

Boundary Conditions Used in NIMROD Helicity Injection Simulations

C. R. Sovinec,¹ E. B. Hooper,² and J. B. O'Bryan¹

¹*University of Wisconsin-Madison*

²*Lawrence-Livermore National Laboratory*

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Some slides are from ICC 2011 and Sherwood 2012.
Also see Phys. Plasmas **18**, 094502.



Introduction: HIT and HIT-II were spherical torus (ST) experiments at U. WA designed to study coaxial helicity injection (CHI) current-drive.

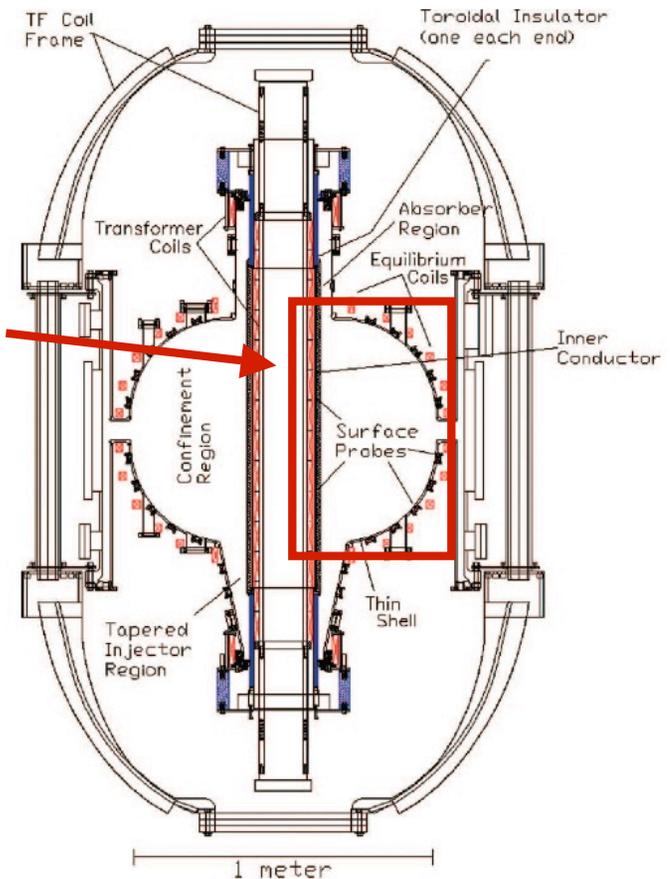
- Unlike CHI in spheromaks, configurations with a conducting center column need an insulating absorber gap to allow steady-state operation. $d(\text{tor. flux})/dt \rightarrow 0$.

Domain for HIT-II computations

- At large I_{INJ}/I_{TF} ratios, MHD instabilities are excited, and the current-density profile relaxes.

- At smaller I_{INJ}/I_{TF} ratios, explored in the 24954-24971 and 26449-26476 series, for example, any relaxation is relatively weak. HIT-II results in these conditions show distinct scaling information.

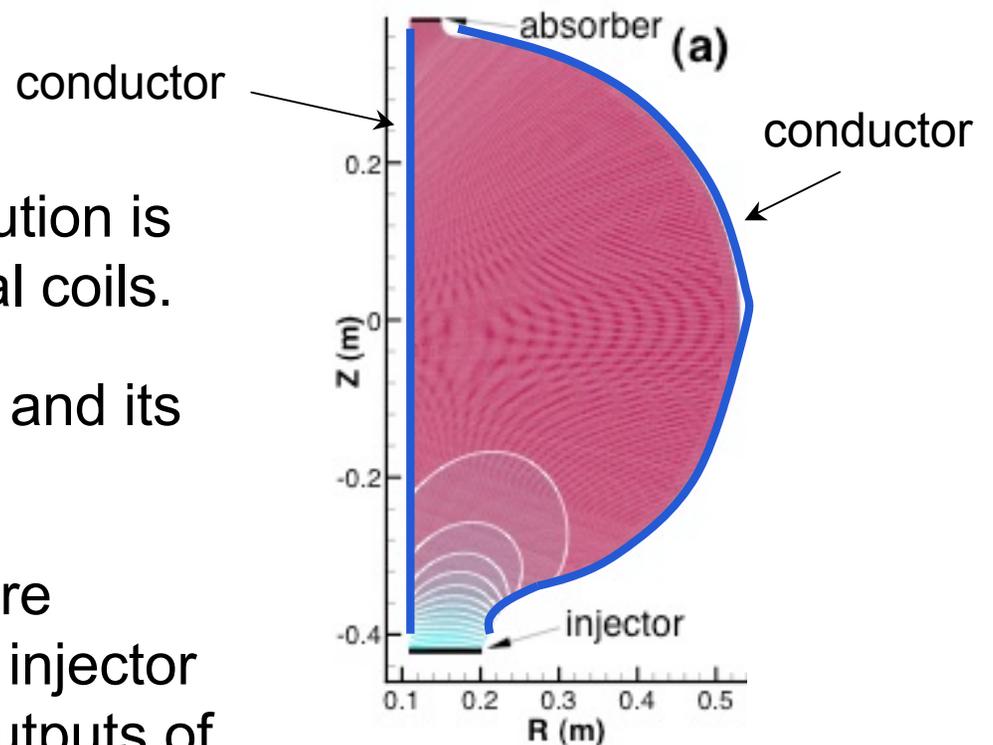
- Our present HIT-II modeling focuses on these weakly relaxing cases.



Schematic of HIT-II cross section shows flux conserver shape, injector (bottom), and absorber (top). 2

All computations start from vacuum magnetic field.

- The initial poloidal flux distribution is computed from a set of external coils.
- The initial $I = RB_\phi$ is uniform, and its value is the prescribed I_{TF} .
- All simulated CHI dynamics are controlled by the absorber and injector boundary conditions and are outputs of the computations.



This cross-section shows the initial poloidal flux distribution, and the geometry of the domain as represented by a 30×70 conforming mesh.

Basics: injecting current means that $I_{inj} \neq I_{abs}$.

- Conducting boundary conditions along the inboard and outboard surfaces do not admit or release toroidal flux.
- Boundary conditions along the injector and absorber allow local flux of B_ϕ .
- $\Delta I = I_{inj}$ is small relative to I_{TF} in tokamak cases.
- The objective of the HIT-II study was **steady-state** behavior at varied I_{TF} and ψ_{inj} .
 - In steady state, $V_{inj} = V_{abs}$.
 - Resistivity affects how much I_{inj} is produced at a given voltage.
 - Force-balance and ψ_{inj} determine the distribution of \mathbf{J} .
 - Raised I_{inj} vs. lowered I_{abs} (relative to prescribed I_{TF}) is inconsequential.

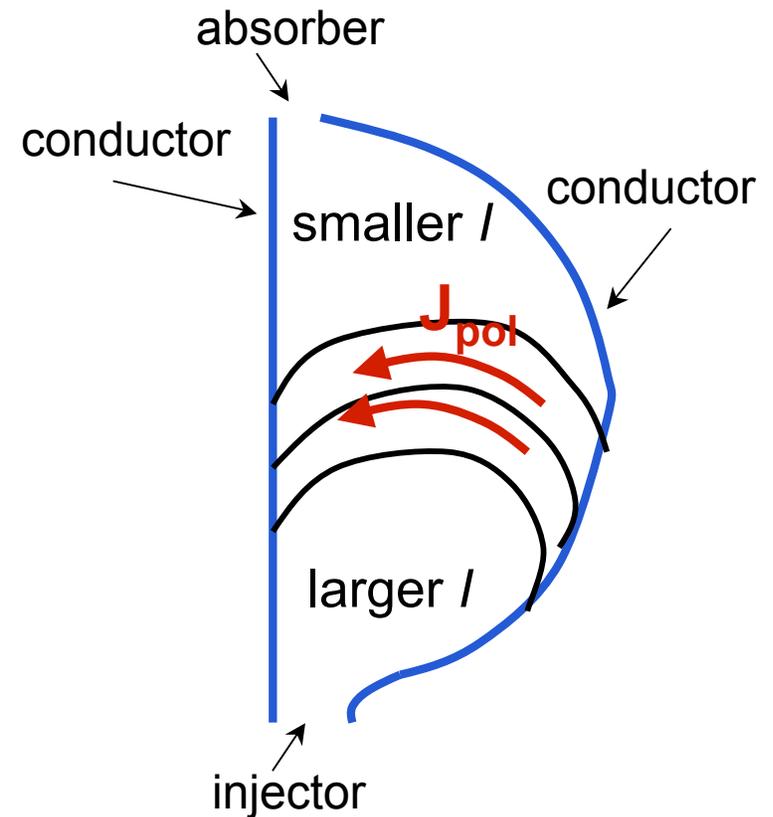


Illustration of contours of constant $I = RB_\phi$ during injection.

HIT-II Modeling & BCs: At low- β , pressure has little influence on the 2D profiles, allowing simplified modeling.

- We model these discharges with the zero- β limit of resistive MHD.

$$\rho \left(\frac{\partial}{\partial t} \mathbf{V} + \mathbf{V} \cdot \nabla \mathbf{V} \right) = \mathbf{J} \times \mathbf{B} + \nabla \cdot \left[\rho \nu \left(\nabla \mathbf{V} + \nabla \mathbf{V}^T - \frac{2}{3} \mathbf{I} \nabla \cdot \mathbf{V} \right) \right]$$

$$\frac{\partial}{\partial t} \mathbf{B} = \nabla \times (\mathbf{V} \times \mathbf{B} - \eta \mathbf{J})$$

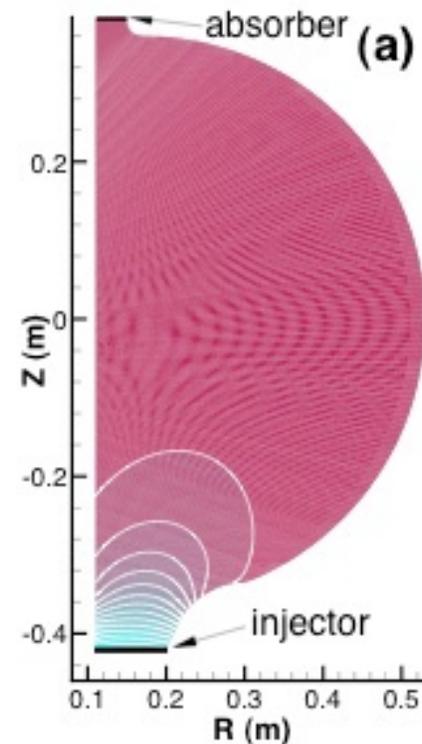
- Mass density ρ is considered a uniform constant.
- With viscosity, tangential- \mathbf{V} (flow) is set to 0 along all boundaries.
- The normal component of \mathbf{V} is zero along the conductors and nonzero along the injector and absorber.
- In NIMROD, equations are solved in weak form. For all test vectors \mathbf{A} , determine \mathbf{B} such that

$$\int \mathbf{A} \cdot \frac{\partial}{\partial t} \mathbf{B} dVol = \int (\mathbf{V} \times \mathbf{B} - \eta \mathbf{J}) \cdot \nabla \times \mathbf{A} dVol + \oint \mathbf{A} \cdot \mathbf{E} \times d\mathbf{S}$$

- The mathematics allows specification of either tangential- \mathbf{B} or $-\mathbf{E}$ along boundaries.

The NIMROD boundary conditions need to represent both the injector gap and the absorber gap.

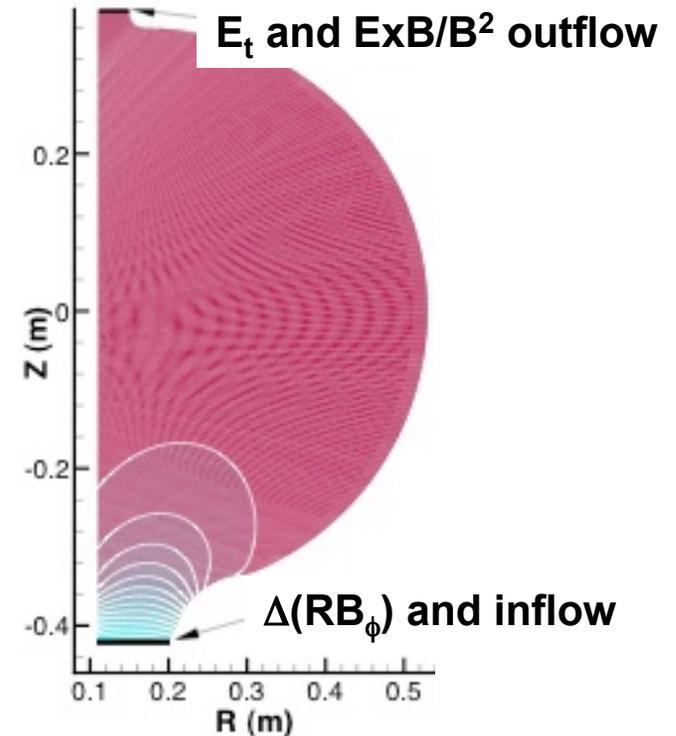
- Voltage in the HIT-II experiment is applied across the injector, and physics determines the voltage along other paths.
- With NIMROD, we may either specify a tangential electric field (Neumann condition) along a gap or B_ϕ (Dirichlet condition).
- $E_t = 0$ along the conductors.
- Applying $E_t \neq 0$ along both gaps presumes knowledge of the rate-of-change of flux as a function of time--not appropriate/practical.



This cross-section shows the initial poloidal flux distribution, and the geometry of the domain as represented by a 30×70 conforming mesh.

Applying a combination of the two possible magnetic-field boundary conditions is effective.

- For HIT-II modeling, we choose to apply E_t along the absorber and RB_ϕ , i.e. ΔI -value, along the injector.
 - **Resistive MHD determines \mathbf{E} everywhere below the absorber.**
 - Outflow at the absorber is set to the $\mathbf{n} \cdot \mathbf{E} \times \mathbf{B} / B^2$ drift speed to avoid a resistive boundary layer (\sim surface current).
 - Inflow at the injector is set to preserve plasma volume, i.e. avoid compression.
- If there is a mismatch in these specifications, B_ϕ along the absorber changes from its initial vacuum value. This represents current beyond the absorber gap, and we subtract this to obtain net injected current, I_{INJ} .
 - Experimental absorber arcs are analogous.



Boundary conditions specified at the two gaps are indicated.

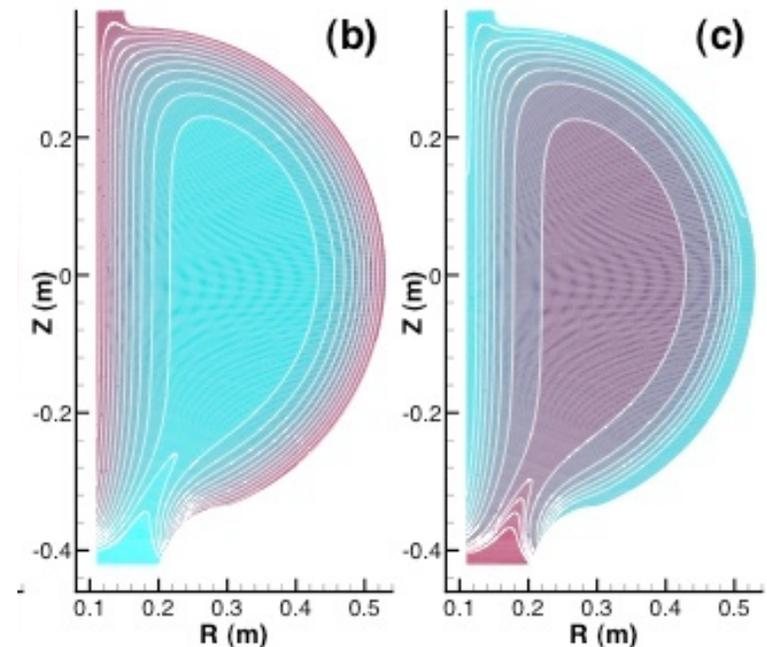
NIMROD results: An example result shows the expanded flux distribution after applying voltage at the absorber and current at the injector.

- In the case presented at right, we set $V=37$ V at the absorber, and ΔI at the injector for 30 kA.

- I_{TF} drifts from 495 kA to 516 kA.
- Net I_{INJ} is 8.8 kA.
- Final $I_p=91$ kA ($>10\times I_{INJ}$).

- The final current density profile is a hollow toroidal layer.

- The voltage is well below the experimental values of 600-700 V. Resistivity in the computations is based on the peak observed T_e , and there is no sheath.



The final distribution of the 6.5 mWb of poloidal flux is shown at left, and contours of RB_ϕ are shown at right.

More detailed modeling is applied to NSTX startup.

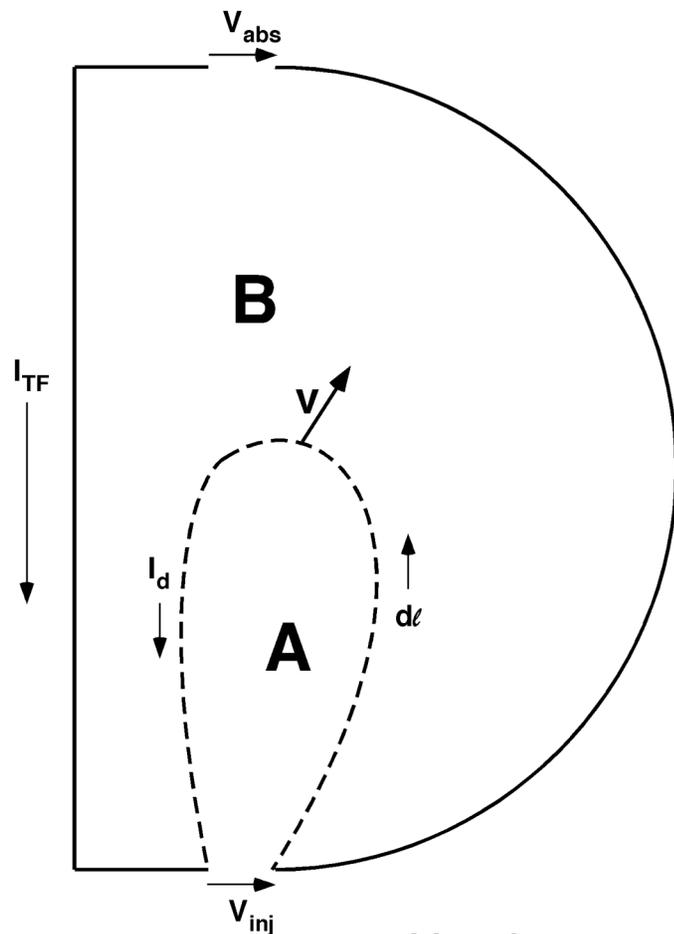
- The system of equations includes temperature and number-density evolution.

$$\frac{3}{2}n\left(\frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla\right)T = -nT \nabla \cdot \mathbf{V} + \nabla \cdot \left[(\kappa_{\parallel} - \kappa_{\perp}) \hat{\mathbf{b}}\hat{\mathbf{b}} + \kappa_{\perp} \mathbf{I} \right] \cdot \nabla T + \eta J^2$$

$$\frac{\partial n}{\partial t} + \nabla \cdot (n\mathbf{V}) = \nabla \cdot D\nabla n$$

- Transport coefficients are T -dependent: $\kappa_{\parallel} \sim T^{5/2}$; $\eta \sim T^{-3/2}$.
- Detailed modeling of the injector bank controls the injector voltage.
- The injector and absorber boundary conditions are swapped with respect to the HIT-II modeling.
 - Tangential- \mathbf{E} is applied at the injector.
 - Δl_{abs} is held at 0, presuming no absorber arc.
 - The resulting flux-change starts from the injector for more accurate transient evolution.

Boundary conditions for NSTX apply the circuit model and preclude drift of I_{TF} .



- Rate-of-change of toroidal flux — equals $V_{inj} - V_{abs}$
- Absorber- I — corresponds to a constant I_{TF}
- T near the absorber is kept low to maintain high resistivity in this region.
- Discharge (injector) current — measured by the change in RB_ϕ just above the injector slot
- Toroidal flux — carried in by ExB flow at the injector and out by ExB flow at the absorber
- Equating flows of *vacuum* toroidal flux yields

$$E_r^{abs} = E_r^{inj} \frac{r_{inj,min}}{r_{abs,min}} \frac{\int_{r_{inj,min}}^{r_{inj,max}} dr \frac{B_\phi}{r^2 B^2}}{\int_{r_{abs,min}}^{r_{abs,max}} dr \frac{B_\phi}{r^2 B^2}}$$

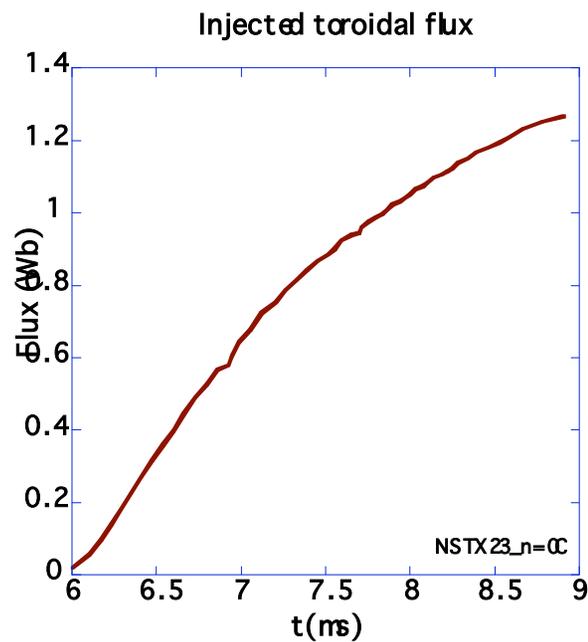
Used to compute outward flow at absorber--not for a BC on **B**.

The quantitative difference between the velocity boundary conditions used for HIT-II and NSTX is very small.

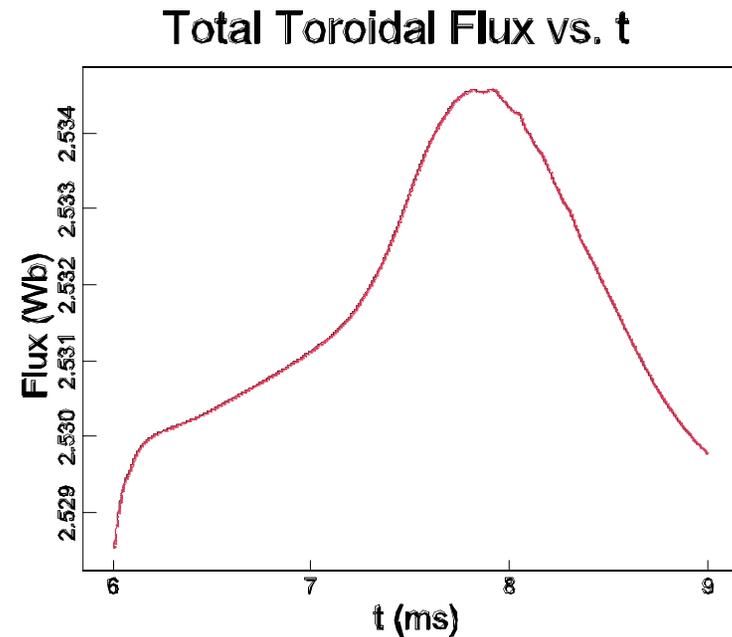
The HIT-II calculations equated plasma flow

- **The two conditions differ by a weighting factor $1/R$ in the integrals**
- **The resulting difference is $O(d_{\text{slot}}/R) \ll 1$**
- **Quantitative comparison of the plasma evolution found very small differences**

The net toroidal-flux change in NSTX is \ll the flux injected at the bottom



Total injected flux > 1 Wb



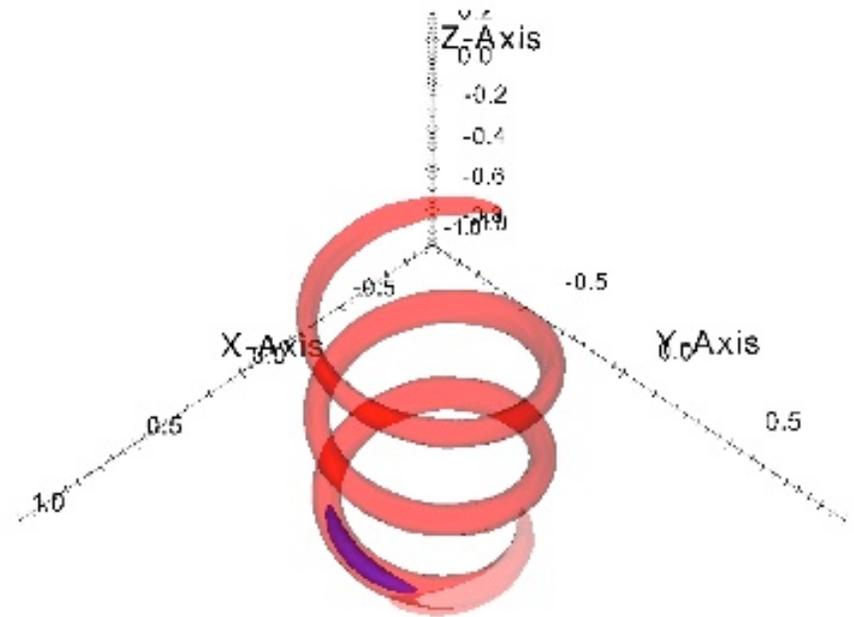
Net flux change $< 0.005/2.5 = 0.2\%$

Pegasus injector modeling: The small size and 3D geometry of the plasma guns requires a different approach.

- Current drive is modeled as a small source region within the domain and not through a boundary condition.
- Ohm's law accommodates the source, applied in the vicinity of the experiment's guns (first configuration in Pegasus):

$$\mathbf{E} + \mathbf{V} \times \mathbf{B} = \eta \mathbf{J} - \mathbf{E}_{inj}$$

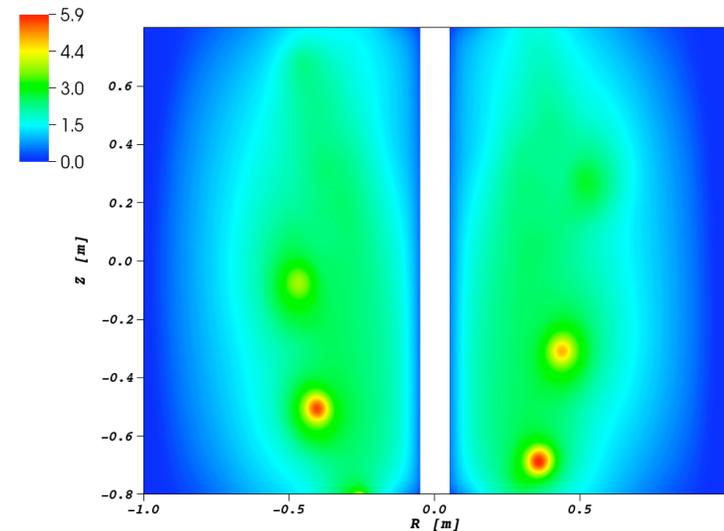
- The applied source is parallel to the local magnetic field and has a Gaussian distribution in poloidal coordinates and in toroidal angle.
- Induced- \mathbf{B} and \mathbf{J} propagate Alfvénically along background- \mathbf{B} (initially).



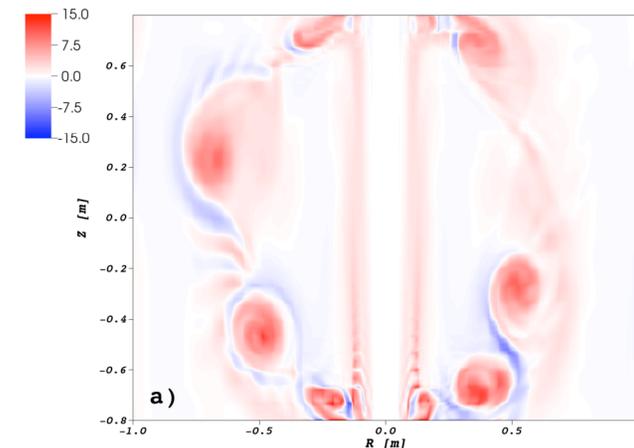
Effective applied \mathbf{E}_{\parallel} (half-max shown in blue) and the resulting current channel ($\lambda \simeq 1\text{m}^{-1}$ shown in red)

Two non-standard boundary conditions are also used in the Pegasus modeling.

- Conductivity of the gun-heated channel with respect to background is critical, so temperature evolution and temperature-dependent resistivity are used.
- With Spitzer- η , fixed low-temperature boundary conditions preclude a conducting path to the walls.
- Insulating conditions with an auxiliary decay term, $-\alpha(T-T_{wall})$, allows the current to heat a path to the walls.
- An effective electrical wall decay rate is also used when advancing B_ϕ so that the net axial current of the channel does not compress toroidal flux.



Cross-section view of temperature early in time.



Parallel current later when $I_p=26\text{kA}$.