

Table of contents : Chapter indexing and suggested authors

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1. Overview of the NSTX Upgrade Research Plan for 2014-2018
 - a. **Menard**, Kaye, Ono, TSG leaders
2. Research Goals and Plans for Transport and Turbulence
 - a. **Ren**, Guttenfelder, Hammett, Kaye, Yuh, Smith
3. Research Goals and Plans for Macroscopic Stability
 - a. **Park**, Berkery, Boozer, Sabbagh, Menard, Gerhardt
4. Research Goals and Plans for Boundary Physics
 - a. **Soukhanovskii**, Diallo, Stotler, Chang, Maingi, Skinner, Jaworski, Canik, Ono
5. Research Goals and Plans for Energetic Particles
 - a. **Podesta**, Fredrickson, Gorelenkov, Crocker, Heidbrink
6. Research Goals and Plans for Wave Heating and Current Drive
 - a. **Taylor**, Hosea, Perkins, Phillips, Bertelli
7. Research Goals and Plans for Plasma Formation and Current Ramp-up
 - a. **Raman**, Mueller, Jardin, Taylor, Gerhardt
8. Research Goals and Plans for Plasma Sustainment: Advanced Scenarios and Control
 - a. **Gerhardt**, Kolemen, Gates, Mueller, Erikson
9. NSTX-U Facility Status and Proposed Upgrades
 - a. **Ono**, Gerhardt, Kaita, Stratton, TSG leaders
10. NSTX-U Collaborator Research Plans by Institution
 - a. Existing and potential NSTX-U collaborators, edited by **Menard**

1. Research Goals and Plans for Plasma sustainment: Advanced Scenarios and Control

1.1. Overview of goals and plans (Gerhardt)

1.1.1. Develop the basis for steady state operations and axisymmetric plasma control for next-step STs while helping resolve key scenario and control issues for ITER

1.1.2. Thrusts and goals by topical area

- 1.1.2.1. Scenario development
- 1.1.2.2. Axisymmetric control development
- 1.1.2.3. Event handling
- 1.1.2.4. Scenario optimization for next step devices

1.2. Research Plans

1.2.1. Thrust 1 – Scenario Development (Gerhardt, Raman)

- 1.2.1.1. Pursue 100% Non-Inductive Current at Progressively Higher I_p and B_T
 - 1.2.1.1.1. Year 1: 0.75T, 600-800kA, few tau-E
 - 1.2.1.1.2. Year 2: 0.75-1T, 600-800kA, few tau-R
 - 1.2.1.1.3. Years 3-5: 1T, 800-1300kA, up to 4-5s
- 1.2.1.2. Develop Long-Pulse Partial Inductive Operation Up to 2 MA, High Power
 - 1.2.1.2.1. Two types of partial inductive operation:
 - 1.2.1.2.1.1. High-IP operation supports collisionality scaling and divertor heat flux studies
 - 1.2.1.2.1.2. Long pulse operation for particle retention and disruptivity reduction studies
 - 1.2.1.2.2. Years 1 & 2: Re-optimize startup for reduced fuelling at $I_p=1200-1500$ kA
 - 1.2.1.2.2.1. Goal: Enhance utility of Li pumping by reducing the early gas load
 - 1.2.1.2.3. Years 3-5: Performance Extension (Gerhardt)
 - 1.2.1.2.3.1. Discharges up to 2 MA for 5 seconds
 - 1.2.1.2.3.2. Long pulse at ~ 1 MA for up to 10 seconds
 - 1.2.1.2.3.3. Connection to heat flux mitigation
- 1.2.1.3. Use of RF heating for improved NSTX-U scenarios (Gerhardt, Taylor)
 - 1.2.1.3.1. Assess HHFW heating for improved non-inductive fraction in high performance plasmas
 - 1.2.1.3.2. Assess EBWCD heating and CD for optimization of the current and pressure profiles in steady state plasmas.
- 1.2.1.4. Couple to non-inductive ramp-up (w/ SFSU) (Gerhardt, Raman)

1.2.2. Thrust 2 – Axisymmetric Control Development

1.2.2.1 n=0 Boundary and VDE Control (Kolemen, Gerhardt)

1.2.2.1.1: Assess and improve n=0 vertical stability (observer, n=0 RWM)

1.2.2.1.2: Incorporate bipolar PF-2 coils into shape and n=0 control loop.

1.2.2.1.3: Develop MIMO shape control for improved inner and bottom gap regulation.

1.2.2.2 Axisymmetric Divertor Control

1.2.2.2.1 Years 1 & 2: (Kolemen, Soukanovskii, Gerhardt)

1.2.2.2.1.1 Develop upper/lower snowflake control at higher current

1.2.2.2.1.2 Assess schemes for dual X-point control w/ new divertor coils

1.2.2.2.1.3 Assess magnetic balance control in the presence of 4 X-points

1.2.2.2.1.4 Document heat flux reductions compared to standard DN

1.2.2.2.1.5 Assess impact of limited Mo coverage on scenarios

1.2.2.2.2 Years 3-5: (Gerhardt, Soukhanovskii)

1.2.2.2.2.1 Utilize cryopump and divertor upgrades to control density in long pulse scenarios

1.2.2.2.2.2 Years 3-5: Pending progress in BP TSG, begin implementation of closed loop radiative divertor control

1.2.2.2.2.3 Utilize PF-1B coil to improve control of the SFD through the full flux swing.

1.2.2.3 Current and Rotation Profile Control (Gerhardt, Kolemen, Yuh, Park, Sabbagh)

1.2.2.3.1 Years 1 & 2: realtime diagnostics and testing.

1.2.2.3.1.1 Feed forward test ability of different beam combinations to modify the q-profile. (Gerhardt)

1.2.2.3.1.2 Install and commission rtMSE and implement as constraint in rtEFIT (Kolemen, Yuh)

1.2.2.3.2 Years 2-4: Current and Rotation Profile Control Tests

1.2.2.3.2.1: Complete controllers for $\beta_N + q_{\min}$ and $\beta_N + F_{T,0}$ control (Kolemen)

1.2.2.3.2.2: Develop first $\beta_N + F_T$ profile control algorithm (Kolemen)

1.2.2.3.3 Years 4-5:

1.2.2.3.3.1 Utilize NCC coil for better NTV control (Kolemen, Park, Sabbagh)

1.2.2.3.3.2 Study feasibility of combined control (for instance, β_N , q_{\min} , F_T profile) (Kolemen, Gerhardt)

1.2.3 Thrust 3 - Disruption Avoidance and Off-Normal Event Handling

1.2.3.3 Years 1 & 2: (Gerhardt)

- 1.2.3.3.1 Implement basic detector in PCS, and design architecture of control response
- 1.2.3.3.2 Incorporate data from new “Digital Coil Protection System”
- 1.2.3.3.3 Assess accuracy of predictor for NSTX-U disruptions, and refine as necessary
- 1.2.3.3.4 Do initial tests of automated rampdowns

1.2.3.4 Years 3-5 (Gerhardt)

- 1.2.3.4.1 Add additional realtime diagnostics for improved detection fidelity
- 1.2.3.4.2 Optimize rampdowns for different types of alarms
- 1.2.3.4.3 Incorporate closed loop MGI if it appears promising

1.2.4 Thrust 4 - Explore Optimal Scenarios for Next Step STs

1.2.4.1 Study optimal profiles for high confinement and good stability (Gerhardt)

- 1.2.4.1.1 Years 3-4: Optimization of the current profile for best confinement and core n=1 stability
- 1.2.4.1.2 Years 3-5: Explore alternative optimal scenarios – EPH or w/ ITBs (Gerhardt, Canik, Yuh)

1.2.4.2 Study the conditions for classical beam current drive (Gerhardt)

- 1.2.4.2.1 Years 1-2: Study what parameters determine when *AE modes lead to anomalies in the fast ion diffusion and NBCD
- 1.2.4.2.2 Years 3-5: Determine if anomalous diffusion be used for scenario optimization

1.2.4.3 Integration of pedestal control tools (Gerhardt, Soukhanovskii, ...)

- 1.2.4.3.1 3D field integration

1.2.4.4 Explore & validate integrated models for projections to FNSF

- 1.2.4.4.1 Years 1-2: Compare NBCD & q-profile predictions from integrated codes to NSTX-U (Gerhardt)
- 1.2.4.4.2 Years 3-4: Test reduced transport models against profiles from most attractive scenario targets. (Gerhardt, Guttenfelder)
- 1.2.4.4.3 Years 4-5: Use knowledge to project scenarios to ST FNSF devices (Gerhardt)

- 1.3 Summary timeline for tool development to achieve research goals (Gerhardt)
 - 1.3.4 Theory and simulation capabilities (Gerhardt)
 - 1.3.2.1 TRANSP/pTRANSP/NCLASS w/ free boundary and passive conductors (Gerhardt)
 - 1.3.2.2 GTC-Neo (Gerhardt, Kaye)
 - 1.3.2.3 Reduced models for thermal and fast ion transport (Gerhardt, Guttenfelder)
 - 1.3.3 Diagnostics (Gerhardt)
 - 1.3.3.1 Real-time rotation
 - 1.3.3.2 Real-time MSE
 - 1.3.3.3 Real-time Thomson Scattering
 - 1.3.3.4 Real-time neutron rate
 - 1.3.3.5 Real-time divertor heat flux measurements
 - 1.3.4 Other facility capabilities including plasma control
 - 1.3.4.1 2nd NBI for current and rotation profile actuator (Gerhardt)
 - 1.3.4.2 2nd SPA for NTV rotation braking control (Gerhardt)
 - 1.3.4.3 Divertor cryopumps for density control (Gerhardt, Canik)
 - 1.3.4.4 NCC for NTV rotation braking control (Park, Sabbagh, Gerhardt)
 - 1.3.4.5 Coil and power supply upgrades (Gerhardt)
 - 1.3.4.6 EBW heating and current drive for J-profile control in advanced scenarios (Taylor, Gerhardt)