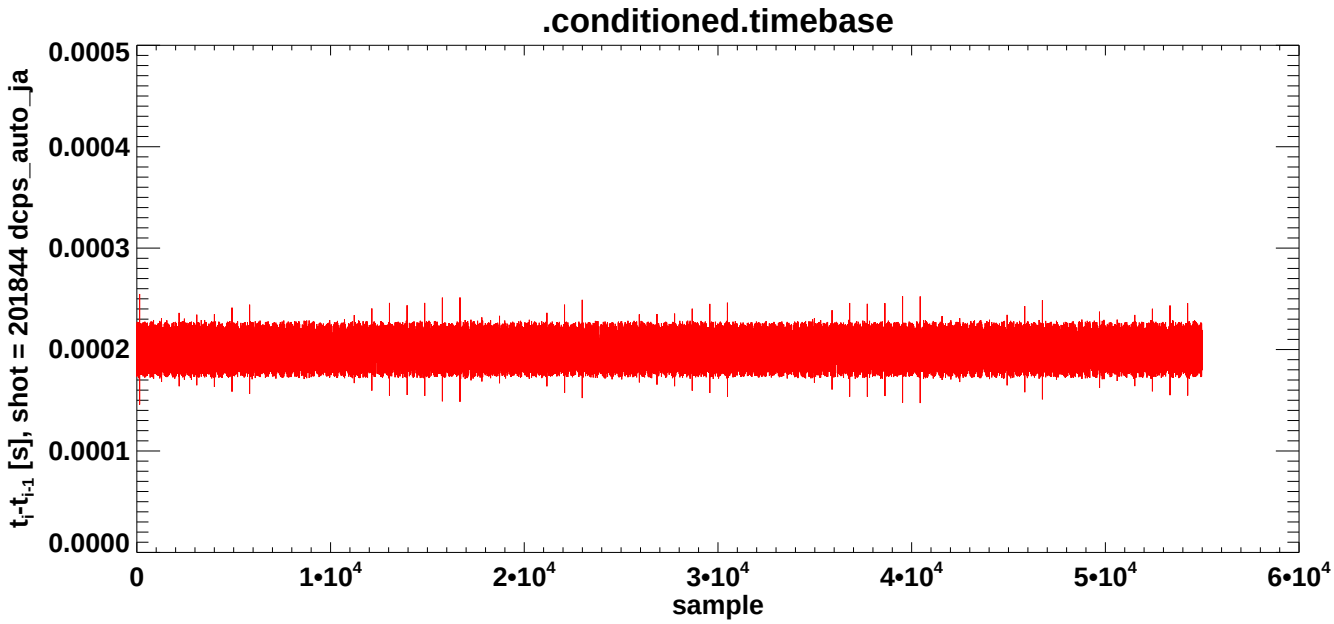
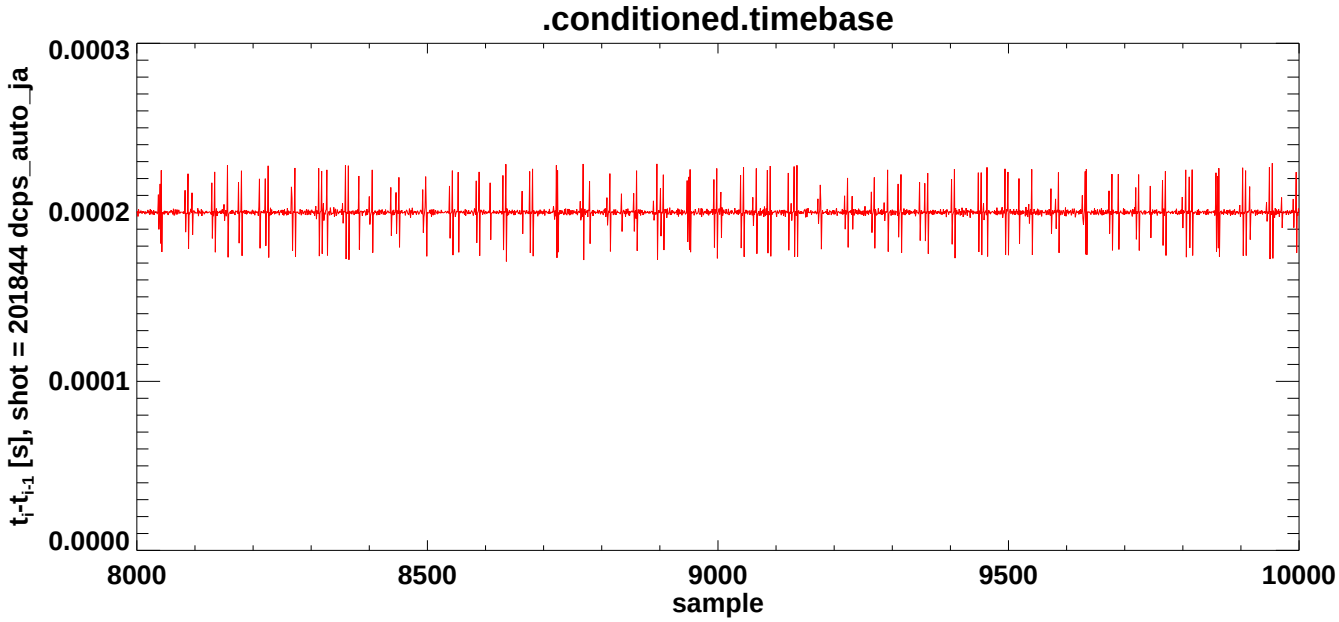
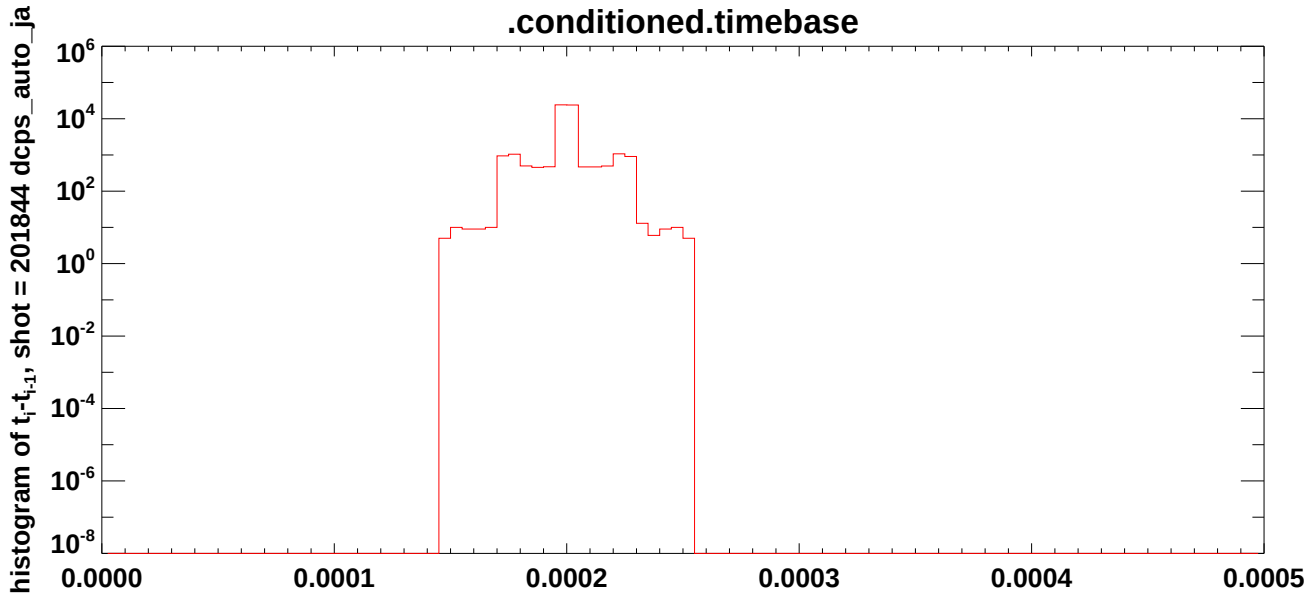
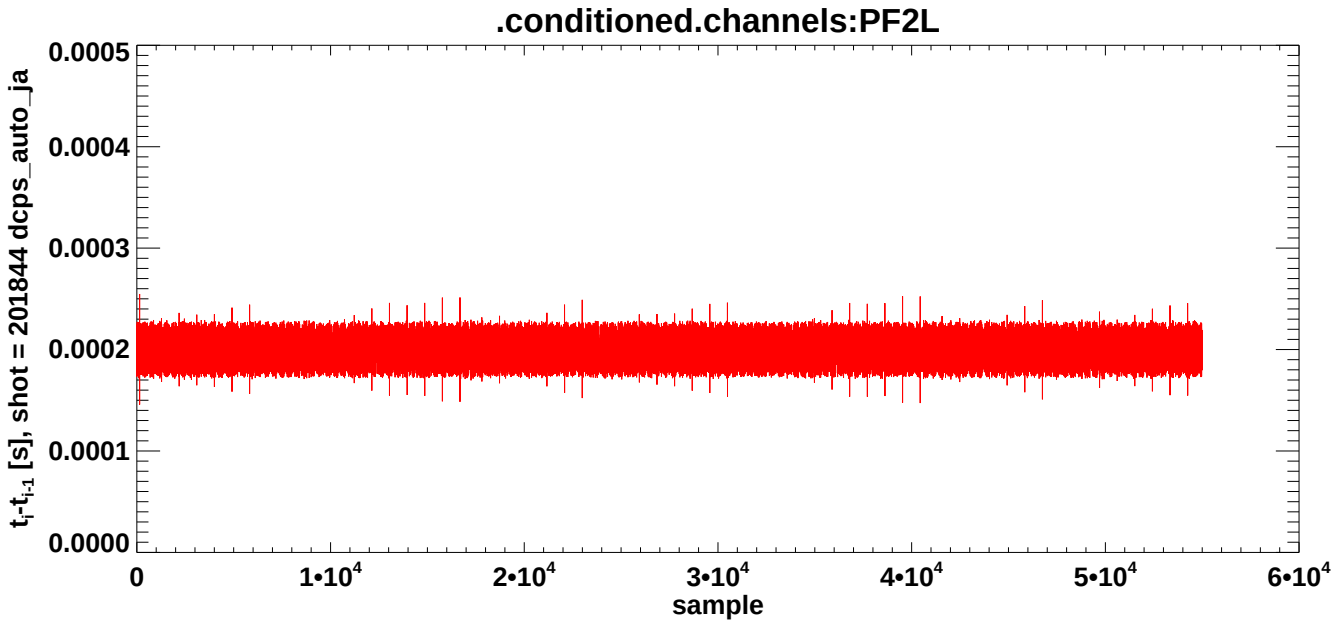
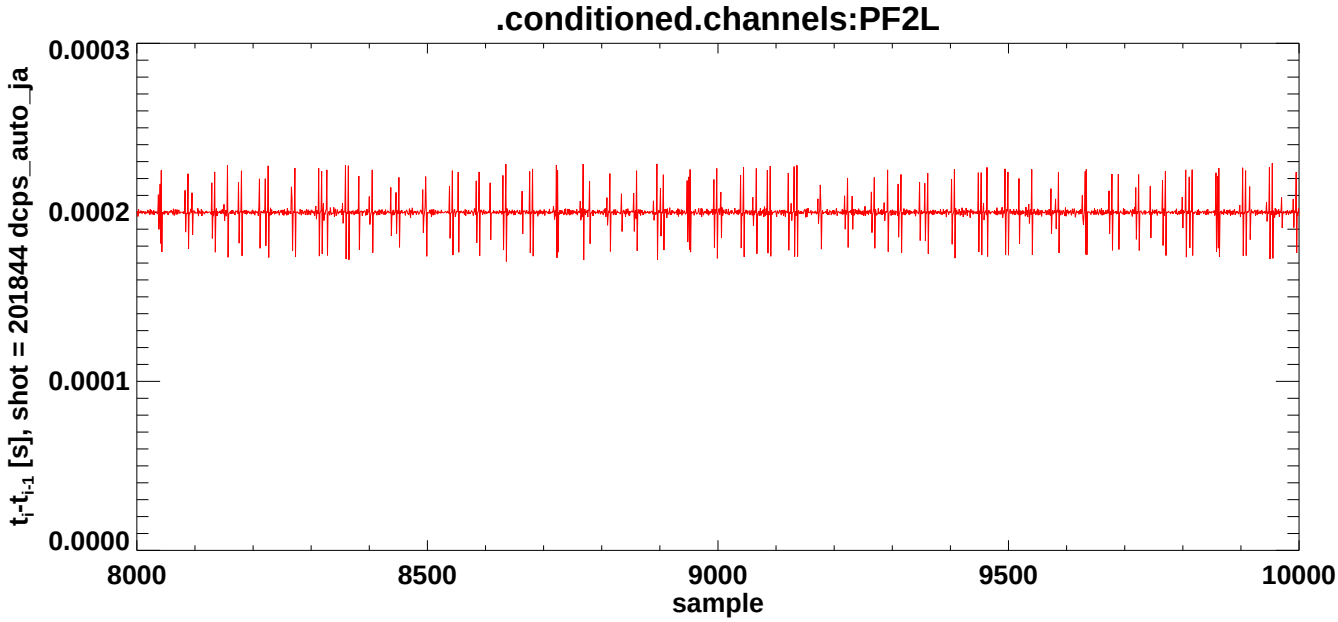
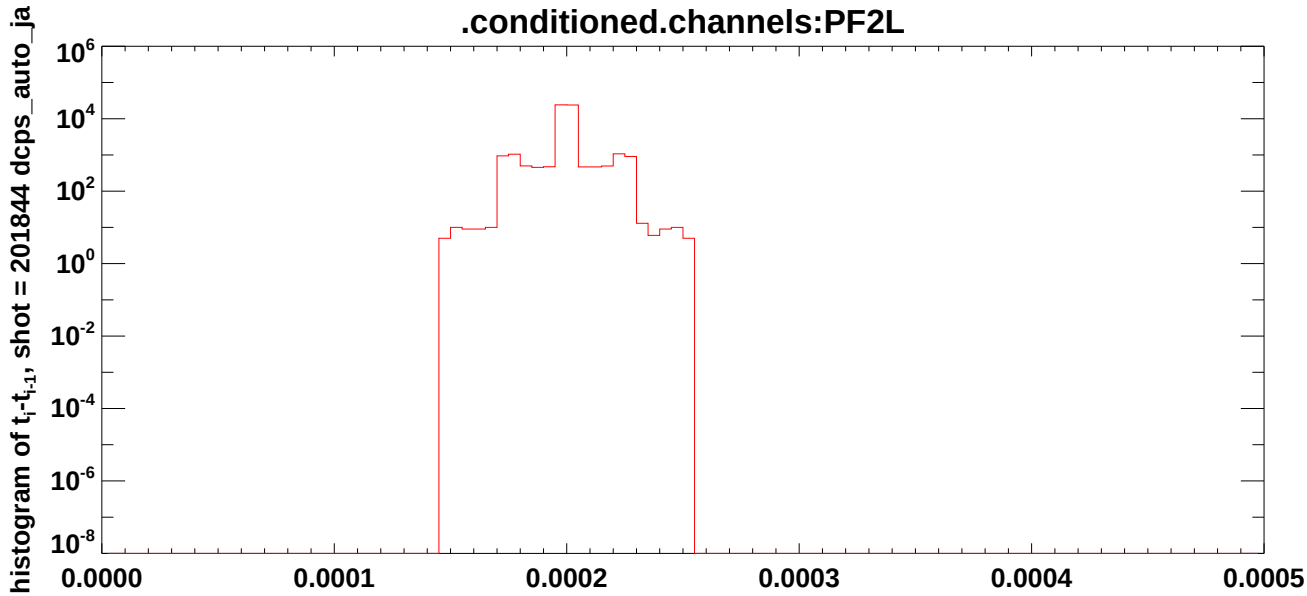

.conditioned.timebase
0.0005
0.0004
0.0003
0.0002
0.0001
0.0000
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0
1•10^4
2•10^4
3•10^4
4•10^4
5•10^4
6•10^4
sample

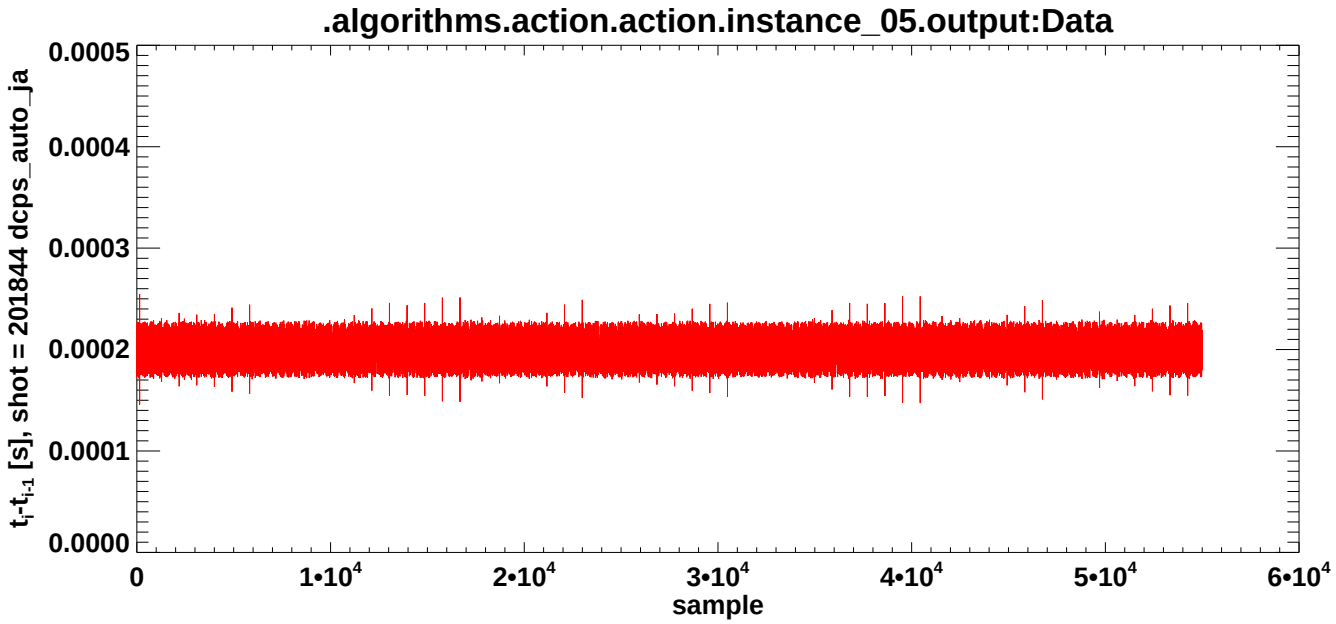

.conditioned.timebase
0.0003
0.0002
0.0001
0.0000
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
8000
8500
9000
9500
10000
sample

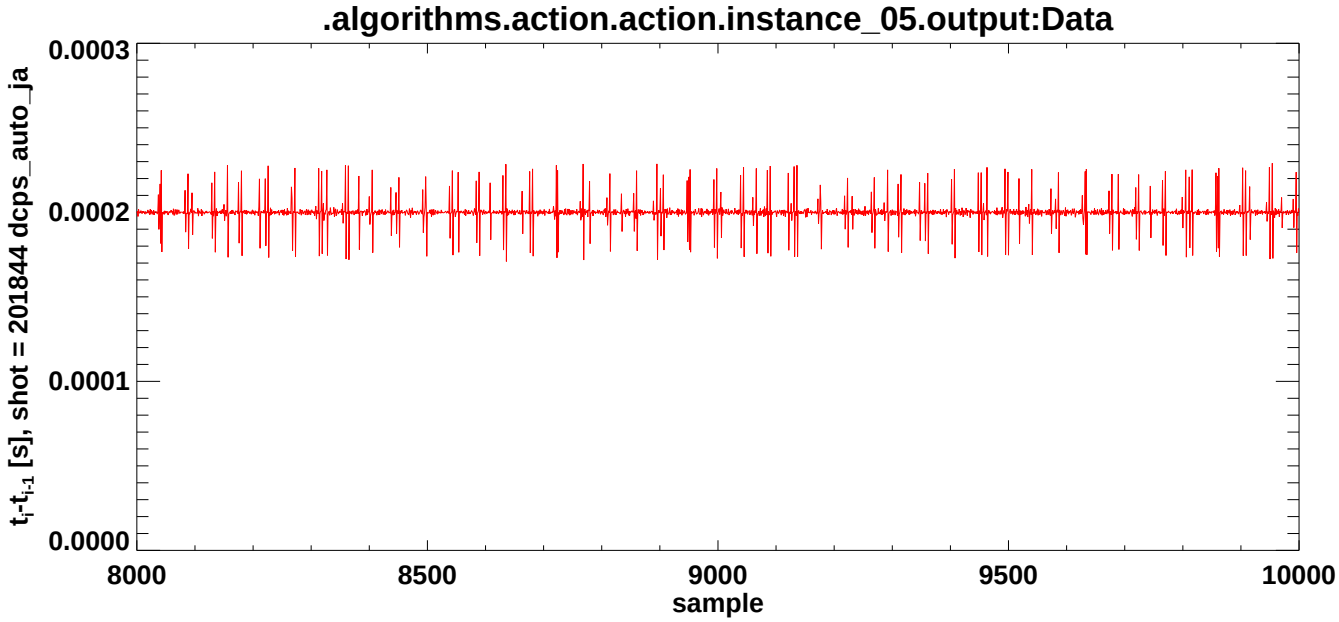

.conditioned.timebase
10^6
10^4
10^2
10^0
10^{-2}
10^{-4}
10^{-6}
10^{-8}
histogram of t_i-t_{i-1}, shot = 201844 dcps_auto_ja
0.0000
0.0001
0.0002
0.0003
0.0004
0.0005

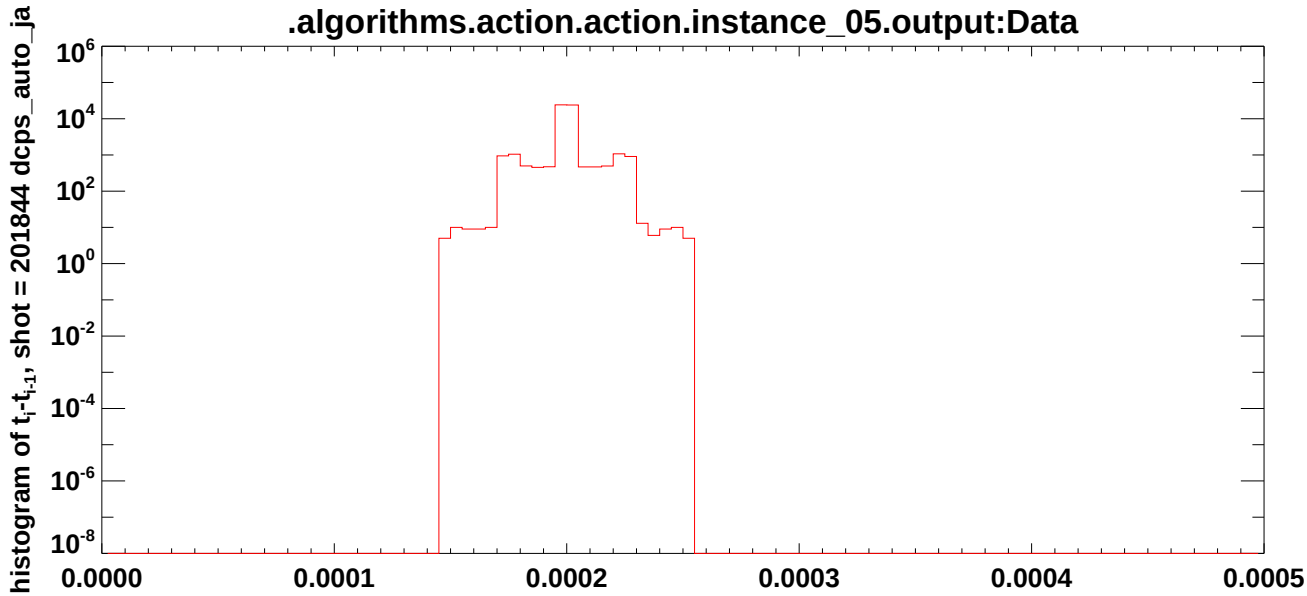

.conditioned.channels:PF2L
0.0005
0.0004
0.0003
0.0002
0.0001
0.0000
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0
1•10^4
2•10^4
3•10^4
4•10^4
5•10^4
6•10^4
sample

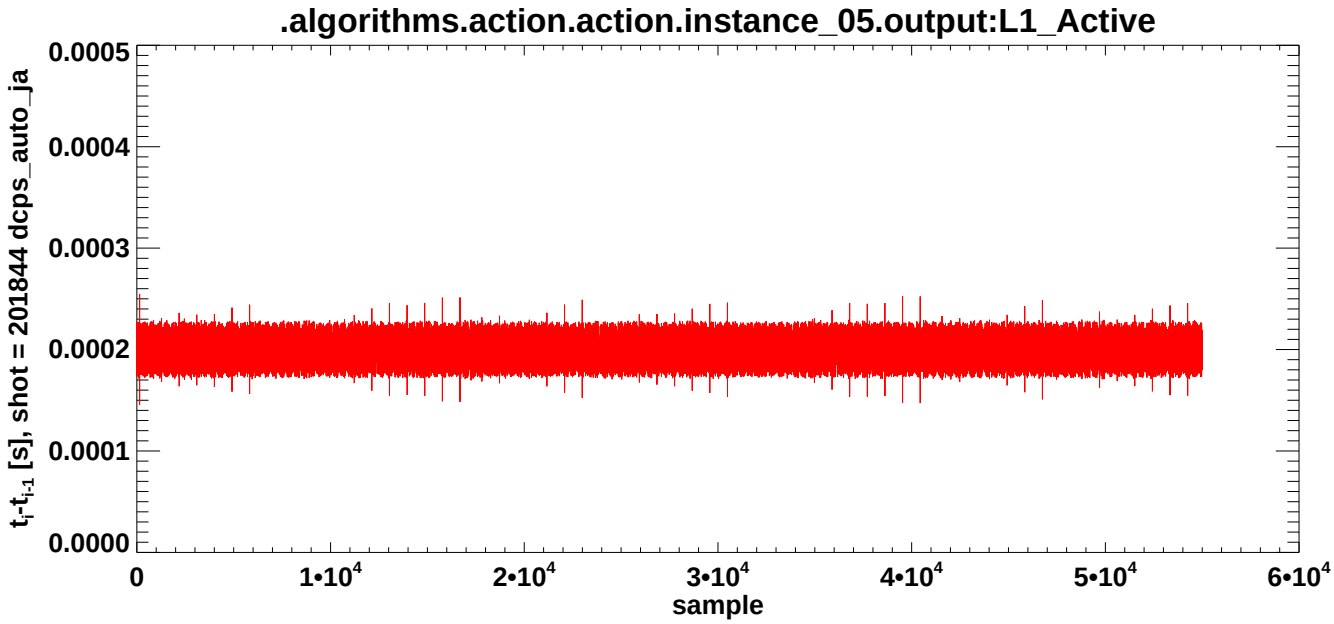

.conditioned.channels:PF2L
0.0003
0.0002
0.0001
0.0000
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
8000
8500
9000
9500
10000
sample

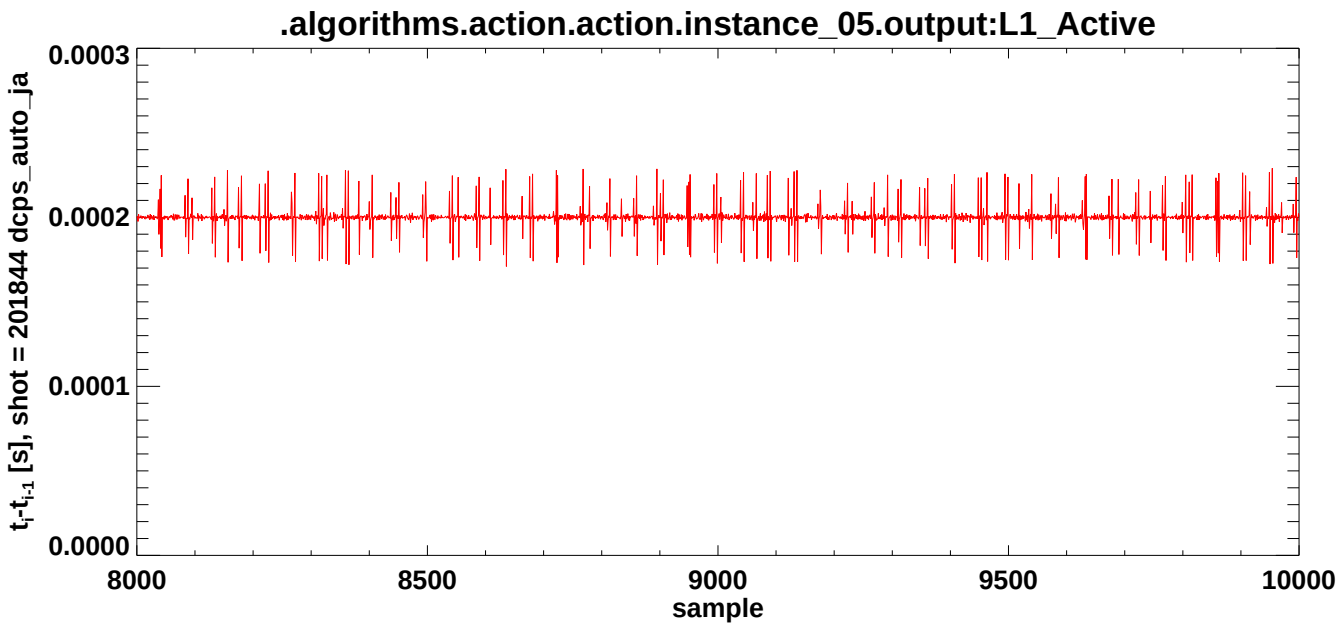

.conditioned.channels:PF2L
10^6
10^4
10^2
10^0
10^{-2}
10^{-4}
10^{-6}
10^{-8}
histogram of t_i-t_{i-1}, shot = 201844 dcps_auto_ja
0.0000
0.0001
0.0002
0.0003
0.0004
0.0005

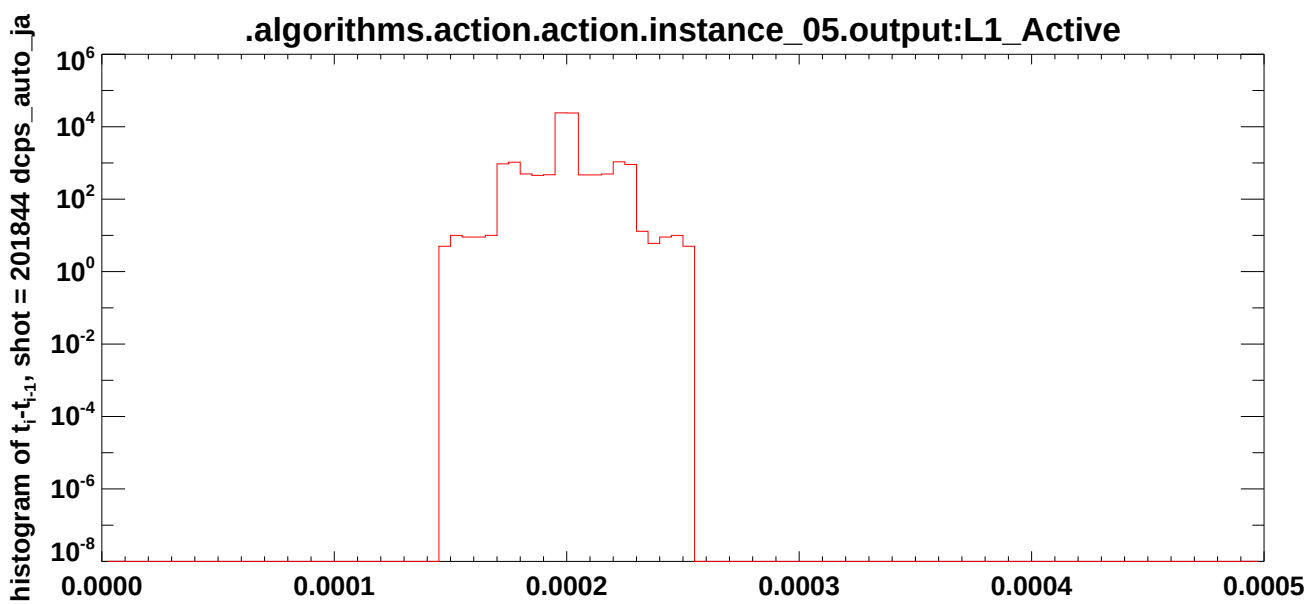

.algorithms.action.action.instance_05.output:Data
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0.0005
0.0004
0.0003
0.0002
0.0001
0.0000
0
1•10^4
2•10^4
3•10^4
4•10^4
5•10^4
6•10^4
sample


.algorithms.action.action.instance_05.output:Data
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0.0003
0.0002
0.0001
0.0000
8000
8500
9000
9500
10000
sample


.algorithms.action.action.instance_05.output:Data
histogram of t_i-t_{i-1}, shot = 201844 dcps_auto_ja
10^6
10^4
10^2
10^0
10^-2
10^-4
10^-6
10^-8
0.0000
0.0001
0.0002
0.0003
0.0004
0.0005


.algorithms.action.action.instance_05.output:L1_Active
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0.0005
0.0004
0.0003
0.0002
0.0001
0.0000
0
1•10^4
2•10^4
3•10^4
4•10^4
5•10^4
6•10^4
sample


.algorithms.action.action.instance_05.output:L1_Active
t_i-t_{i-1} [s], shot = 201844 dcps_auto_ja
0.0003
0.0002
0.0001
0.0000
8000
8500
9000
9500
10000
sample


.algorithms.action.action.instance_05.output:L1_Active
histogram of t_i-t_{i-1}, shot = 201844 dcps_auto_ja
10^6
10^4
10^2
10^0
10^-2
10^-4
10^-6
10^-8
0.0000
0.0001
0.0002
0.0003
0.0004
0.0005