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Advances in Global MHD Mode Stabilization Research on NSTX

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22nd IAEA Fusion Energy Conference

October 13 - 18, 2008 Geneva, Switzerland

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<u>Abstract</u>

Stabilizing modes that limit plasma beta and reducing their deleterious effects on plasma rotation are key goals for efficient operation of a fusion reactor. Passive stabilization and active control of global kink/ballooning modes and resistive wall modes (RWM) have been demonstrated on NSTX and research now advances to understanding the stabilization physics and reliably maintaining the high beta plasma for confident extrapolation to ITER and CTF. Active n = 1 control experiments with an expanded sensor set, combined with low levels of n = 3 field phased to reduce error fields, reduced resonant field amplification and maintained plasma rotation, exceeded normalized beta = 6, and produced record discharge durations limited by magnet system constraints. Details of RWM active control show the mode being converted to a rotating kink that decays, or saturates leading to tearing modes. Discharges with rotation reduced by n = 3 magnetic braking suffer beta collapse at normalized beta = 4.2 approaching the no-wall limit, while normalized beta greater than 5.5 has been reached in these plasmas with n = 1 active control, in agreement with single-mode RWM theory. Advanced statespace control algorithms proposed for RWM control in ITER theoretically yield significant stabilization improvements. Values of relative phase between the measured n = 1 mode and the applied correction field that experimentally produce stability/instability agree with theory. Experimental mode destabilization occurs over a large range of plasma rotation, challenging the notion of a simple scalar critical rotation speed defining marginal stability. Stability calculations including kinetic modifications to ideal theory are applied to marginally stable experimental equilibria. Plasma rotation and collisionality variations are examined in the calculations. Intermediate rotation levels are less stable, consistent with experimental observations. Trapped ion resonances play a key role in this result. Recent experiments have demonstrated magnetic braking by non-resonant n = 2 fields. The observed rotation damping profile is broader than found for n = 3 fields. Increased ion temperature in the region of maximum braking torque increases the observed rate of rotation damping, consistent with theory.



Research advances to understanding mode stabilization physics and reliably maintaining the high beta plasmas

Motivation

 $\hfill \square$ Maintenance of high $\beta_{\it N}$ with sufficient physics understanding allows confident extrapolation to ITER and CTF

CTF:
$$\beta_N = 3.8 - 5.9 \ (W_L = 1-2 \ MW/m^2)$$
 ST-DEMO: $\beta_N \sim 7.5$

- Both at, or above ideal no-wall β -limit; deleterious effects at $\sim \frac{1}{2} \beta_N^{no-wall}$
- high β_N accelerates neutron fluence goal takes 20 years at $W_I = 1 \text{ MW/m}^2$)

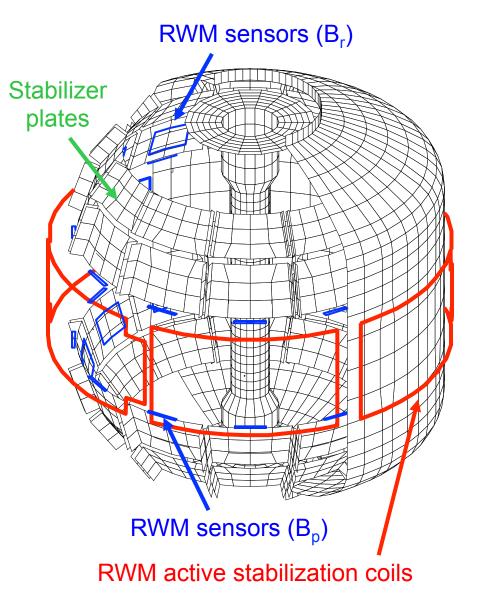
Outline

- Active control of beta amplified n = 1 fields / global instabilities
- Mode dynamics and evolution during active control
- Control performance compared to theory, connection to ITER
- Kinetic effects on resistive wall mode (RWM) stabilization
- Non-axisymmetric field influence on plasma rotation profile



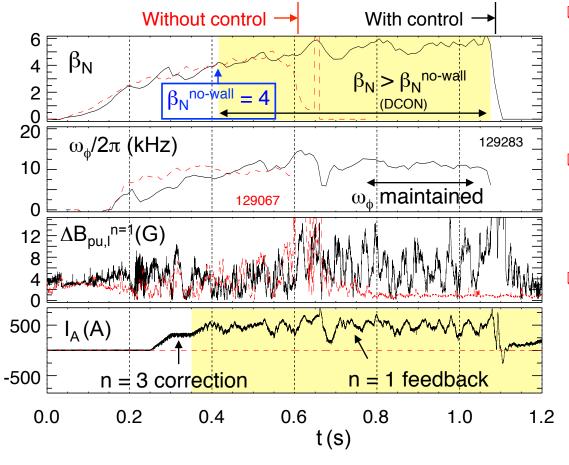
NSTX equipped for passive and active RWM control

- Stabilizer plates for kink mode stabilization
- External midplane control coils closely coupled to vacuum vessel
- Varied sensor combinations used for feedback
 - □ 24 upper/lower B_p: (B_{pu}, B_{pl})
 - □ 24 upper/lower B_r: (B_{ru}, B_{rl})





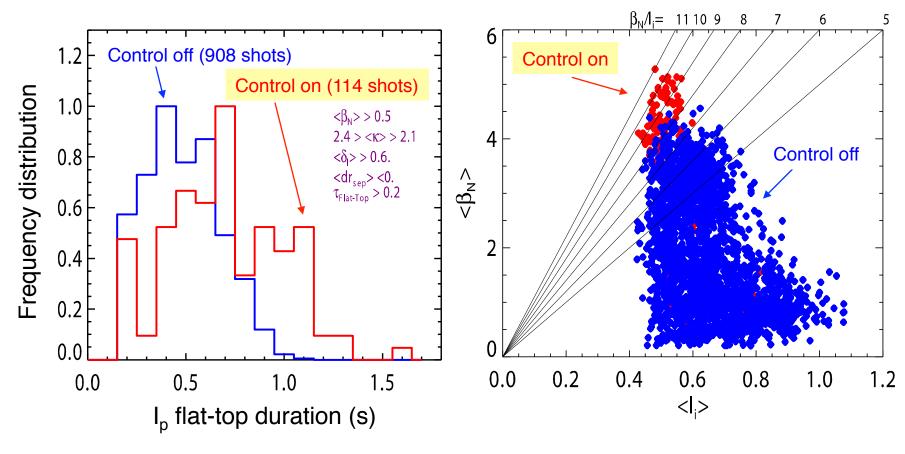
Active RWM control and error field correction maintain high β_N plasma



- n = 1 active, n = 3 DC control
 - □ n = 1 response \sim 1 ms < 1/ γ_{RWM}
 - $\beta_N/\beta_N^{\text{no-wall}} = 1.5 \text{ reached}$
 - lacktriangle best maintains ω_{ϕ}
- NSTX record pulse lengths
 - limited by magnet systems
 - n > 0 control first used as standard tool in 2008
- Without control, plasma more susceptible to RWM growth, even at high ω_{ϕ}
 - Disruption at $\omega_{\phi}/2\pi \sim 8 \text{kHz}$ near q = 2
 - More than a factor of 2 higher than marginal ω_{ϕ} with n = 3 magnetic braking



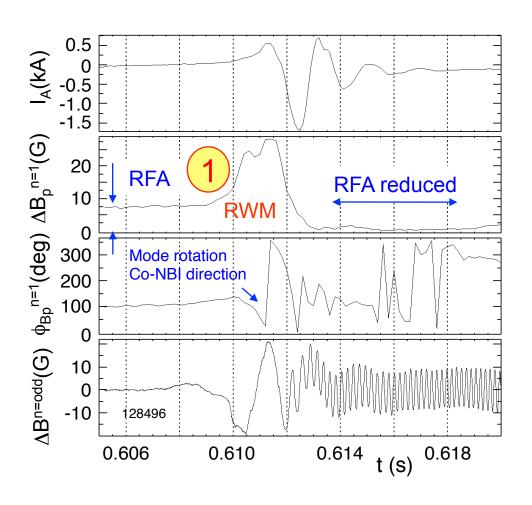
Probability of long pulse and $<\beta_N>_{pulse}$ increases significantly with active RWM control and error field correction



- Standard H-mode operation shown
 - I_p flat-top duration > 0.2s (> 60 RWM growth times)
- □ Control allows $<\beta_N>_{pulse}>4$



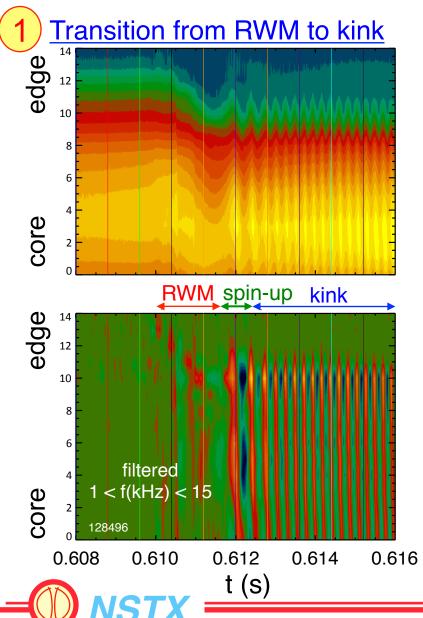
<u>During n=1 feedback control, unstable RWM evolves into</u> rotating global kink



- 1 RWM grows and begins to rotate
 - With control off, plasma disrupts at this point
 - With control on, mode converts to global kink, RWM amplitude dies away
 - Resonant field amplification (RFA) reduced
 - $\begin{tabular}{ll} \hline \square Conversion from RWM to rotating kink occurs on τ_w timescale \\ \end{tabular}$
 - Kink either damps away, or saturates
 - Tearing mode can appear during saturated kink

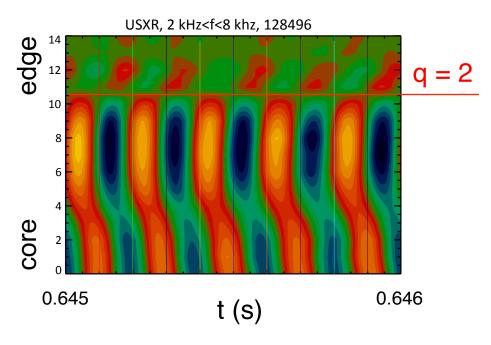


Soft X-ray emission shows transition from RWM to global kink



Tearing mode appears during kink

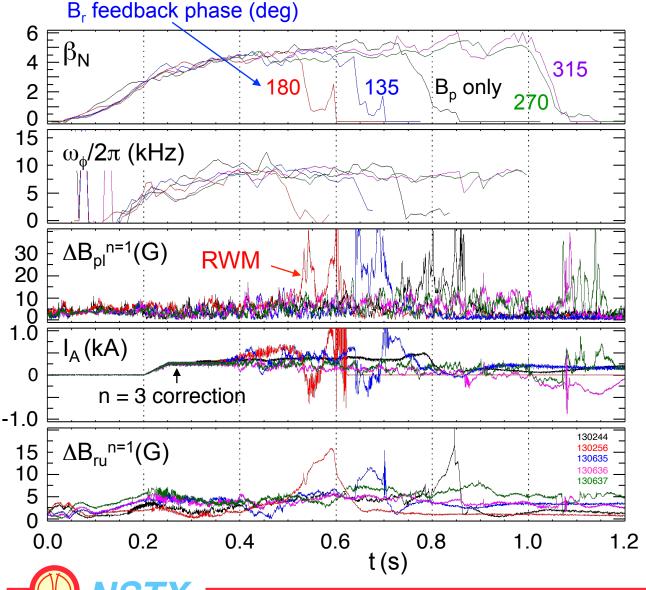
RWM onset time + 35 ms



- Initial transition from RWM to saturated kink
- Tearing mode appears after 10 RWM growth times and stabilizes



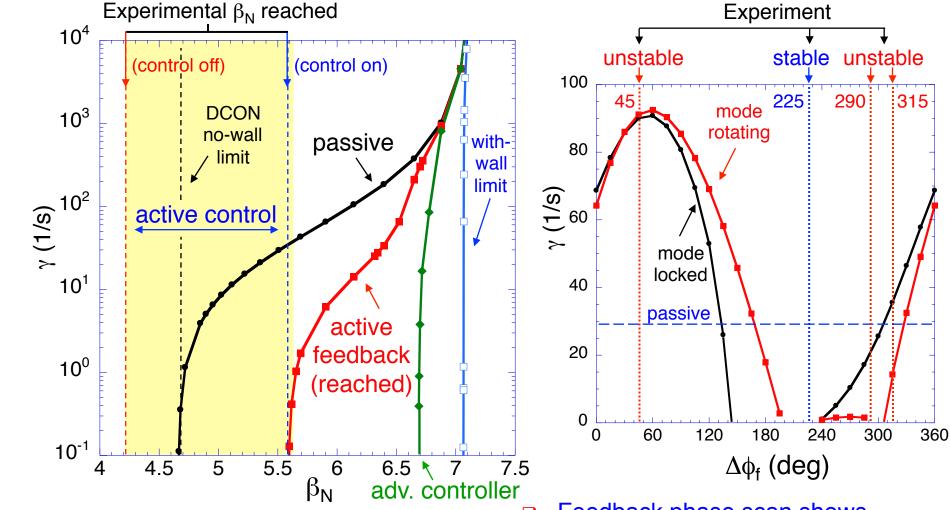
Favorable feedback settings found for B_p + B_r sensors



- lefta Steady $\omega_{_{lat}}$
 - □ n = 1 feedback + n = 3 EFC
- B_r feedback phase scan
 - All RWM sensors used
 - Favorable B_p feedback settings
 - B_r gain, phase varied to find best settings



Experimental RWM control performance consistent with theory



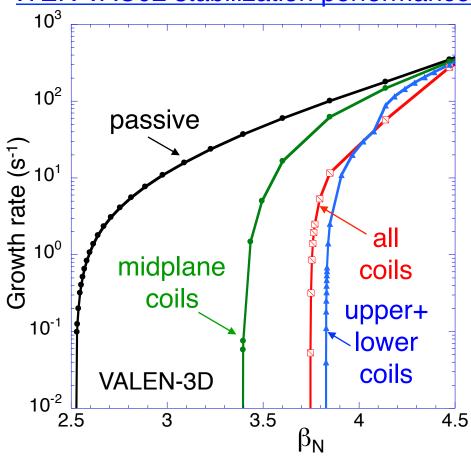
VALEN code with realistic sensor geometry, plasmas with reduced V_b Feedback phase scan shows superior settings

Agreement between theoretical and experimental feedback behavior



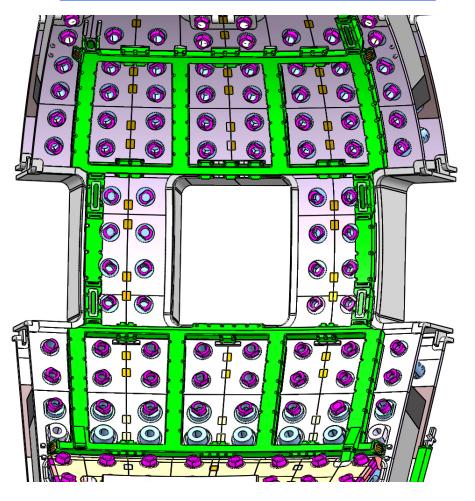
Significant β_N increase expected by internal coil proposed for ITER

ITER VAC02 stabilization performance



50% increase in β_N over RWM passive stability

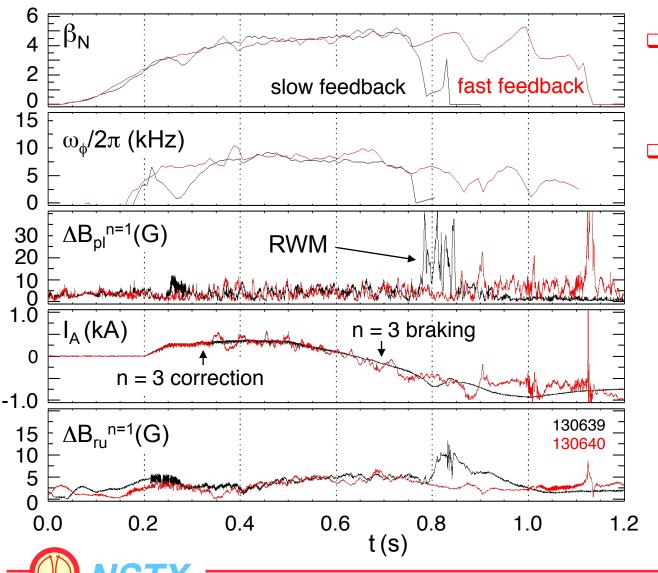
ITER VAC02 design (40° sector)



3 toroidal arrays, 9 coils each



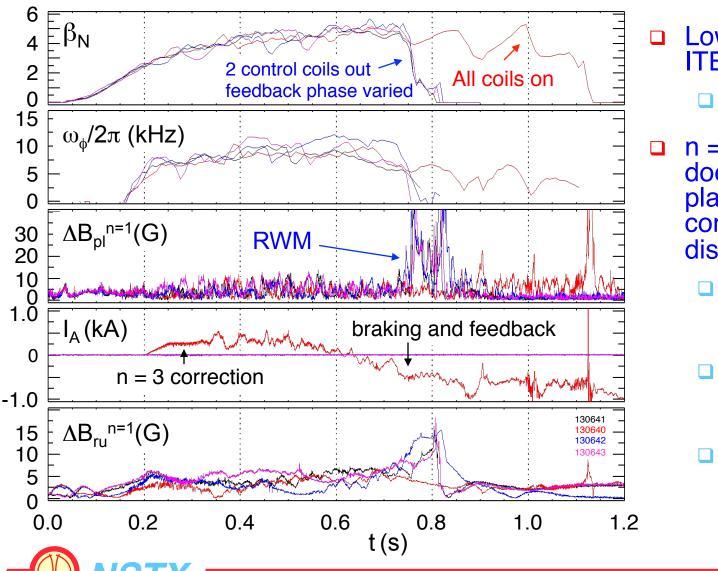
ITER support: Low ω_{ϕ} , high β_{N} plasma not accessed when feedback response sufficiently slowed



- Low ω_{ϕ} access for ITER study
 - \square use n = 3 braking
 - n = 1 feedback response speed significant
 - "fast" (unfiltered) n = 1 feedback allows access to low V_{ϕ} , high β_{N}
 - "slow" n = 1"error field correction" (75m s smoothing of control coil current) suffers RWM at $\omega_{\phi} \sim$ 5kHz near q = 2



ITER support: Low ω_{ϕ} , high β_{N} plasma not accessed when two feedback control coils are disabled



- Low ω_{ϕ} access for ITER study
 - use braking
- n = 1 feedback doesn't stabilize plasma with 2 of 6 control coils disabled
 - scenario to simulate failed coil set in ITER
 - Feedback phase varied, but no settings worked
 - RWM onset at identical time, plasma rotation

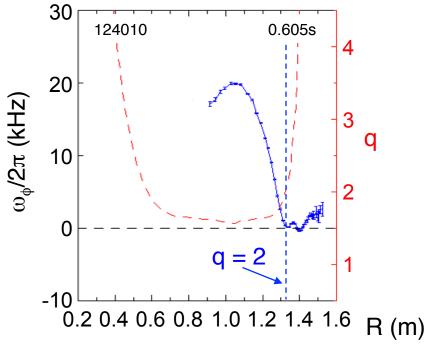


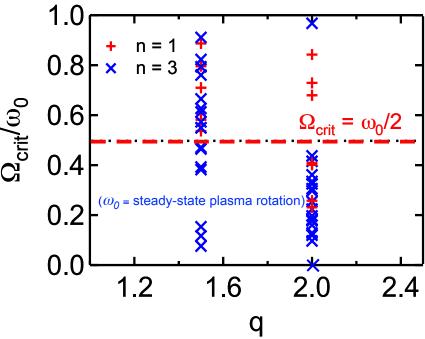
Non-resonant magnetic braking allows V_b modification to probe RWM critical rotation and stabilization physics

- Scalar plasma rotation at q = 2 inadequate to describe stability
 - Marginal stability $\beta_N > \beta_N^{\text{no-wall}}, \omega_{\phi}^{\text{q=2}} = 0$



A.C. Sontag, et al., NF 47 (2007) 1005.





- Slowest rotation profiles produced in NSTX are at DIII-D balanced-NBI levels
- Ion collisionality profile variation appears to alter experimental Ω_{crit} profile



Modification of Ideal Stability by Kinetic theory (MISK code) investigated to explain experimental stability

- Simple critical ω_{ϕ} threshold stability models or loss of torque balance do not describe experimental marginal stability Sontag, et al., Nucl. Fusion 47 (2007) 10 Sontag, et al., Nucl. Fusion 47 (2007) 1005.
- Kinetic modification to ideal MHD growth rate
 - Trapped and circulating ions, trapped electrons
 - Alfven dissipation at rational surfaces

$$\gamma \tau_{w} = -\frac{\delta W_{\infty} + \delta W_{K}}{\delta W_{b} + \delta W_{K}}$$

Hu and Betti, Phys. Rev. Lett 93 (2004) 105002.

- Stability depends on
 - □ Integrated ω_{δ} profile: resonances in δW_{κ} (e.g. ion precession drift)
 - Particle collisionality

 ω_{ϕ} profile (enters through ExB frequency)

<u>Trapped ion component of δW_{κ} (plasma integral)</u>

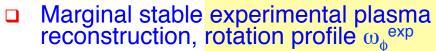
$$\omega_E = \omega_{\phi}^D - \omega_{*i}^D - \frac{v_{\theta}^D}{2\pi R} \frac{B_{\phi}}{R}$$

$$\delta W_K \propto \int \left[\frac{\omega_{*N} + (\hat{\varepsilon} - \frac{3}{2})\omega_{*T} + \omega_E - \omega - i\gamma}{\langle \omega_D \rangle + l\omega_b - i\nu_{eff} + \omega_E - \omega - i\gamma} \right] \hat{\varepsilon}^{\frac{5}{2}} e^{-\hat{\varepsilon}} d\hat{\varepsilon} \qquad \leftarrow \text{Energy integral}$$
precession drift bounce collisionality

Kinetic modifications show decrease in RWM stability at relatively high V_b – consistent with experiment

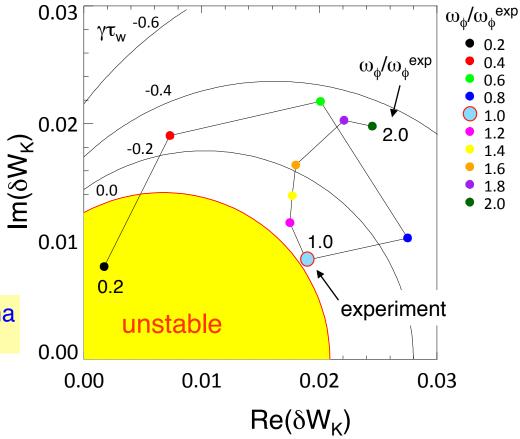
Theoretical variation of ω_φ

80 $\omega_{\phi}\!/\!\omega_{\phi}^{}\text{exp}$ Marginally stable 60 $ω_{\phi}/2π$ (kHz) 2.0 experimental profile 1.0 121083 0.2 0 0.2 0.4 0.6 8.0 1.0 0.0 ψ/ψ_a



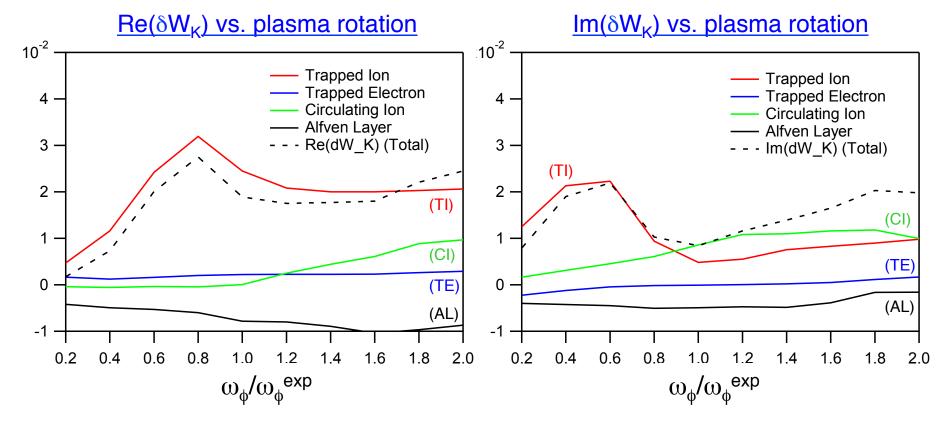
- Variation of ω_{ϕ} away from marginal profile increases stability
- Unstable region at low ω_{ϕ}

RWM stability vs. V_{ϕ} (contours of $\gamma \tau_{w}$)





Stabilizing influence of kinetic effects changes as plasma rotation varies

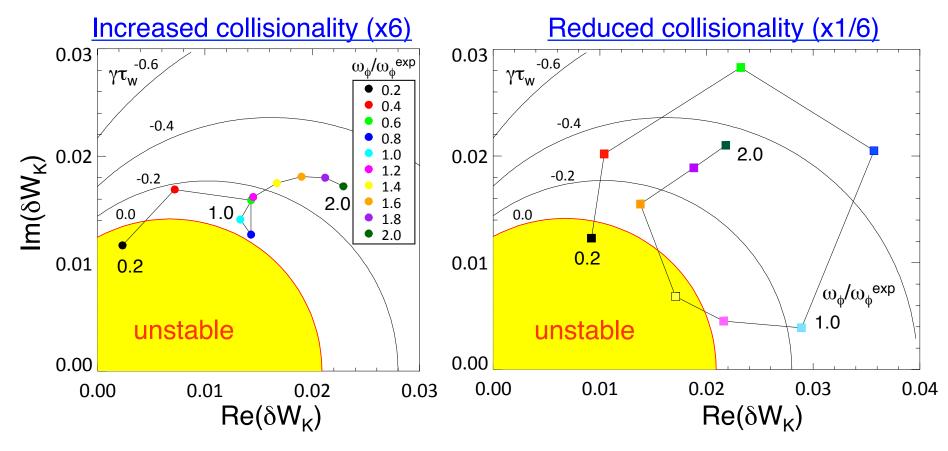


- **Low** ω_{ϕ} : kinetic effects relatively small
- □ Intermediate ω_{ϕ} : trapped ion strengthens/weakens
- lacktriangle High ω_{ϕ} : circulating ion stabilization increases

- => plasma unstable
- => stable/marginal
- => plasma stable



Kinetic model shows overall increase in stability as collisionality decreases



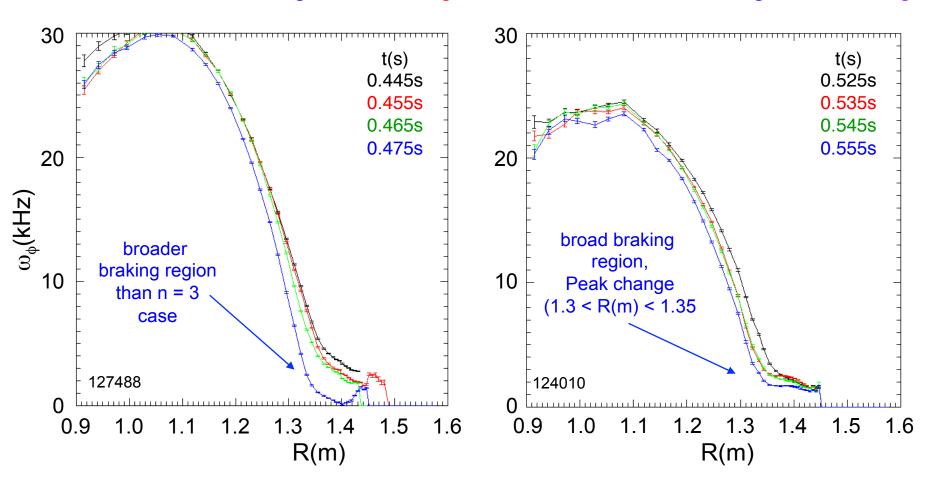
- □ Vary v by varying T, n at constant β
- $\hfill\Box$ Simpler stability dependence on ω_ϕ at increased ν
- □ Increased stability at $\omega_{\phi}/\omega_{\phi}^{\text{exp}} \sim 1$



Non-resonant rotation braking produced using n = 2 field

Rotation evolution during n = 2 braking

Rotation evolution during n = 3 braking



 \square n = 2 has broader braking profile than n = 3 field (from field spectrum)



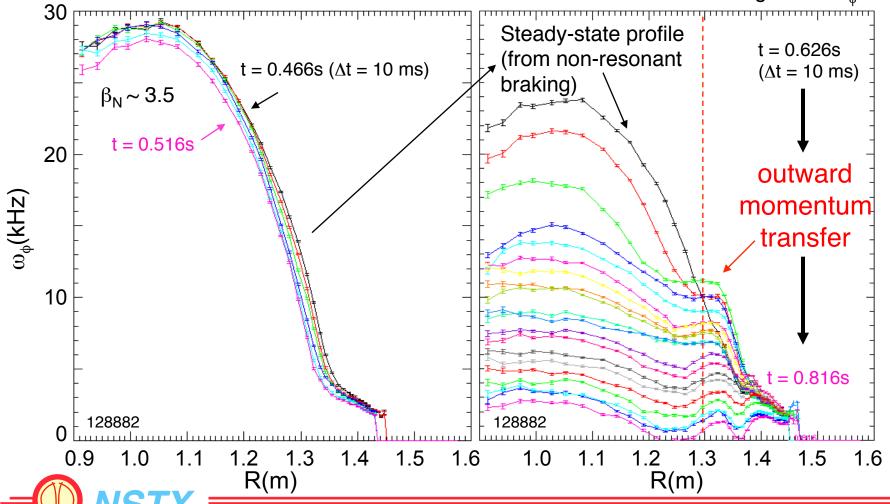
n = 2 non-resonant braking evolution distinct from resonant

Non-resonant:

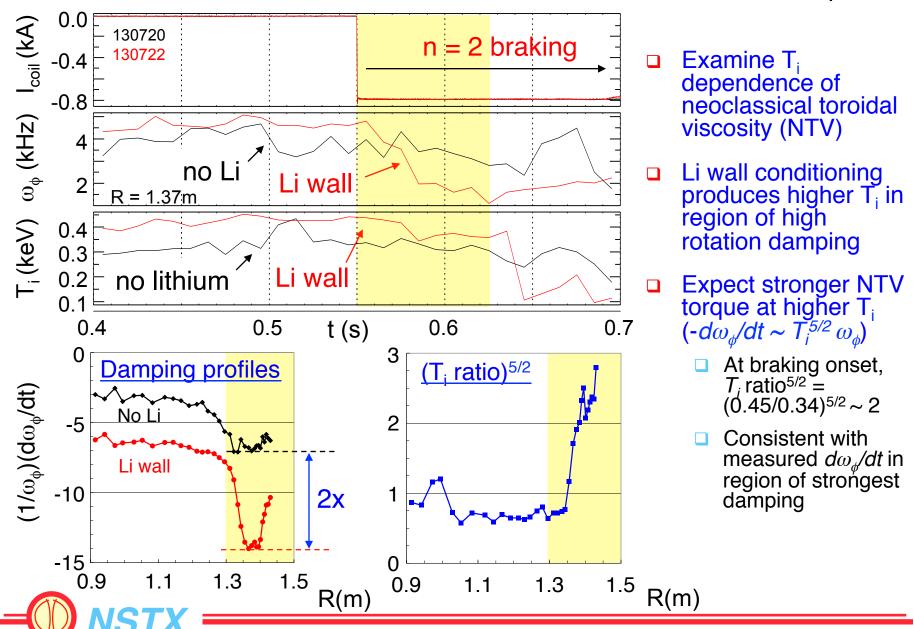
- broad, self-similar reduction of profile
- \blacksquare Reaches steady-state (t = 0.626s)

Resonant:

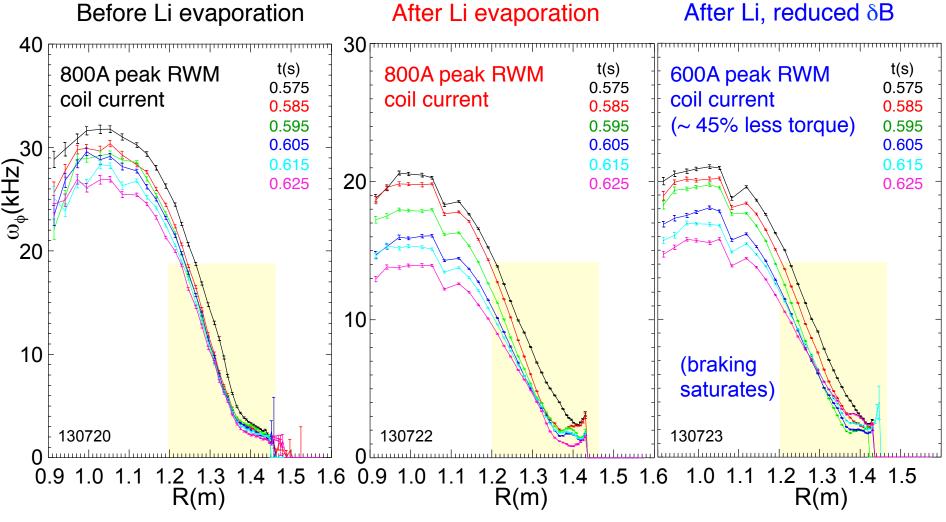
- Clear momentum transfer across rational surface
- evolution toward rigid rotor core
- □ Local surface locking at low ω_{ϕ}



Stronger non-resonant braking at increased T_i



Non-resonant n = 2 braking evolution altered by Li evaporation



- Stronger ω_{ϕ} damping by NTV at higher T_i $(\tau_{NTV} \sim T_i^{5/2})$
- **The** $ω_{\phi}$ saturates in case with lithium at reduced applied δB



Advances in global mode feedback control, kinetic stabilization physics and magnetic braking research

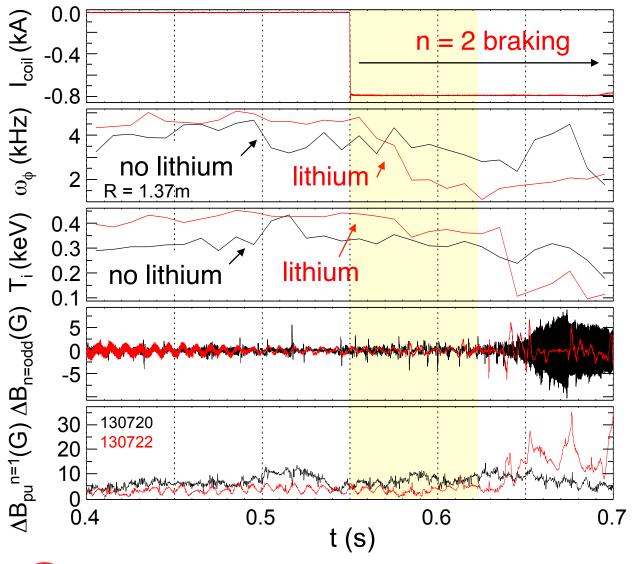
- □ Active n = 1 control, DC n = 3 error field correction maintain high β_N plasma over ideal $\beta_N^{\text{no-wall}}$ limit for long pulse
 - Growing RWM converts to kink that stabilizes; can yield tearing mode
- Control performance compares well to theory
 - $lue{}$ Significant eta_N increase expected for ITER with proposed internal coil
- Kinetic modifications to ideal stability can reproduce behavior of observed RWM marginal stability vs. V_b
 - Simple critical rotation threshold models for RWM stability inadequate
- Non-resonant V_b braking observed due to n = 2 applied field
 - Braking magnitude increases with increased T_i



Reprints



Stronger non-resonant braking at increased Ti



- Examine T_i
 dependence of
 neoclassical toroidal
 viscosity (NTV)
- Li wall conditioning produces higher T_i in region of high rotation damping
- Expect stronger NTV torque at higher T_i (~T_i^{5/2})
 - At braking onset, Ti ratio^{2.5} = $(0.45/0.34)^{2.5} \sim 2$
 - Consistent with measured dω_φ/dt in region of strongest damping

