

# XP728: RWM active stabilization and optimization – ITER scenario

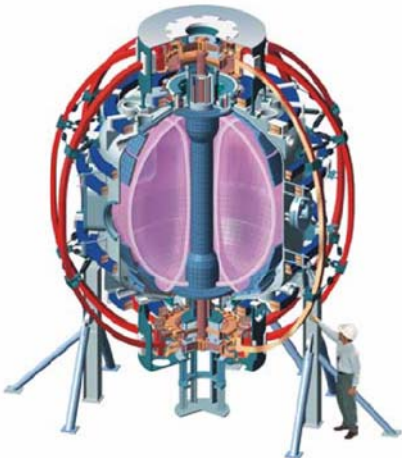
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## **NSTX Results Review**

July 24th, 2007

Princeton Plasma Physics Laboratory

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# RWM feedback studied with expanded sensor set, reduced $V_\phi$

## □ Goals

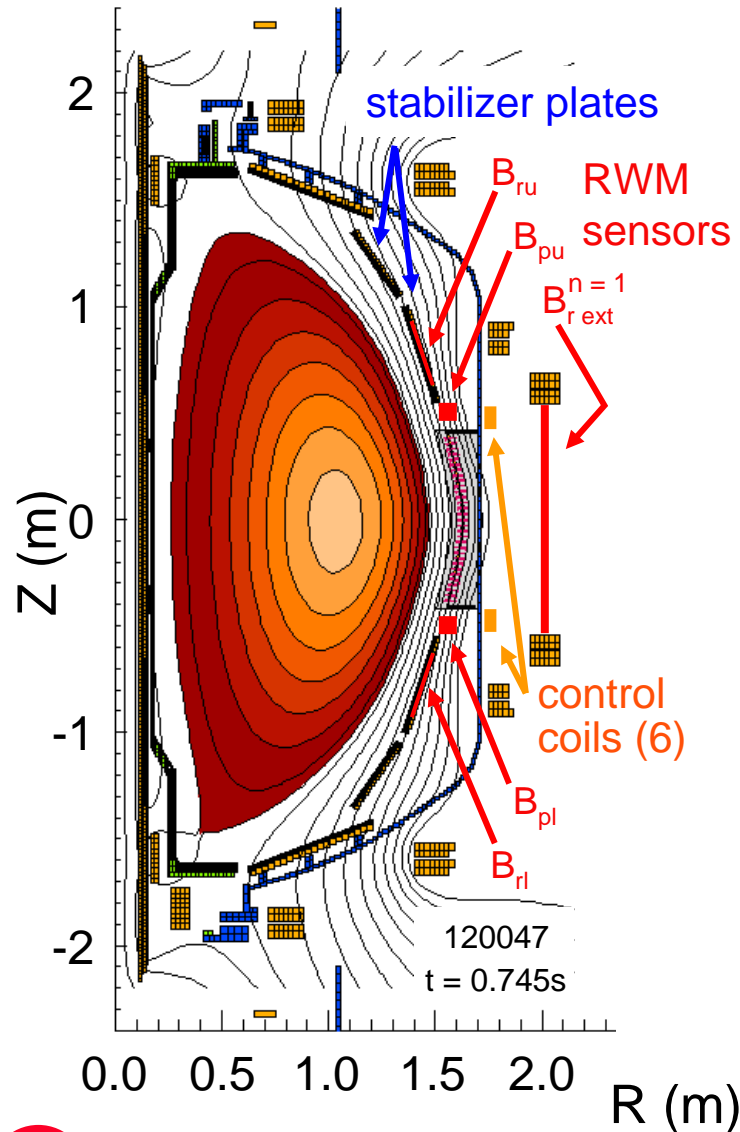
- Investigate variations of control sensor combinations to optimize RWM stabilization at low plasma rotation,  $\omega_\phi$  (more robust, reach higher  $\beta_N$ )
  - Use upper/lower RWM  $B_r$ ,  $B_p$  sensors for feedback (ran out of time in 2006)
  - Examine possible poloidal deformation of RWM during feedback
- Investigate active stabilization of recent plasmas that exhibit unstable RWM activity leading to discharge termination at high  $\omega_\phi$ .
- Explore possible stable region at  $\omega_\phi < \omega_{*i}$  with feedback is turned off
- Investigate RWM active stabilization of low  $\omega_\phi$  plasma with superposed time-averaged  $n = 1$  error field correction +  $n = 3$  magnetic braking
  - (Fredrickson, Garofalo suggestion from 2006, but no run time)
- Measure  $n = 2-3$  RFA, attempt to destabilize  $n = 2$  RWM with  $n = 1$  stable
- Introduce and study effect of applied time delay on feedback (ITER support)
  - Depends on control system time delay capability in 2007

## □ Addresses

- **NSTX milestone R(07-2)**, NSTX PAC request
- ITPA experiment MDC-2, ITER issue card RWM-1, USBPO MHD task



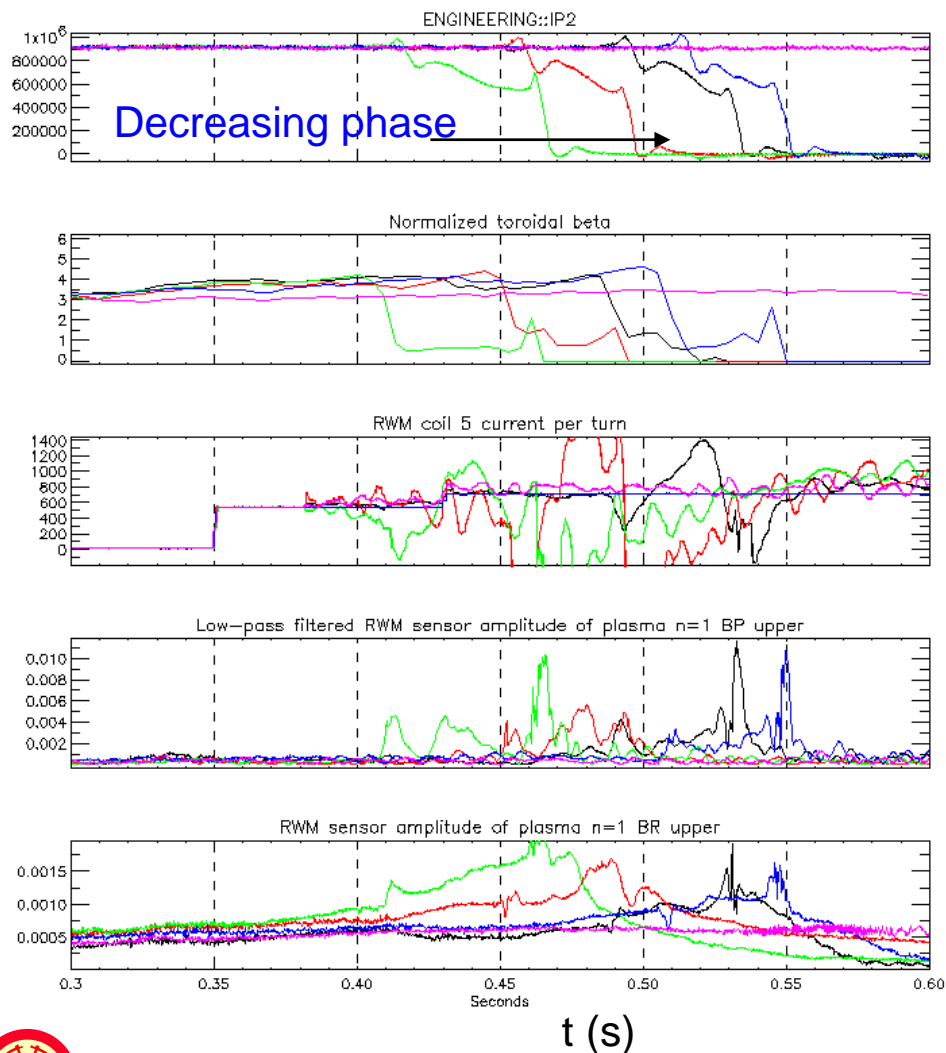
# RWM active feedback system now uses more sensors



- ❑ Stabilizer plates for kink mode stabilization
- ❑ External midplane control coil closely coupled to vacuum vessel
  - ❑ Similar to ITER port coil designs
- ❑ New sensor combinations
  - ❑  $B_{pu} + B_{pl}$  (used  $B_{pu}$  in past)
  - ❑  $B_{ru}$ ;  $B_{ru} + B_{rl}$
  - ❑  $B_{pu} + B_{pl}$  with spatial offset
  - ❑ All sensors in combination

# Feedback phase continues to be a key feedback variable

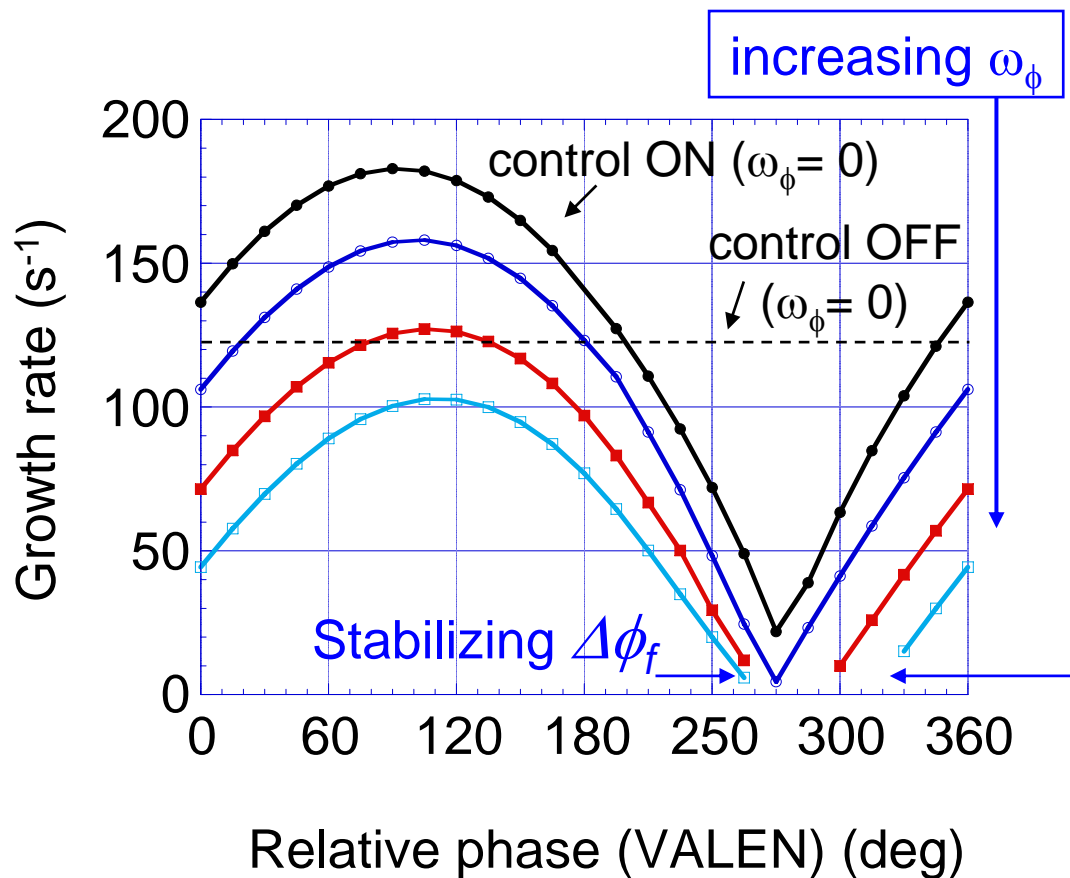
## Feedback phase scan with $B_p^{\text{upper}} + B_p^{\text{lower}}$



- ❑ Recreated past active feedback with  $B_p^{\text{upper}}$  sensors
  - ❑ Plasma rotation slowed using  $n = 3$  non-resonant magnetic braking
- ❑ Completed feedback phase scan using with  $B_p^{\text{lower}} + B_p^{\text{upper}}$  sensors
- ❑ Key detail in mode dynamics during feedback – further analysis needed
  - ❑ Poloidal deformation of mode reported in 2006 PRL seen again with upper sensors; changed by upper/lower sensor feedback

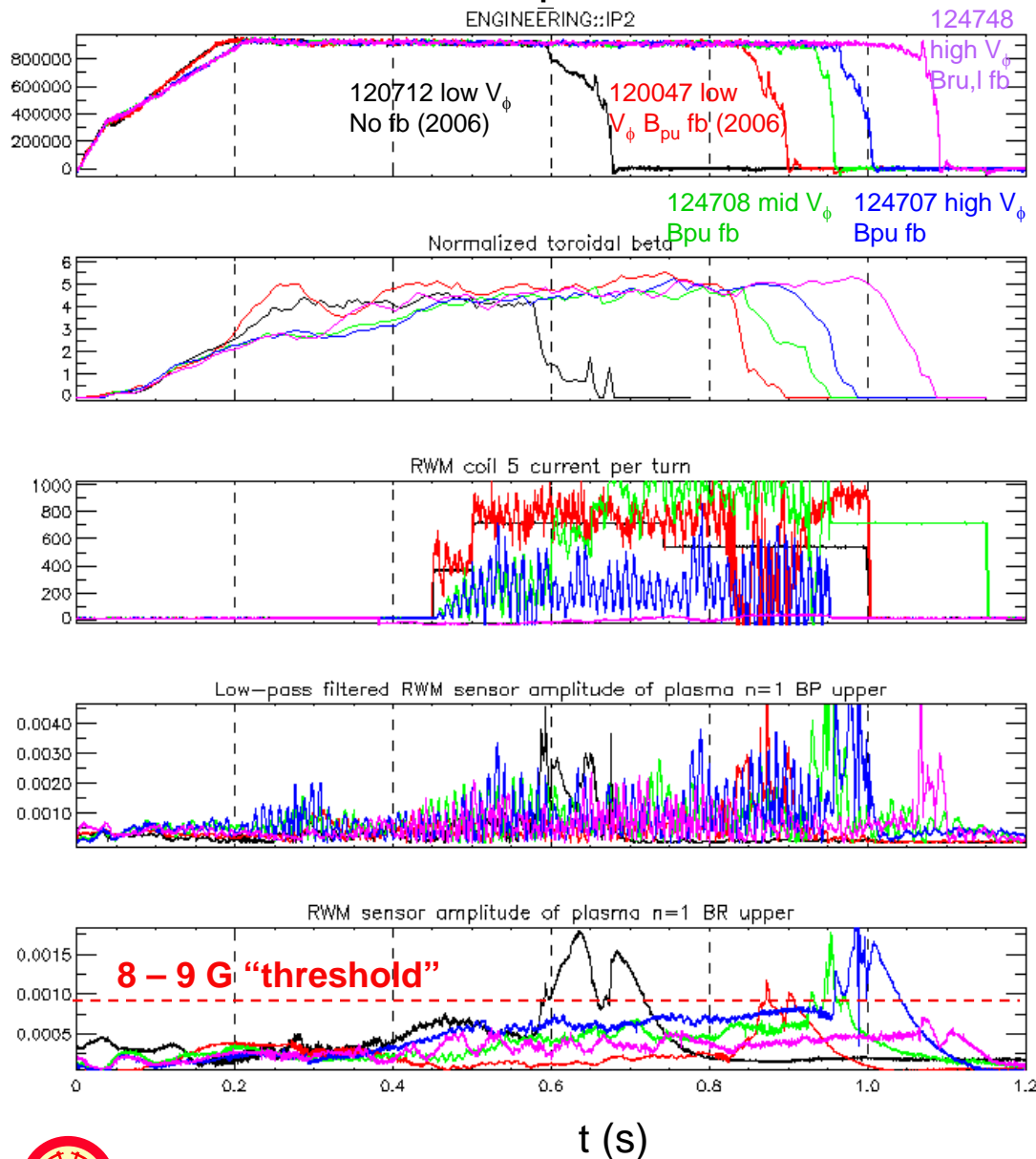


# Past VALEN-3D analysis of optimal relative phase $\Delta\phi_f$ for active control being expanded for XP728



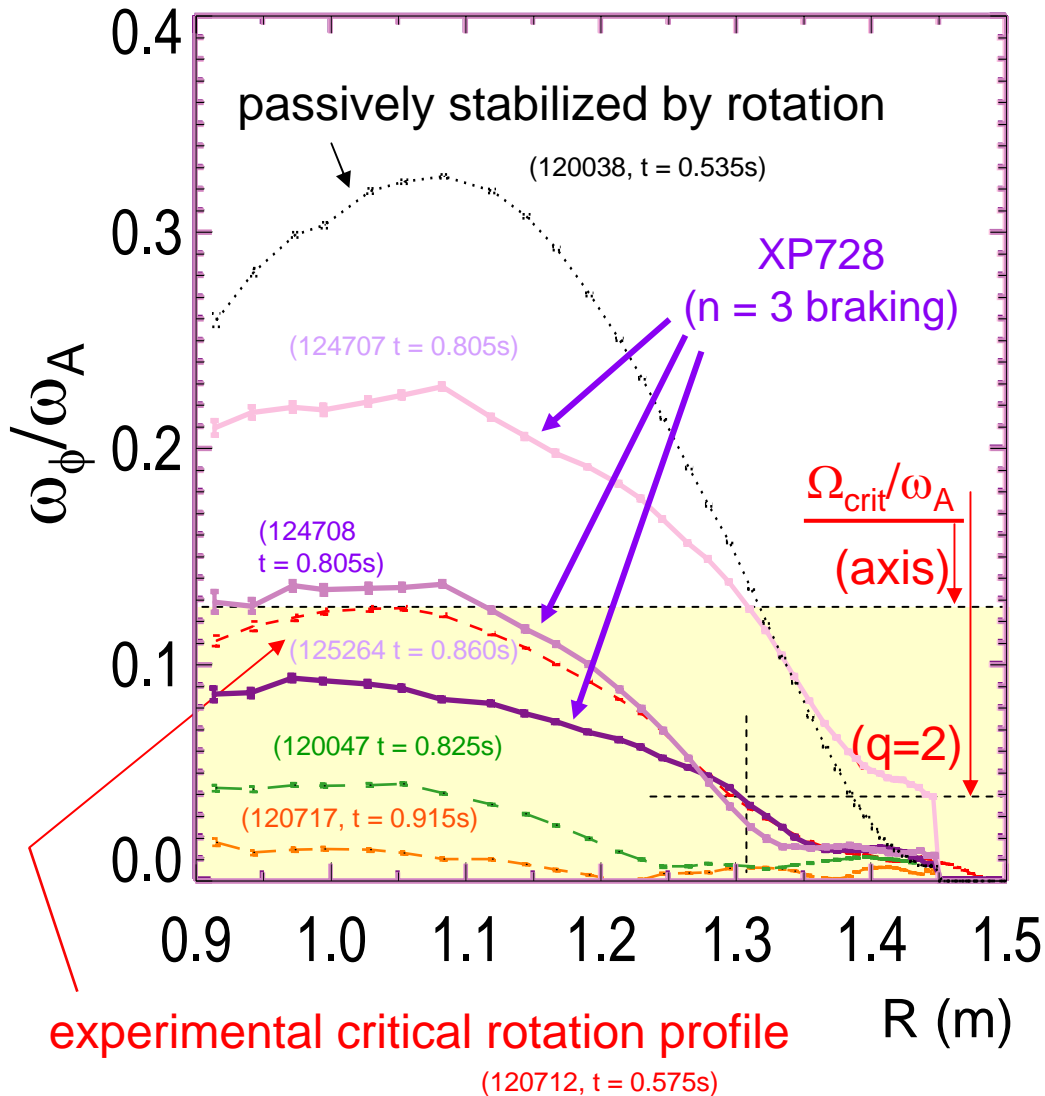
- ❑ Past results (“midplane sensors”)
  - ❑ Unfavorable  $\Delta\phi_f$  drives mode growth
  - ❑ Stable range of  $\Delta\phi_f$  increases with increasing  $\omega_\phi$
- ❑ NEW analysis uses actual experimental sensor positions
  - ❑ Stabilization found without the need for plasma rotation ( $B_p$  sensors)
  - ❑ Further calculations will model all sensor combinations used

# Upper / lower $B_r$ sensors for feedback for first time



- Determined feedback phase for best response with  $B_r^{\text{upper}} + B_r^{\text{lower}}$  sensors
  - Detailed feedback dynamics, apparent poloidal deformation of mode
  
- Maximum  $n = 1$   $B_r$  amplitude plasma can tolerate  $\sim 8 - 9$  G
  - Analogous  $n = 1$   $B_p$  sensor value of about 15–20 G
  
- Feedback using  $B_r^{\text{upper}} + B_r^{\text{lower}}$  sensors at high rotation available as tool for other XPs

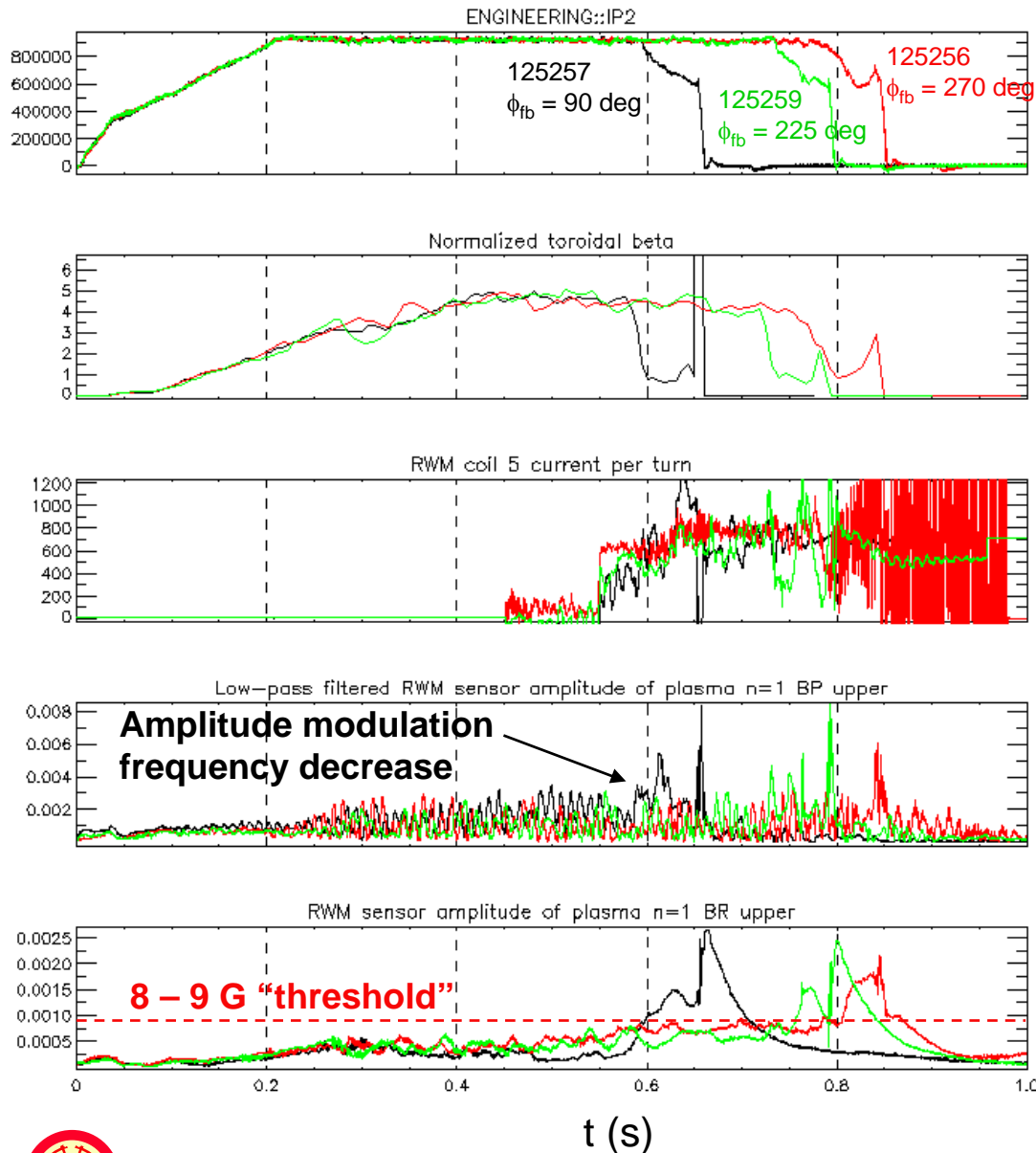
# XP728 filled in rotation profiles produced during RWM feedback



## 2007 data - range of rotation profiles for RWM analysis

- Broader  $\omega_\phi$  in some cases
- Created RWM *passively* stable plasma with zero rotation at  $q = 2$  surface
  - Supports past NSTX data showing rotation profile important to stability, not just at single  $q$  surface
- Unstable RWM observed at high rotation ( $\sim 40$  kHz core)
  - Is the mode observed an RWM?
- No indication, so far, of stable low rotation state, feedback off
- Rotation may not have been slowed enough; analysis of trapped particle precession stabilization may tell

# Further sensor combinations used for feedback



Feedback phase scan for  $B_p$  lower +  $B_p$  upper sensor average,  $180^\circ$  degree spatial offset

- favorable  $270^\circ$  degree feedback phase expected by simple RWM theory

- $B_p$  sensor amplitude modulation decreases in frequency during mode onset

Feedback with full  $B_r$ ,  $B_p$  sensor set

- XP702 – plasma stable at high  $V_\phi$  to 1.3s with feedback

- Similar plasma showed instability – again showing mode amplitude modulation decrease in frequency