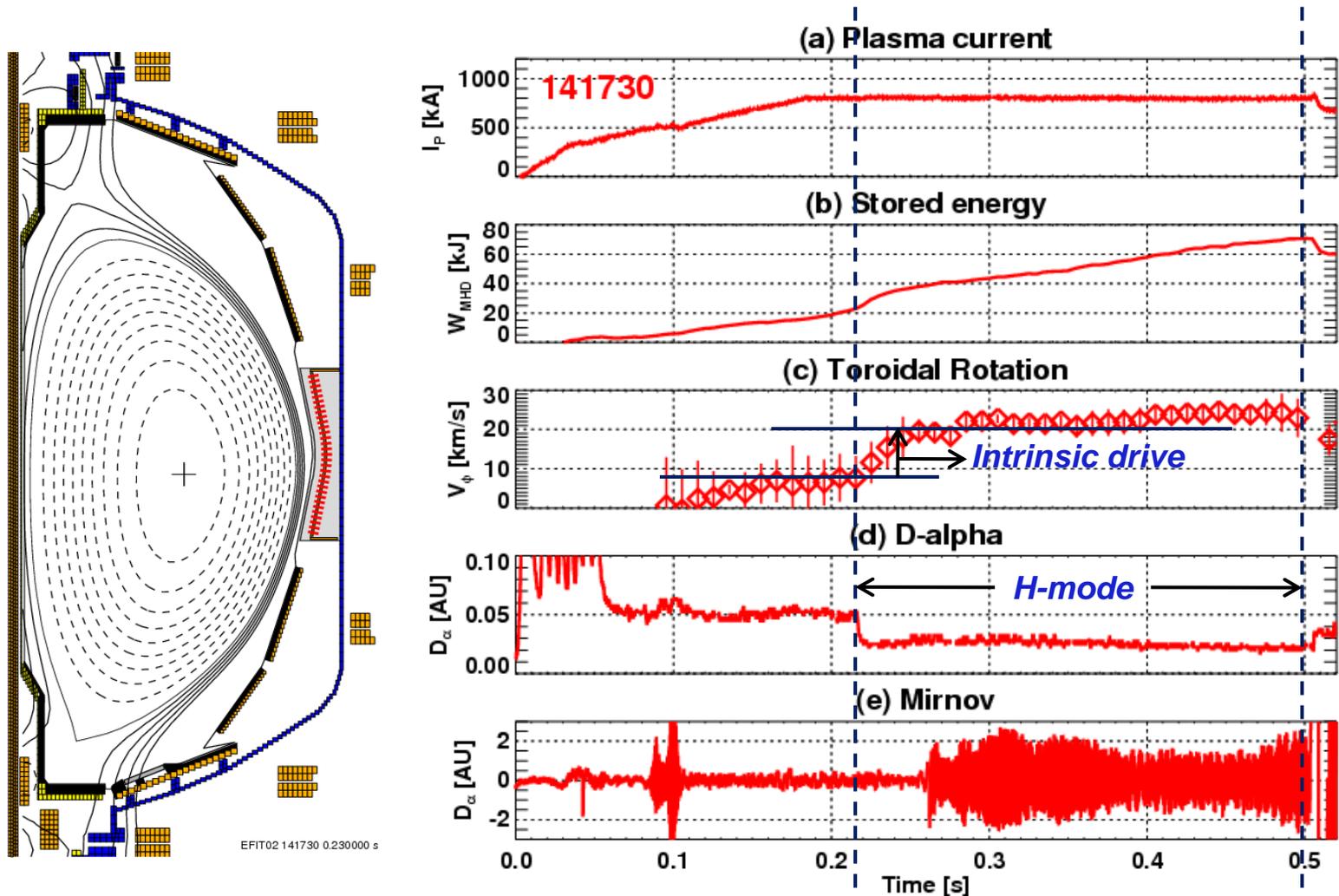
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Introduction

- Intrinsic torque and rotation generation have been observed by passive CHERS, in NSTX Ohmic L-H transition
 - There were Ohmic H-mode plasmas in NSTX (C. Bush, S. Kubota)
 - Passive CHERS provides ion temperature and rotation information
- Rotation jump is clear and perhaps highly free from ‘non-intrinsic’ torques
 - No NBIs, weak NTVs, short periods for rotation evolution
- Study of intrinsic torque in NSTX can provide unique information and data for STs
 - Intrinsic torque and rotation vs. thermodynamic forces
 - Intrinsic torque and rotation scaling, and Rice scaling

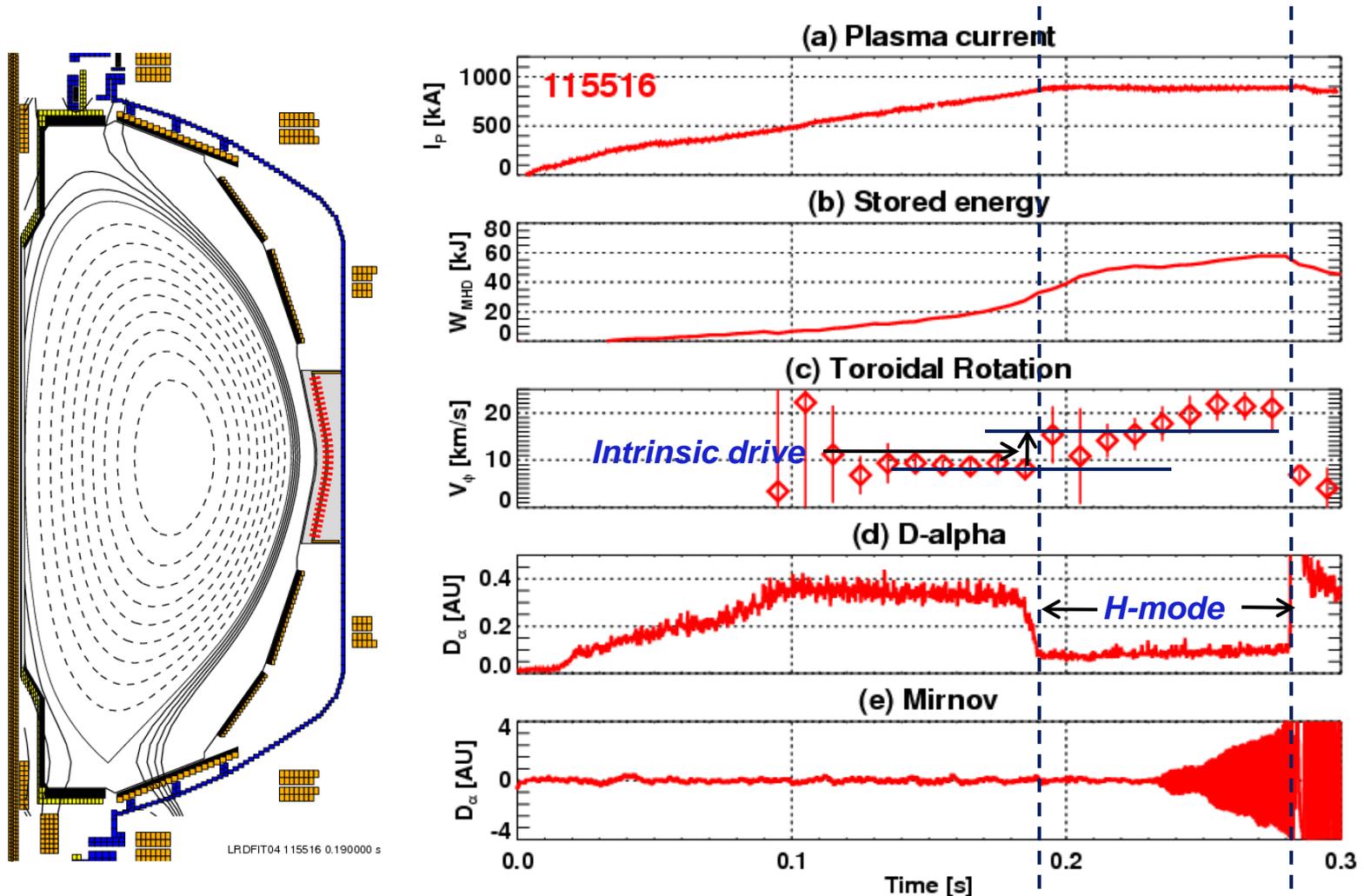
Intrinsic rotation in Ohmic L-H transition (#1)

- Rotation is increased by $\sim 10\text{km/s}$ in L-H and stays in H-mode



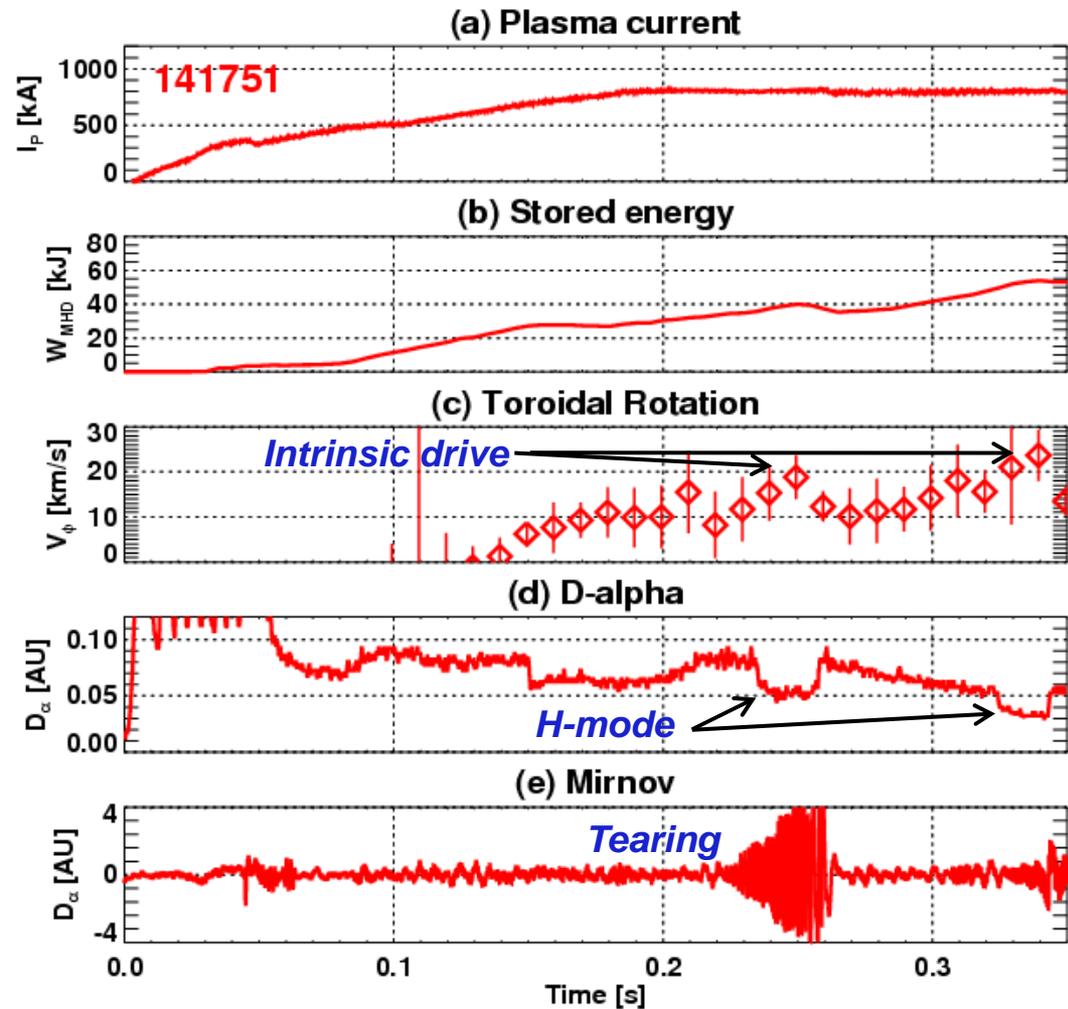
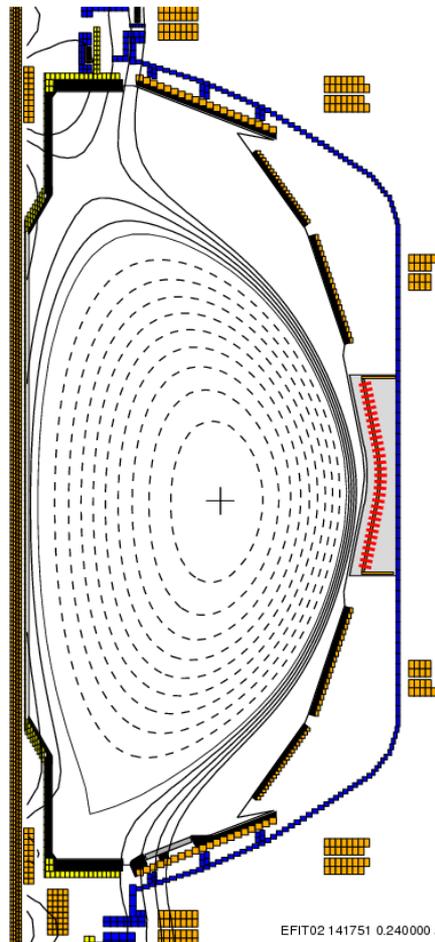
Intrinsic rotation in Ohmic L-H transition (#2)

- Rotation is increased by ~ 10 km/s in L-H and slightly evolves in H-mode



Intrinsic rotation in Ohmic L-H transition (#3)

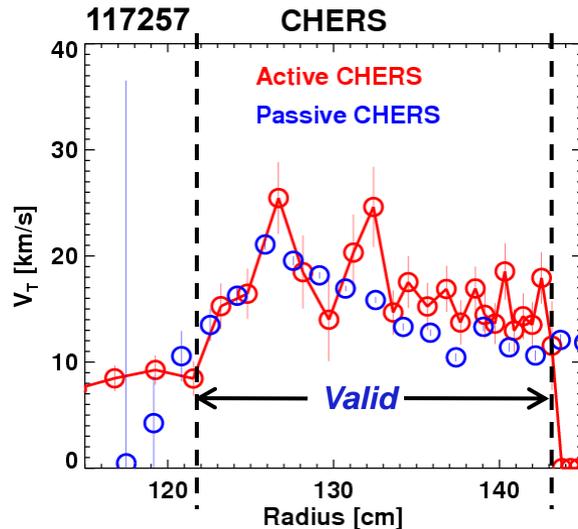
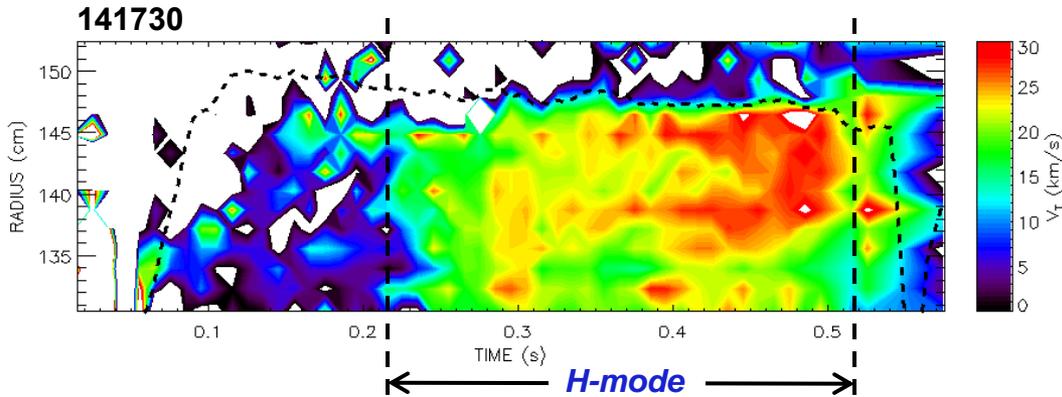
- Rotation jump is clear in L-H even if tearing mode is present



Passive CHERS provides (T_i, V_ϕ) profile evolution information using background Carbons

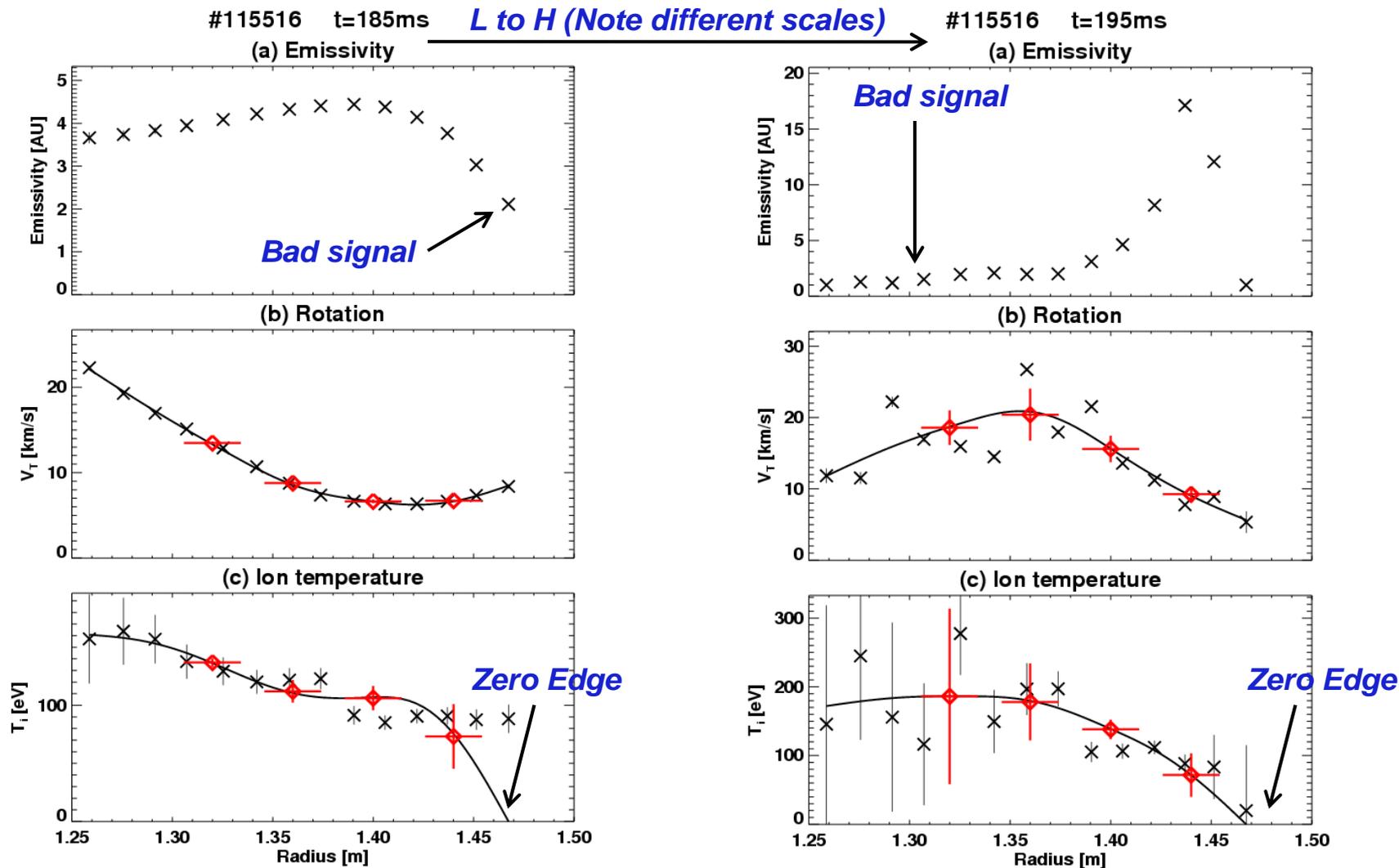
Passive CHERS

[Bell, POP 17, 082507 (2010)]



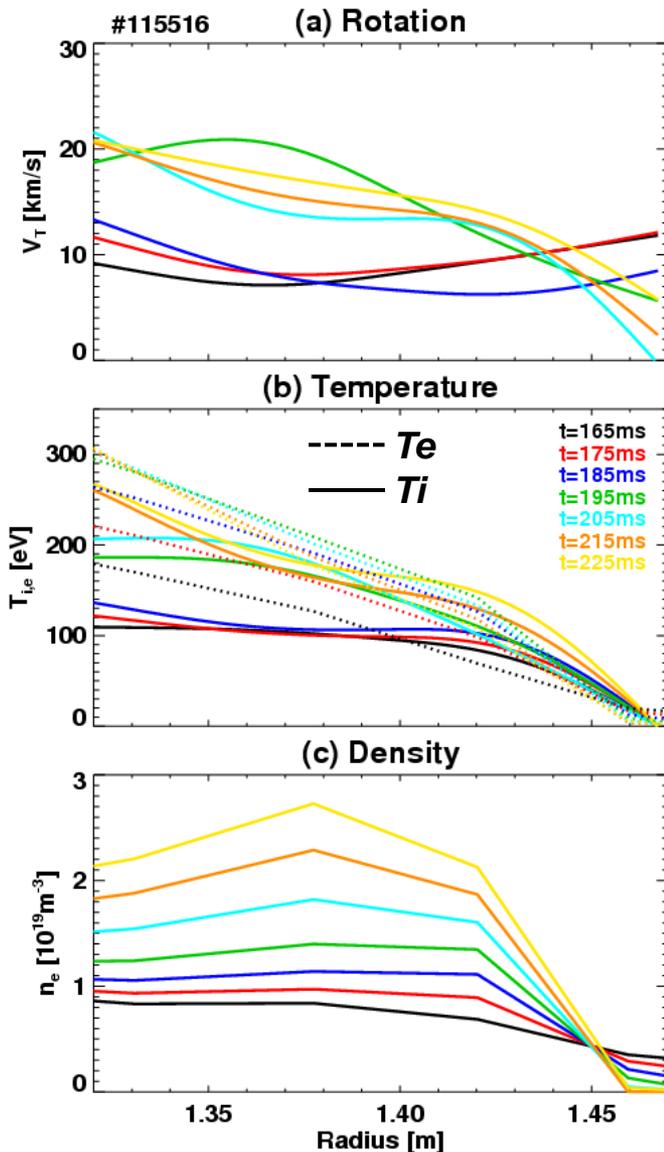
- Passive CHERS measures Carbon impurities (C^{5+}) in the background and gives (T_i, V_ϕ) profile information
- Passive and active CHERS agree well in the edge, indicating differences can be ignored and ExB can be assumed
 - ExB rotation can be measured by ignoring diamagnetic contribution (since Z is high), but toroidal rotation for main ions may be different – will be discussed later
- (T_i, V_ϕ) profiles perhaps can be fully used in the edge if adequate fitting procedure is added

Secondary fitting is used for (T_i, V_ϕ) profiles



* *Errors are propagated to the final analysis and used to rule out bad signals*

Profile evolution clearly shows rotation jump, associated with ion temperature change



- Rotation clearly jumps through L-H transition, and stays in quite a long time afterwards
- T_i (gradient) also clearly changes through L-H transition, and slowly evolves afterwards
- T_e and n_e (gradient) gradually increase through L-H transition

In 10ms around L-H transition,

- $\nabla T_e, \nabla n_e \uparrow$ at the end of pedestal
- $\nabla T_i, V_\phi \uparrow$ at the top of pedestal

Rotation change during Ohmic L-H transitions is dominantly driven by intrinsic torque

- Simplified form of rotation evolution is

$$\frac{\partial}{\partial t} (mnRV_\phi) = T_{input} - T_{NTV} - \nabla \cdot \Pi_\phi, \text{ where } \Pi_\phi = -mnR \left(\chi_\phi \frac{\partial V_\phi}{\partial r} - V_{pinch} V_\phi \right) + \Pi_{r,\phi}^R$$

- One can study the residual term alone when removing input torque, NTV, and zeroing rotation, which is however impossible in NSTX
- Nonetheless, through Ohmic L-H transition:

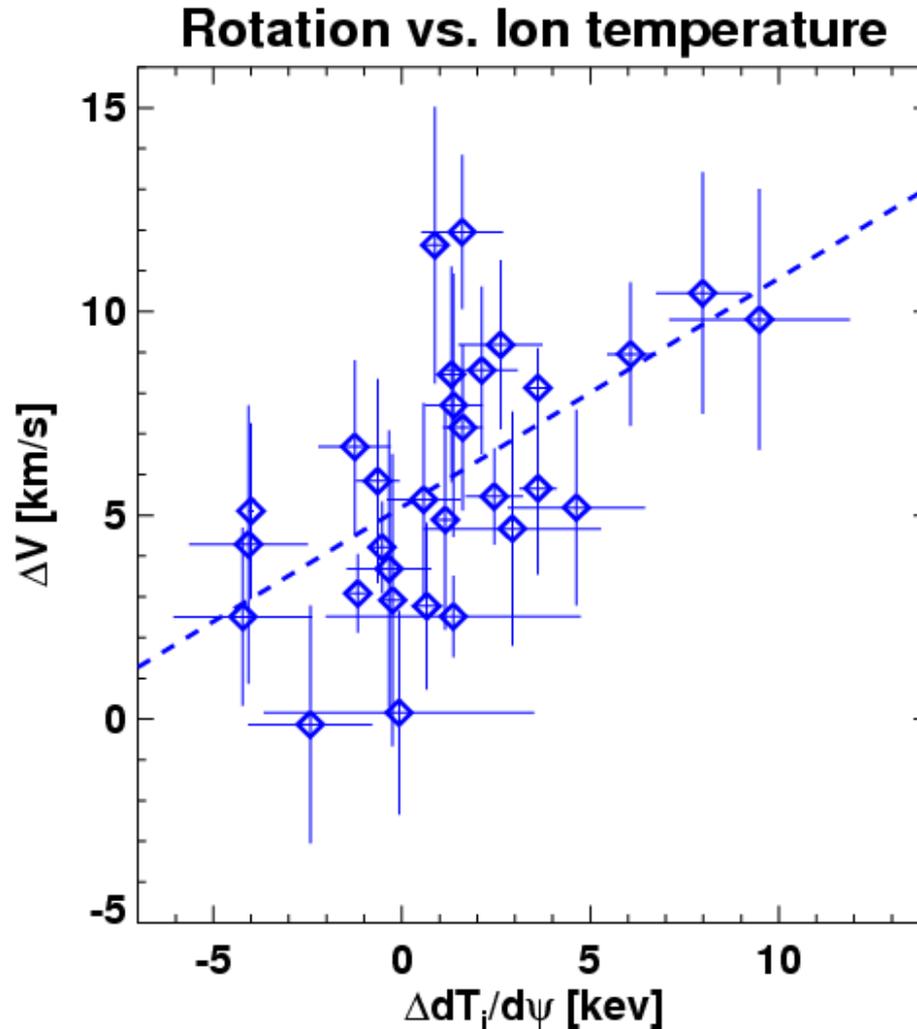
$$T_{input} = 0 \text{ and } T_{NTV} \cong T_{1/v} \approx 0$$

ignoring self -dependent evolution on V_ϕ in short time (10ms)

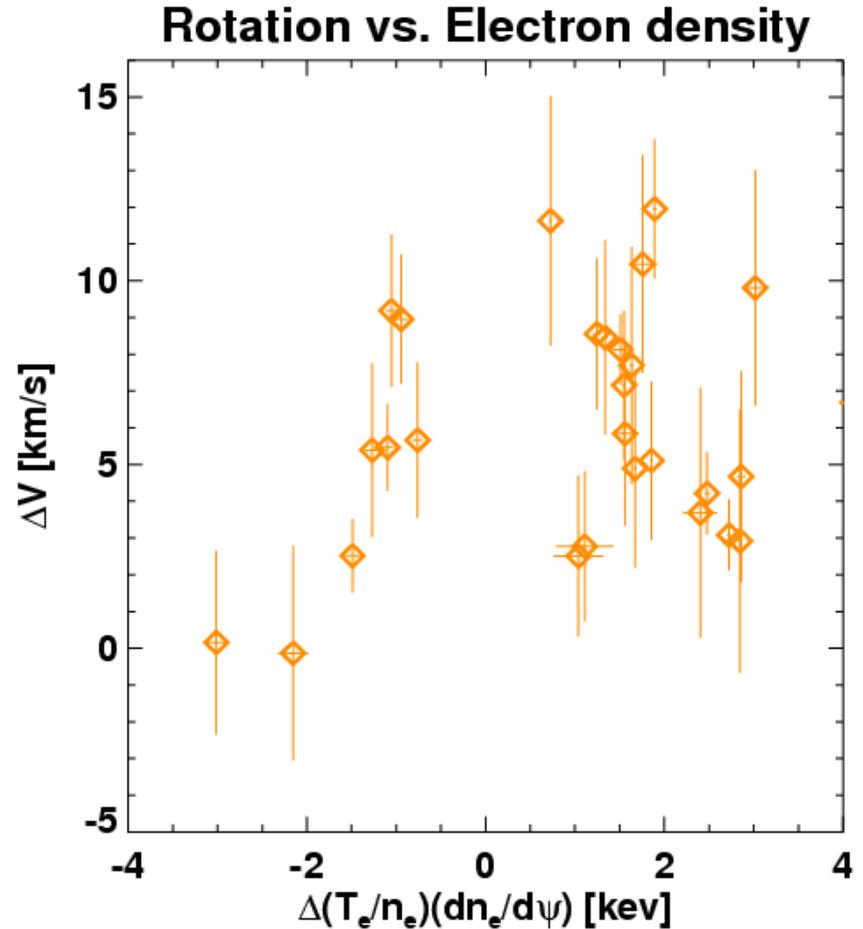
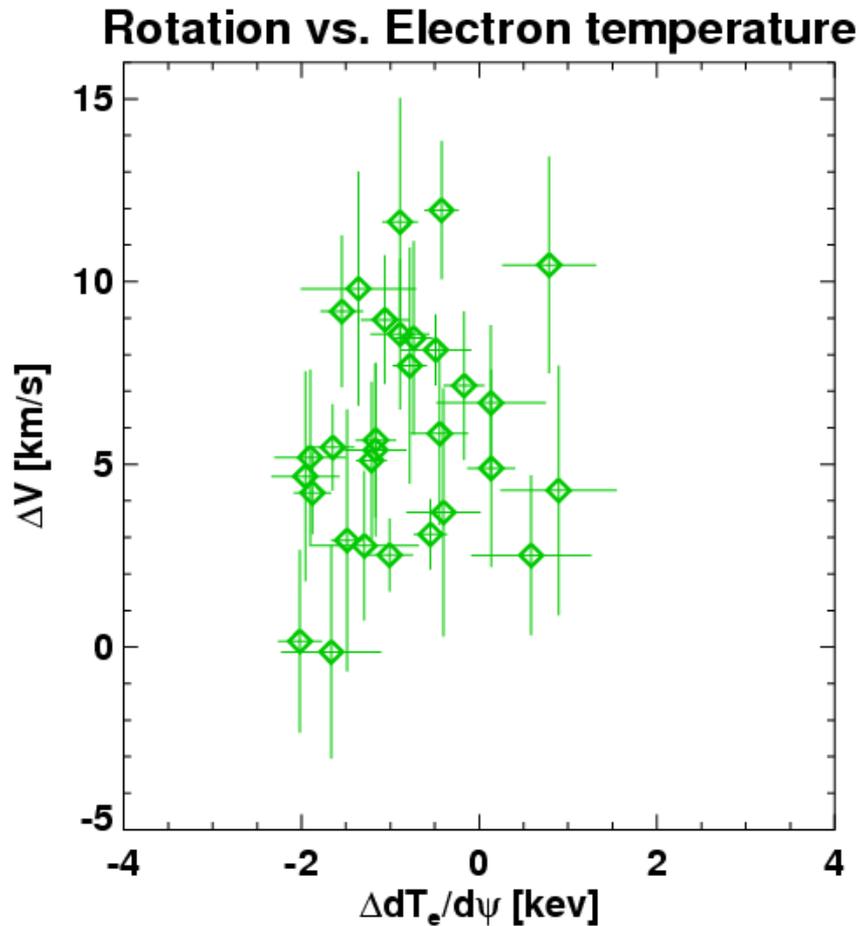
$$\frac{\partial}{\partial t} (mnRV_\phi) \approx -\nabla \cdot \Pi_{r,\phi}^R \quad \text{e.g. } \frac{\partial V}{\partial t} = V + C \rightarrow V = C\delta t + O(\delta t^2)$$

- Here the goal is to investigate $\Delta[V_\phi] (\text{or } \tau_\phi) \propto \Delta[\nabla \cdot \Pi_{r,\phi}^R] \propto \Delta \left[\frac{\partial n_{e,i}}{\partial r} \text{ or } \frac{\partial T_{e,i}}{\partial r} \right]$

Best correlation can be found between $\Delta(\nabla T_i, V_\phi)$



Correlations are not good for $\Delta(\nabla T_e, \nabla n_e, V_\phi)$



Experiment and recent theory agree well with small Prandtl number

- ExB shear is directly related to thermodynamic force

[McDevitt, POP 16, 052302 (2009)]

- A theoretical form for intrinsic rotation generation is given by

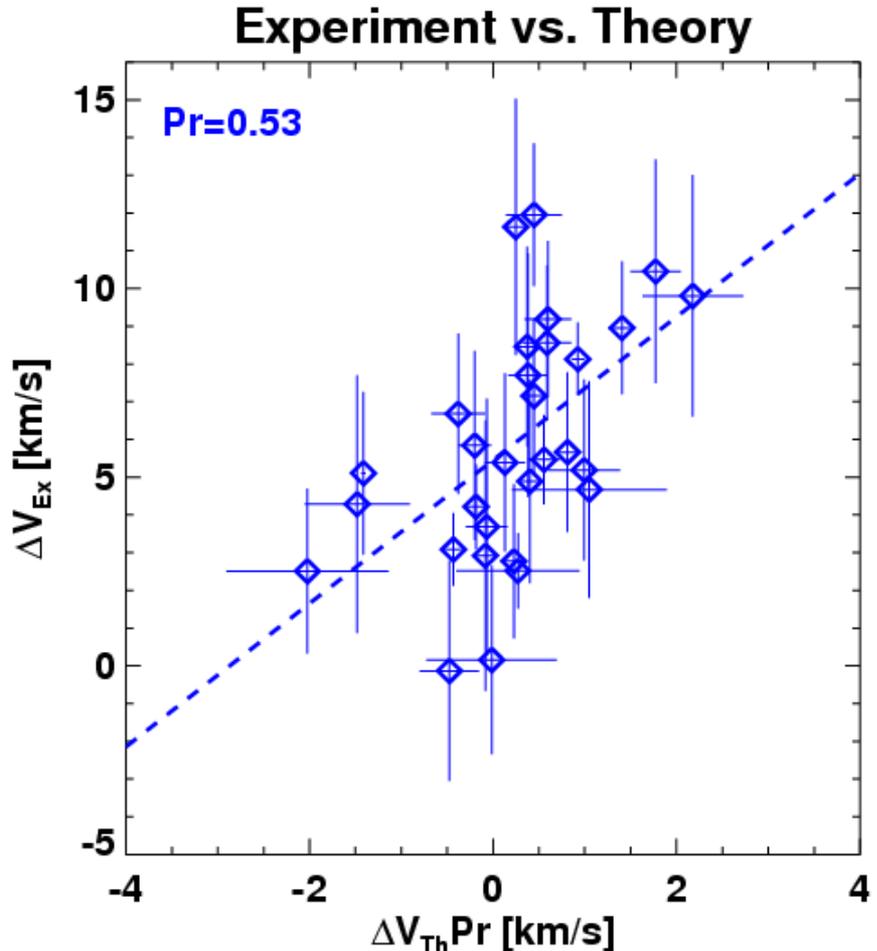
$$\langle V_{\parallel} \rangle \cong \frac{1}{2} \rho^* v_{thi} \frac{\chi_i}{\chi_{\phi}} \frac{L_s}{L_T} \sqrt{\frac{T_i}{T_e}} \quad \text{Pr} \equiv \frac{\chi_{\phi}}{\chi_i}$$

[Kosuga, POP 17, 102313 (2010)]

[Rice, PRL 106, 215001 (2011)]

- Experiment and theory correlates well with $\text{Pr} \sim 0.53$

– This small Prandtl number is consistent with previous NSTX momentum transport studies



Uncertainty exists due to difference between impurity and main ion rotations

- Difference between main ion rotation and impurity rotation may not be ignorable when rotation is low
- The 1st order gyro-expansions of moment equations give

$$V_s \cdot \nabla \varphi = - \left(\frac{d\Phi}{d\psi} + \frac{1}{Z_s e n_s} \frac{dP_s}{d\psi} - q V_s \cdot \nabla \theta \right) = - \left(\frac{d\Phi}{d\psi} + \frac{1}{Z_s e n_s} \frac{dP_s}{d\psi} - \frac{c_p}{Z_s e} \frac{dT_s}{d\psi} \right)$$

- For Carbon species (Z=5-6) or Argon species (Z=13-14), diamagnetic rotations and poloidal flows can be ignored
- For main ions,
 - If poloidal flows follow neoclassical predictions, two rotations are similar

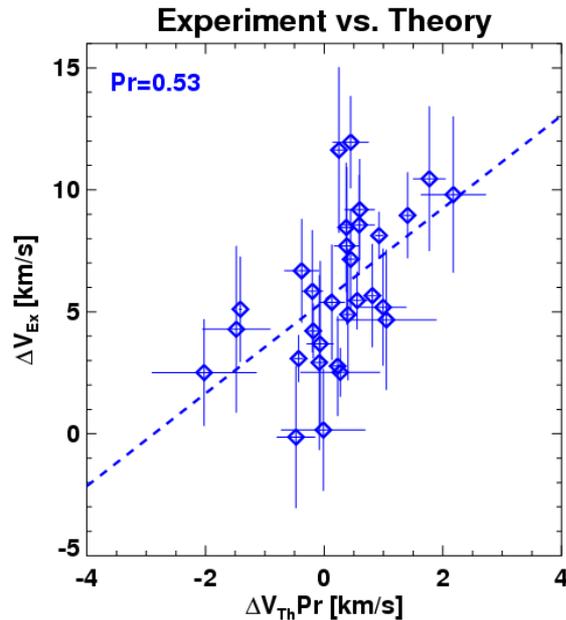
$$V_i \cdot \nabla \varphi \cong V_s \cdot \nabla \varphi - \frac{1}{e n_i} \frac{dP_i}{d\psi} + \frac{1}{e} \frac{dT_i}{d\psi} = V_s \cdot \nabla \varphi - \frac{T_i}{e n_i} \frac{dn_i}{d\psi}$$

- If poloidal flows are negligible, diamagnetic corrections are needed

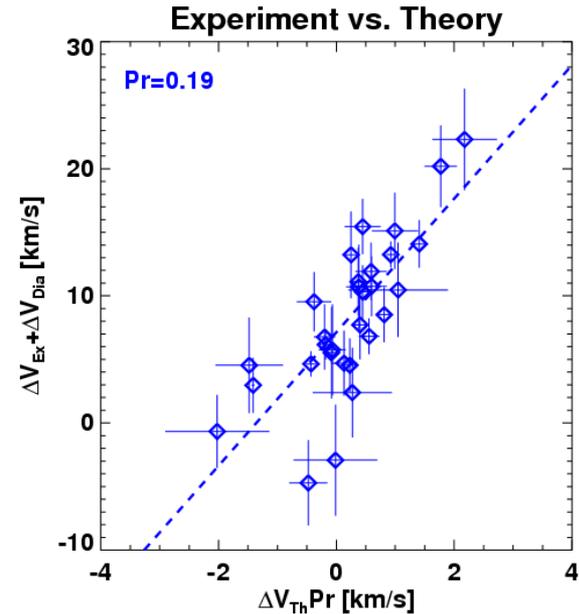
$$V_i \cdot \nabla \varphi \cong V_s \cdot \nabla \varphi - \frac{1}{e n_i} \frac{dP_i}{d\psi} = V_s \cdot \nabla \varphi - \frac{T_i}{e n_i} \frac{dn_i}{d\psi} - \frac{1}{e} \frac{dT_i}{d\psi}$$

Uncertainty with diamagnetic or poloidal rotation is as large as intrinsic rotation

- Diamagnetic correction for measurements:



➔
With diamagnetic correction



- Diamagnetic contribution in theory:

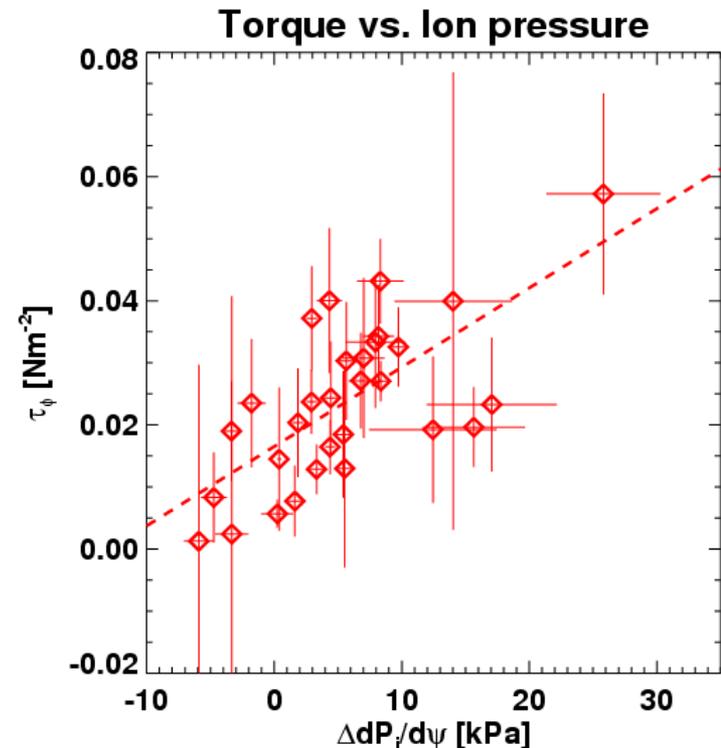
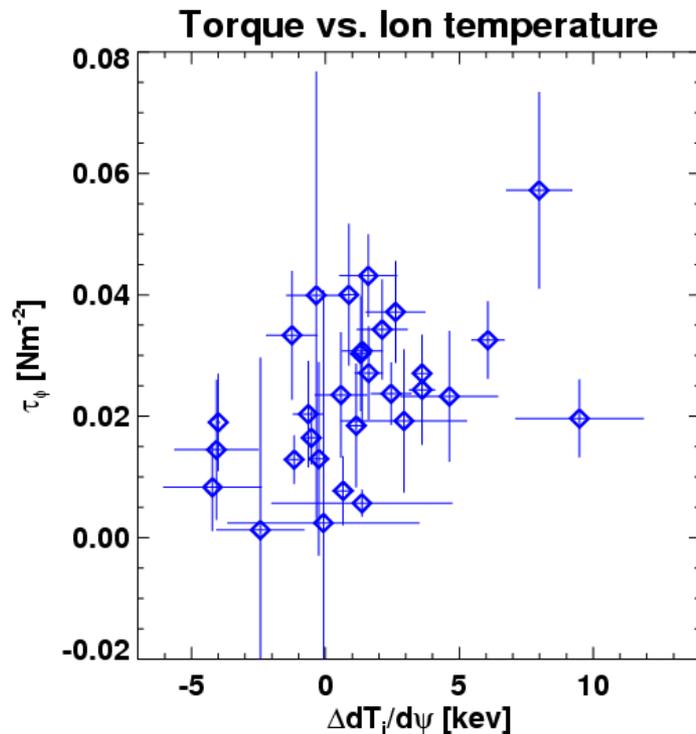
$$V_{RS} \cong \frac{1}{2} \rho_* v_{thi} \frac{\chi_i}{\chi_\phi} \frac{L_s}{L_T} \sqrt{\frac{T_i}{T_e}} \cong \frac{1}{2\hat{s} Pr} \frac{1}{eB_\theta} \frac{dT_i}{dr} \cong \frac{1}{2\hat{s} Pr} V_{Diamagnetic}$$

If $Pr \sim 1$ and $2\hat{s} \gg 1$ as usual, $V_{RS} \ll V_{Diamagnetic}$

Intrinsic torque scaling is essentially needed rather than intrinsic rotation scaling

- Torque is more fundamental than rotation in theory
- Intrinsic torque is better correlated with ∇P_i than ∇T_i

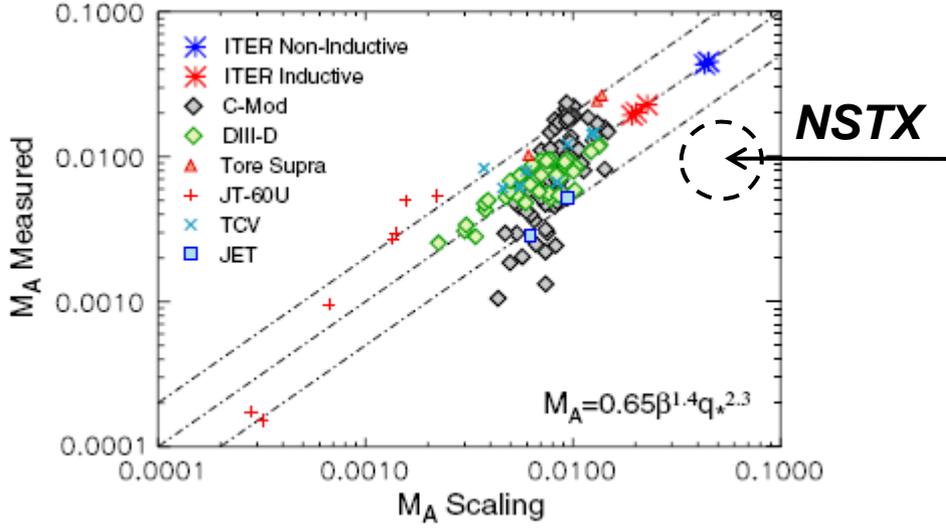
$$V_\phi \propto \nabla T_i, \text{ so } \tau_\phi \propto \frac{\partial(n_i R V_\phi)}{\partial t} \propto n_i \nabla T_i \propto \nabla P_i ?$$



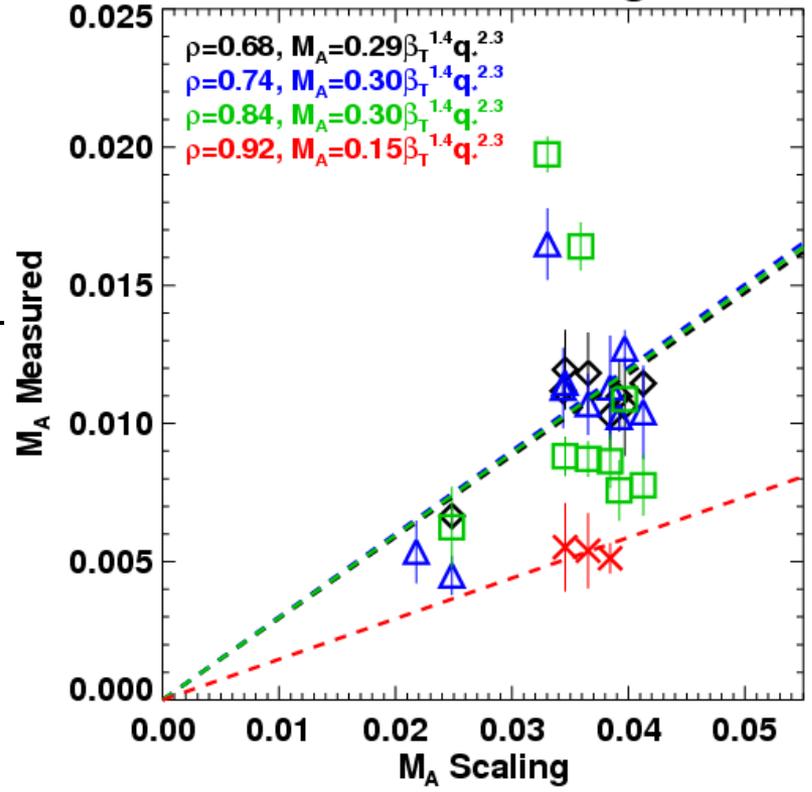
Comparison with other tokamak scaling (by Rice)

- NSTX intrinsic rotation through L-H transitions may follow empirical scaling of conventional tokamaks (by Rice)
- However, NSTX results yield small proportional factor due to large toroidal β and q_* in ST

[Rice, NF 47, 1618 (2007)]



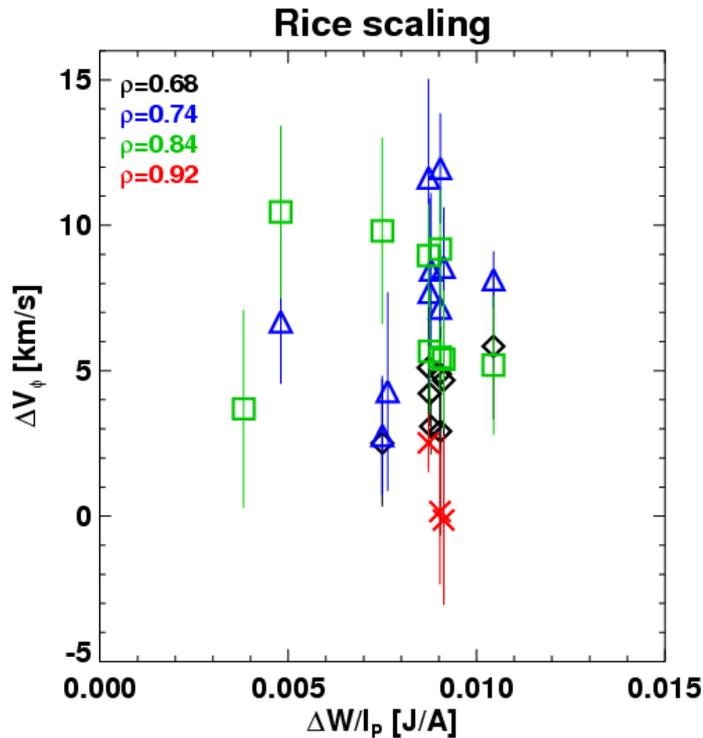
Rotation scaling



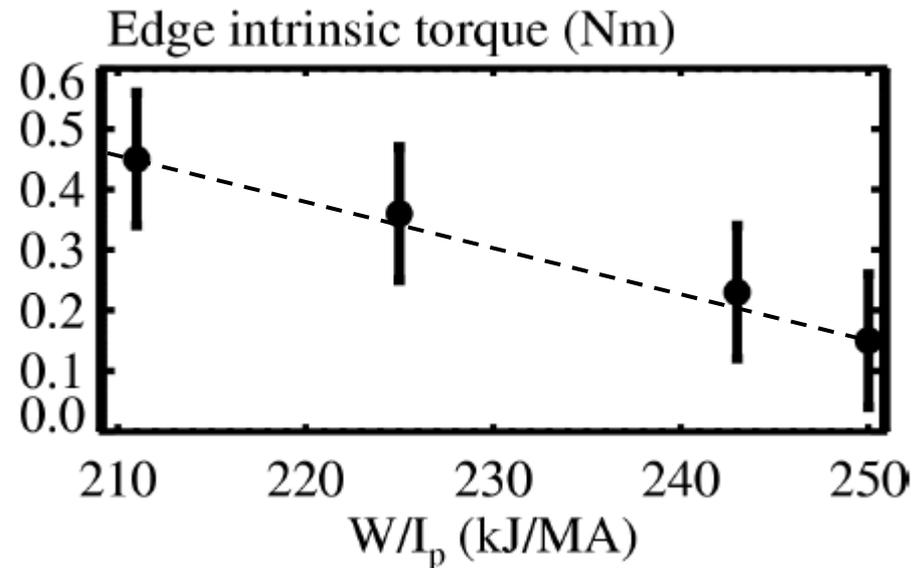
Comparison with Rice scaling

- NSTX data do not follow Rice scaling?

Scaling for Ohmic plasmas
(J.-K. Park)



Scaling from NBI plasmas
(W. M. Solomon)



Summary and Future work

- NSTX intrinsic rotation studies are successfully done through Ohmic L-H transitions, using Passive CHERS
- Best correlation can be found between $(\nabla T_i, V_\phi)$ and $(\nabla P_i, \tau_\phi)$
- Theory and experiment agree well with small Pr
- However, uncertainty with diamagnetic or poloidal rotation is as large as intrinsic rotation itself
- This smallness of intrinsic rotation can be seen by $V_{RS} \cong \frac{1}{2\hat{s}Pr} V_{Diamagnetic}$
- NSTX intrinsic rotation may follow empirical scaling with small proportional factor, but does not follow Rice scaling
- Future work may include
 - TRANSP and NCLASS calculations
 - Intrinsic NTV calculations
 - Pinch and diffusivity calculations?

It is hard to estimate other terms of momentum transport in this analysis

- Simplified momentum transport:

$$\frac{\partial}{\partial t} (mnRV_\phi) = \nabla \cdot \left[mnR \left(\chi_\phi \frac{\partial V_\phi}{\partial r} - V_{pinch} V_\phi \right) + \Pi_{r,\phi}^R \right] \longrightarrow \frac{\partial L}{\partial t} = T_{RS} - \frac{L}{\tau_\phi}$$

- It requires at least three time slices to estimate both quantities
- However, changes except L-H transition are not apparent and would not be reliable in terms of errors

