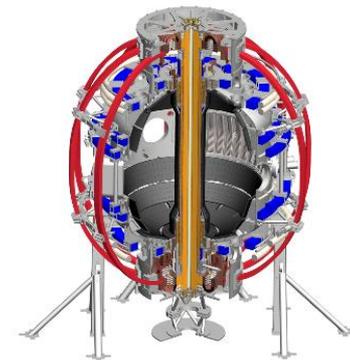




# Columbia U. Group - Collaborative Research on NSTX-U for Disruption Avoidance

S.A. Sabbagh – for the Columbia U. / NSTX-U Group  
(J.W. Berkery, J.M. Bialek, Y.S. Park)

Report to DOE and NSTX-U Program  
PPPL  
7/23/15



# Near 100% disruption avoidance is a critical need for future tokamaks; Columbia Research on NSTX-U is focused on this

- The new “grand challenge” in tokamak stability research
  - Can be done! (JET: < 4% disruptions w/C wall, < 10% w/ITER-like wall)
    - ITER disruption rate: < 1 - 2% (energy load, halo current); << 1% (runaways)
- Strategic plan: utilize/expand stability/control research success
  - Disruption prediction, avoidance, and mitigation (DPAM) is multi-faceted, best addressed by a focused, (inter)national effort (multiple devices/institutions)
- FESAC 2014 Strategic Planning report defined “*Control of Deleterious Transient Events*” highest priority (Tier 1) initiative
- NSTX-U is a world-leading laboratory for focused research on disruption avoidance with quantitative measures of progress
  - Columbia U. group endorsed by NSTX-U Program in a leadership role for this research, building on past success in MHD stability and control research

# Columbia Group Research at PPPL provides key **disruption avoidance research**, emphasis on global mode stabilization

## □ Physics Elements

- Kinetic RWM stabilization physics - unification between NSTX / DIII-D
- NTV used in plasma rotation control (supports NSTX-U  $V_\phi$  control)
- Physics model-based active RWM state-space controller ↖ Princeton student
- Dual-component sensor RWM PID control
- RWM control analysis of upgraded 3D coils for NSTX-U
- NSTX-U equilibrium reconstruction – key basis for stability analysis
- Planned real-time MHD spectroscopy for NSTX-U (in 5 Year Plan)
- Related high normalized beta and NTV experiments on KSTAR

## □ Research synergism

- These elements now being brought together as part of a disruption prediction/avoidance system; **NSTX-U DPAM working group formed**)
- New Disruption Characterization and Prediction code / initial results

## □ Response to DOE call for enhanced university participation

- CU-PPPL group outreach to Columbia U. APAM department; new diagnostic proposal to be submitted (Volpe/Sabbagh)

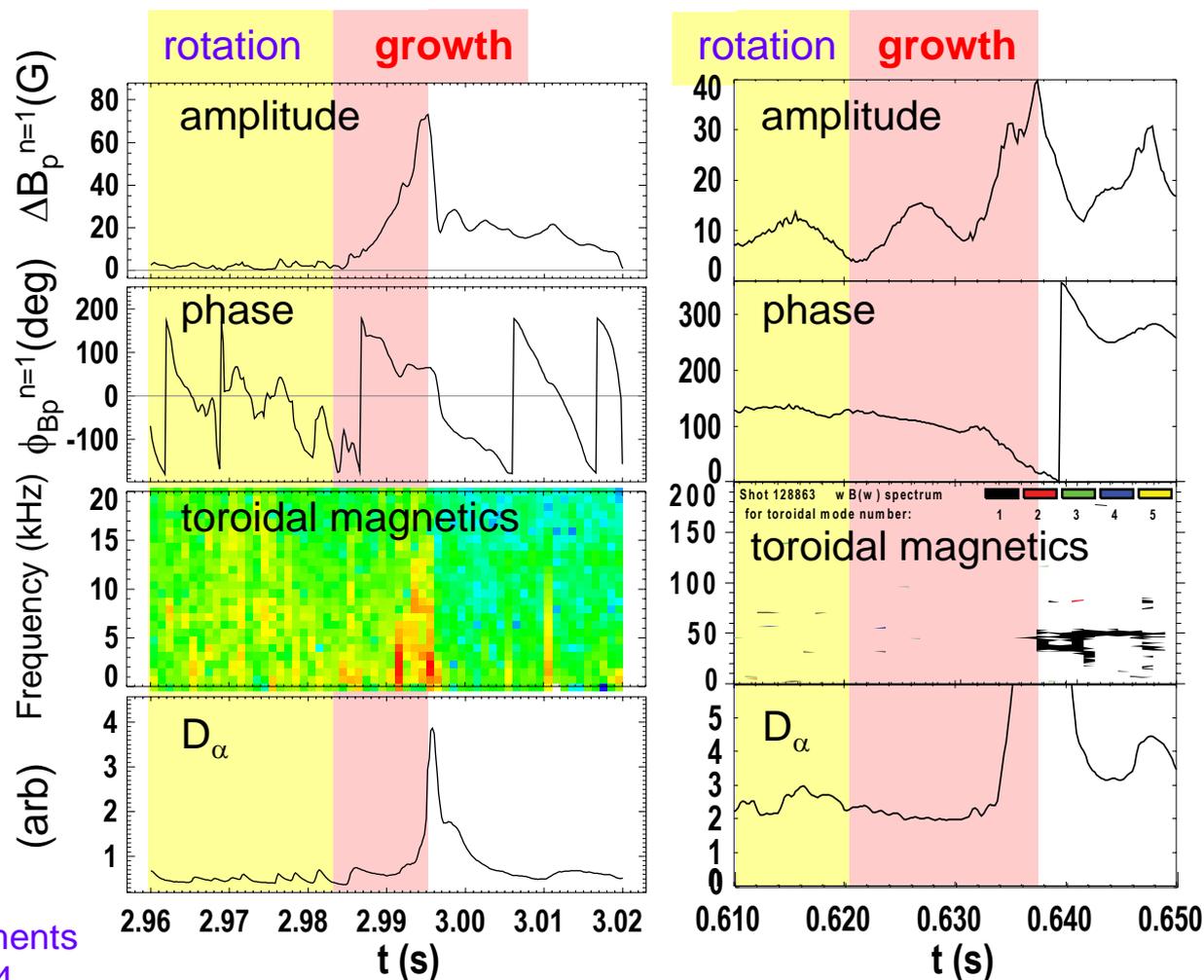
# Joint NSTX / DIII-D experiments and analysis gives **unified kinetic RWM physics understanding** for disruption avoidance

## RWM Dynamics

- RWM rotation and mode growth observed
- No strong NTM activity
- Some weak bursting MHD in DIII-D plasma
  - Alters RWM phase
- No bursting MHD in NSTX plasma

DIII-D ( $\beta_N = 3.5$ )

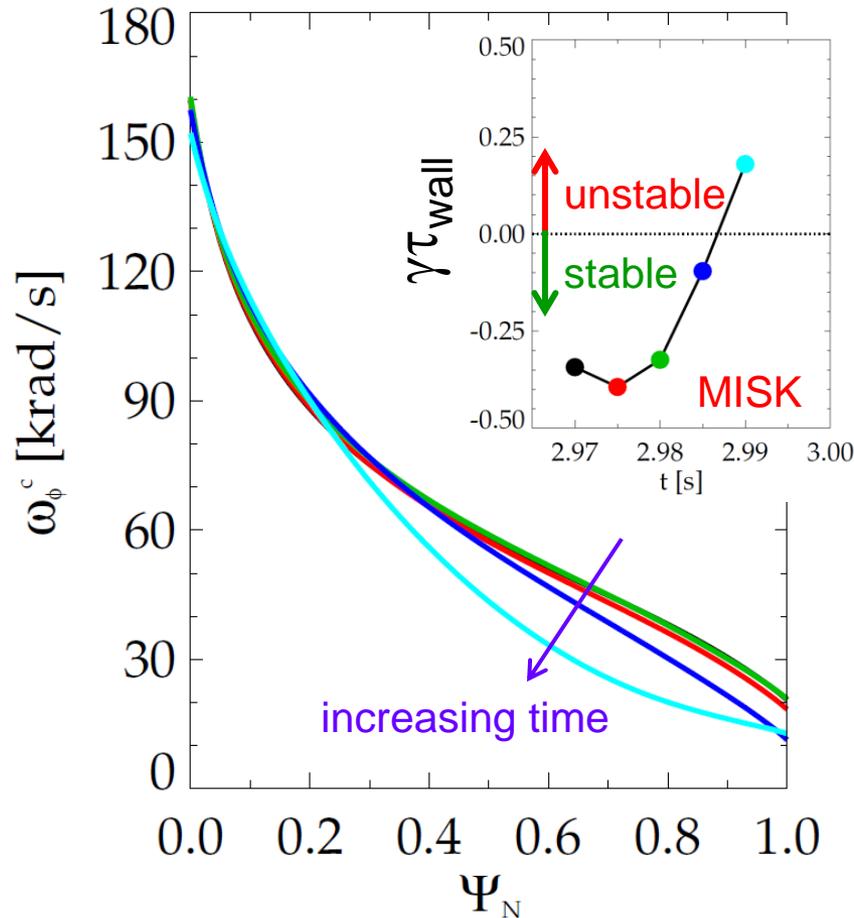
NSTX ( $\beta_N = 4.4$ )



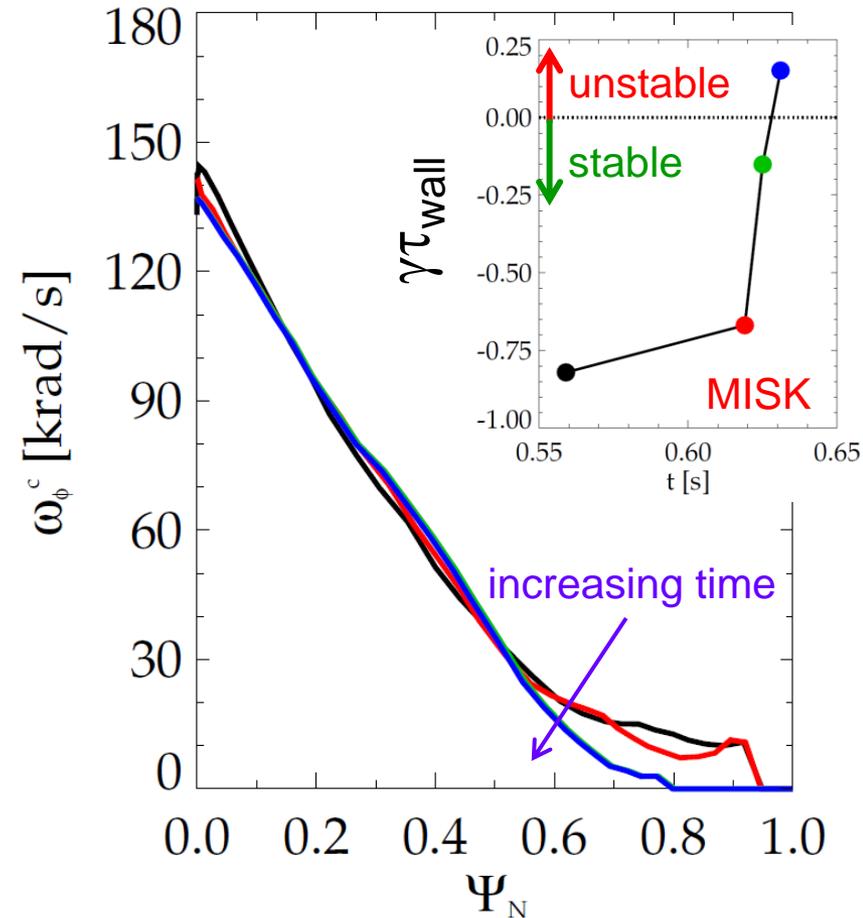
S. Sabbagh et al., DIII-D/NSTX experiments  
 S. Sabbagh et al., APS Invited talk 2014

# Evolution of plasma rotation profile leads to linear kinetic RWM instability as disruption is approached

## DIII-D (minor disruption)



## NSTX (major disruption)



S. Sabbagh et al., DIII-D/NSTX experiments; S. Sabbagh et al., APS Invited talk 2014

# Kinetic RWM stability evaluated for DIII-D and NSTX plasmas, reproduces experiments over wide rotation range

## Summary of results

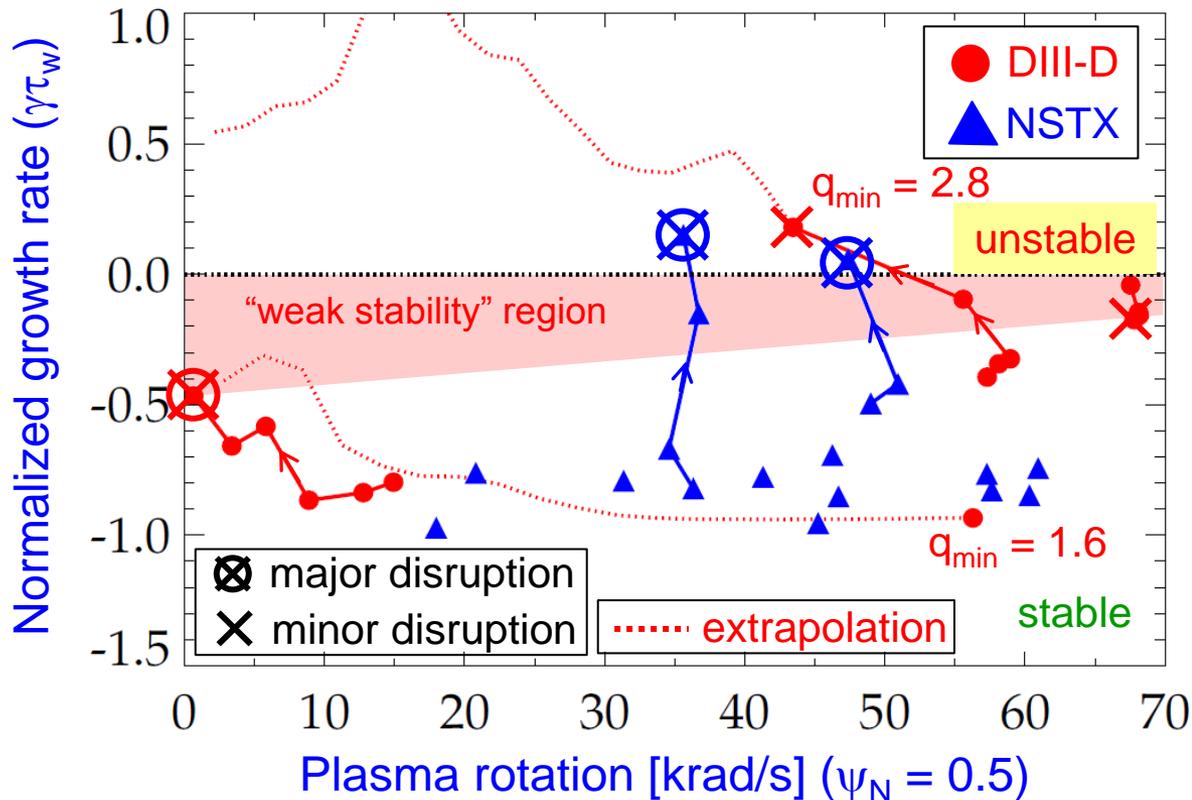
- Plasmas free of other MHD modes can reach or exceed linear kinetic RWM marginal stability

- Bursting MHD modes can lead to non-linear destabilization before linear stability limits are reached

- Extrapolations of DIII-D plasmas to different  $V_\phi$  show marginal stability is bounded by  $1.6 < q_{\min} < 2.8$

- Reduced models of kinetic RWM stability now being investigated to support real-time disruption avoidance (e.g. by rotation profile control)

## Kinetic RWM stability analysis for experiments (MISK)



J.W. Berkery, J.M. Hanson, S.A. Sabbagh (Columbia U.)

# Rotation feedback controller designed for NSTX-U using non-resonant NTV and NBI used as actuators

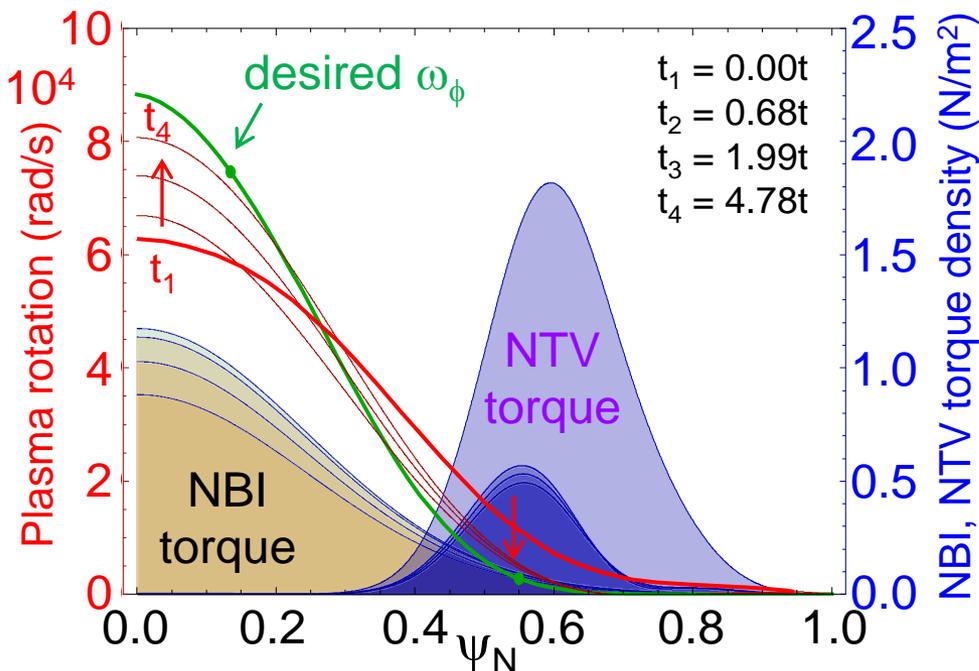
- Momentum force balance –  $\omega_\phi$  decomposed into Bessel function states

$$\sum_i n_i m_i \langle R^2 \rangle \frac{\partial \omega}{\partial t} = \left( \frac{\partial V}{\partial \rho} \right)^{-1} \frac{\partial}{\partial \rho} \left[ \frac{\partial V}{\partial \rho} \sum_i n_i m_i \chi_\phi \langle (R \nabla \rho)^2 \rangle \frac{\partial \omega}{\partial \rho} \right] + T_{NBI} + T_{NTV}$$

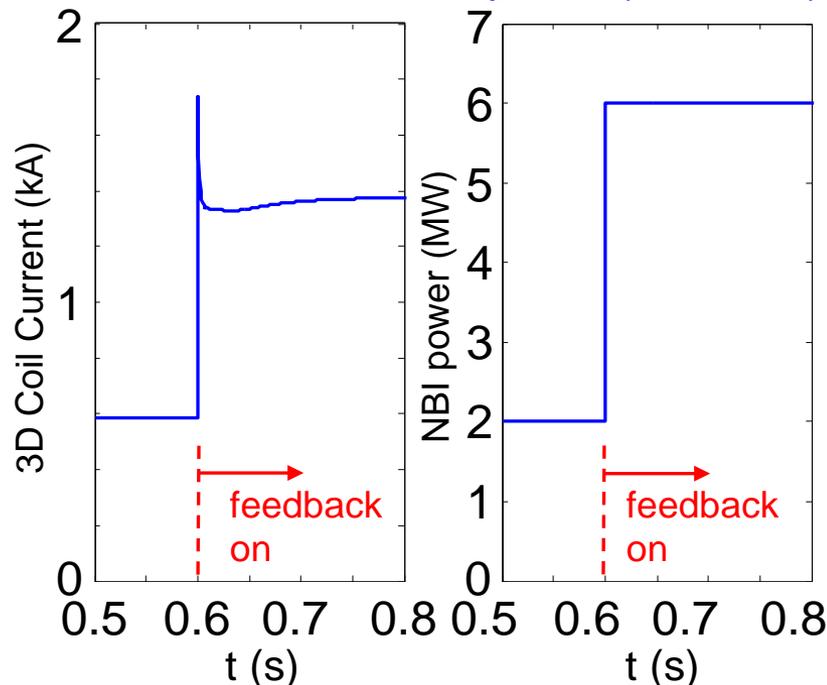
- NTV torque:

$$T_{NTV} \propto K \times f(n_{e,i}^{K1} T_{e,i}^{K2}) g(\delta B(\rho)) [I_{coil}^2 \omega] \quad \text{(non-linear)}$$

Rotation evolution and NBI and NTV torque profiles



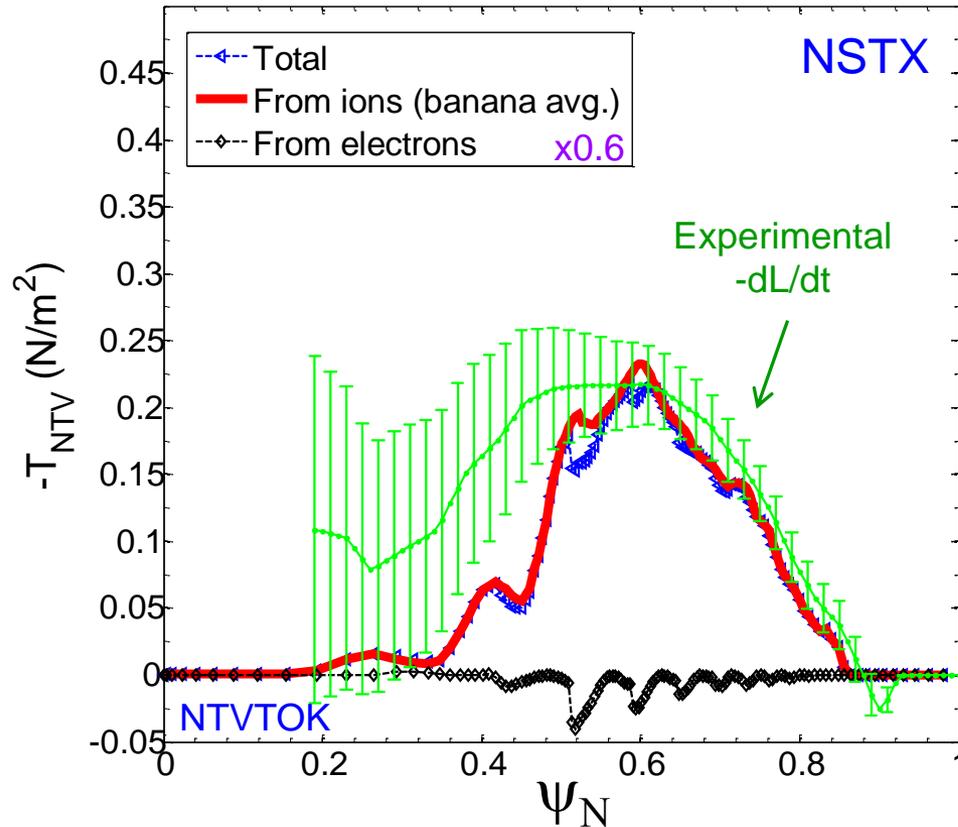
3D coil current and NBI power (actuators)



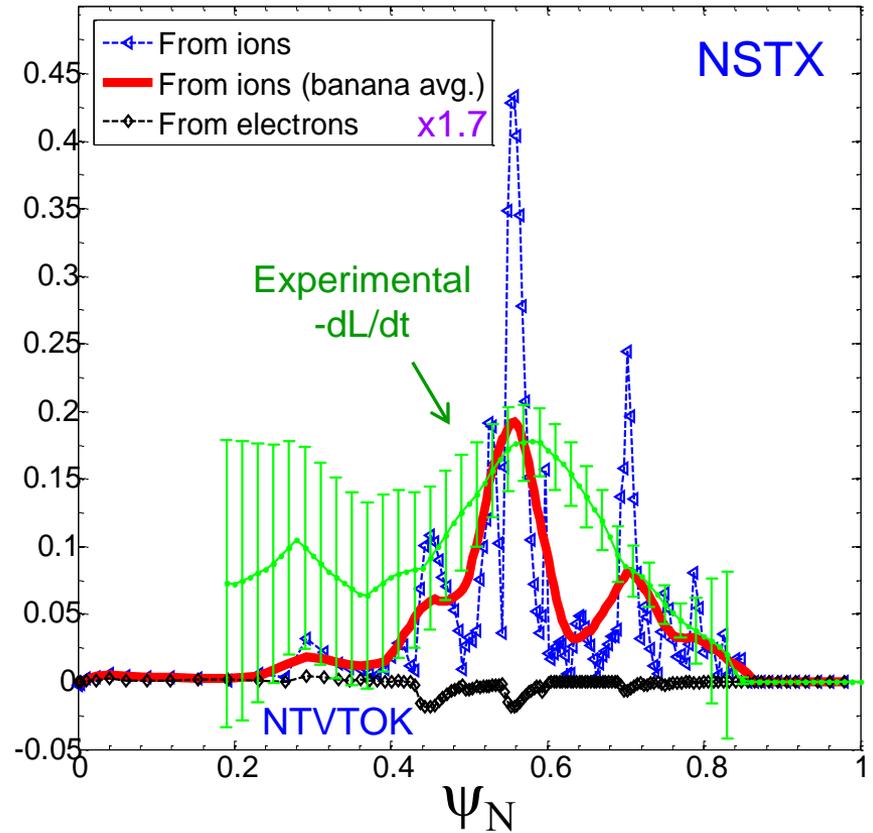
I. Goumiri (P.U. student), S.A. Sabbagh (Columbia U.), C. Rowley (P.U.), D.A. Gates, S.P. Gerhardt (PPPL)

# NTV physics studies for rotation control: measured NTV torque density profiles quantitatively compare well to theory

$n = 3$  coil configuration



$n = 2$  coil configuration

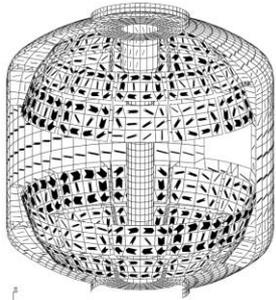


- $T_{NTV}$  (theory) scaled to match *peak* value of measured  $-dL/dt$ 
  - Scale factor  $((dL/dt)/T_{NTV}) = 1.7$  and  $0.6$  for cases shown above –  $O(1)$  agreement

S. Sabbagh et al., IAEA FEC 2014 (EX/1-4)

# Model-based RWM state space controller including 3D model of plasma and wall currents used at high $\beta_N$

Full 3-D model ~3000+ states

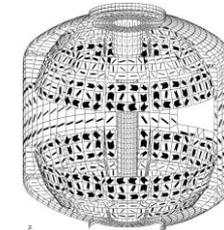
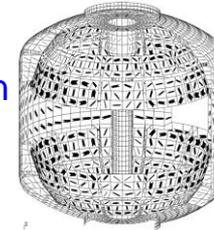


~3000+ states

Balancing transformation

State reduction (< 20 states)

RWM eigenfunction (2 phases, 2 states)



...

$(\hat{x}_1, \hat{x}_2)$

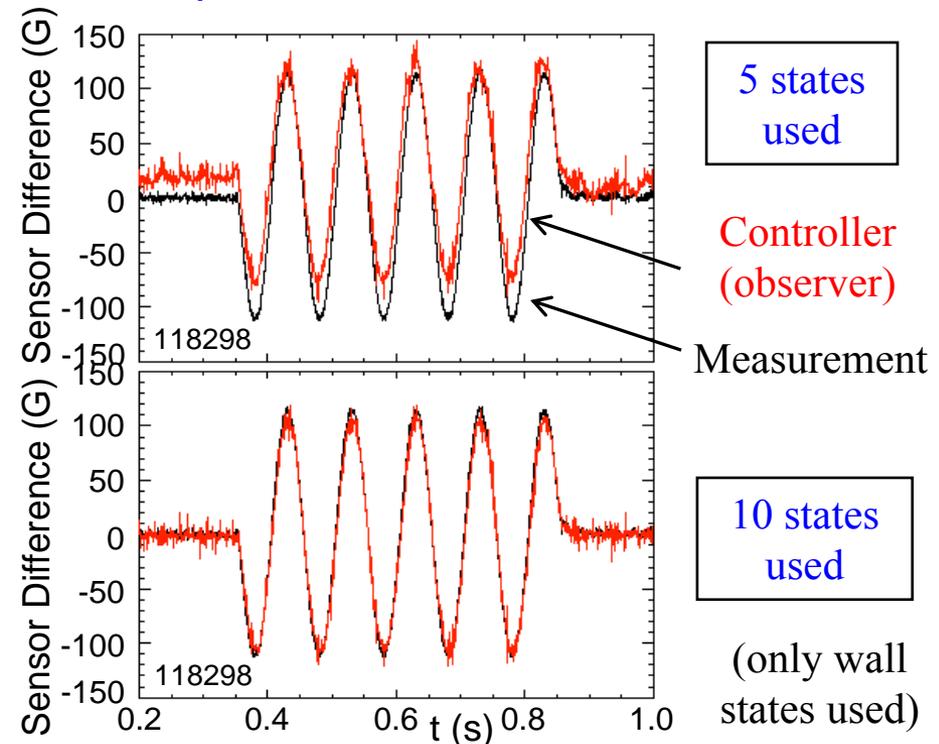
$\hat{x}_3$

$\hat{x}_4$

Controller reproduction of  $n = 1$  field in NSTX

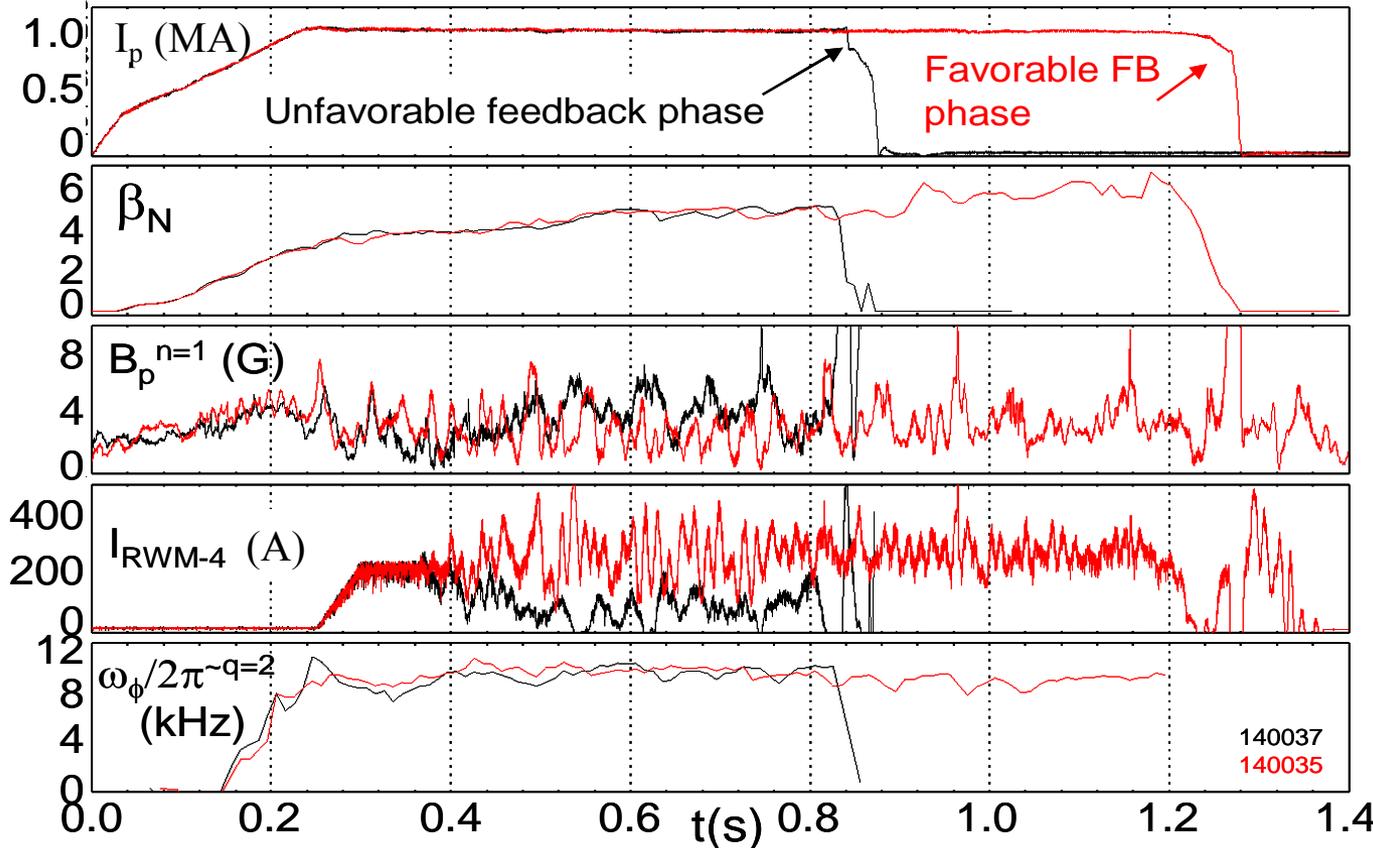
- Controller model can compensate for wall currents
  - Includes plasma mode-induced current
- Potential to allow more flexible control coil positioning
  - May allow control coils to be moved further from plasma, and be shielded (e.g. for ITER)

Katsuro-Hopkins, et al., NF 47 (2007) 1157
- Straightforward inclusion of multiple modes (with  $n = 1$ , or  $n > 1$ ) in feedback



# NSTX RWM state space controller sustains high $\beta_N$ , low $I_i$ plasma

## RWM state space feedback (12 states)



## NSTX Experiments

- $n = 1$  applied field suppression
  - Suppressed disruption due to  $n = 1$  field
- Feedback phase scan
  - Best feedback phase produced long pulse,  $\beta_N = 6.4$ ,  $\beta_N/I_i = 13$

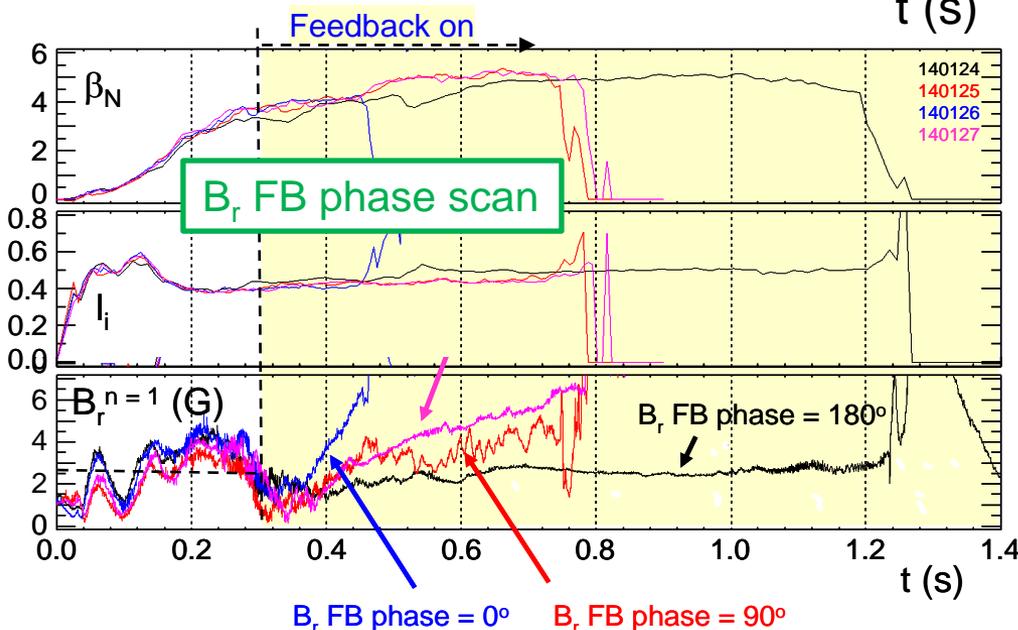
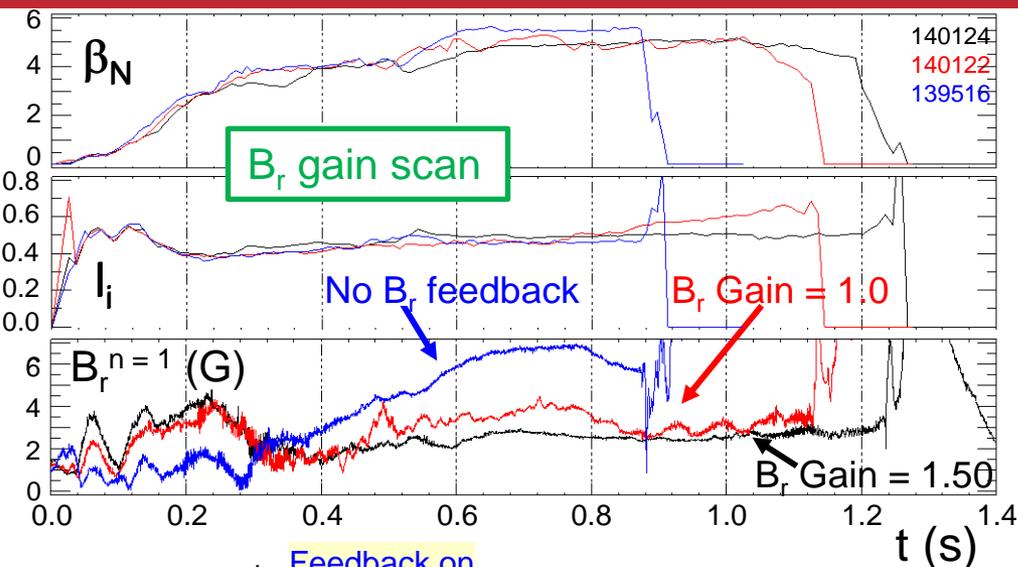
□ Run time has been allocated for continued experiments on NSTX-U

S. Sabbagh et al., Nucl. Fusion **53** (2013) 104007

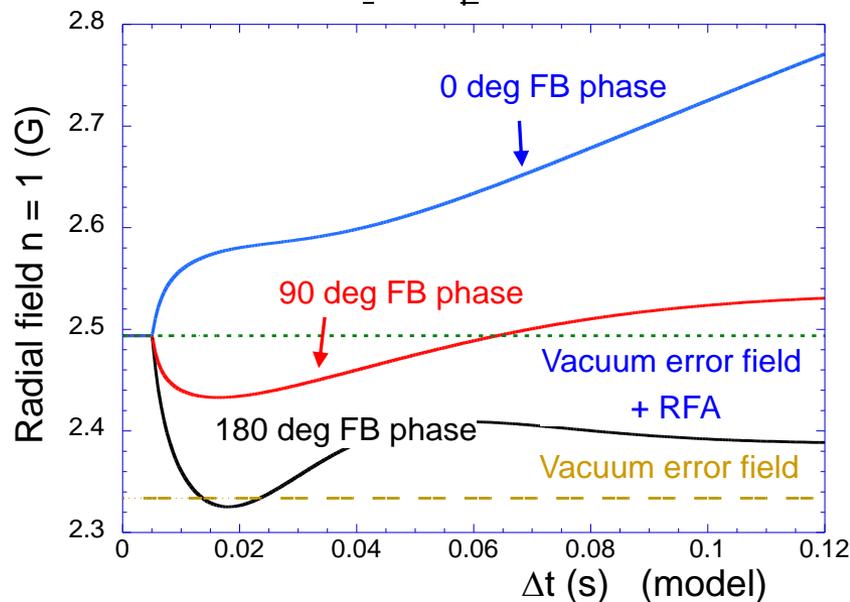
# Active RWM control: dual $B_r + B_p$ sensor feedback gain and phase scans produce significantly reduced $n = 1$ field

- Favorable  $B_p + B_r$  feedback (FB) settings found (low  $I_i$  plasmas)
- Time-evolved theory simulation of  $B_r + B_p$  feedback follows experiment

S. Sabbagh et al., Nucl. Fusion 53 (2013) 104007

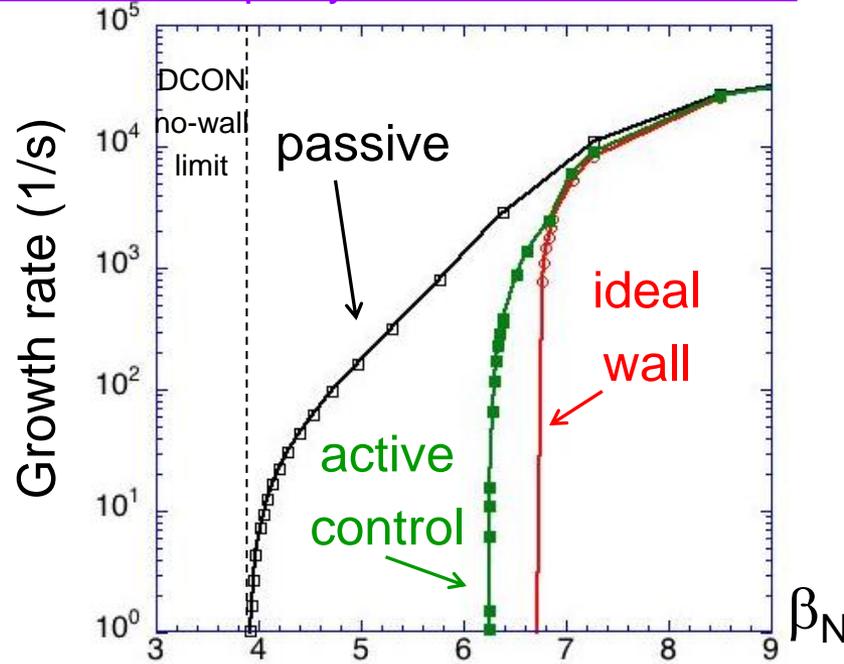


## Simulation of $B_r + B_p$ control (VALEN)

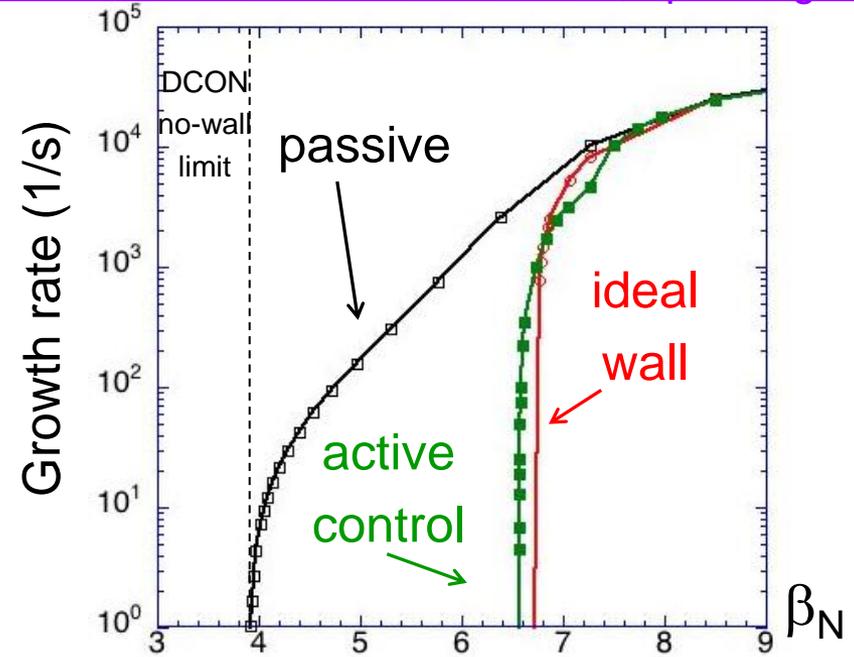


# Active RWM control design study for proposed NSTX-U 3D coil upgrade (NCC coils) shows superior capability

NCC 2x6 odd parity, with favorable sensors

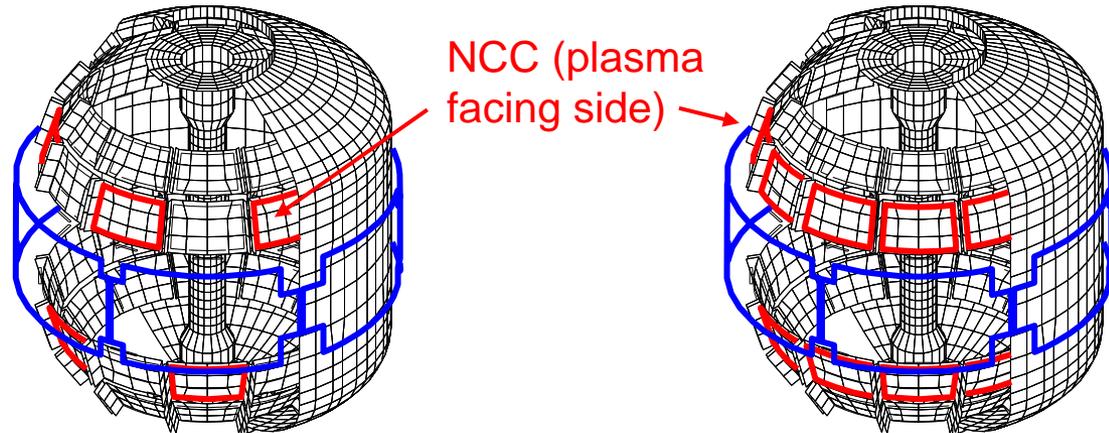


NCC 2x12 with favorable sensors, optimal gain

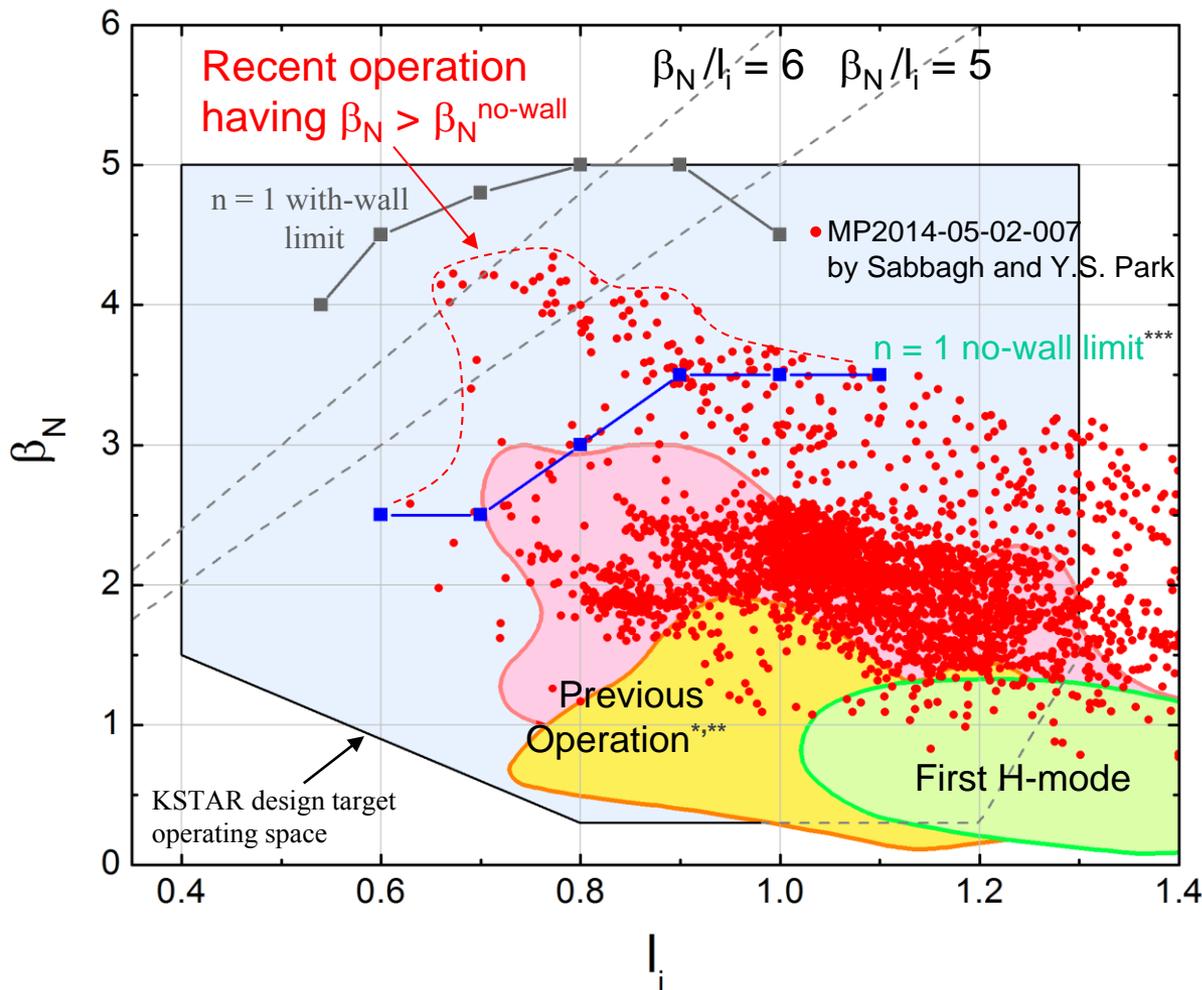


Full NCC coil set allows control close to ideal wall limit

- NCC 2x6 odd parity coils: active control to  $\beta_N/\beta_N^{\text{no-wall}} = 1.58$
- NCC 2x12 coils, optimal sensors: active control to  $\beta_N/\beta_N^{\text{no-wall}} = 1.67$



# Columbia U. experiments yield record $\beta_N$ for KSTAR, significantly surpassed the ideal MHD $n = 1$ stability limit



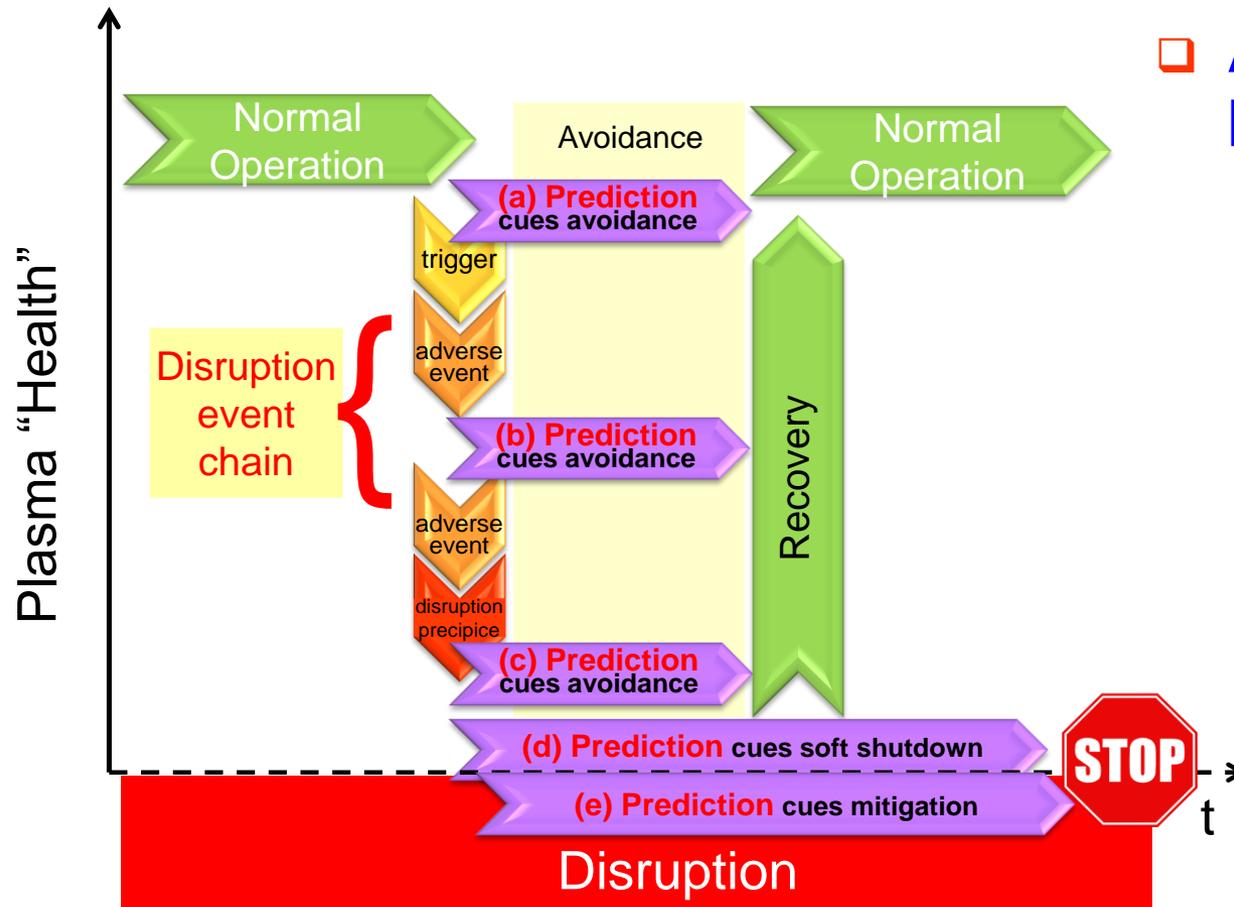
Normalized beta vs. internal inductance from KSTAR EFIT

- \*Y.S. Park, et al., Nucl. Fusion **53** (2013) 083029
- \*\*Y.S. Park, et al., Phys. Plasmas **21** (2014) 012513
- \*\* O. Katsuro-Hopkins, et al., Nucl. Fusion **50** (2010) 025019

- Plasma parameters
  - $q_{95} \sim 4.5$
  - $P_{\text{NBI}} = 2.7 - 4$  MW (2 or 3 beam sources)
- $\beta_N/l_i > 6$  (50% increase from the highest values in previous operations)
  - A high value for advanced tokamaks
  - $\beta_N$  up to 4.3
  - $l_i$  ranging 0.66 - 0.87 with  $\beta_N > 4$
  - Discharge  $\beta_N$  was **not** limited by  $n > 0$  events

Y.S. Park, S.A. Sabbagh, et al.,  
KSTAR Conference 2015

# Disruption event chain characterization capability started for NSTX-U as next step in disruption avoidance plan



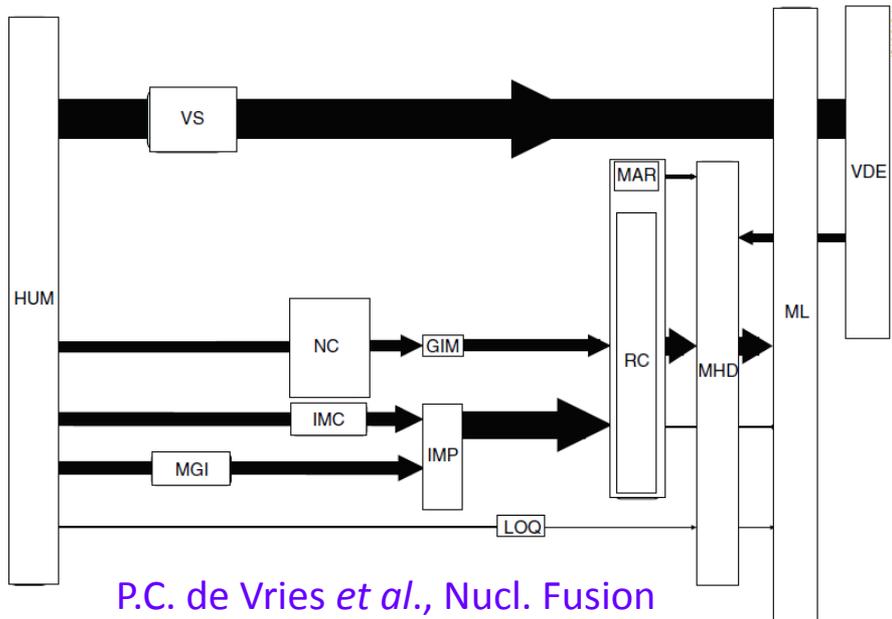
## Approach to disruption prevention

- Identify disruption event chains and elements
- Predict events in disruption chains
  - Attack events at several places
  - Give priority to early events
- Provide cues to avoidance system to break the chain
- Provide cue to mitigation system if avoidance deemed untenable

General code written (Python) to address the first step – initial test runs started using NSTX data

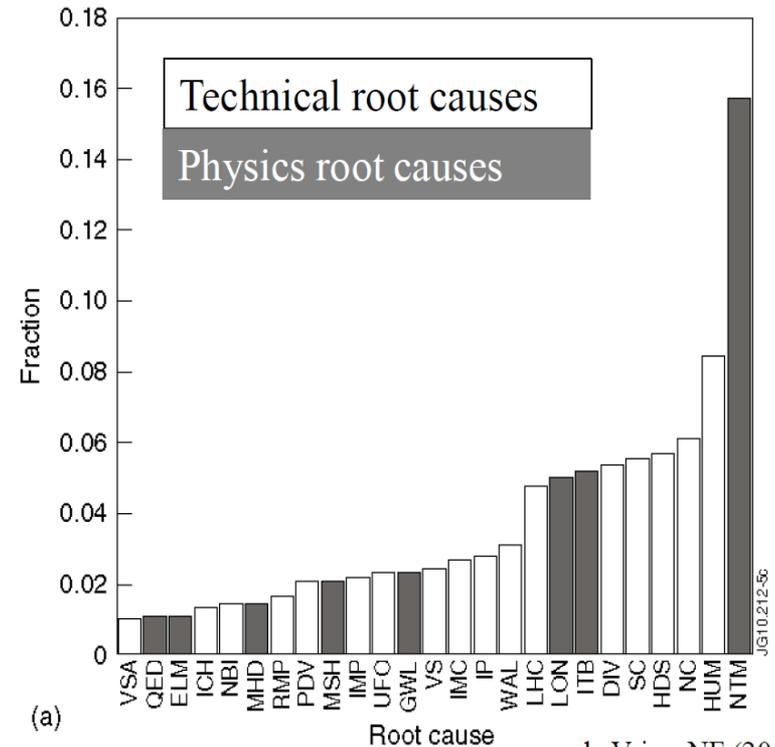
# JET disruption event characterization provides framework to follow for understanding / quantifying DPAM progress

## JET disruption event chains



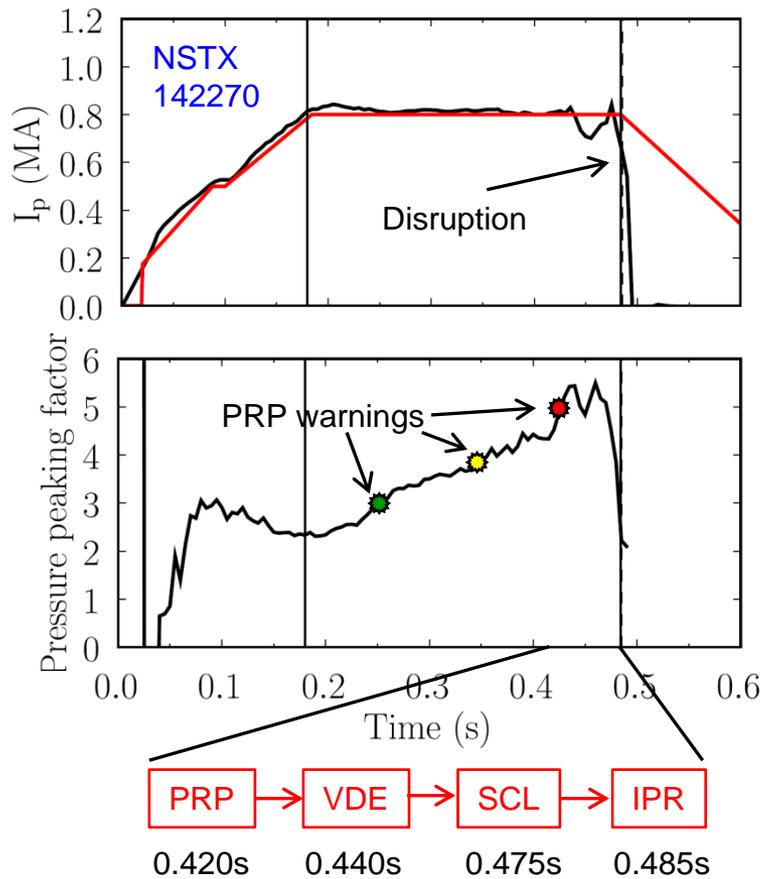
P.C. de Vries *et al.*, Nucl. Fusion  
51 (2011) 053018

## Related disruption event statistics



- ❑ JET disruption event chain analysis performed by hand, need to automate
- ❑ NSTX-U DPAM Working Group formed (w/ Columbia U. Group leadership):  
List of disruption chain events defined, interested individuals identified

# Disruption Characterization Code now yielding initial results: disruption event chains, with related quantitative warnings



- 10 physical disruption chain events and related quantitative warning points are presently defined in code
  - Code is easily expandable, portable to other tokamaks
  
- This example: Pressure peaking (PRP) disruption event chain identified by code
  1. (PRP) Pressure peaking warnings identified first
  2. (VDE) VDE condition subsequently found 20 ms after last PRP warning
  3. (SCL) Shape control warning issued
  4. (IPR) Plasma current request not met

J.W. Berkery, S.A. Sabbagh, Y.S. Park (Columbia U.)

# NSTX-U is a world leading program on disruption avoidance, Columbia U. Group Research providing a leadership role

## □ Physics Elements

- Kinetic RWM stabilization physics
- NTV physics for plasma rotation control (for instability avoidance)
- Active RWM control (physics-based RWM state-space controller)
- RWM control analysis of upgraded 3D coils for NSTX-U
- NSTX-U equilibrium reconstruction – key basis for stability analysis
- Planned real-time MHD spectroscopy for NSTX-U (in 5 Year Plan)
- Related high normalized beta and NTV experiments on KSTAR

## □ Research synergism

- Elements now being brought together as part of a disruption prediction/avoidance system; [NSTX-U DPAM working group leadership](#)
- Disruption Characterization/Prediction code initiated

## □ Action to enhance university / student / post-doc participation

- New diagnostic proposal to be submitted (Volpe/Sabbagh)

# Supporting slides follow

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# Modification of Ideal Stability by Kinetic theory (MISK code) is used to determine proximity of plasmas to stability boundary

Initially used for NSTX since simple critical scalar  $\omega_\phi$  threshold stability models did not describe RWM stability Sontag, et al., Nucl. Fusion **47** (2007) 1005

Kinetic modification to ideal MHD growth rate

- Trapped / circulating ions, trapped electrons, etc.
- Energetic particle (EP) stabilization

$$\gamma\tau_w = -\frac{\delta W_\infty + \delta W_K}{\delta W_{wall} + \delta W_K}$$

Hu and Betti, Phys. Rev. Lett **93** (2004) 105002

Stability depends on

- Integrated  $\omega_\phi$  profile: resonances in  $\delta W_K$  (e.g. ion precession drift)
- Particle collisionality, EP fraction  $\omega_\phi$  profile (enters through ExB frequency)

## Trapped ion component of $\delta W_K$ (plasma integral over energy)

Some NSTX / MISK analysis references

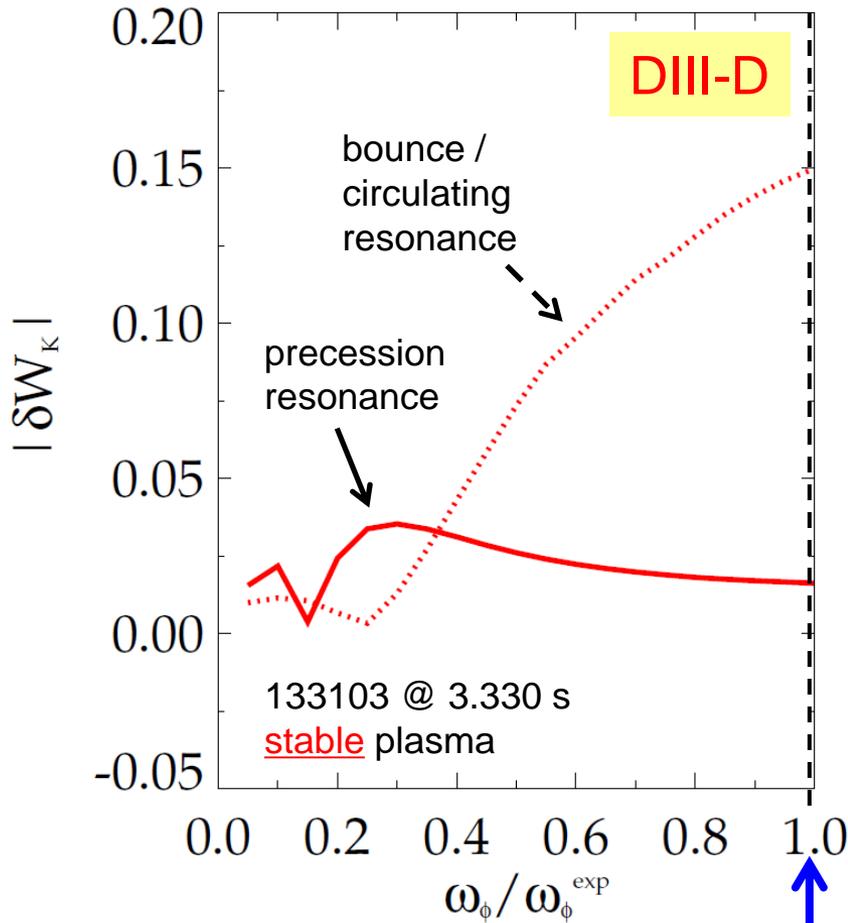
$$\delta W_K \propto \int \left[ \frac{\omega_{*N} + \left(\hat{\epsilon} - \frac{3}{2}\right)\omega_{*T} + \omega_E - \omega - i\gamma}{\langle \omega_D \rangle + l\omega_b - i\nu_{eff} + \omega_E - \omega - i\gamma} \right] \hat{\epsilon}^{\frac{5}{2}} e^{-\hat{\epsilon}} d\hat{\epsilon}$$

precession drift
bounce
collisionality

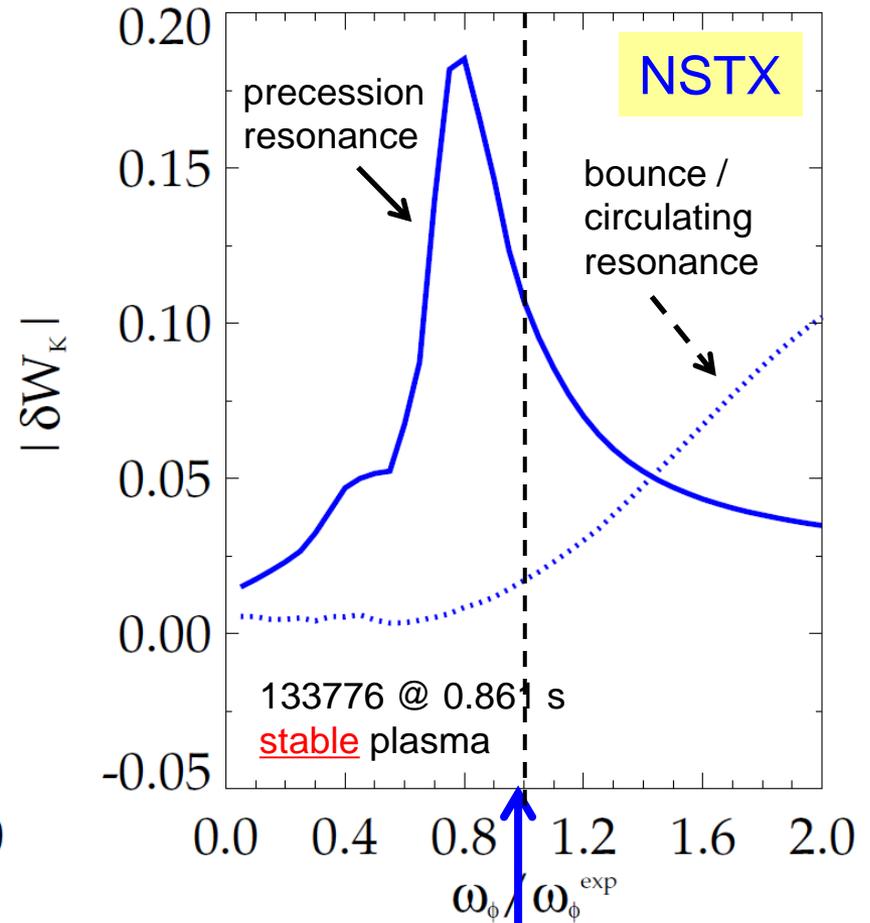
J. Berkery et al., PRL **104**, 035003 (2010)  
 S. Sabbagh, et al., NF **50**, 025020 (2010)  
 J. Berkery et al., PRL **106**, 075004 (2011)  
 J. Berkery et al., PoP **21**, 056112 (2014)  
 J. Berkery et al., PoP **21**, 052505 (2014)  
 (benchmarking paper)

# Bounce resonance stabilization dominates for DIII-D vs. precession drift resonance for NSTX at similar, high rotation

$|\delta W_K|$  for trapped resonant ions vs. scaled experimental rotation (MISK)



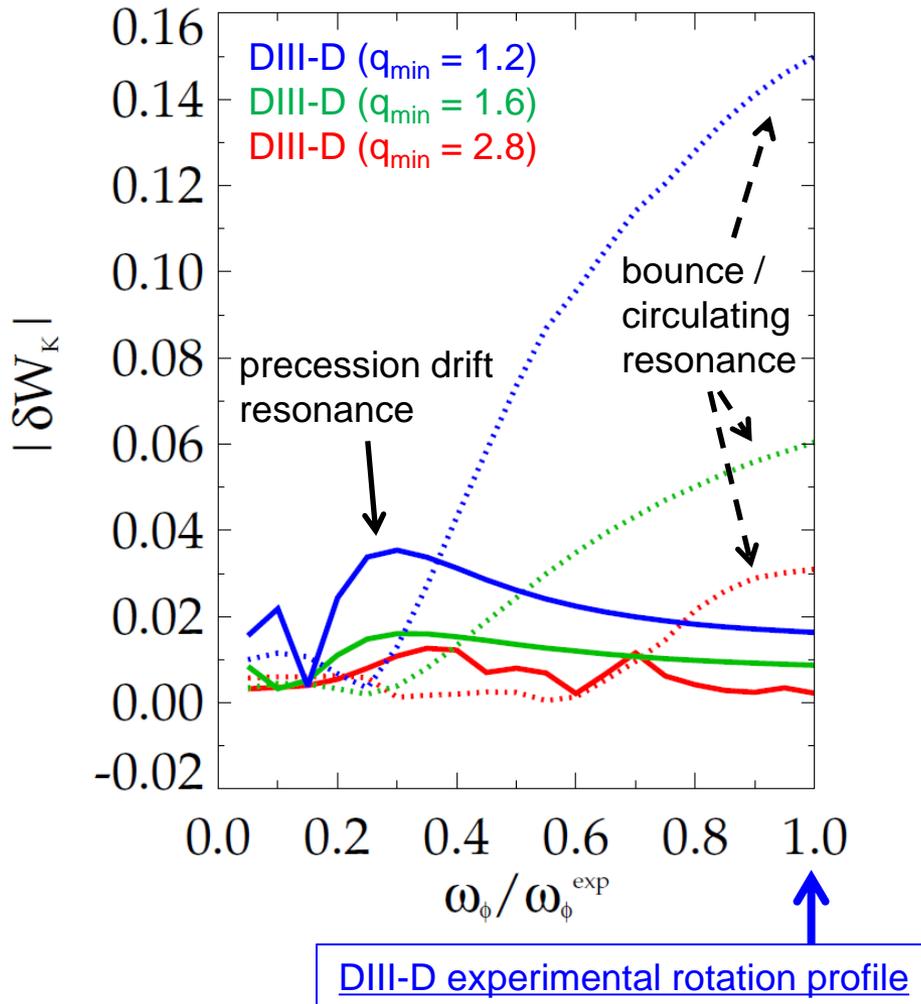
DIII-D experimental rotation profile



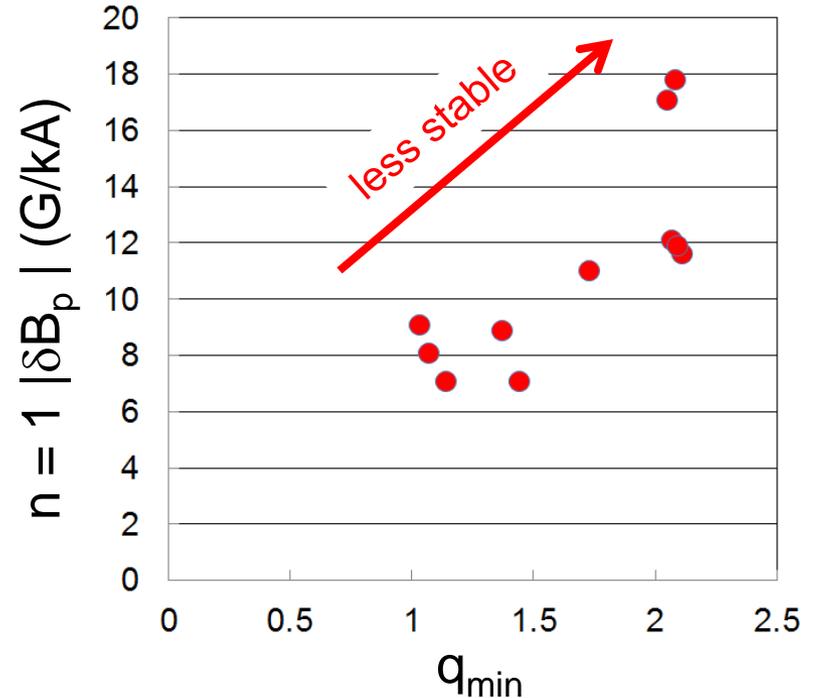
NSTX experimental rotation profile

# Increased RWM stability measured in DIII-D plasmas as $q_{\min}$ is reduced is consistent with kinetic RWM theory

$|\delta W_K|$  for trapped resonant ions vs. scaled experimental rotation (MISK)



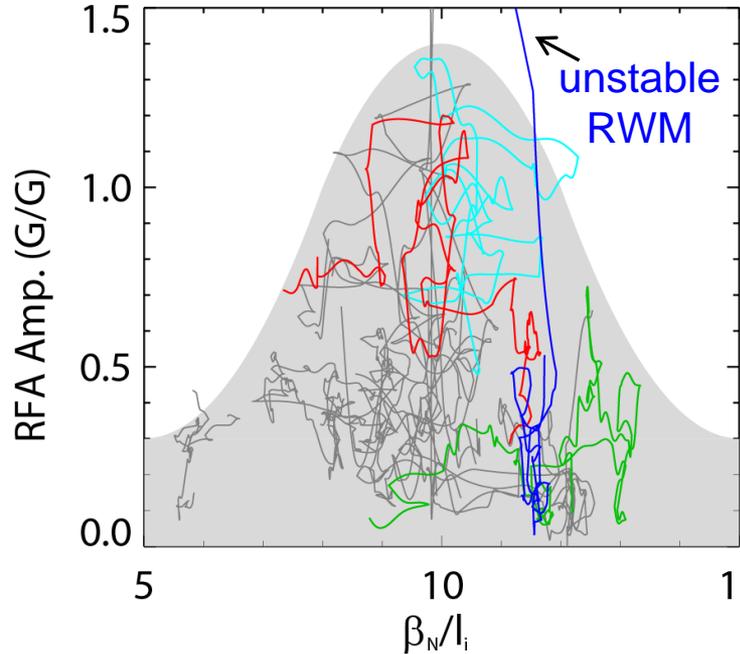
Measured plasma response to 20 Hz,  $n = 1$  field vs  $q_{\min}$



- Bounce resonance dominates precession drift resonance for all  $q_{\min}$  examined at the experimental rotation

# Experiments directly measuring global stability using MHD spectroscopy (RFA) support kinetic RWM stability theory

Resonant Field Amplification vs.  $\beta_N/I_i$



(trajectories of 20 experimental plasmas)

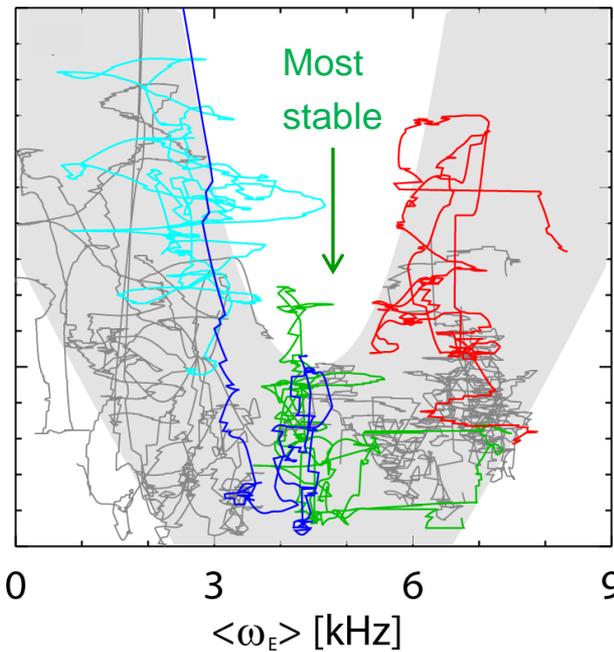
## Stability vs. $\beta_N/I_i$

- ▣ decreases up to  $\beta_N/I_i = 10$ ,
- ▣ increases at higher  $\beta_N/I_i$
- ▣ Consistent with kinetic resonance stabilization

S. Sabbagh, et al., NF **53** (2013) 104007

J. Berkery, et al., PoP **21** (2014) 056112

RFA vs. rotation ( $\omega_E$ )



## Stability vs. rotation

- ▣ Largest stabilizing effect from ion precession drift resonance with  $\omega_\phi$

Minimize  $|\langle \omega_D \rangle + \omega_E|$

$$\delta W_k \sim \frac{1}{\langle \omega_D \rangle + \omega_E - i\nu_{eff}}$$

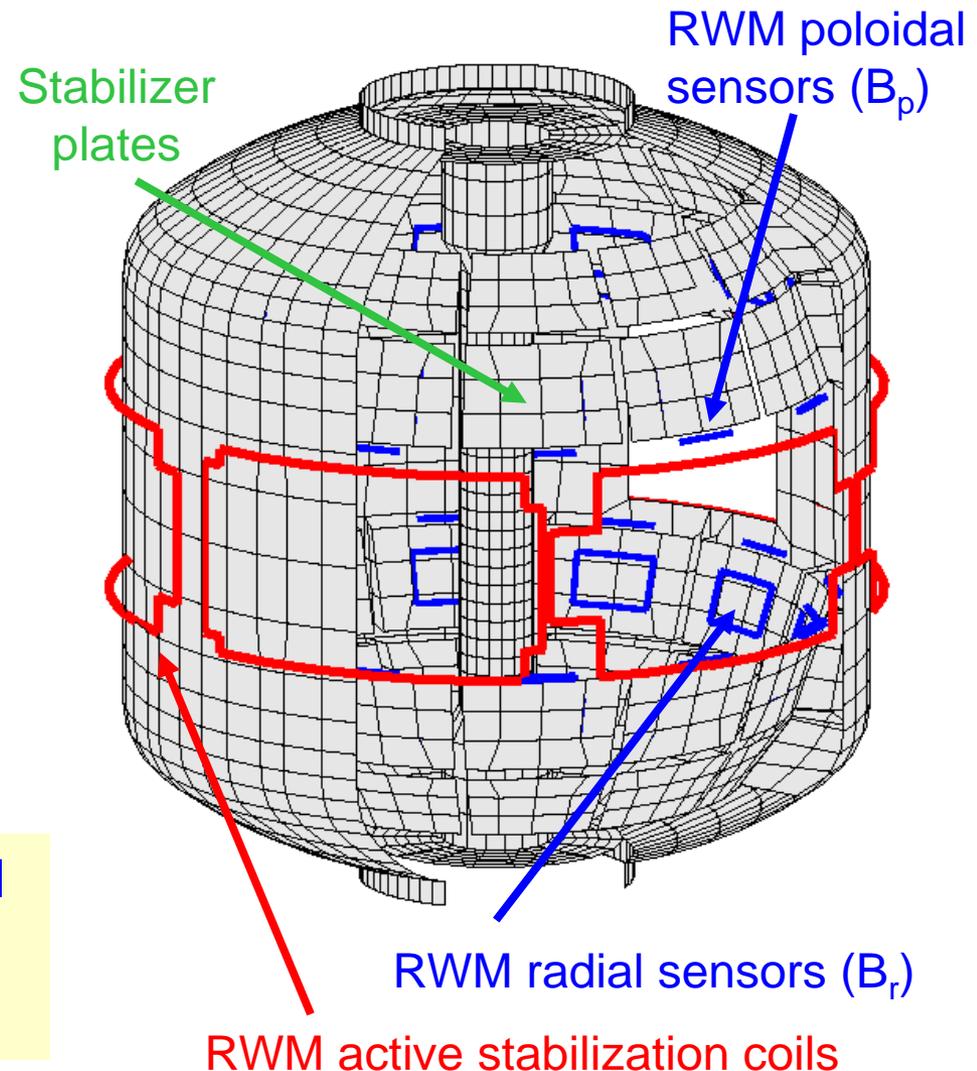
## NSTX experiments

- ▣ Stability at lower  $\nu$ 
  - ▣ Collisional dissipation is reduced
  - ▣ Stabilizing resonant kinetic effects are enhanced
  - ▣ Stabilization when near broad  $\omega_\phi$  resonances; almost no effect off-resonance

# NSTX is a spherical torus equipped to study passive and active global MHD control

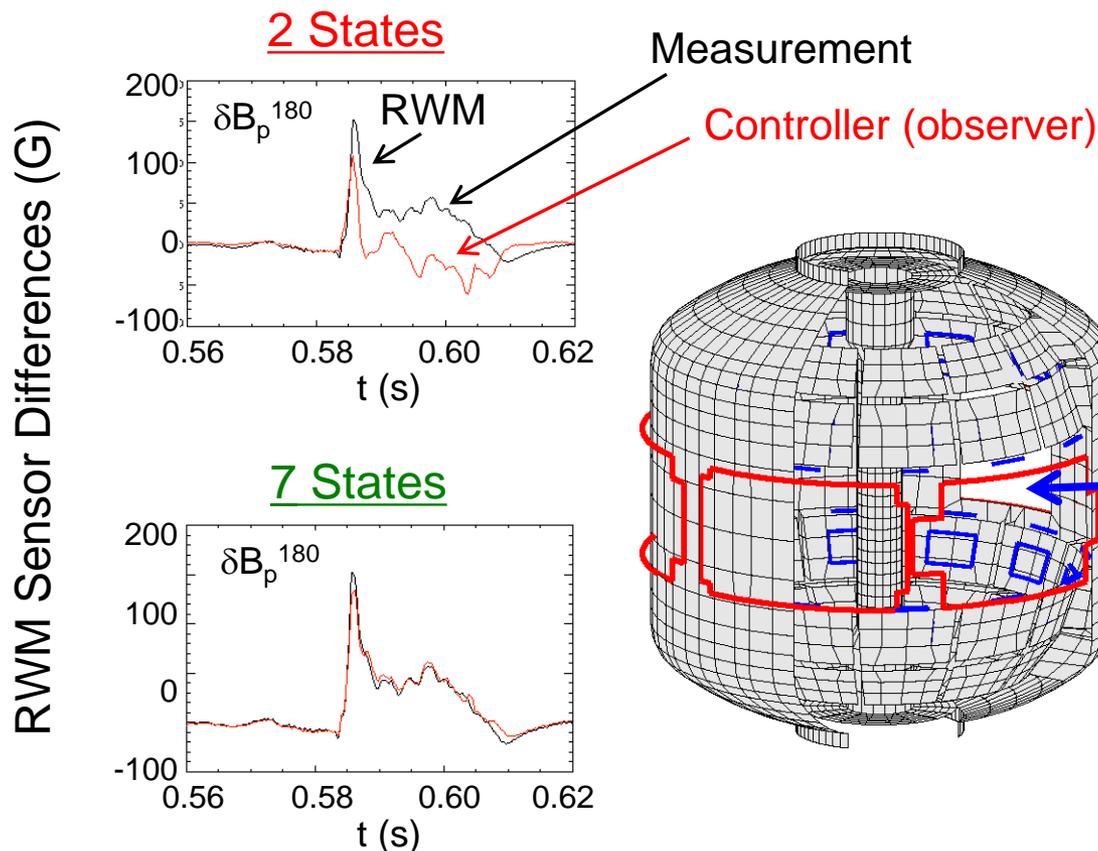
- High beta, low aspect ratio
  - $R = 0.86$  m,  $A > 1.27$
  - $I_p < 1.5$  MA,  $B_t = 5.5$  kG
  - $\beta_t < 40\%$ ,  $\beta_N > 7$
- Copper stabilizer plates for kink mode stabilization
- Midplane control coils
  - $n = 1 - 3$  field correction, magnetic braking of  $\omega_\phi$  by NTV
  - $n = 1$  RWM control
- Combined sensor sets now used for RWM feedback
  - 48 upper/lower  $B_p$ ,  $B_r$

## 3D Structure Model

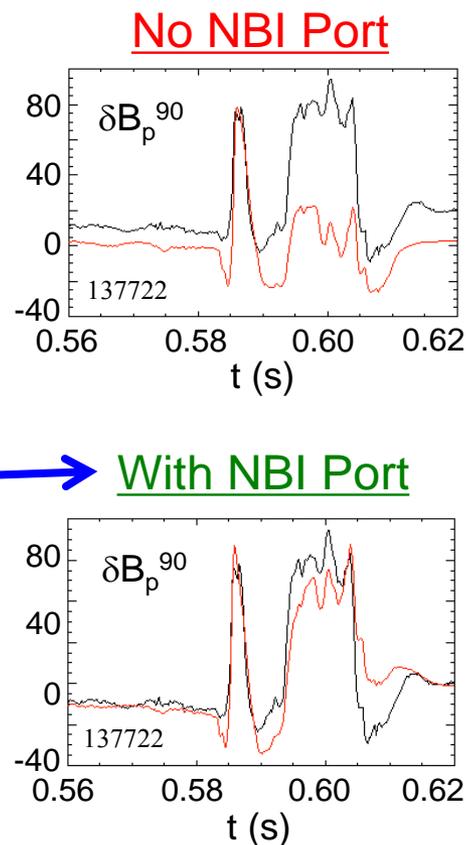


# Open-loop comparisons between measurements and RWM state space controller show importance of states and model

## A) Effect of Number of States Used



## B) Effect of 3D Model Used

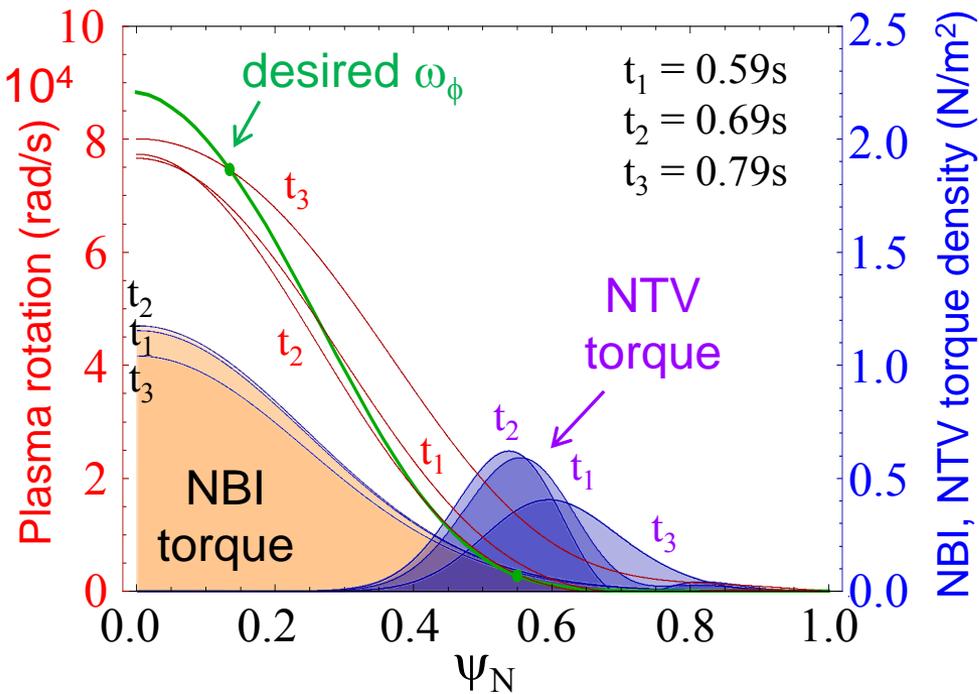


❑ Improved agreement with sufficient number of states (wall detail)

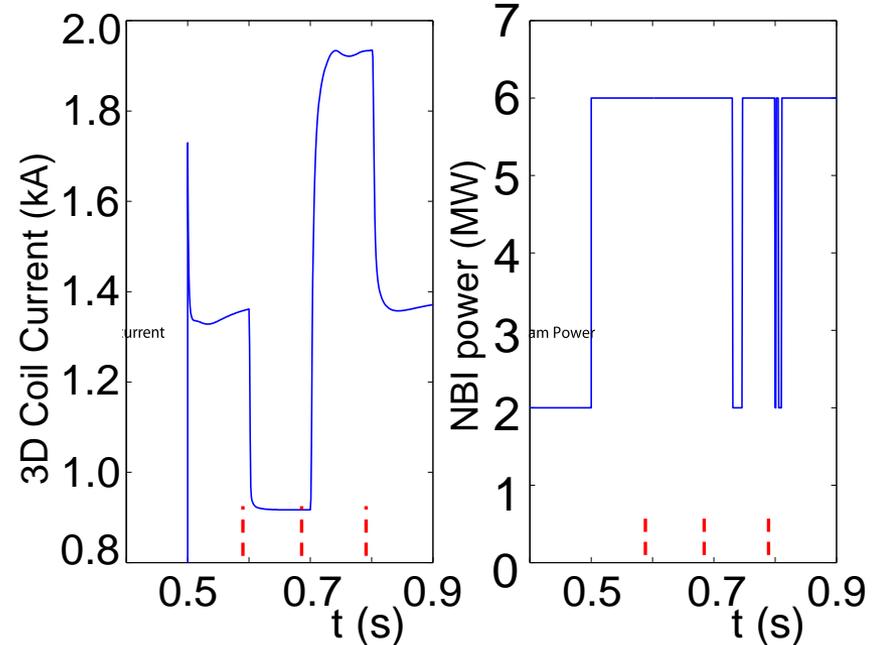
❑ 3D detail of model important to improve agreement

# When $T_i$ is included in NTV rotation controller model, 3D field current and NBI power can compensate for $T_i$ variations

Rotation evolution and NBI and NTV torque profiles



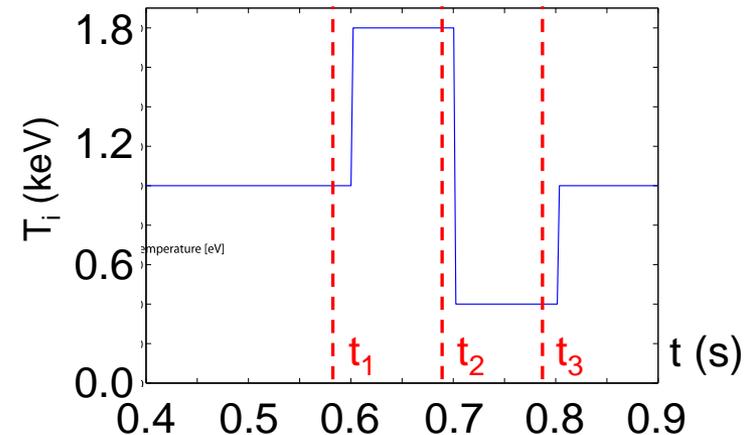
3D coil current and NBI power (actuators)



$$T_{NTV} \propto K \times f(n_{e,i}^{K1} T_i^{K2}) g(\delta B(\rho)) [I_{coil}^2 \omega]$$

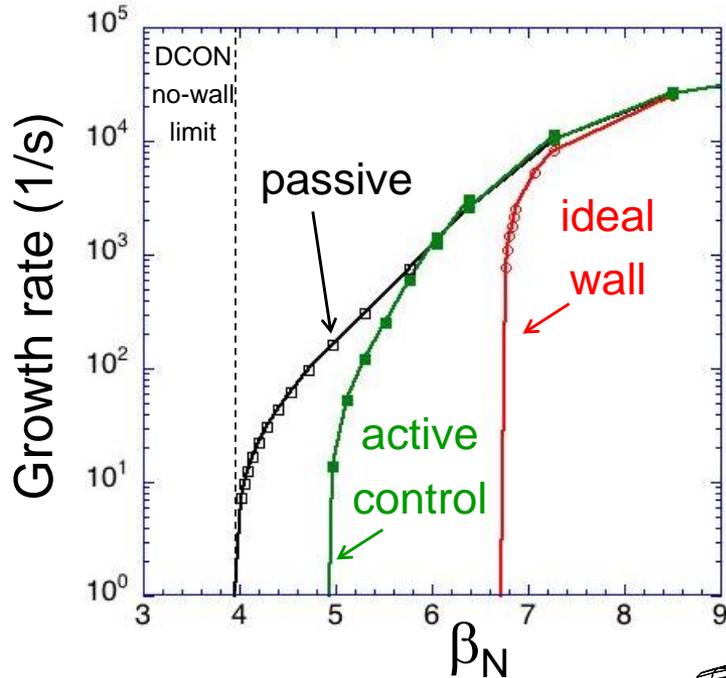
$K1 = 0, K2 = 2.5$

□ NTV torque profile model for feedback dependent on ion temperature

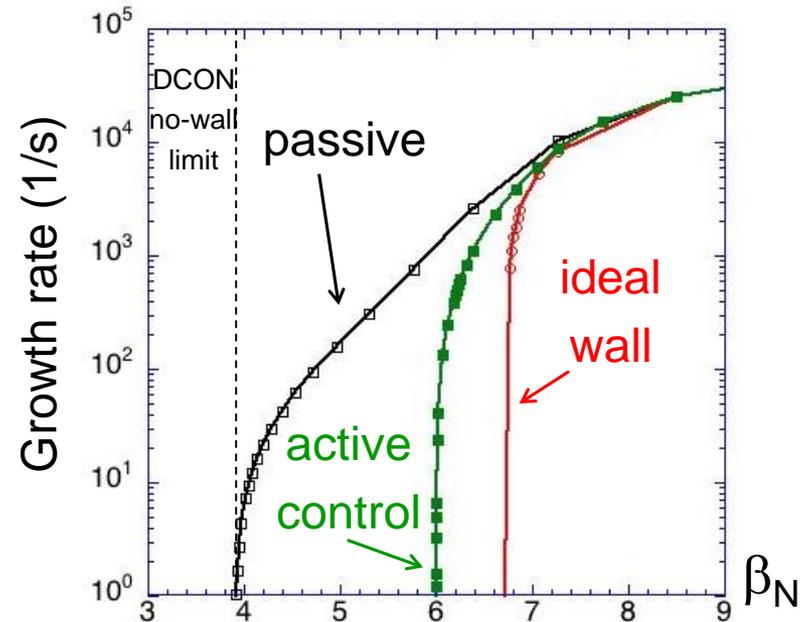


# NSTX-U: RWM active control capability increases as proposed 3D coils upgrade (NCC coils) are added

Using present midplane RWM coils

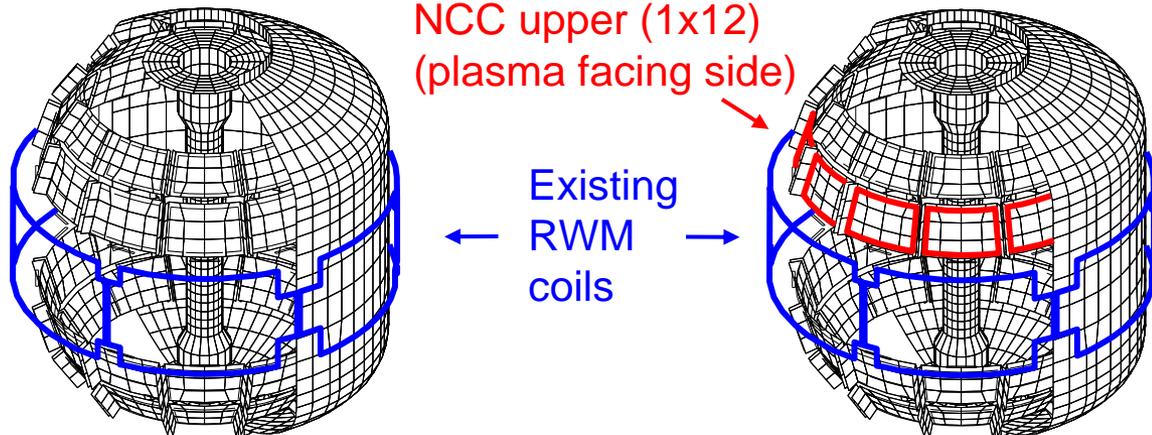


Partial NCC 1x12 (upper), favorable sensors



Partial 1x12 NCC coil set significantly enhances control

- Present RWM coils: active control to  $\beta_N/\beta_N^{\text{no-wall}} = 1.25$
- NCC 1x12 coils: active control to  $\beta_N/\beta_N^{\text{no-wall}} = 1.52$



# Real-time MHD spectroscopy, model-based active control, and kinetic physics will be used for disruption avoidance

## MHD Spectroscopy

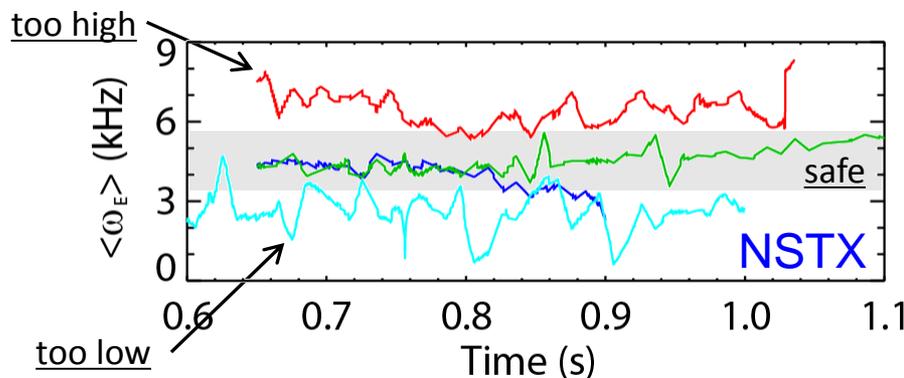
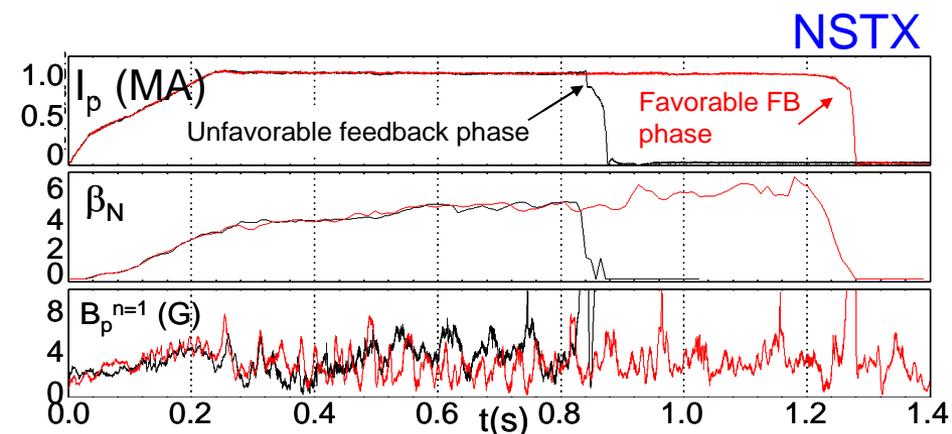
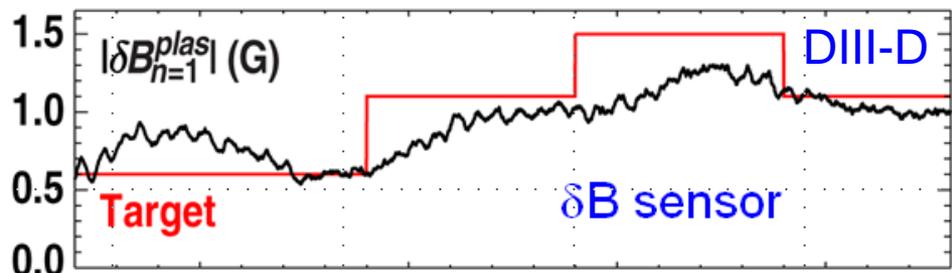
- Use real-time measurement of plasma global mode stability to “steer” toward increased stability

## Advanced active control

- Combined Br + Bp feedback reduces  $n = 1$  field amplitude, improves stability
- RWM state space controller sustains low  $I_i$ , high  $\beta_N$  plasma

## Simplified kinetic physics models

- “steer” profiles (e.g. plasma toroidal rotation) toward increased stability in real-time



# NSTX-U DPAM Working Group meeting: List of disruption chain events defined, interested individuals identified

- ❑ **Impurity control (NC)**
  - ❑ bolometry-triggered shutdown (SPG); "tailoring" radiation-induced TM onset (LD, DG)
  - ❑ change plasma operational state / excite ELMs, etc. (TBD – perhaps JC)
- ❑ **Greenwald limit (GWL)**
  - ❑ density/power feedback, etc. (DB)
- ❑ **Locked TM (LTM)**
  - ❑ TM onset and stabilization conditions, locking thresholds (JKP,RLH,ZW)
  - ❑ TM entrainment (YSP)
- ❑ **Error Field Correction (EFC)**
  - ❑ NSTX-U EF assessment and correction optimization (CM,SPG)
  - ❑ NSTX-U EF multi-mode correction (SAS, YSP, EK)
- ❑ **Current ramp-up (IPR)**
  - ❑ Active aux. power / CD alteration to change q (MDB, SPG)
- ❑ **Shape control issues (SC)**
  - ❑ Active alteration of squareness, triangularity, elongation – RFA sensor (SPG,MDB)
- ❑ **Transport barrier formation (ITB)**
  - ❑ Active global parameter,  $V_{\phi}$ , etc. alteration techniques (SAS,JWB,EK)
- ❑ **H-L mode back-transition (HLB)**
  - ❑ Active global parameter,  $V_{\phi}$ , etc. alteration techniques (SAS,JWB,EK)
- ❑ **Approaching vertical instability (VSC)**
  - ❑ Plasma shape change, etc. (SPG, MDB)
- ❑ **Resistive wall mode (RWM)**
  - ❑ Active global parameter,  $V_{\phi}$ , etc. alteration techniques (SAS,JWB)
  - ❑ Active multi-mode control (SAS,YSP,KT)
- ❑ **Ideal wall mode (IWM)**
  - ❑ Active global parameter,  $V_{\phi}$ , etc. alteration techniques (JEM)
- ❑ **Internal kink/Ballooning mode (IKB)**
  - ❑ Active global parameter,  $V_{\phi}$ , etc. alteration techniques (SAS,JWB)
  - ❑ Active multi-mode control (SAS, YSP, KT)

## Abbreviations:

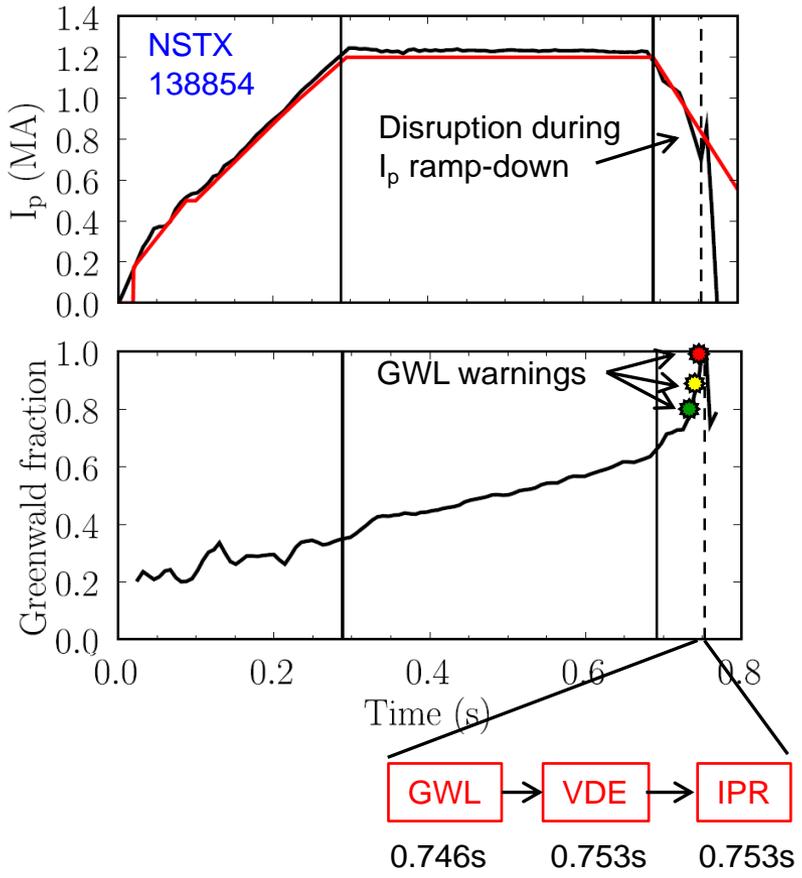
JWB: Jack Berkery  
AB: Amitava Bhattacharjee  
DB: Devon Battaglia  
MDB: Dan Boyer  
JC: John Canik  
LD: Luis Delgado-Aparicio  
DG: Dave Gates  
SPG: Stefan Gerhardt  
MJ: Mike Jaworski  
EK: Egemen Kolemen  
RLH: Rob La Haye  
JEM: Jon Menard  
CM: Clayton Myers  
JKP: Jong-Kyu Park  
YSP: Young-Seok Park  
RR: Roger Raman  
SAS: Steve Sabbagh  
KT: Kevin Tritz  
ZW: Zhirui Wang  
TBD: (To be decided)

## ❑ Interest from Theory

- ❑ Amitava Bhattacharjee, Allen Boozer, Dylan Brennan, Bill Tang have requested involvement

Interested? contact:  
sabbagh@pppl.gov  
raman@pppl.gov

# Disruption Characterization Code now yielding initial results: disruption event chains, with related quantitative warnings (2)



- This example: Greenwald limit warning during  $I_p$  rampdown
  1. (GWL) Greenwald limit warning issued
  2. (VDE) VDE condition then found 7 ms after GWL warning
  3. (IPR) Plasma current request not met

J.W. Berkery, S.A. Sabbagh, Y.S. Park