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High-β Error Field Detection (1515) and Dynamic Error Field Correction (1516)

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XP 1515, 1516 MS TSG Review July 28, 2015



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XP Goals and Allocations

- XP 1515: High-beta *n*=1,2,3 error field detection
 - Goal: Assess *n*=1,2,3 error fields at high- $\beta \rightarrow$ detect not correct
 - − Allocation: 0.5 run day (non-XMP CCE) \rightarrow ~12 shots
- XP 1516: Dynamic error field correction (DEFC)
 - Goal: Optimize DEFC observer (miu) and PID controller
 - − Allocation: 1.0 run days (non-XMP CCE) \rightarrow ~24 shots

Diagnostic & target plasma requirements

- Diagnostics:
 - RWM/EF sensors (locked modes)
 - CHERS (rotation)
 - Disruptions
- Target plasmas:
 - H-mode discharges above the no-wall limit
 - Need CHERS as fast as it will go \rightarrow NB1 only (?)
- Hardware requirements:
 - NSTX-U fiducial shot
 - RWM coils + SPAs

XP 1515: High-β Error Field Detection



XP 1515-16 - NSTX-U MS TSG Review - Error Fields - Clayton Myers - 7/27/2015

Step 1: *n*=1 compass scan (4 shots)

- Ramp applied n=1 amplitude at fixed phase \rightarrow look for locked mode
- Four points to fill out the circle \rightarrow identifies intrinsic *n*=1 error field



Menard et al., NF 50, 045008 (2010)

Step 2: *n*=1 amplitude and/or phase sweep (2 shots)

- Try to use DIII-D technique of ramping amplitude through zero at fixed phase
- Need to fill out two axes in complex phase space (see below)
- Only takes one shot in DIII-D \rightarrow at least two in NSTX-U (need ~1s flattop?)
- Could alternatively scan phase at fixed amplitude (traveling wave)



N. C. Logan, Ph.D. Thesis, Princeton University (2015)

Steps 3 & 4: n=2,3 amplitude (or phase) sweep (5 shots)

- 6 SPA setup allows *n*=2,3 perturbations in same XP
- For *n*=2 (3 shots):
 - Amplitude modulation with 5 Hz phase sweep on top (three amplitudes per shot, 300 ms flattop per amplitude)
 - Run same shot positive and negative
 - Select three refined amplitudes for third shot
 - [Or try amplitude sweep as with *n*=1]
- For *n*=3 (2 shots):
 - Three amplitudes per shot
 - No phase sweep possible
 - Simply flip sign in second shot



XP 1515 Synthesized Shot Plan

•	Step 1:	<i>n</i> =1 compass scan (locking)	4 shots
•	Step 2:	<i>n</i> =1 amplitude sweep (rotation)	2 shots
•	Step 3:	<i>n</i> =2 amplitude modulation/phase sweep	3 shots
•	Step 4:	n=3 amplitude modulation	2 shots
•	Step 5:	Fire shot at best combined settings	1 shot
			Total: 12 shots

XP 1516: Dynamic Error Field Correction



XP 1515-16 - NSTX-U MS TSG Review - Error Fields - Clayton Myers - 7/27/2015

Dynamic Error Field Correction in NSTX

- Previous results
 - Longest NSTX discharges achieved with real time *n*=1 EF correction
 - Standard tool for NSTX operation
- This XP: Optimization of PID dynamic error field correction
 - The mode ID upgrade (miu) algorithm corrects for static and AC pickup on the RWM/EF sensors
 - Tune the sensors, phases, and gains in the miu-based PID feedback algorithm
 - Utilize low pass filter (already available in PCS) to isolate the effect of DEFC from fast RWM control



J. E. Menard, et al., NF 50, 045008 (2010)



Real-time sensor compensations for "Mode ID"

- Sensors should measure the *n*=1 field from the plasma only.
 - Need to "compensate" the ith sensor B_i for other sources of field
 - With proper compensations, vacuum shots produce no signal
- Three Two compensations now in real-time system



remaining compensation: vessel eddy currents via loop voltages

DEFC tuning prescription (Menard et al.)

Pre-programmed n=1 EF correction requires a priori estimate of intrinsic EF Detect plasma response \rightarrow EF correction using <u>only feedback on RFA</u>

RFA Suppression Algorithm

- Use discharge with rotationally stabilized RWM.
- Deliberately apply n=1 EF in order to reduce rotation, destabilize an RWM.
- Find feedback phase that reduces the applied n=1 currents (B_P sensors).
 - Direct coil-sensor pickup is removed.
- Increase the gain until currents are nearly nulled and plasma stability is restored.



→ Use same gain/phase settings to suppress RFA from intrinsic EF **and** any unstable RWMs

XP Preparation

- Prove that RWM/EF sensor compensation is working
- Early decision point:
 - Use intrinsic or deliberate n=1 error field for DEFC tuning?
- Will tune DEFC with two independent observers: the B_P and B_R RWM/EF sensors:
 - Should get preliminary gain and phase scan from XMP 121 (6 SPA RWM control checkout)
 - For each sensor set, need "optimum spatial phase" \rightarrow see next slide
- Parameters to scan per observer (B_P, B_R) :
 - Feedback gain
 - Feedback phase
 - Low pass filter (LPF) time constant = [off, 20 ms, 40 ms]?

Determining the upper/lower spatial phase difference

- Find time in discharge when there is likely to be a dominant n=1 mode.
 - Just after an n=1 mode stops rotating and locks to the wall.
 - Large RWM.
- Find spatial phase that maximizes the n=1 amplitude.
- For B_P sensors, spatial phase of 150-180° is the clear winner.
- Appears to be an optimum for B_R sensors around 180° as well.
 - XP-802 used 0° $B_{\rm R}$ spatial phase for feedback, while off-line analysis presently uses 250°.



Use this spatial phase (180°) when generating the mode-ID matrix for realtime control



- Run shots with three settings per shot (~250 ms duration?)
- Step 1: B_P obs. = 2 gains × 4 phases × 3 tLPF 8 shots
- Step 2: B_R obs. = 2 gains × 4 phases × 3 tLPF 8 shots
- Step 3a: Test against intrinsic EF if deliberate EF used 4 shots
- Step 3b: Run with $B_P + B_R$ feedback for comparison
- Step 5: Apply traveling wave of various frequencies to test suppression via DEFC
 4 shots

Total: 24 shots