



# Equilibrium, NTV, and Disruption Event Characterization and Forecasting Results Update for NSTX/NSTX-U

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## NSTX-U Results Review

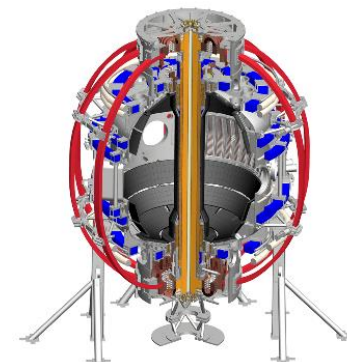
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PPPL

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99ER54524*



V1.2



# OUTLINE – Updates on three subjects

- ❑ Impact of PF1aU on equilibrium reconstruction
- ❑ Disruption Event Characterization and Forecasting development
- ❑ Neoclassical Toroidal Viscosity on NSTX-U
  - ❑ One shot identified in Walter's L-mode experiments has sufficient data for NTV profile analysis
  - ❑ More to do, not enough time to show – will send by email

# Equilibrium reconstruction recent conclusion: PF1aU issue has negligible effect on reconstructions since it appeared

## Near maximum difference

## Near peak stored energy

### Stored energy

### Stored energy

### DRSEP

Shot	t (s)	Wtot (kJ)			Pct Diff (%)	t (s)	Wtot (kJ)			Pct Diff (%)	DRSEP (cm)		Diff (mm)
		EFIT04	EFIT02				EFIT04	EFIT02			EFIT04	EFIT02	
203655	0.266	50.1	46.6	6.986%	0.673	142.79	142.72	0.049%	0.422	0.183	2.39		
204112	0.196	36.3	33.6	7.438%	0.772	284.8	282.8	0.702%	-0.298	-0.397	0.99		
204118	0.2	34.2	32	6.433%	0.674	335.14	333.2	0.579%	-0.702	-0.838	1.36		
204971	0.18	24.4	24.18	0.902%	0.731	73.5	73.6	-0.136%	-0.637	-0.603	-0.34		
204980	0.2	31.37	31.37	0.000%	0.5	87.91	88.22	-0.353%	0.107	0.1136	-0.066		
205055	0.173	12.06	11.44	5.141%	0.307	118.46	118.25	0.177%	-0.3	-0.38	0.8		
205057	0.196	39.33	39.25	0.203%	0.346	146.6	146.48	0.082%	-0.418	-0.444	0.26		
205062	0.16	14.74	14.47	1.832%	0.325	44.05	44.18	-0.295%	-0.36	-0.387	0.27		
205069	0.163	15.92	15.65	1.696%	0.331	61.58	61.78	-0.325%	-0.59	-0.65	0.6		
205084	0.225	29.43	29.36	0.238%	0.289	27.84	27.87	-0.108%	0.046	0.032	0.14		
Average				3.087%				0.037%			0.6404		

- ❑ Reconstructions use PF coil currents, have small error (~ 0.5%), so PF1aU issue might affect result
- ❑ However, the balance of the magnetics minimize reconstruction changes
  - ❑ The **fitted** PF1aU **does** deviate from the measured value – becomes worse in time

# DECAF is structured to ease parallel development of disruption characterization, event criteria, and forecasting

## □ Initial DECAF analysis goals

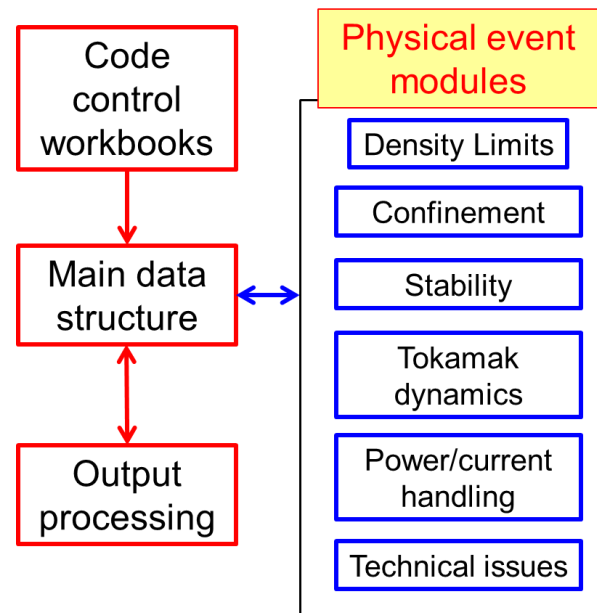
- ✓ Define physics criteria that define an initial set of disruption “events”
- ✓ Characterize time sequences of events in disruptive shots
- □ Produce initial physics models to define marginal points of key events
- □ Enable initial disruption forecasting capability for most well-defined events / sequences

## DECAF disruption events and chains

→ e.g. **SCL** Loss of shape control



## DECAF code schematic



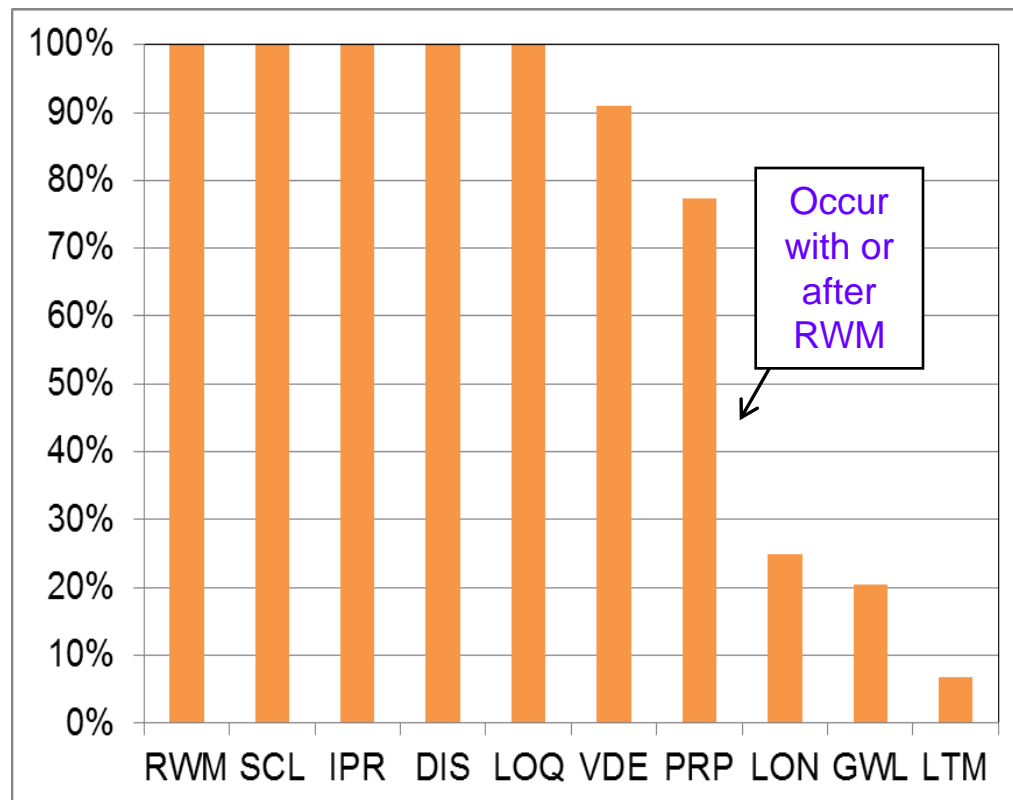
# Recap: DECAF results detect disruption chain events when applied to dedicated 44 shot NSTX RWM disruption database

## Several events detected for all shots

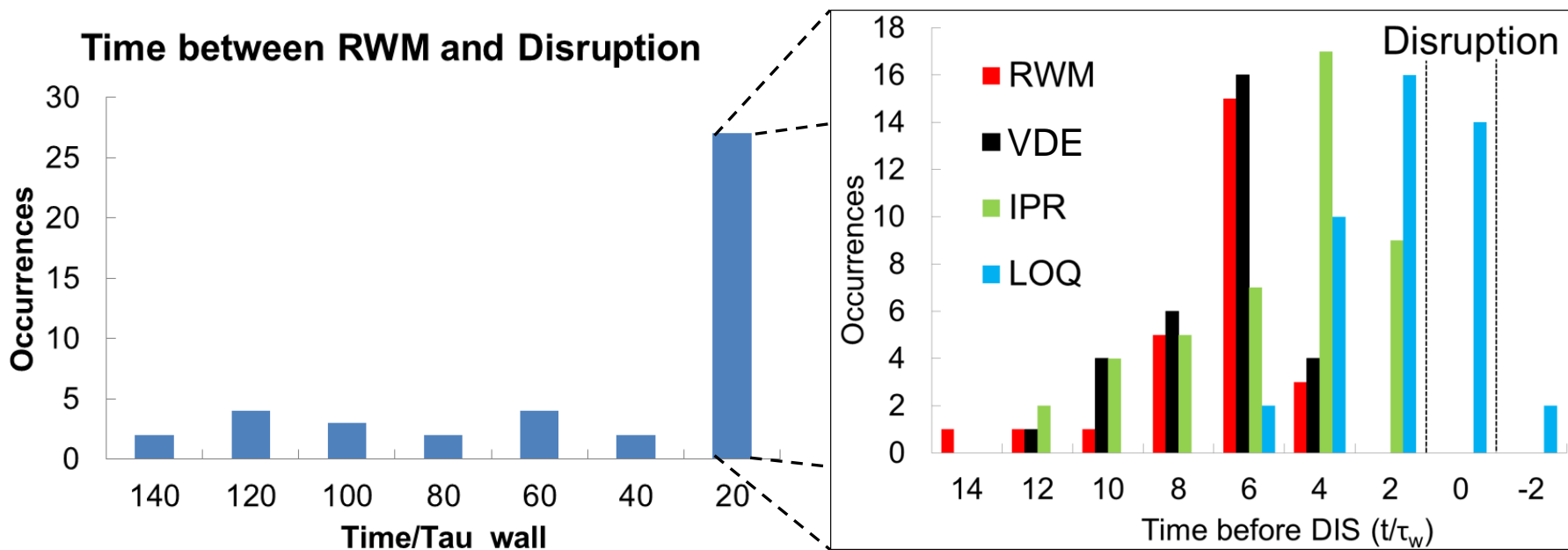
- ❑ **RWM**: RWM event warning
- ❑ **SCL**: Loss of shape control
- ❑ **IPR**: Plasma current request not met
- ❑ **DIS**: Disruption occurred
- ❑ **LOQ**: Low edge q warning
- ❑ **VDE**: VDE warning (40 shots)

## Others:

- ❑ **PRP**: Pressure peaking warning
- ❑ **GWL**: Greenwald limit
- ❑ **LON**: Low density warning
- ❑ **LTM**: Locked tearing mode

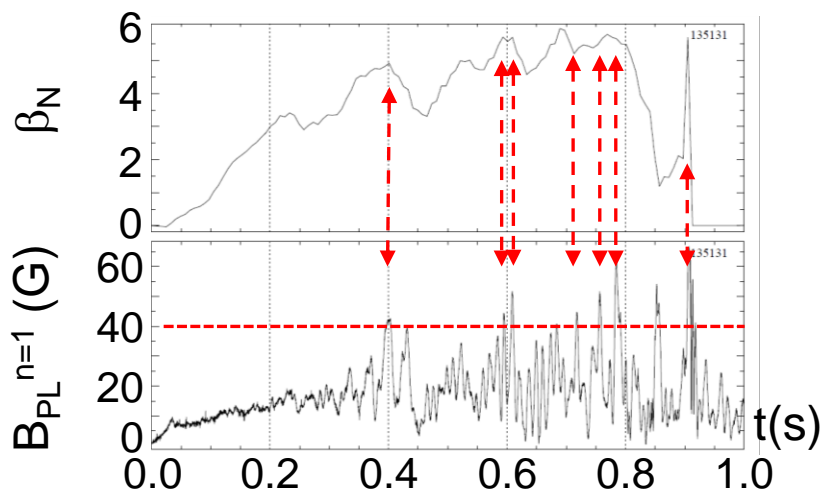


# DECAF results detect disruption chain events when applied to dedicated 44 shot NSTX RWM disruption database



## Most RWM near major disruption

- 61% of RWM occur within  $20 \tau_w$  of disruption time ( $\tau_w = 5$  ms)
- Earlier RWM events **NOT false positives** – cause large decreases in  $\beta_N$  with recovery (minor disruptions)



# Initial DECAF analysis finds common disruption event chains (44 shot NSTX disruption database)

## Common disruption event chains (52.3%)



### Related chains

- RWM → SCL → VDE → IPR → DIS
- VDE → RWM → SCL → IPR → DIS
- VDE → RWM → IPR → DIS → SCL
- RWM → SCL → VDE → GWL → IPR → DIS

## Disruption event chains w/o VDE (11.4%)

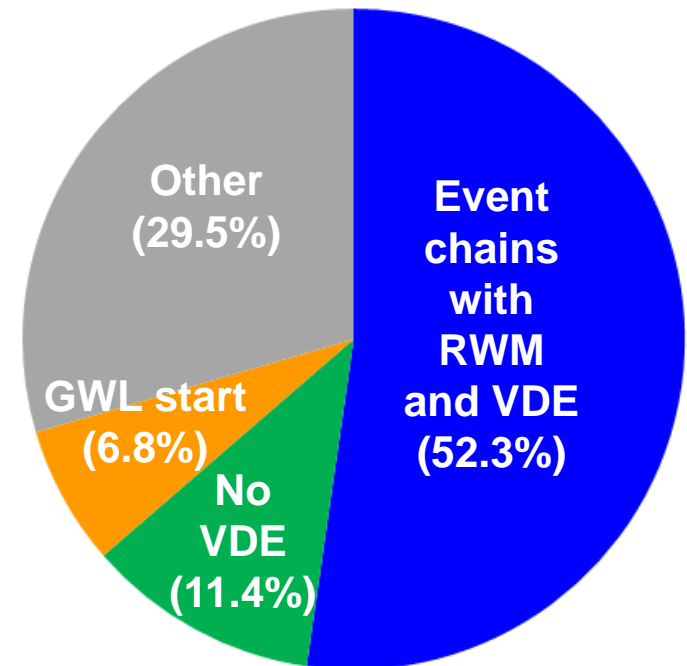
## New insights being gained

- Chains starting with GWL are found that show rotation and  $\beta_N$  rollover before RWM (6.8%)


### Related chains

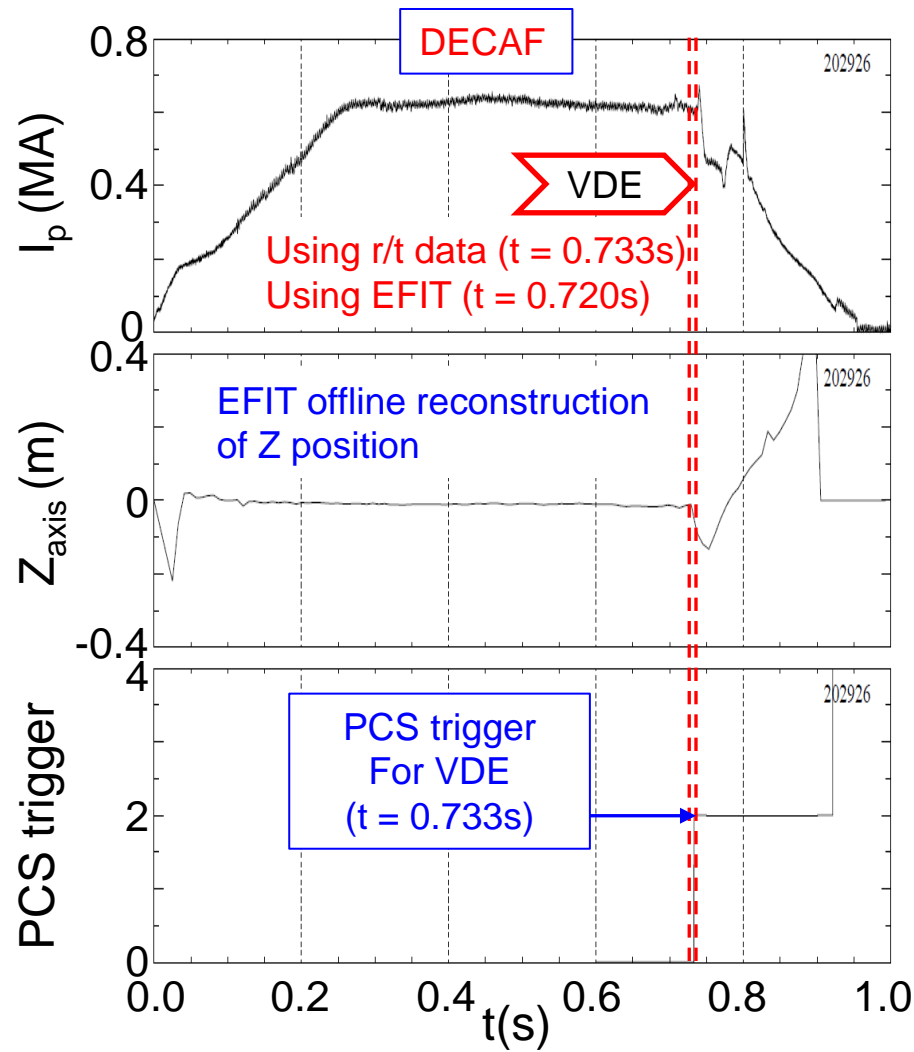
- GWL → VDE → RWM → SCL → IPR → DIS
- GWL → SCL → RWM → IPR → DIS

## Disruption event chains with RWM



# First DECAF results for NSTX-U replicate the triggers found in new real-time state machine shutdown\* capability

- Important capability of DECAF to compare analysis using offline vs. real-time data
  - Simple, initial test
- PCS Shut-down conditions are analogous to DECAF events
  - PCS loss of vertical control → DECAF 
- DECAF comparison: VDE event
  - Matches PCS when r/t signal used (1 criterion)
  - VDE event 13 ms earlier using offline EFIT signals (3 criteria)



\*See S.P. Gerhardt, et al., NSTX-U shutdown handler talk



# Next essential step for DECAF analysis: Identification of rotating MHD (e.g. NTMs)

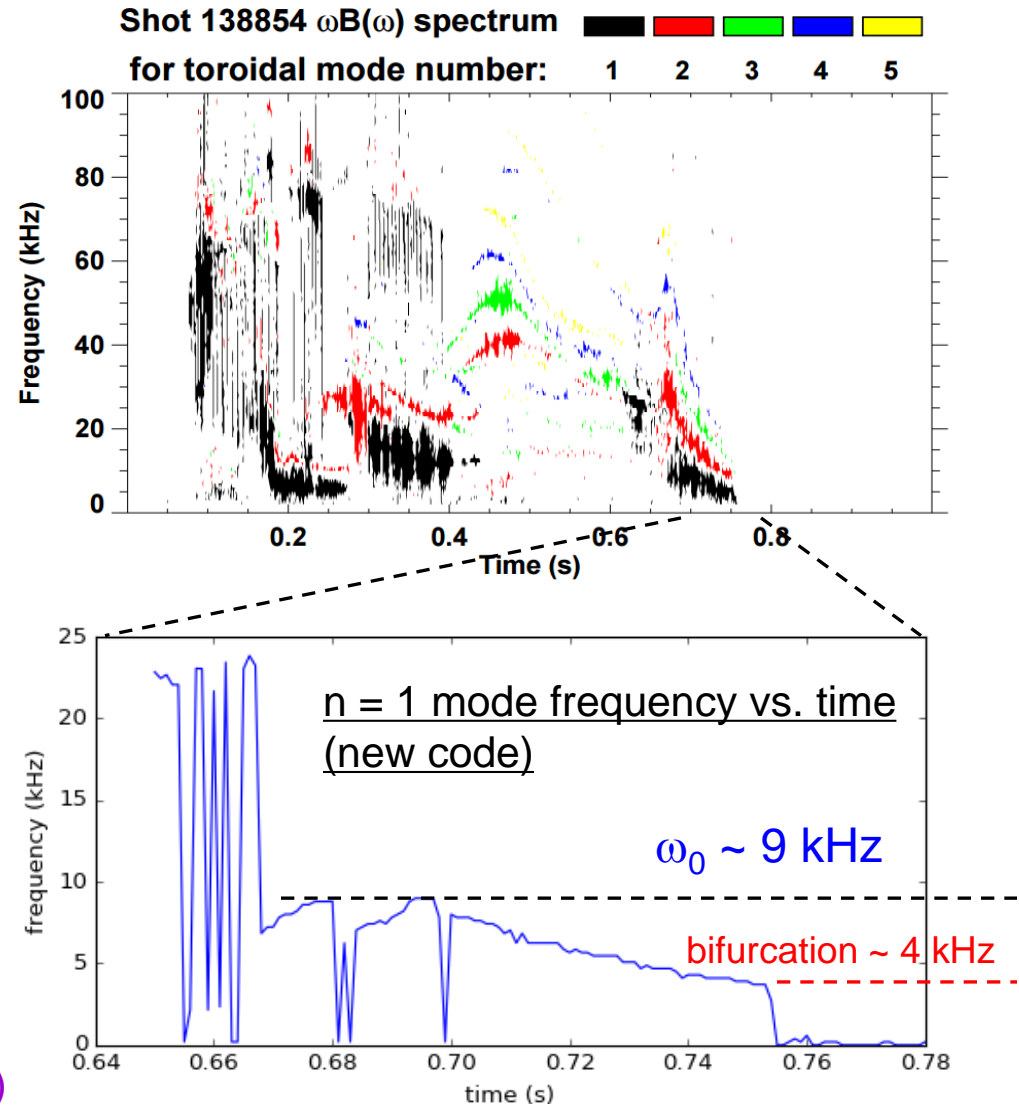
## □ Initial goals

- Create portable code to identify existence of rotating MHD modes
- Track characteristics that lead to disruption
  - e.g. rotation bifurcation, mode lock

## □ Approach

- Apply FFT analysis to determine mode frequency, bandwidth evolution
- Determine bifurcation and mode locking

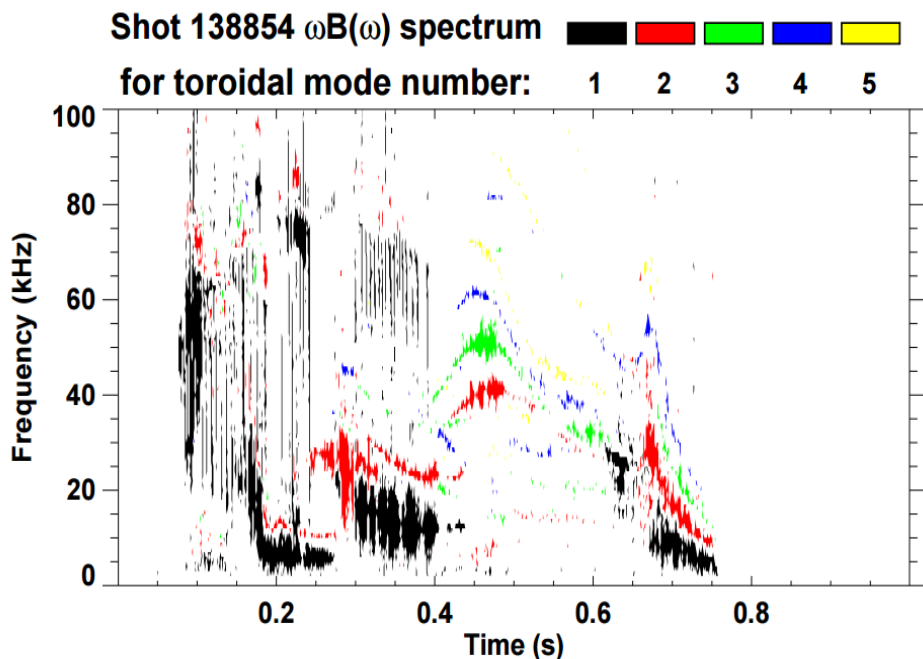
w/ J. Riquezes (U. Michigan – SULI student)



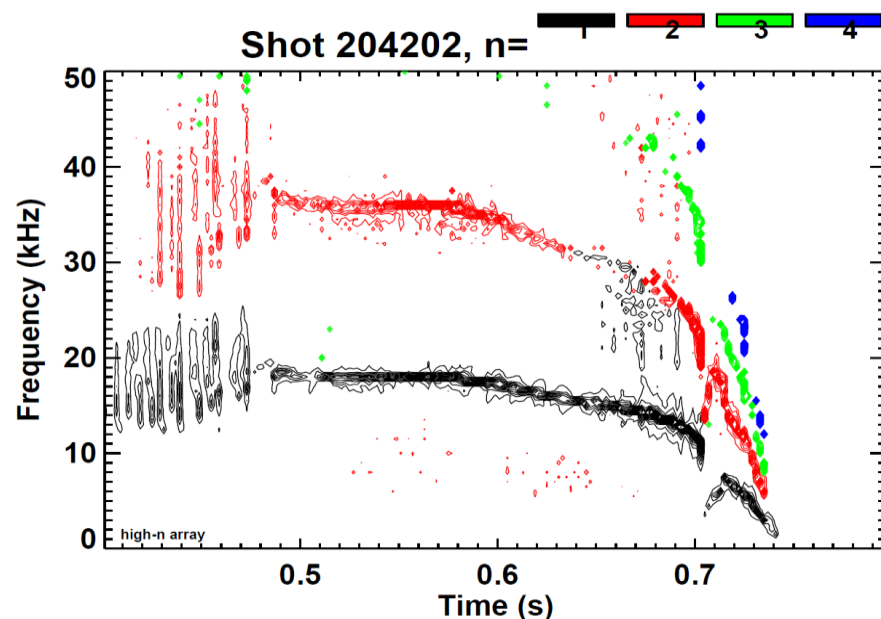
# Many shots with rotating MHD (e.g. NTMs) examined for NSTX and NSTX-U – two illustrated here

## Magnetic spectrogram of rotating MHD mode locking termination

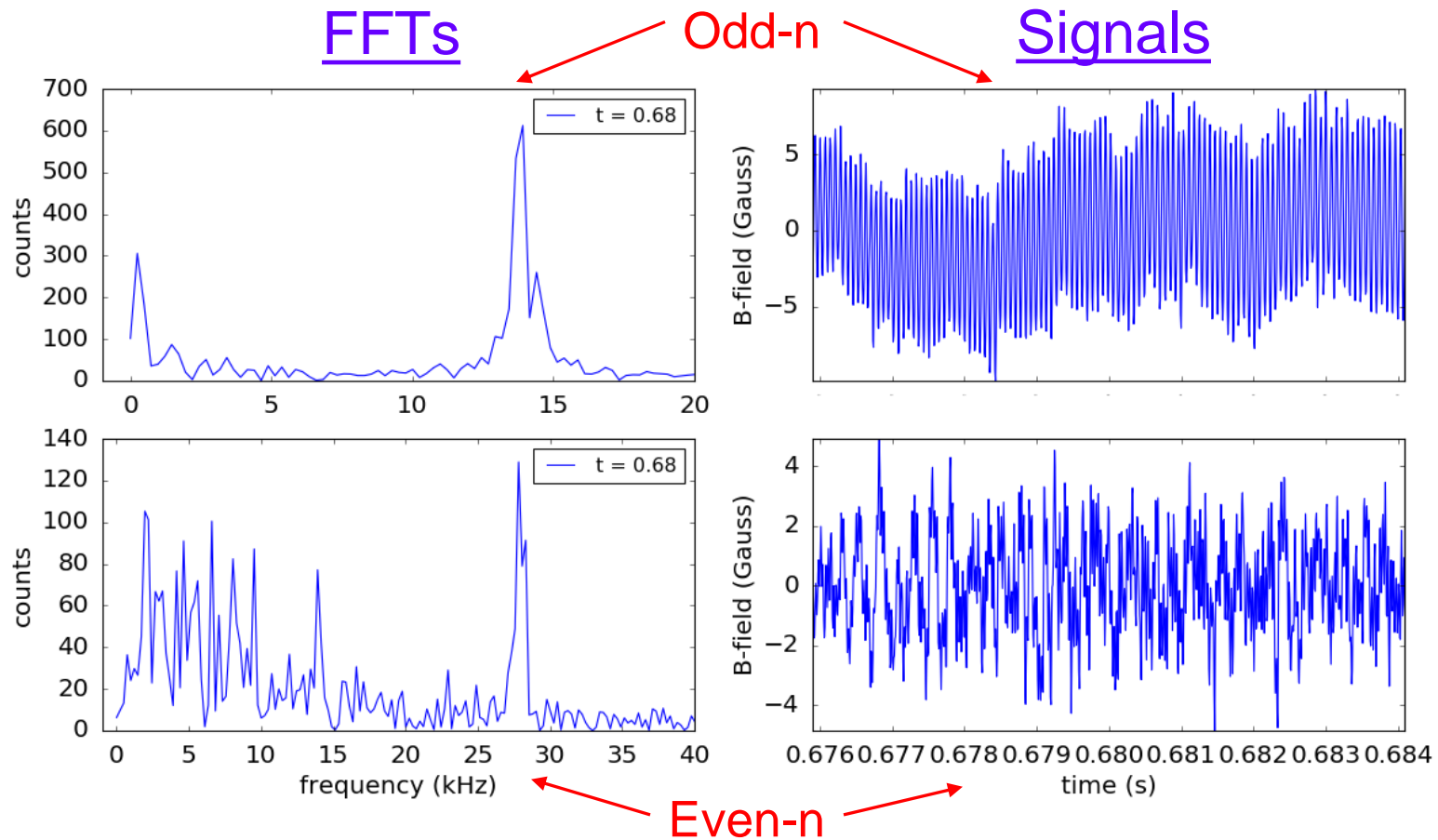
NSTX 138854



NSTX-U 204202



# Fast Fourier transforms used to find mode peak frequency within a time interval

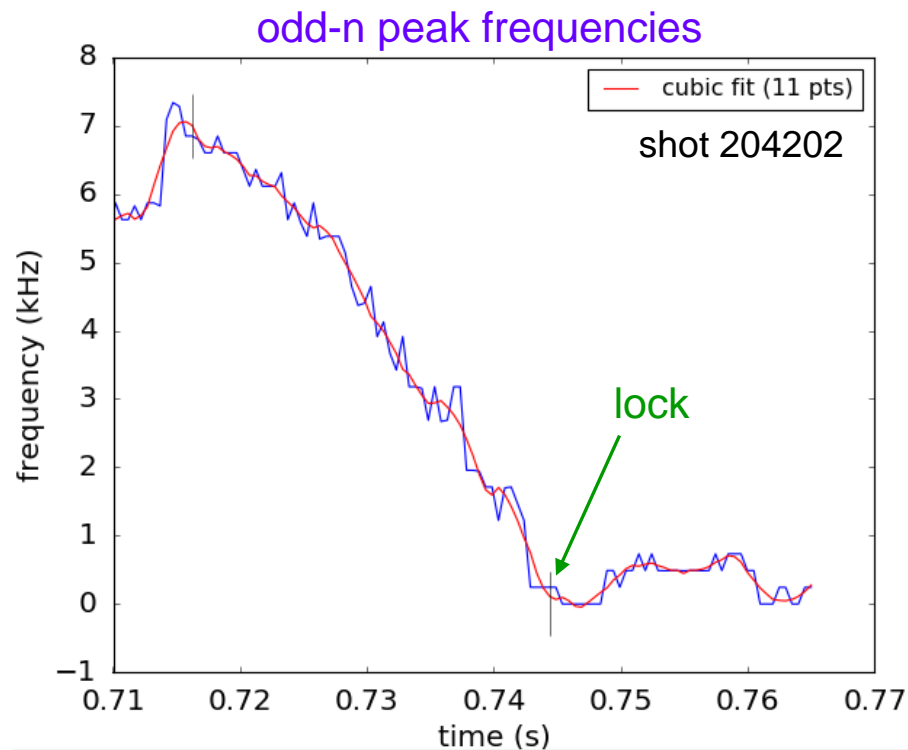
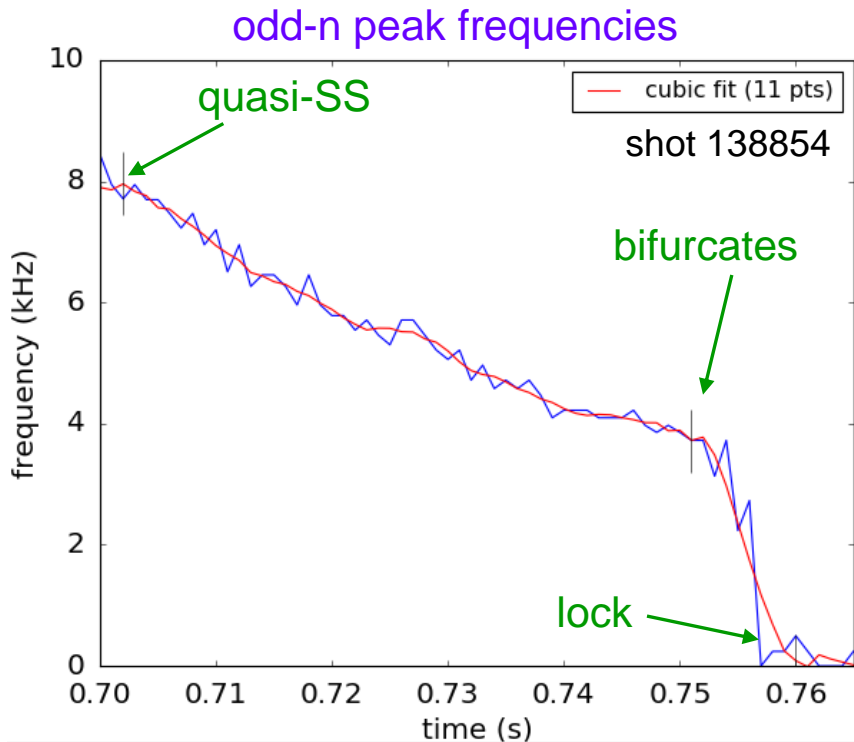


- ❑ Reveals potential issues handling multiple frequency peaks
- ❑ Next step to include toroidal array /  $n$  number discrimination

J. Riquezes (U. Michigan – SULI student)

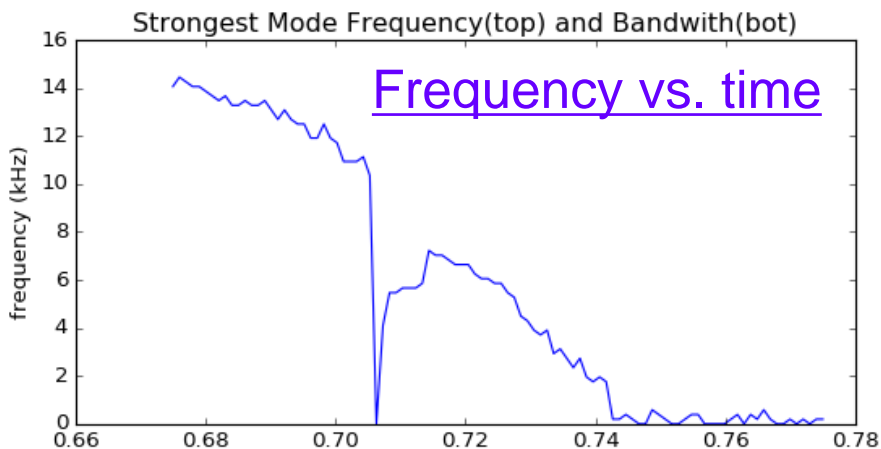
# The characterization algorithm shows that the expected bifurcation event can be found

- Algorithm written looks for a “quasi-steady state” period, a potential bifurcation, the possible mode locking

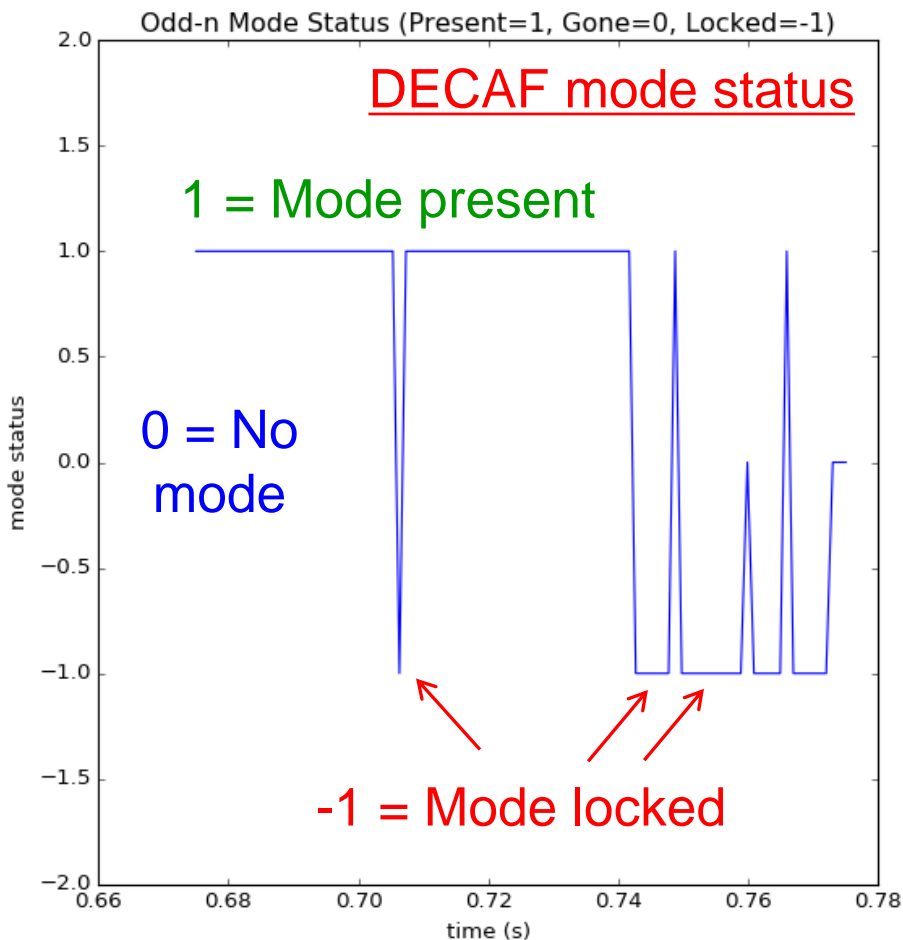
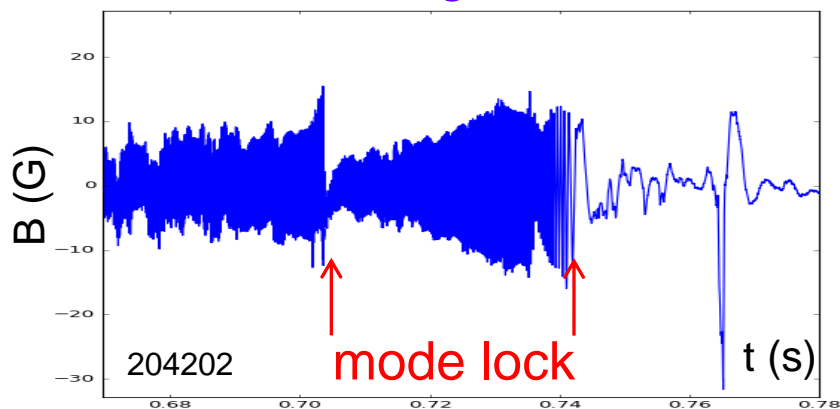


# Continuing analysis of rotating MHD for DECAF includes accurate analysis of mode “status” (I)

## Odd-n magnetic signal / analysis (mode locking / unlocking)

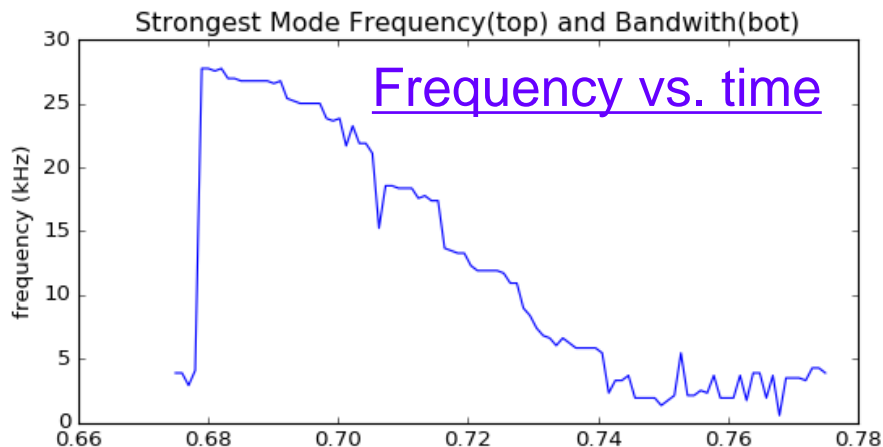


### Signal

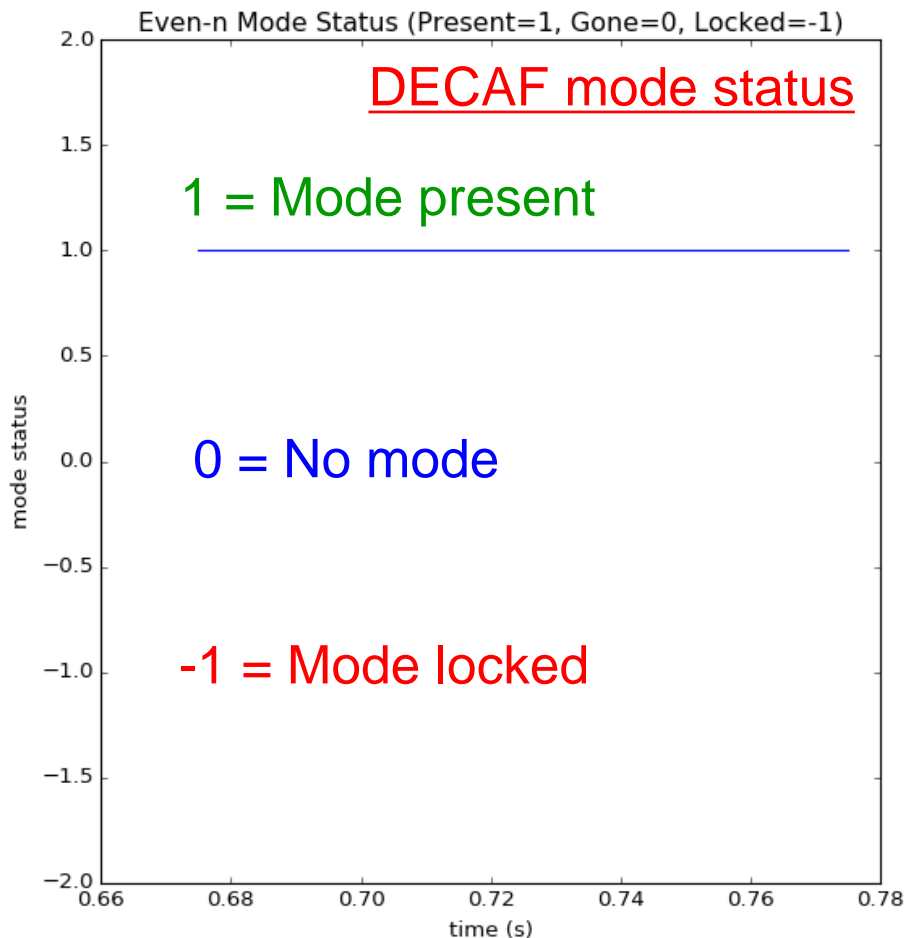
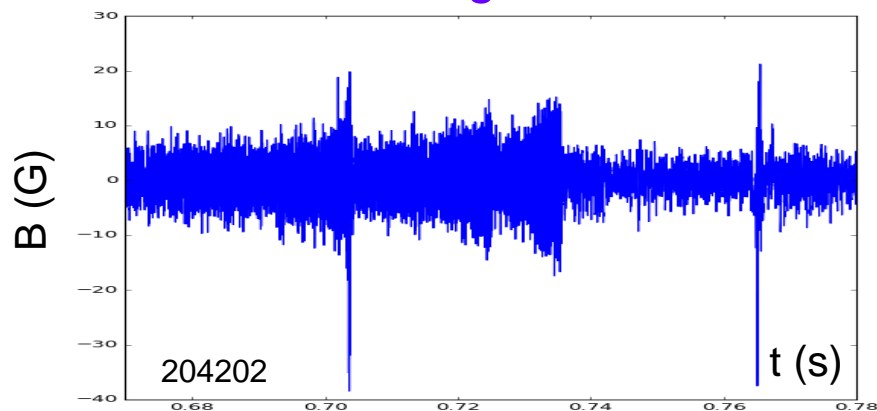


# Continuing analysis of rotating MHD for DECAF includes accurate analysis of mode “status” (II)

## Even-n magnetic signal / analysis (mode present, not locked)



### Signal



# Model for mode rotation evolution / mode lock forecasting derived, will be tested in DECAF in next step

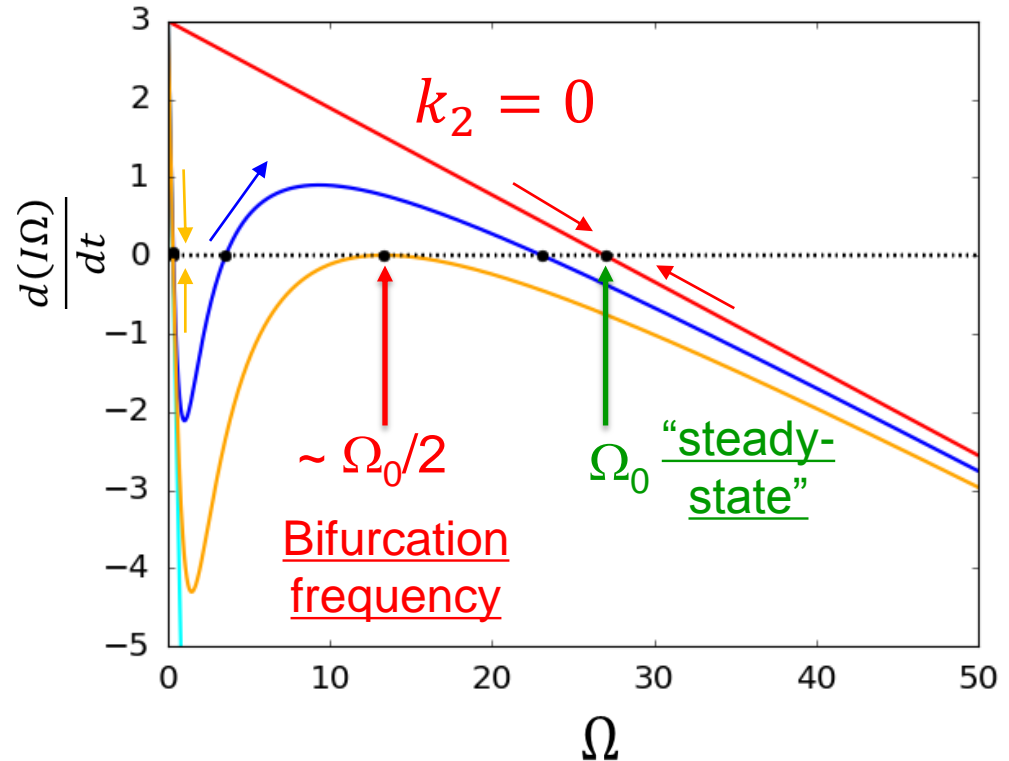
- Model derived to allow island drag for both “slip” and a “no slip” condition

$$T_{mode} = \frac{k_2 \Omega}{1 + k_3 \Omega^2}$$

Model based on  
R. Fitzpatrick et al., Nucl. Fusion **33** (1993) 1049

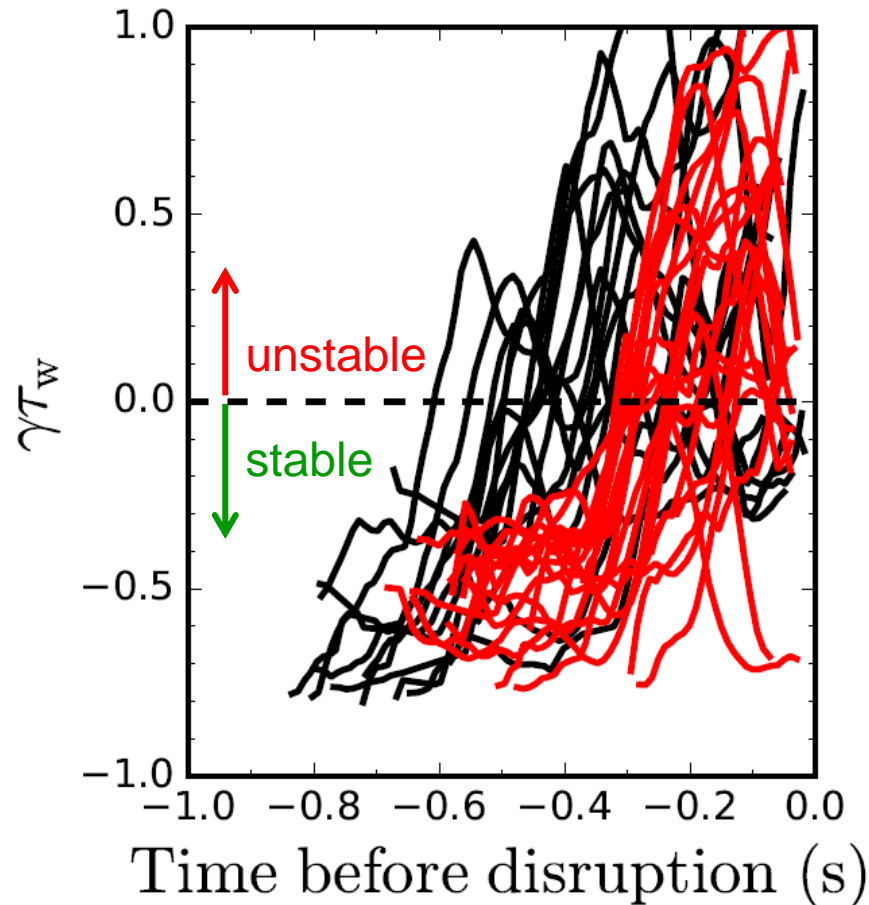
- Simple “ $\Omega_0$ ” defines steady state
  - Best way to define this?
- Simple “ $\Omega_0/2$ ” defines bifurcation point
  - Next step is to analyze this model using DECAF

$$\frac{d(I\Omega)}{dt} = T_{aux} - \frac{k_2 \Omega}{1 + k_3 \Omega^2} - \frac{(I\Omega)}{\tau_{2D}}$$



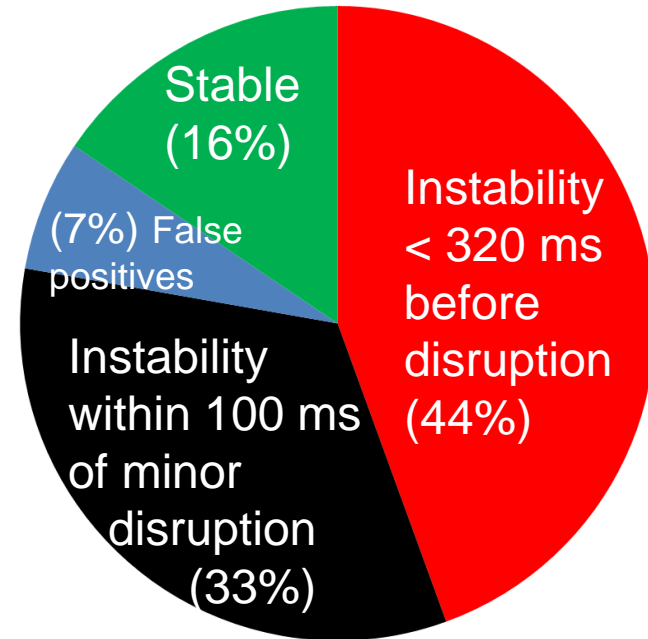
# DECAF reduced kinetic MHD model implemented: initially tested on database of NSTX discharges with unstable RWMs

Normalized growth rate vs. time



See Jack Berkery's talk (next) for full detail

Predicted instability statistics (45 shots)



- ❑ 84% of shots are predicted unstable
- ❑ 44% predicted unstable < 320 ms (approx.  $60\tau_w$ ) before current quench
- ❑ 33% predicted unstable within 100 ms of a minor disruption



# Another criterion: what levels of plasma disturbances ( $\delta B_p$ ; $\delta B_p/B_p(a)$ ) are permissible to avoid disruption MHD modes?

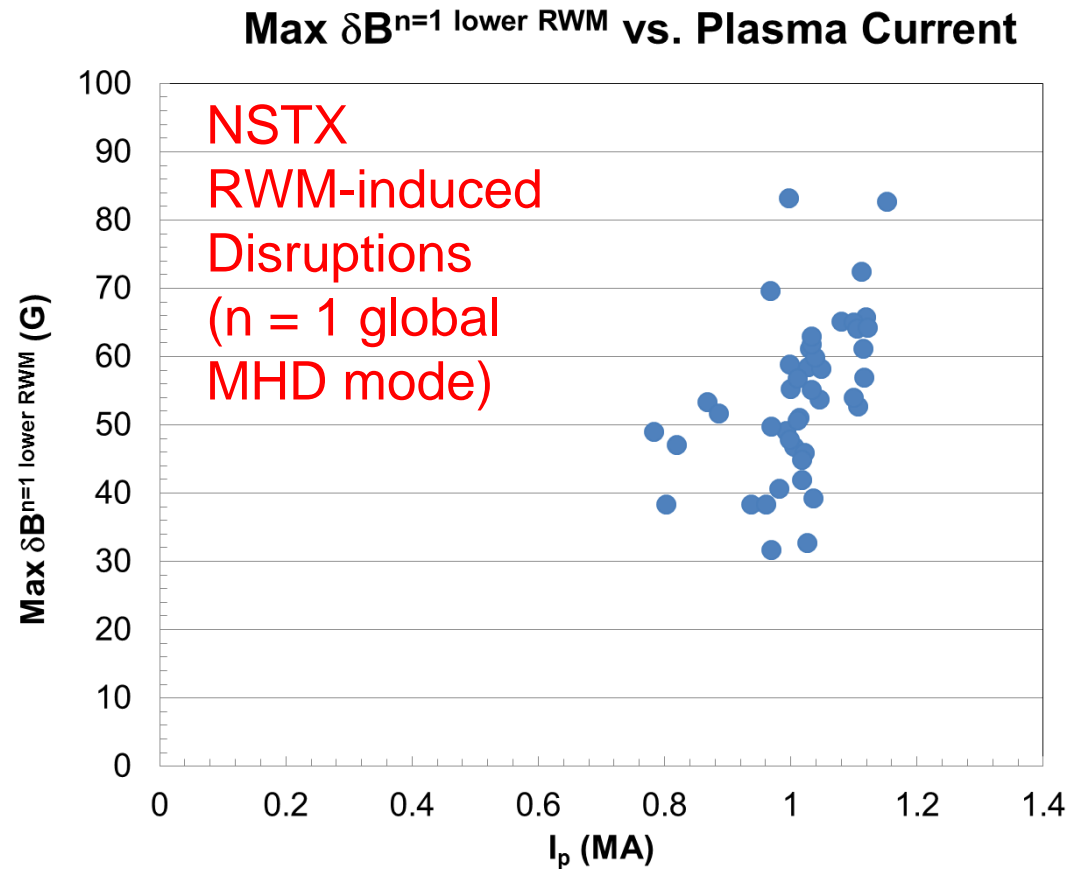
## ITER high priority need

- Analysis requested by ITER
- Vetted through ITPA

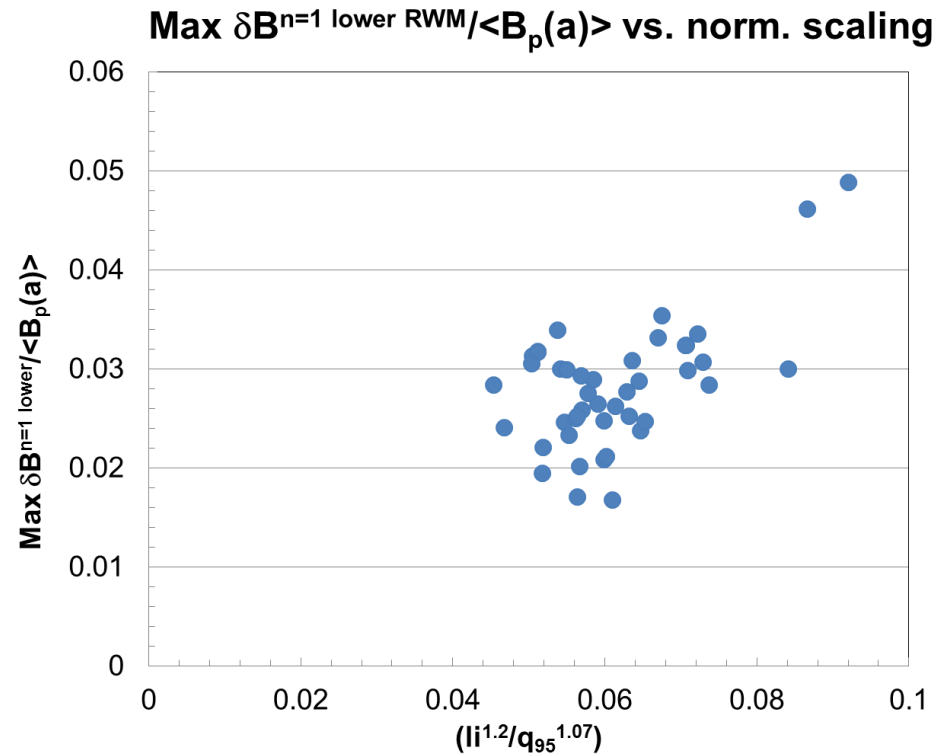
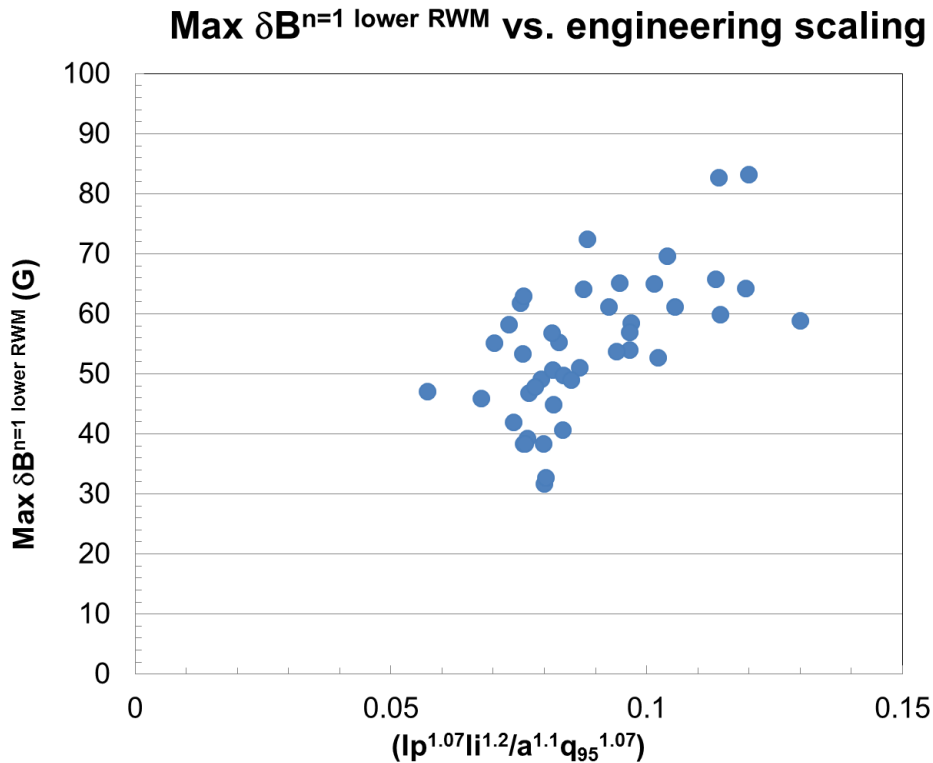
## Compare maximum $\delta B_p$ ( $n = 1$ amplitude) causing disruption vs $I_p$

- Maximum  $\delta B_p$  increases with  $I_p$

## Further analysis may provide guidance for a disruption predictor in DECAF



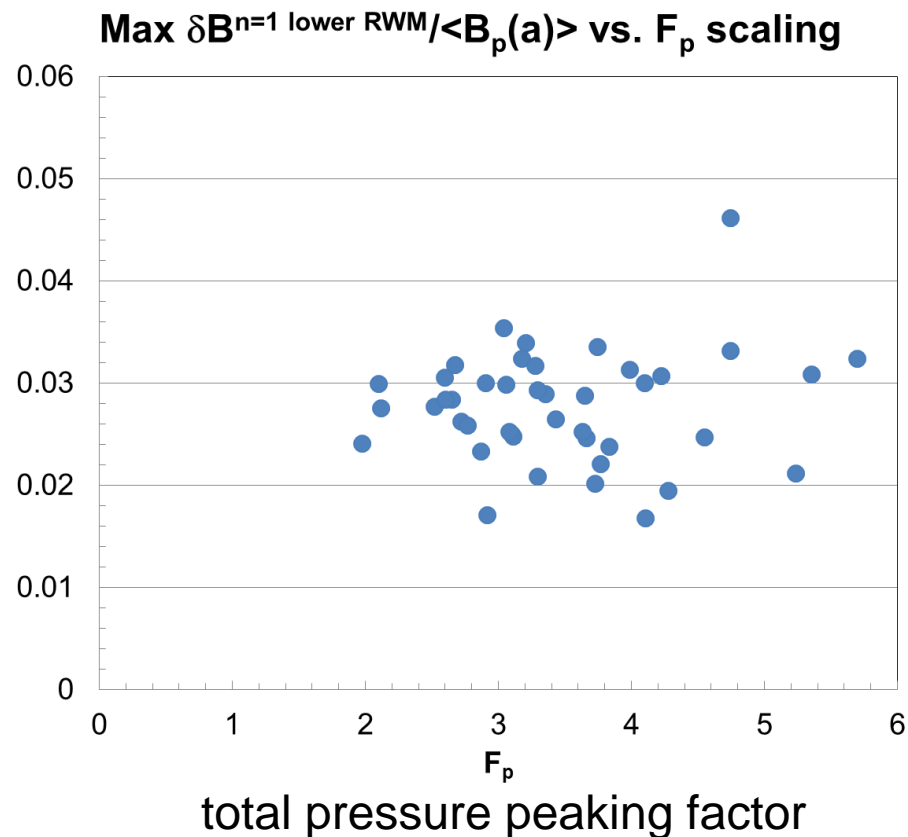
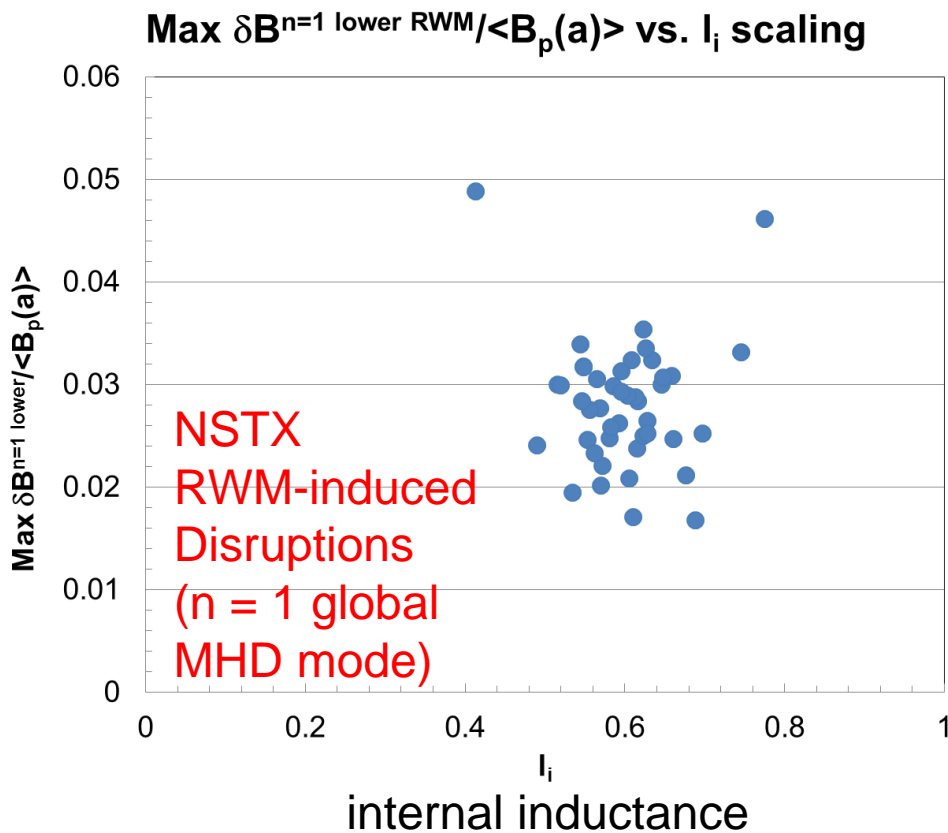
# Maximum $\delta B_p$ might follow de Vries-style\* empirical scalings



- ❑ NSTX RWM-induced disruptions ( $n = 1$  global MHD mode)
- ❑ Will be tested in DECAF as a “tolerable limit” to global mode amplitude

\*P.C. de Vries, G. Pautasso, E. Nardon, et al., Nucl. Fusion **56** (2016) 026007

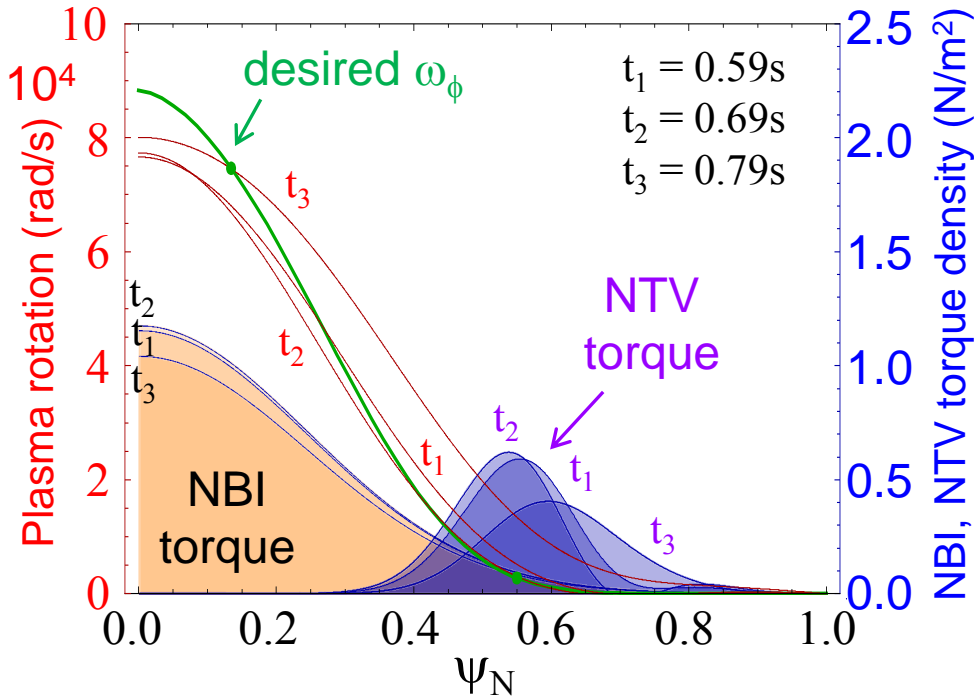
# In contrast, maximum $\delta B_p / \langle B_p(a) \rangle$ seems independent of scaling on $(I_i)$ or $(F_p)$ (or $(F_p/I_i)$ )



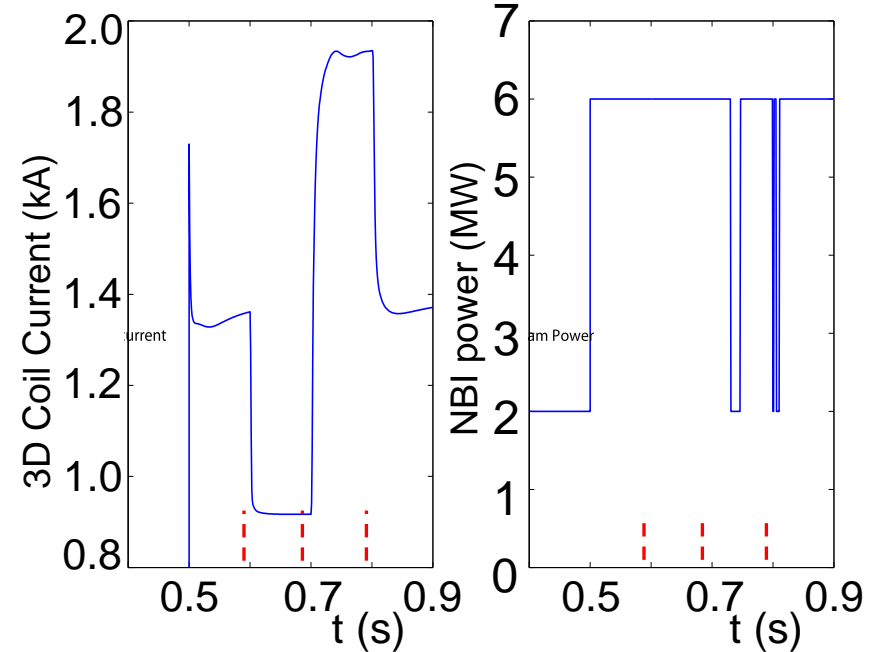
- $F_p = p_{\text{tot}}(0) / \langle p_{\text{tot}} \rangle_{\text{vol}}$  (from kinetic equilibrium reconstructions)
- Dependence on  $I_i$ ,  $F_p$  expected for RWM marginal stability points

# Reminder: NSTX-U rotation controller including NTV and NBI torque profiles can compensate for $T_i$ variations in NTV

Rotation evolution and NBI and NTV torque profiles



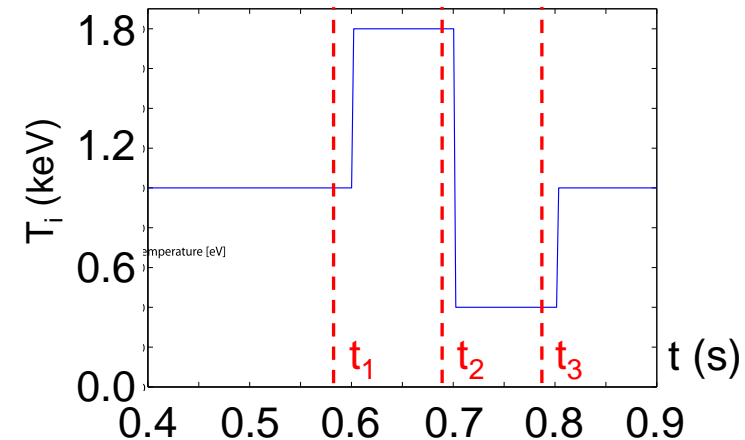
3D coil current and NBI power (actuators)



$$T_{NTV} \propto K \times f(n_{e,i}^{K1} T_i^{K2}) g(\delta B(\rho)) [I_{coil}^2 \omega]$$

$$K1 = 0, K2 = 2.5$$

- NTV torque profile model for feedback dependent on ion temperature

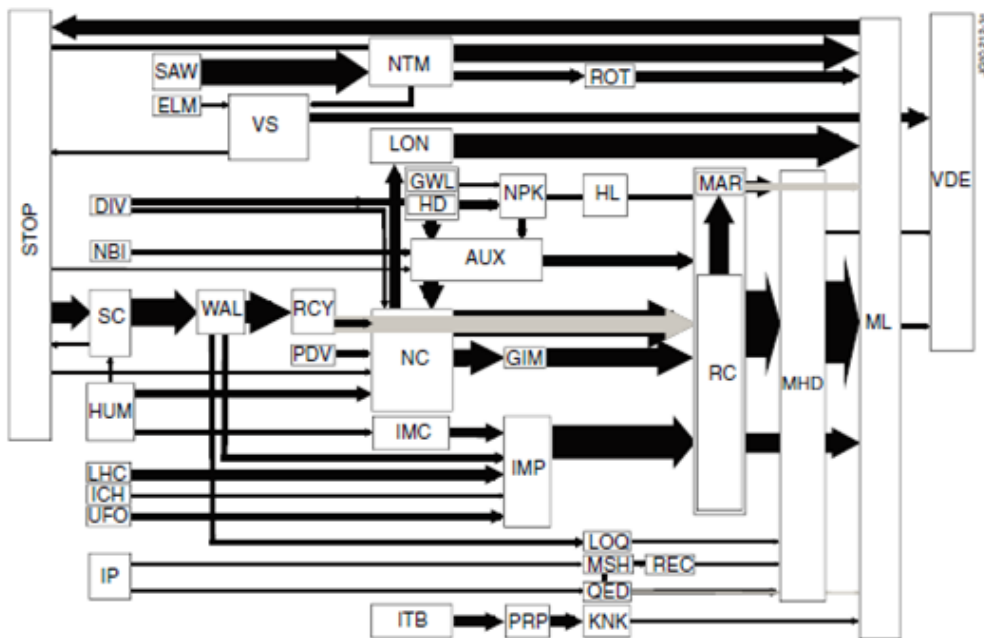


# Supporting Slides Follow

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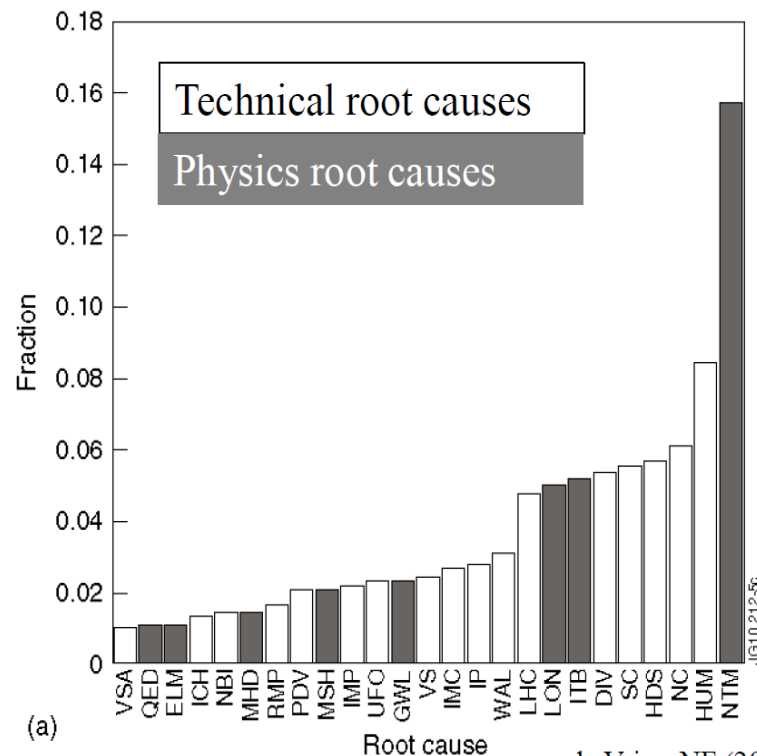
# JET disruption event characterization provides framework for understanding / quantifying disruption prediction

## JET disruption event chains



P.C. de Vries *et al.*, Nucl. Fusion **51** (2011) 053018

## Related disruption event statistics



(a)

de Vries, NF (2011)

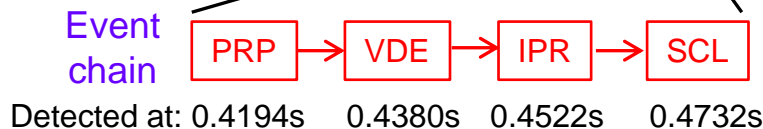
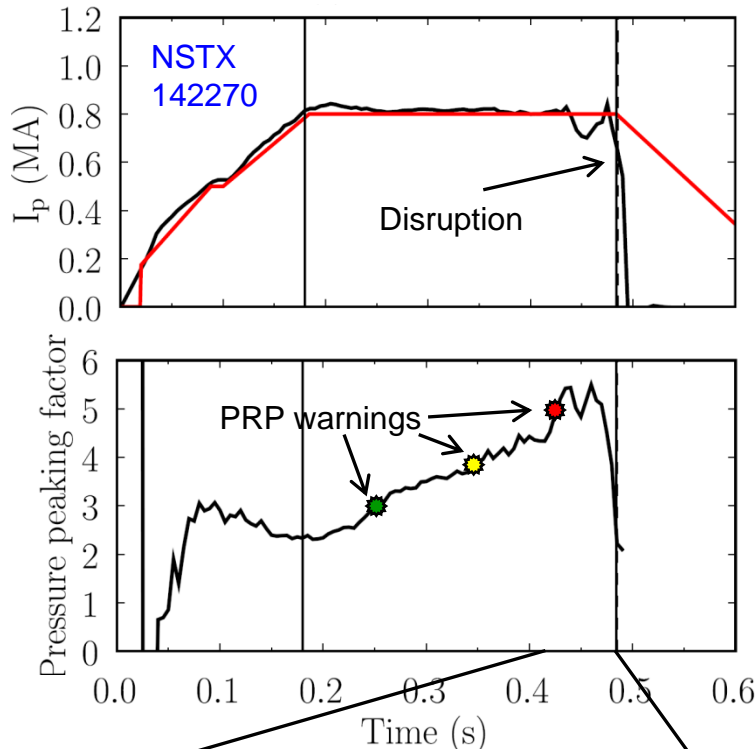
- JET disruption event chain analysis performed by hand, desire to automate

# Disruption Event Characterization And Forecasting Code (DECAF) yielding initial results (pressure peaking example)

- 10 physical events presently defined in code with quantitative warning points
  - Builds on manual analysis of de Vries  
P.C. de Vries *et al.*, Nucl. Fusion **51** (2011) 053018
  - Builds on warning algorithm of Gerhardt  
S.P. Gerhardt *et al.*, Nucl. Fusion **53** (2013) 063021
  - New code written (in Python), easily expandable, portable to other tokamaks (can now read DIII-D data)

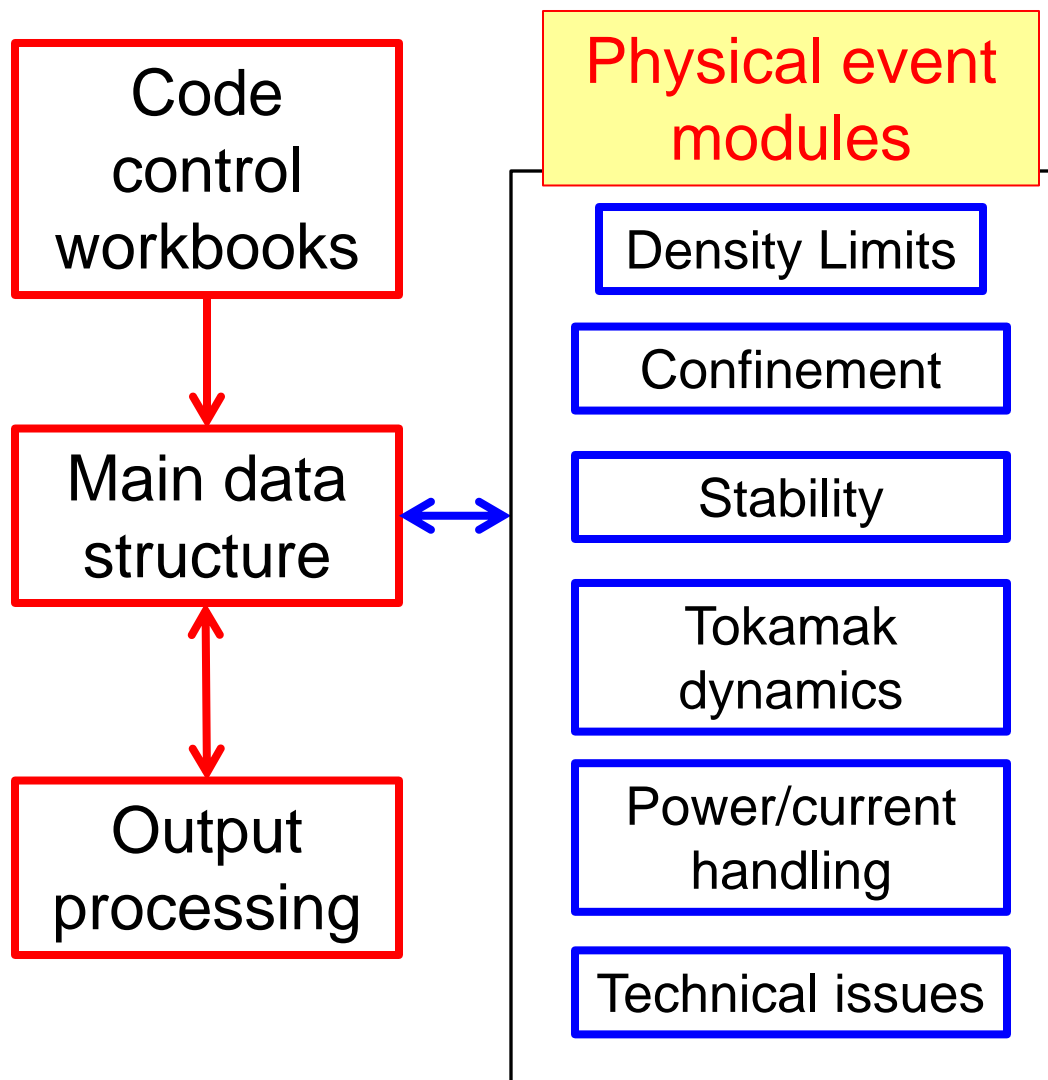
- Example: Pressure peaking (PRP) disruption event chain identified by code before disruption

- (PRP) Pressure peaking warnings identified first
- (VDE) VDE condition subsequently found 19 ms after last PRP warning
- (IPR) Plasma current request not met
- (SCL) Shape control warning issued



J.W. Berkery, S.A. Sabbagh, Y.S. Park (Columbia U.)  
and the NSTX-U Disruption PAM Working Group

# DECAF is structured to ease parallel development of disruption characterization, event criteria, and forecasting



- Physical event modules encapsulate disruption chain events
  - Development focused on improving these modules
  - Structure eases development
    - E.g. separate code by C. Myers that improved disruption timing definition was quickly imported
- Physical events are objects in physics modules
  - e.g. VDE, LOQ, RWM are objects in “Stability”
  - Carry metadata, event forecasting criteria, event linkages, etc.



# The model using a “no slip” condition has no steady state solutions at a large enough island width ( $k_1$ )

□ For steady state

solutions:  $\left(\frac{d(I\Omega)}{dt} = 0\right)$

□  $k_1 = 0$  : “red curve”

□ No mode present

□  $k_1 < \frac{T_{aux}^2 \tau_{2D}}{4I}$  : “blue curve”

□ Two steady state solution

□  $k_1 = \frac{T_{aux}^2 \tau_{2D}}{4I}$  : “orange curve”

□ One steady state solution ( $\sim \frac{\Omega_0}{2}$ )

□ **Bifurcation**

• At close to half the steady state natural rotation frequency ( $\Omega_0$ )

$$\frac{d(I\Omega)}{dt} = T_{aux} - \frac{k_1}{\Omega} - \frac{(I\Omega)}{\tau_{2D}}$$

