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# Physics and Engineering Design Considerations for **NHTX**

**N**ational **H**igh-power advanced **T**orus **eX**periment

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With contributions from:

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R. Woolley, and the NSTX Research Team

# The development of advanced fusion reactors will require the integration of key areas of fusion science

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- **NHTX mission:**

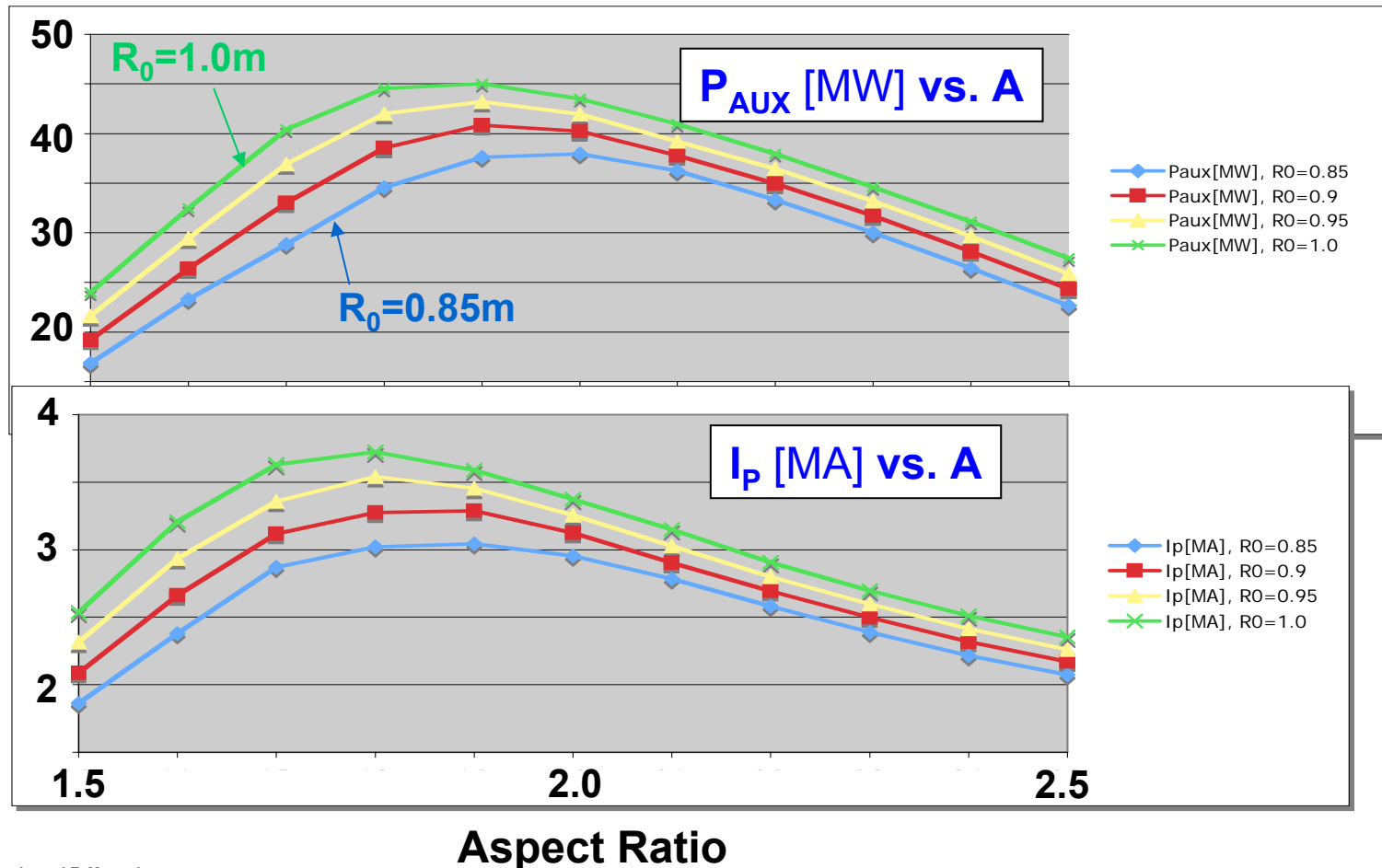
“To study the integration of high-confinement, high-beta, long-pulse non-inductive plasma operation with a fusion-relevant high-power plasma-boundary interface.”

- Metrics for the four key fusion areas:

1. High thermal confinement → H-mode with  $HH > 1$
2. High plasma beta → at or above no-wall limit
3. Steady state operation →  $f_{BS} \geq 0.7 + \text{NBI}$ , RF CD →  $n_e$  control
4. Reactor-level heat-flux-handling compatible w/ above → need innovation

# Systems code identifies optimal aspect ratio A=1.8-2 based on NHTX mission and design

- A=1.8-2 maximizes P/R and  $I_p$  (or  $I_p \times A$ ) at fixed magnet power
  - Fixed  $HH_{98y2}=1.3$ , use  $\kappa(A)$  and **n=1 no-wall limit**  $\beta_N(A)$  scalings
  - $I_p$  from BS and NBI – additional LHCD, ECCD/EBW to be assessed



# NHTX Heating and Current Drive

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- Total auxiliary heating and current drive power = 50MW
  - Neutral beams: 32 MW, 110 kV  $D_0$  NBI, steerable off axis
  - 18 MW RF – type to be determined
- Results from NSTX, C-MOD, DIII-D will be critical to selection of RF system(s)
  - EBWCD: High efficiency, remote coupling.
  - LHCD: High efficiency, intimate coupling.
  - ECCD: Inside-launch 120 GHz 2nd harmonic: lower efficiency, more complex access.
  - ICRF: Cost-effective electron or ion heating, intimate coupling
- 2MA bootstrap current at operating point
- For confidence in 3.5 MA steady-state operation, desirable to be able to drive  $\sim 1.5$  MA with beams + RF ( $R_0 = 1\text{m}$ )

# Overview of NHTX design progress

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- Systems code has identified favorable design point:
  - $A=1.8-2$ ,  $R_0=1\text{m}$ ,  $I_p=3-4\text{MA}$ ,  $B_T=2\text{T}$ ,  $\kappa=2.7-3$ , fully non-inductive
  - Maximizes  $I_p$ ,  $I_p \times A$ , and  $P/R$  for given magnet power
  - $HH_{98Y} = 1.3$ ,  $\beta_N=4.5$ ,  $\beta_T=15\%$ ,  $f_{BS} = 65\%$ ,  $f_{GW}=0.4-0.5$
  - High  $\beta$  possible with  $\Omega_\phi$  & feedback stabilization of RWM
- Favorable PF coil configuration identified
  - Divertor flexibility without PF coil modification
  - Strong shaping flexibility ( $\kappa$ ,  $\delta$ , squareness, flux expansion)
  - Large midplane vertical gap for beam steering ( $\Delta Z$ ), diagnostics, access
- NBI current drive efficiency & profiles studied with TRANSP
  - $R_{TAN}$  and  $Z_{TAN}$  variations allow for  $J_{NBI}$  profile control
  - NBICD scalings used in systems code are reasonable

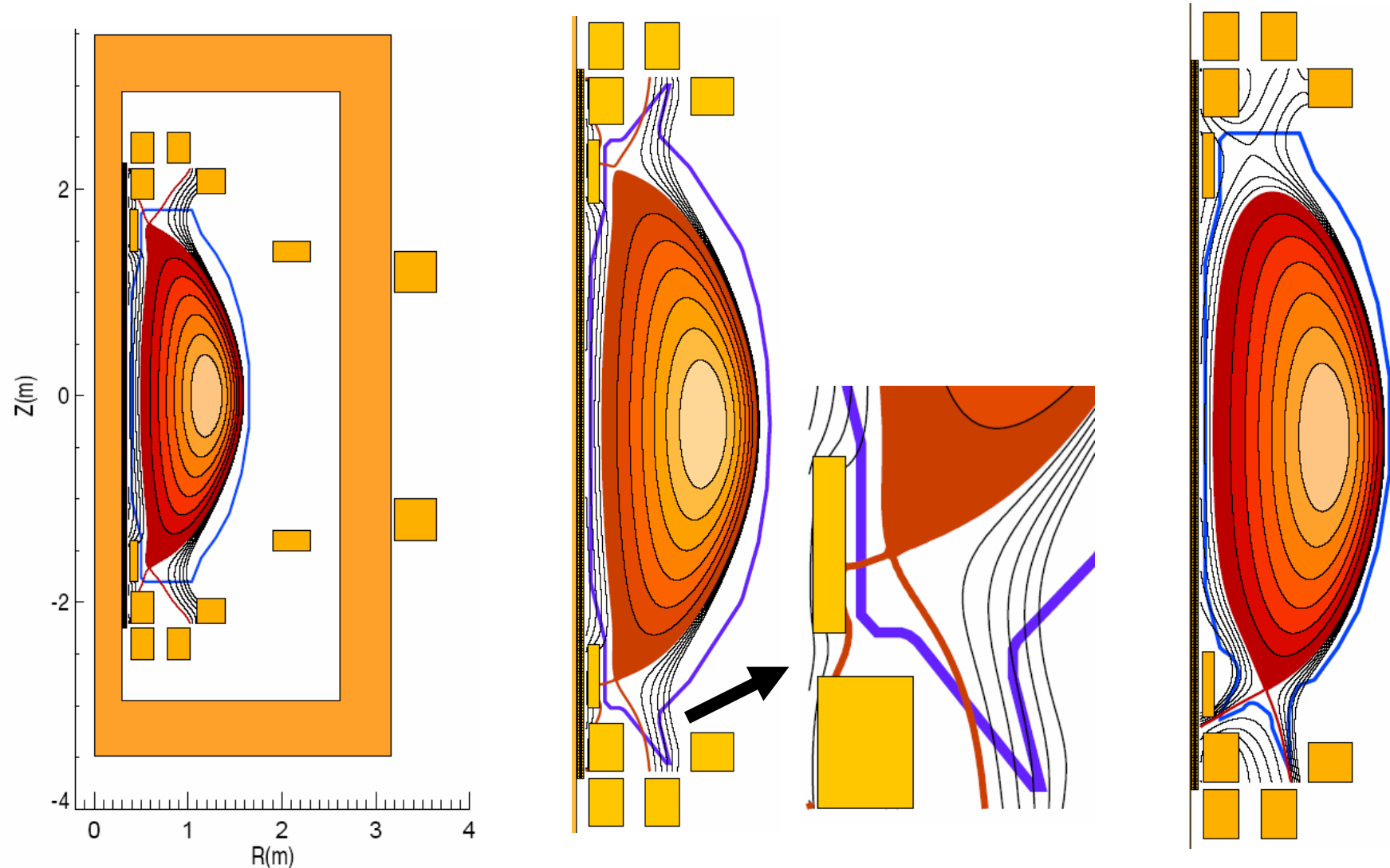
# Single coil set supports range of divertor configurations

## *Example configurations:*

Open DN divertor

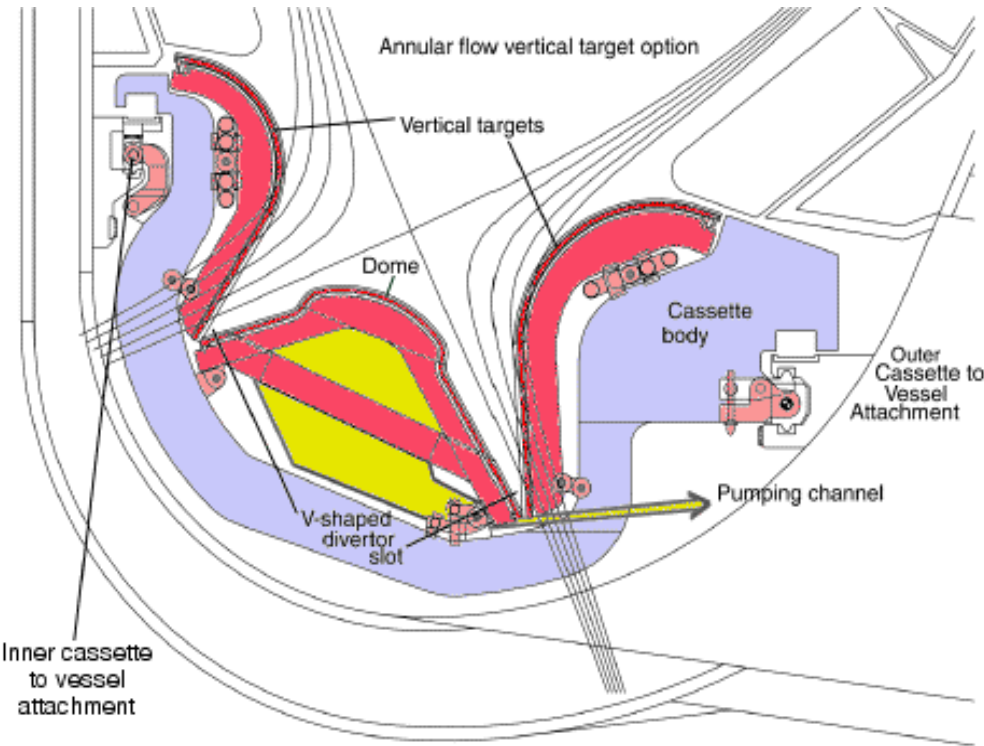
Pumped DND, JET-like

ITER-like LSN divertor

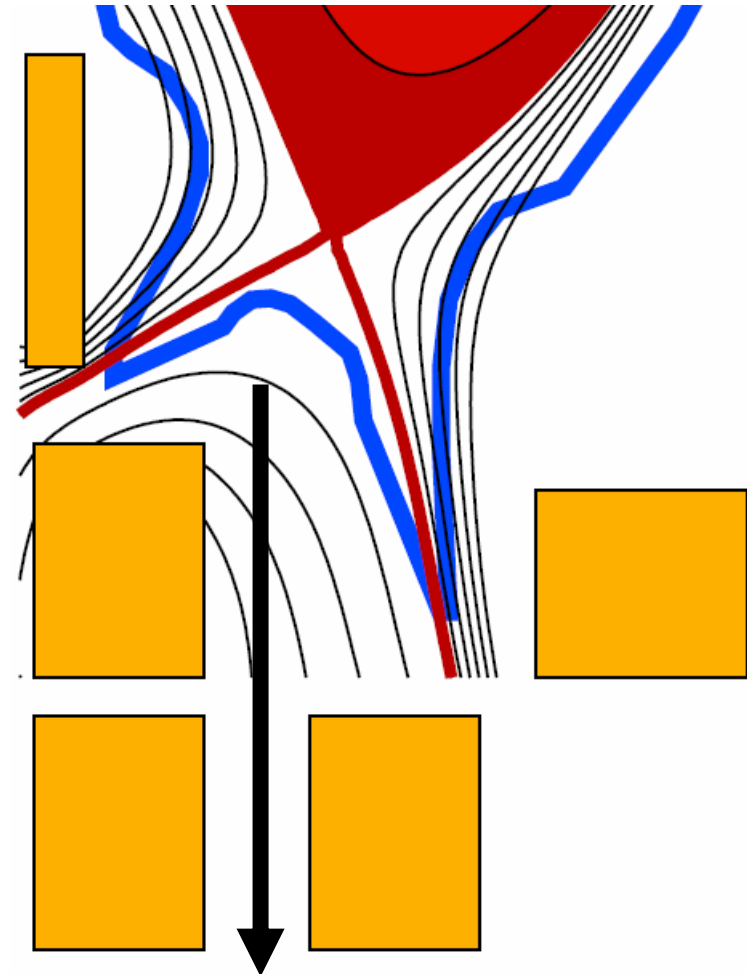


# NHTX coil set supports ITER-like LSN divertor

## ITER



## NHTX

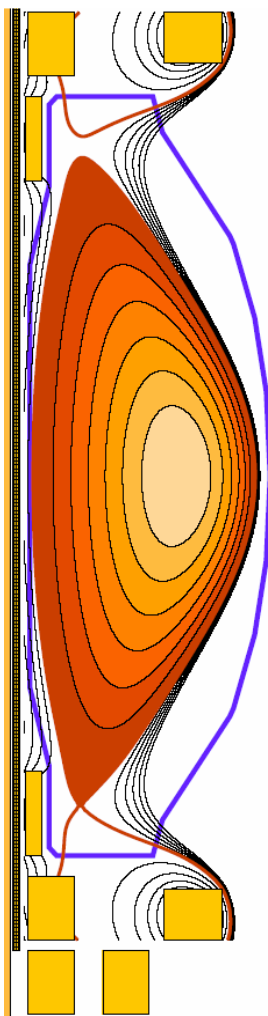


Pumping channel from dome

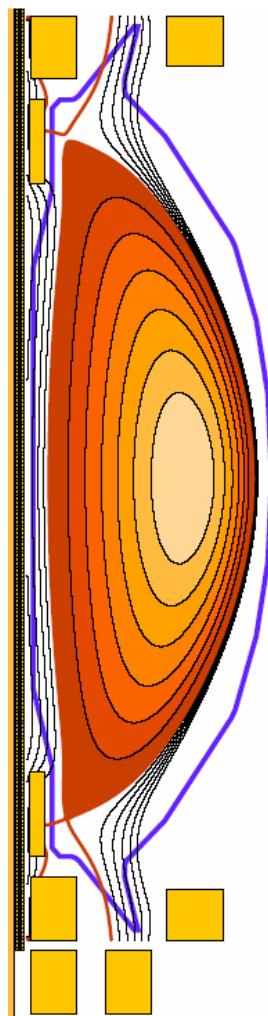
# Coil set supports wide range of boundary shapes

- Shaping plays important role in determining global and ELM stability

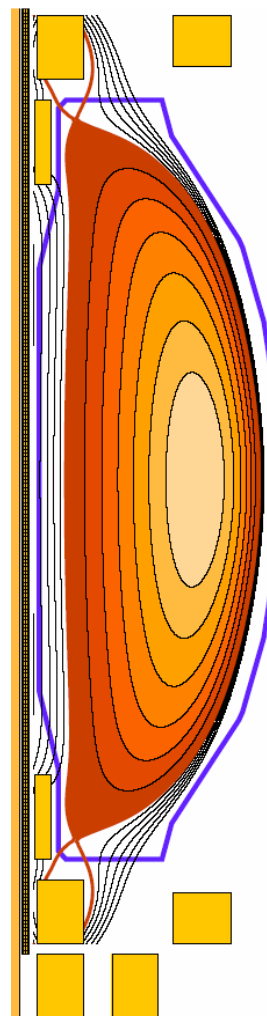
DND w/ negative  
squareness  $\zeta \approx -0.15$



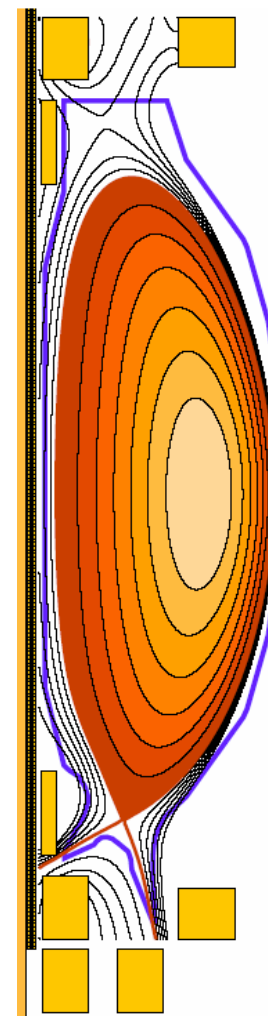
DND w/ near zero  
squareness



DND w/ positive  
squareness  $\zeta \approx 0.25$



Example  
LSN shape



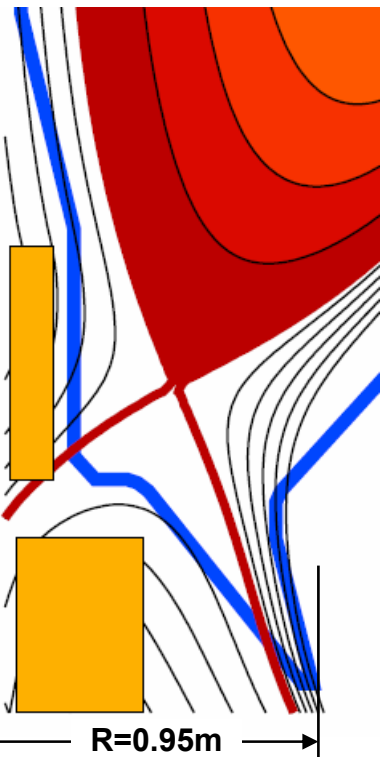


# Divertor coil set supports wide range of flux expansion

Poloidal flux expansion factor  $f_{exp} \equiv |\nabla\psi|_{\text{mid-plane}} / |\nabla\psi|_{\text{strike-point}}$   
Poloidal B-field angle of incidence into target plate  $\equiv \alpha_p$   
Total B-field angle of incidence into target plate  $\equiv \alpha_t$

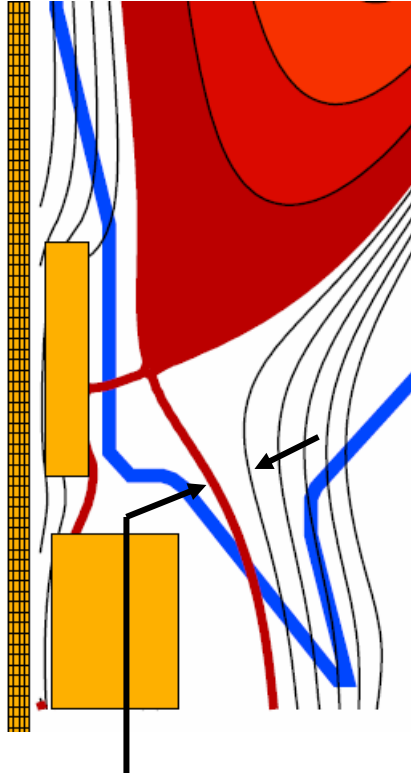
$$f_{exp} = 2.8$$

$$\alpha_p = 22^\circ \quad \alpha_t = 5.1^\circ$$



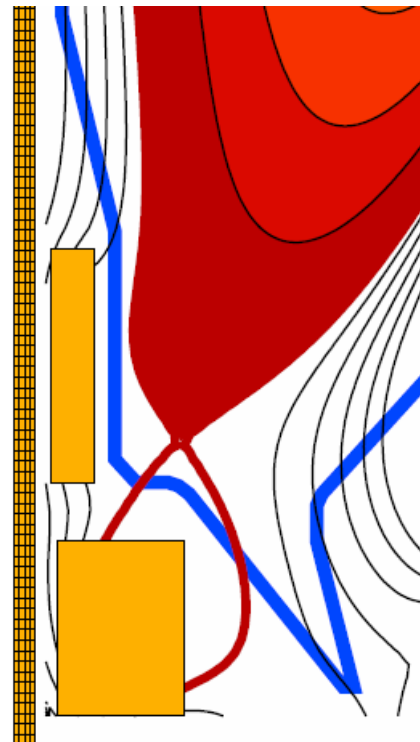
$$f_{exp} = 9$$

$$\alpha_p = 23^\circ \quad \alpha_t = 1.8^\circ$$



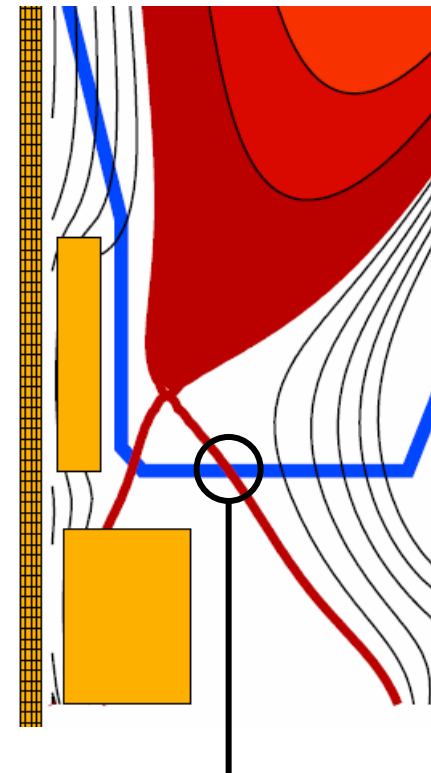
$$f_{exp} = 17$$

$$\alpha_p = 25^\circ \quad \alpha_t = 1.0^\circ$$



$$f_{exp} = 35$$

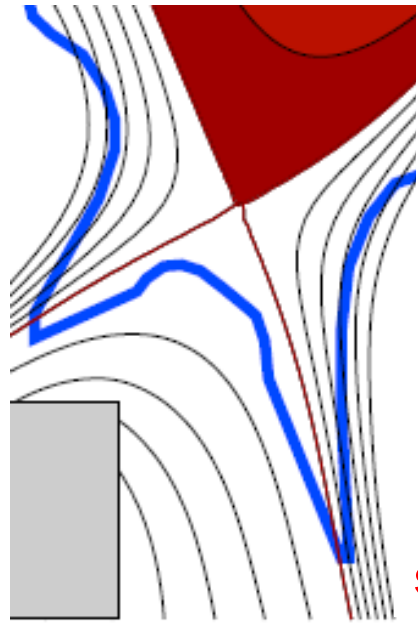
$$\alpha_p = 64^\circ \quad \alpha_t = 1.1^\circ$$



Flux contours have 5mm separation at midplane

$f_{exp}$ ,  $\alpha$  values computed at strike-point

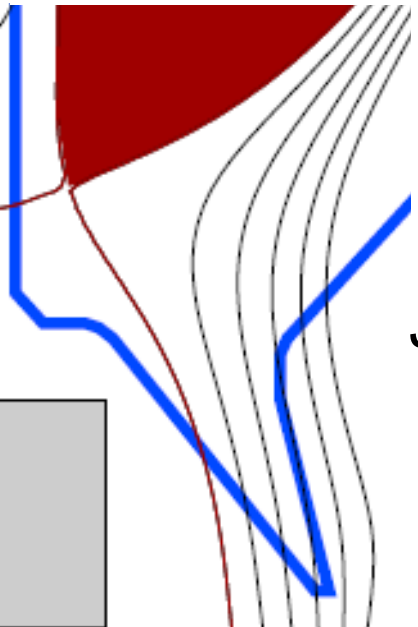
# Operation w/ LSN and low flux expansion challenging



Note: ITER designed for  $q_{\text{div}} \leq 10 \text{ MW/m}^2$

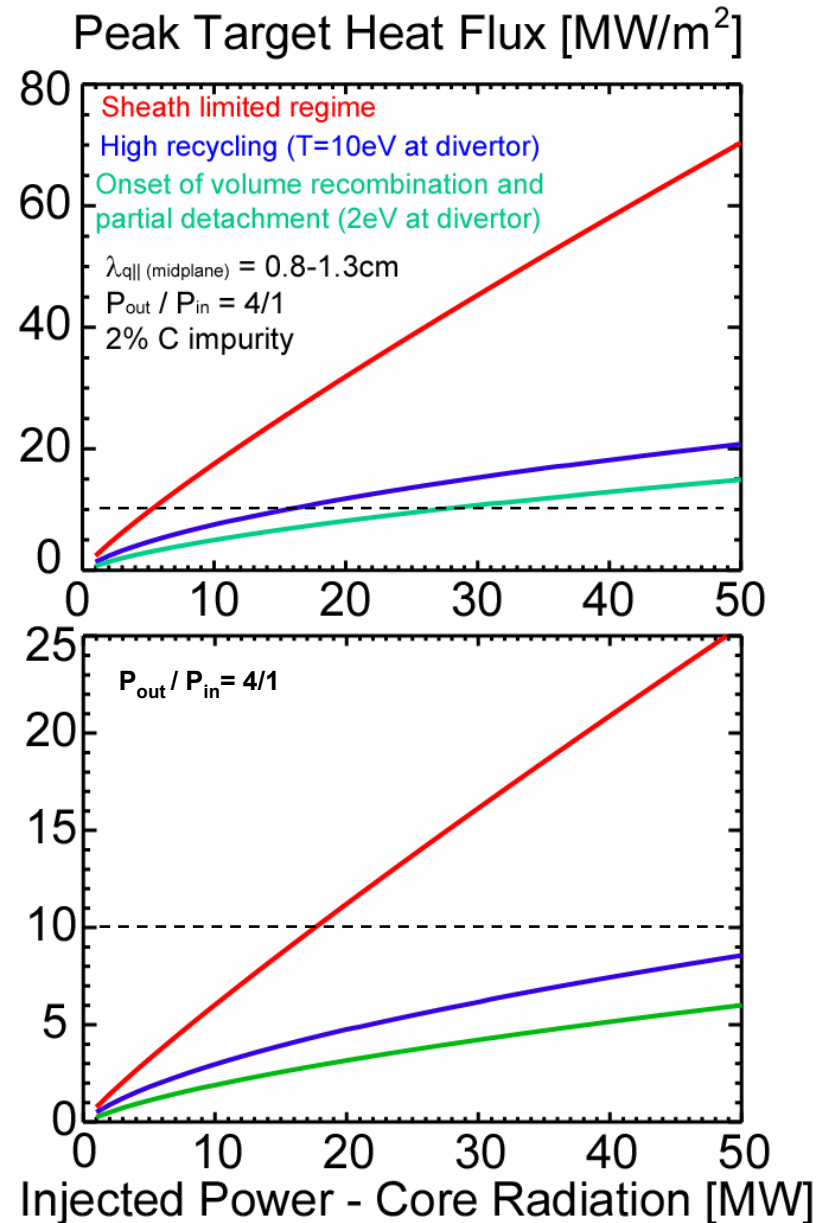
ITER-like div. - LSN  
 $f_{\text{exp}} = 3$  at strike-pt

Compatible with solid divertor material?



JET-like div. - DND  
 $f_{\text{exp}} = 9$  at strike-pt

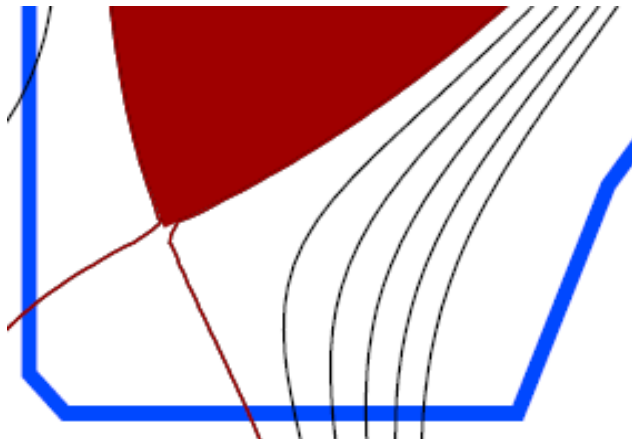
Compatible with efficient pumping?



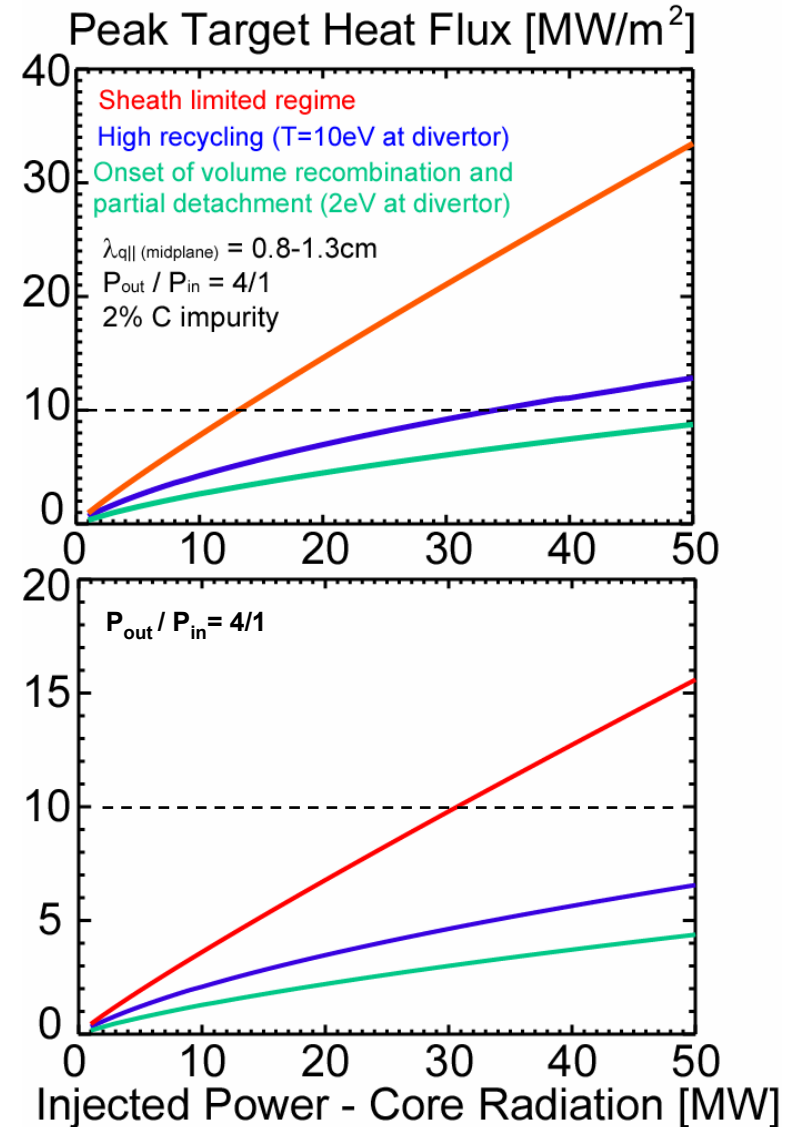
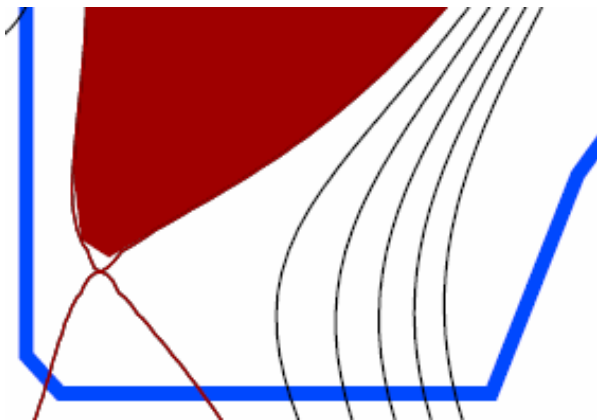
# Large flux expansion and/or plate-tilt is attractive...

...but can one pump over large surface area? (liquid lithium?)

DND -  $f_{\text{exp}} = 10$  at strike-point



DND -  $f_{\text{exp}} = 35$  at strike-point



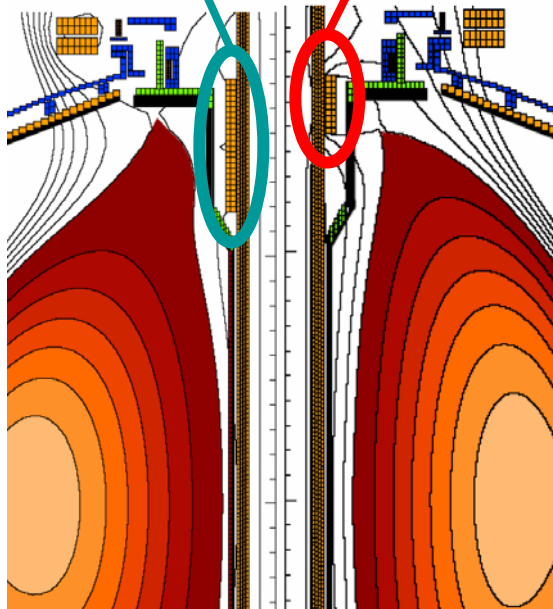
# NHTX requires advanced control of high $\kappa/\delta$ boundary, strike point placement, and flux expansion

- NSTX: Sustained  $\kappa \geq 2.8$  (reached  $\kappa = 3$ ) for many  $\tau_{\text{WALL}}$  using rtEFIT isoflux control
- High  $\kappa$  n=0 stability research important for NHTX and CTF/FDF design studies

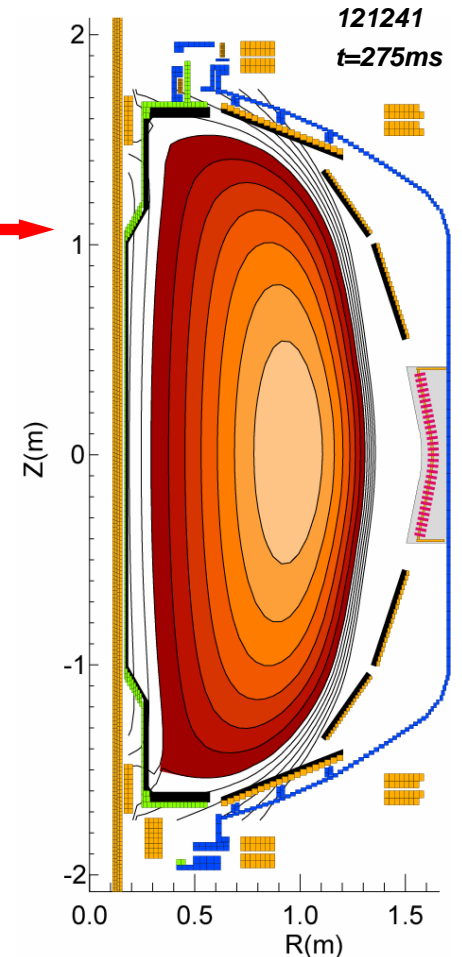
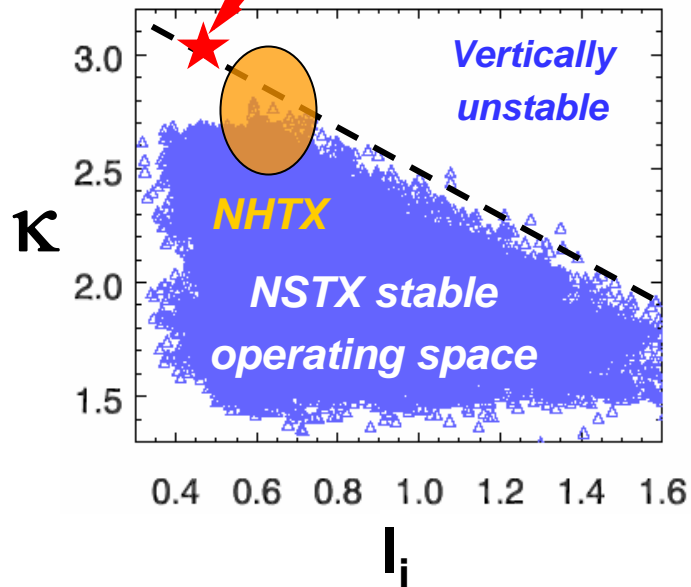
## Divertor coil upgrade

2004

2005

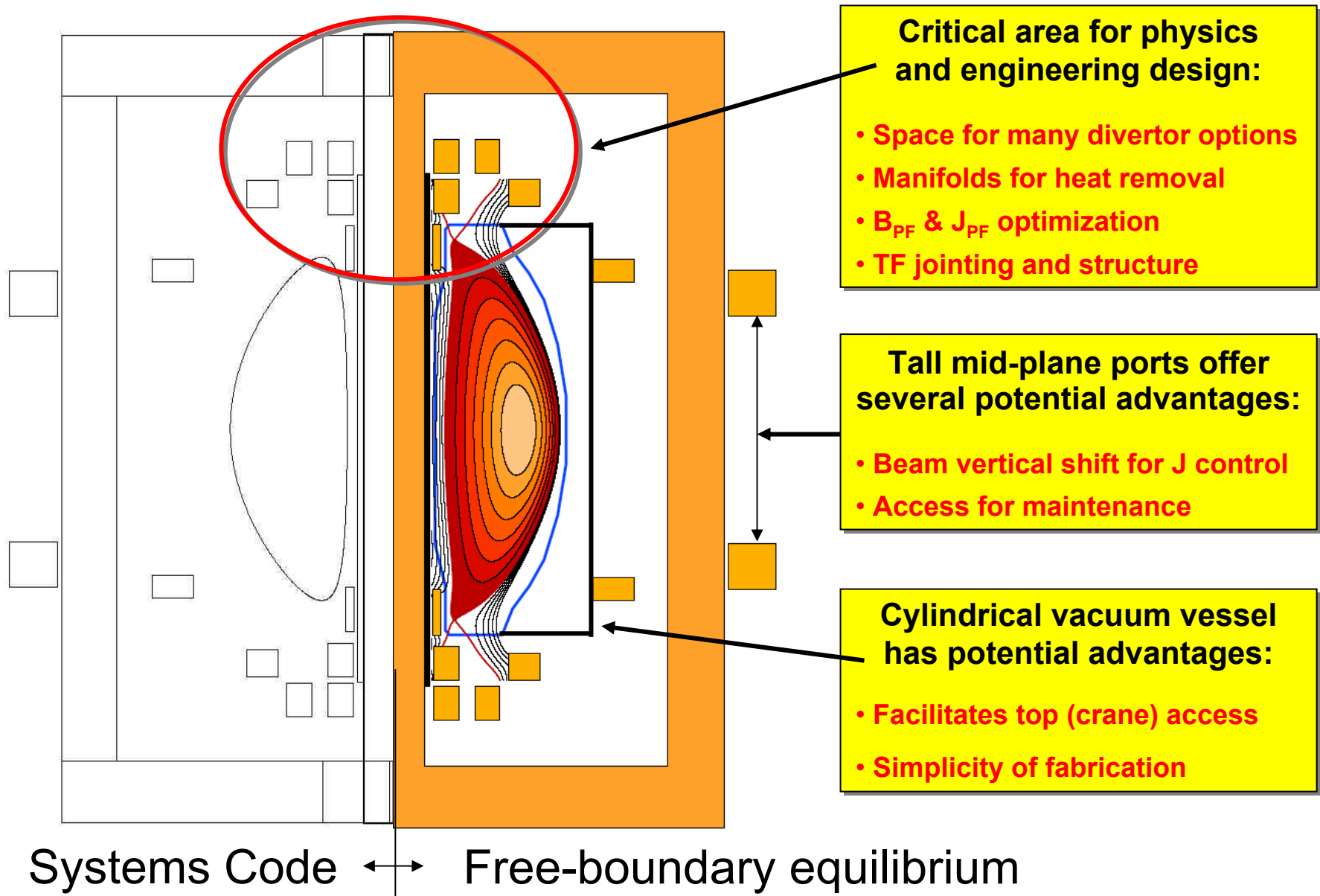


2006:  $\kappa = 3.0$ ,  $\delta_x = 0.8$   
 $I_i = 0.45$

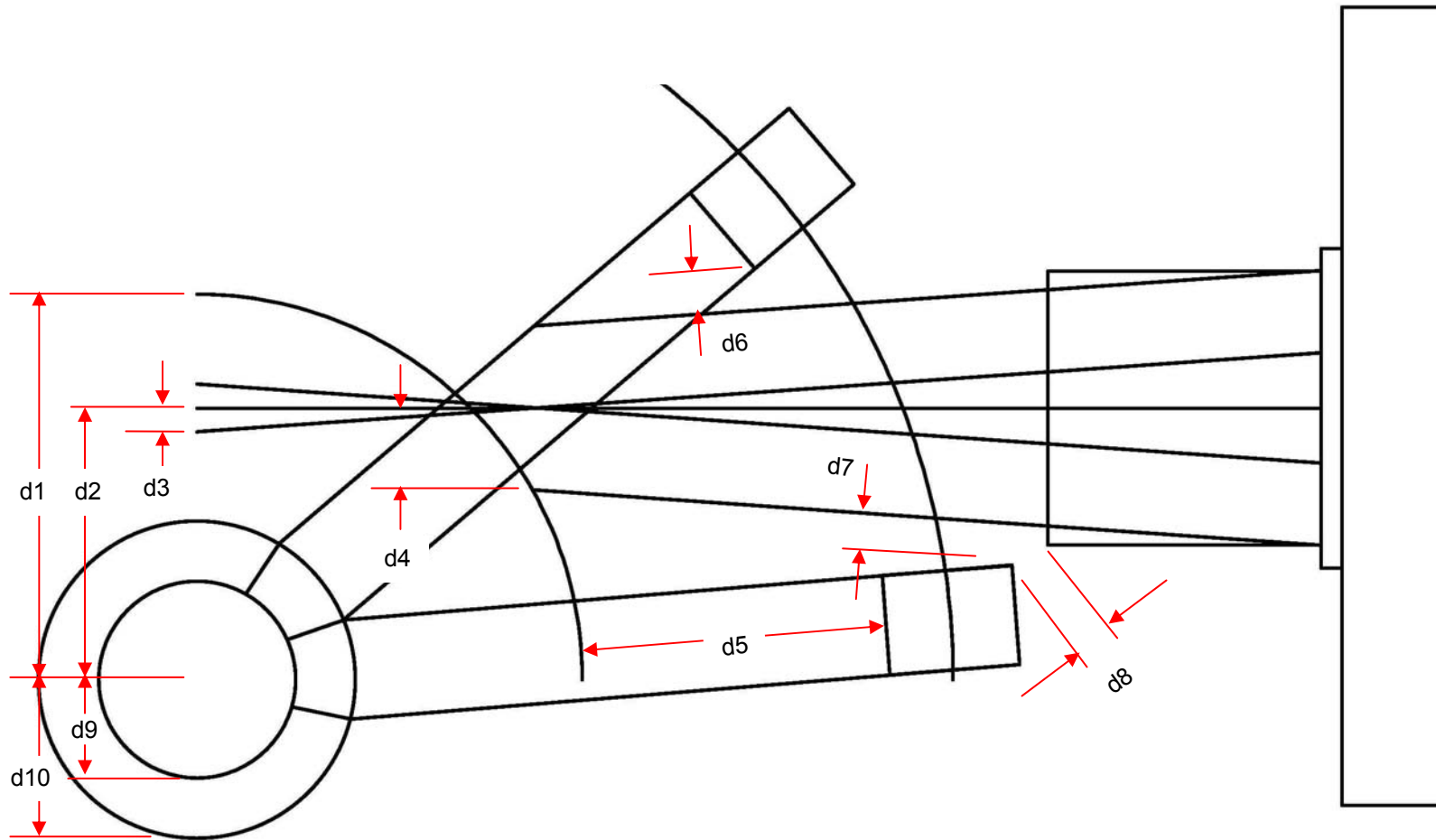


Gates, et al., PoP 13 (2006) 056122  
 Gates, et al., NF 46 (2006) 17

# Many engineering issues remain to be addressed



# Systems code incorporates NBI geometry, TF ripple < 0.5%, and $J_{TF}$ limits into TF outer leg layout and sizing

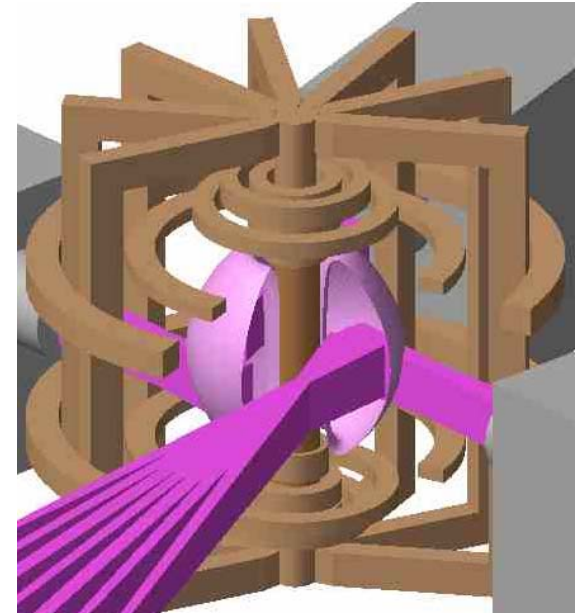
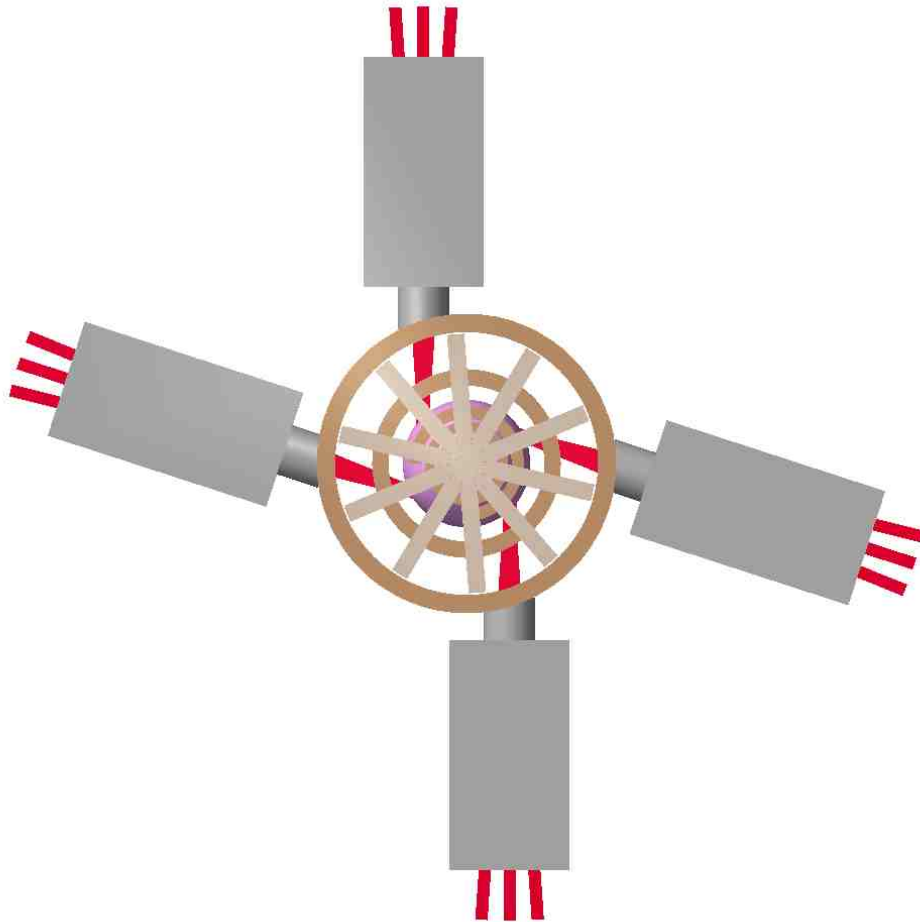


$d1 = R0+a$   
 $d2 = R\_tangency$   
 $d3 = \text{beam centerline spacing around } R\_tangency$   
 $d4 = \text{extent of beam duct w.r.t. beam centerline}$

$d5 = \text{gap } R0+a \text{ to TF outer leg}$   
 $d6, d7 = \text{gaps TF outer legs to beam duct}$   
 $d8 = \text{gap TF outer leg to beam nozzle}$   
 $d9 = \text{radius of TF inner leg}$   
 $d10 = \text{radius of TF outer leg taper}$

# TF coil layout (10 coils) and sizing allows for $R_{TAN}$ variation of NBI for J-profile control

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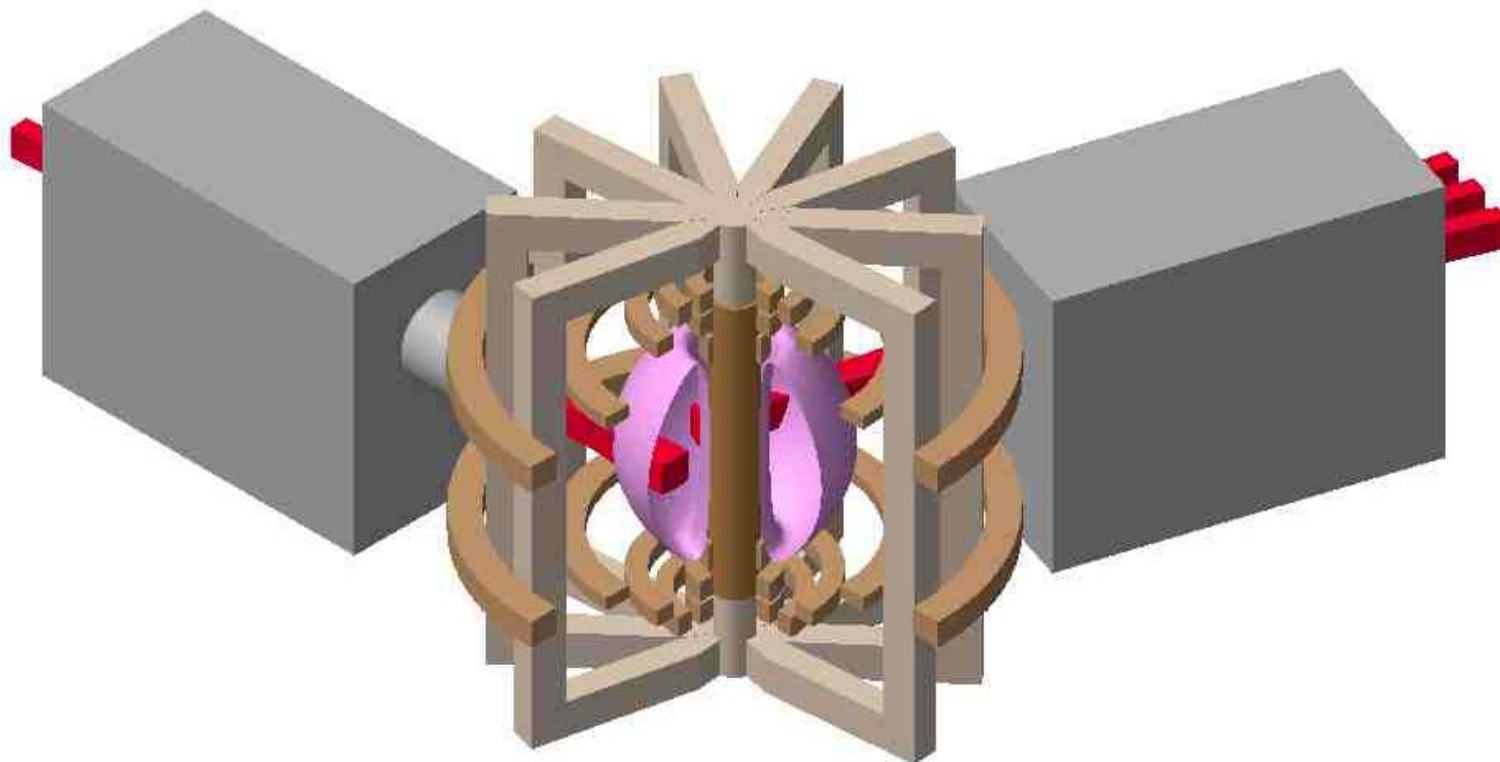


- $R_{TAN}$  range =  $1\text{m} \pm 0.2\text{m}$  possible with cross-over point at vessel entrance
  - Analyzing access port and beam dump layouts

## Large vertical gap between outer PF coils also allows for vertical shifting of NBI for J-profile control

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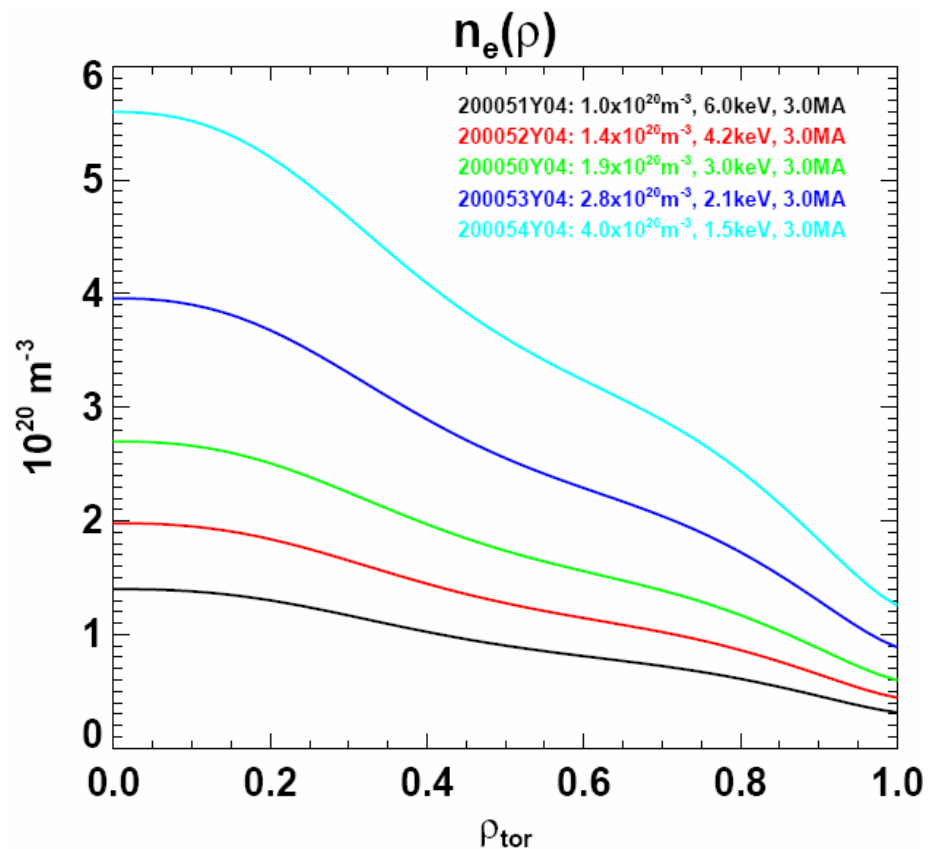
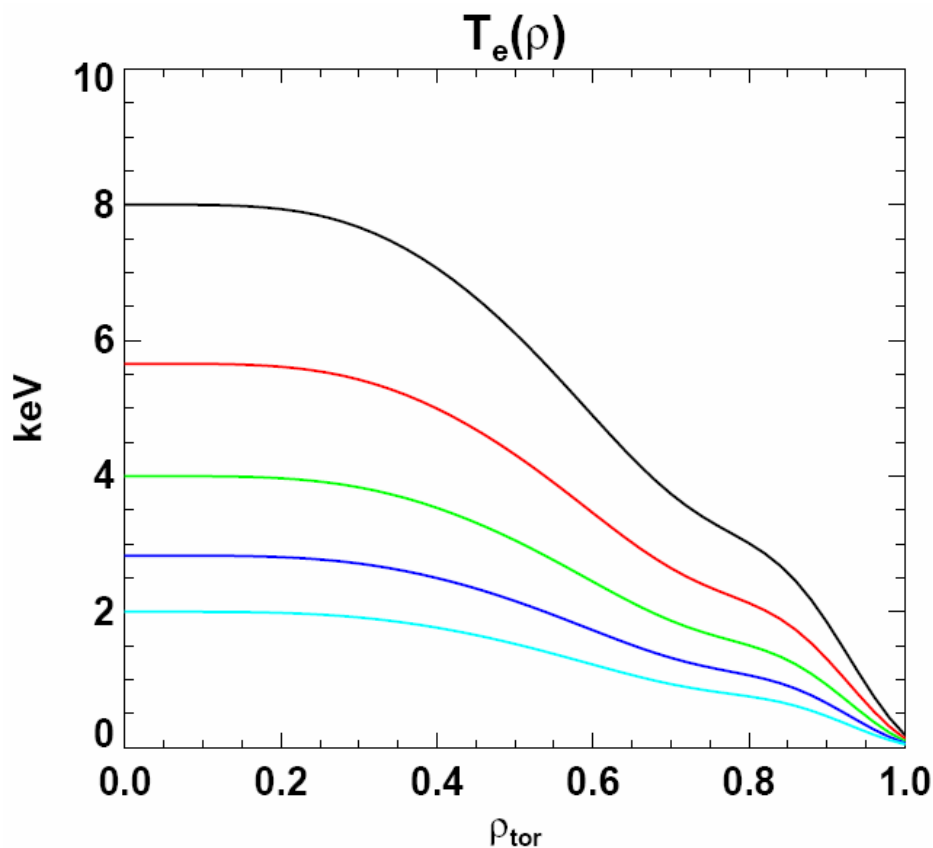
- High  $\kappa$  capability requires outer-most PFs to be outside TF
- If  $R_{TAN}$  variation is chosen, these PFs could have smaller R
  - Reduces PF power consumption, but...
  - Lose accessibility of large vertical midplane gap





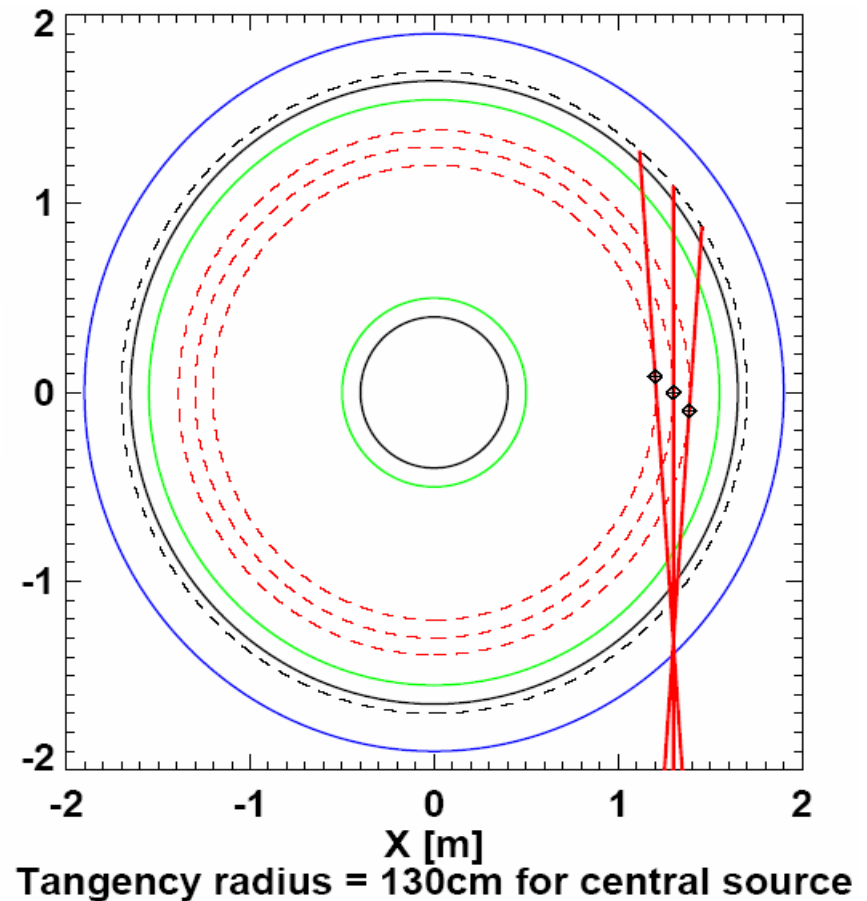
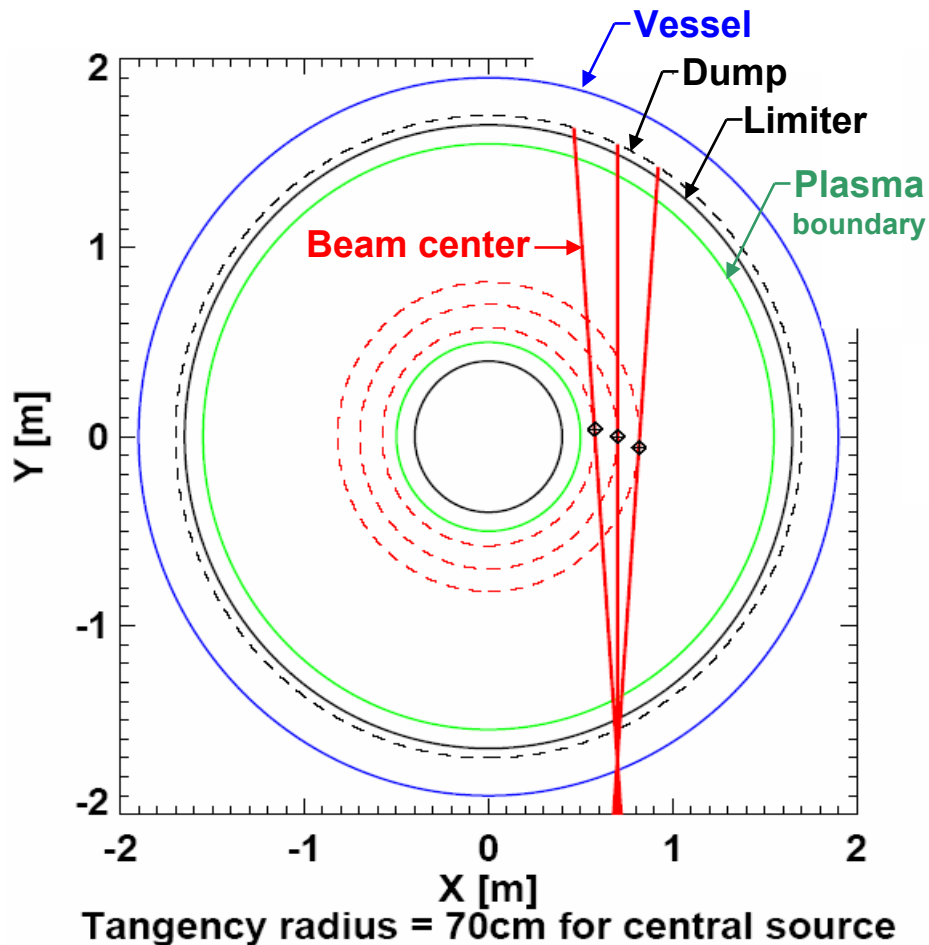
# NBICD assessment w/ TRANSP uses thermal profile shapes based on high $f_{NI} = 60-70\%$ NSTX discharges

- Scale  $n_e$ ,  $T_e$  profiles from 116313 - fixed  $T_i / T_e = 1.5$ ,  $\beta_T = 14\%$



# Scan $R_{\text{TAN}}$ within range $R_0 \pm 30\text{cm}$ to assess NBICD efficiency and profiles

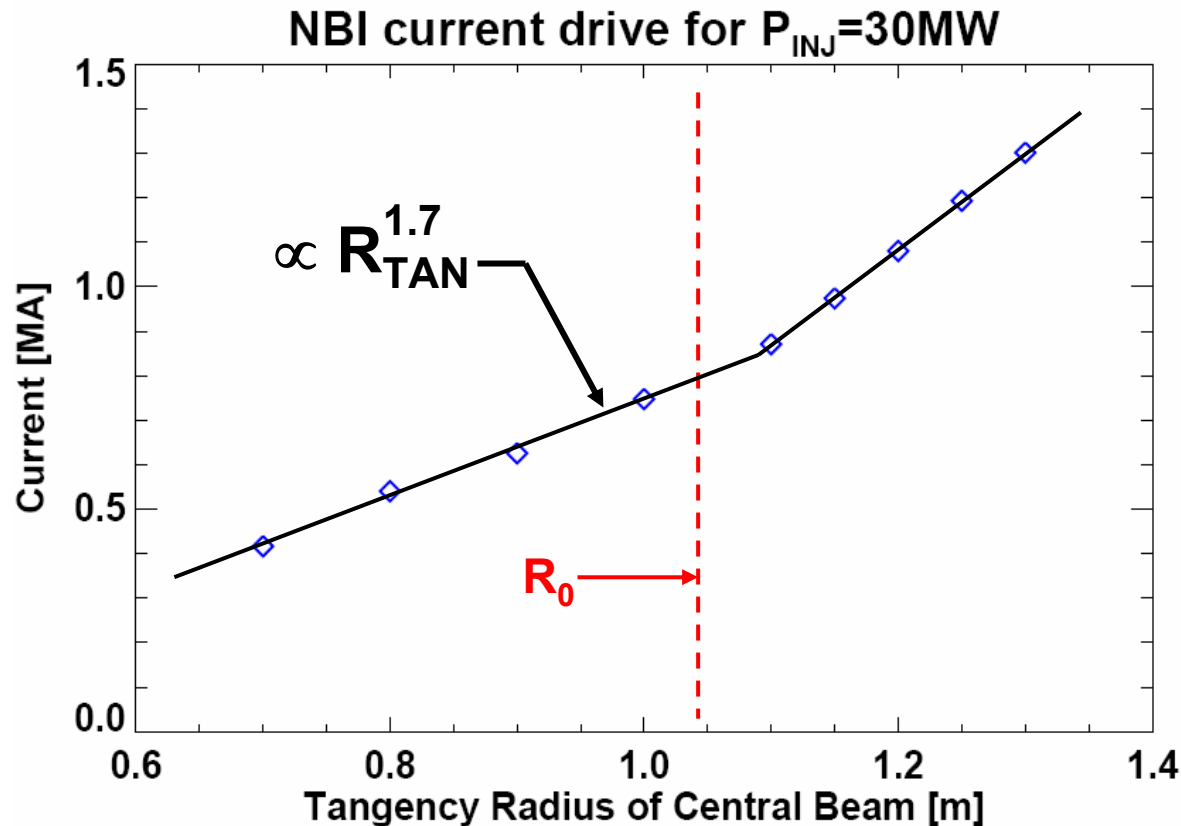
- Fix source cross-over radius at  $R_{\text{CO}} = 1.85\text{m}$  to be near vessel entrance
- Simulates horizontal beam-line swing with bellows near vessel



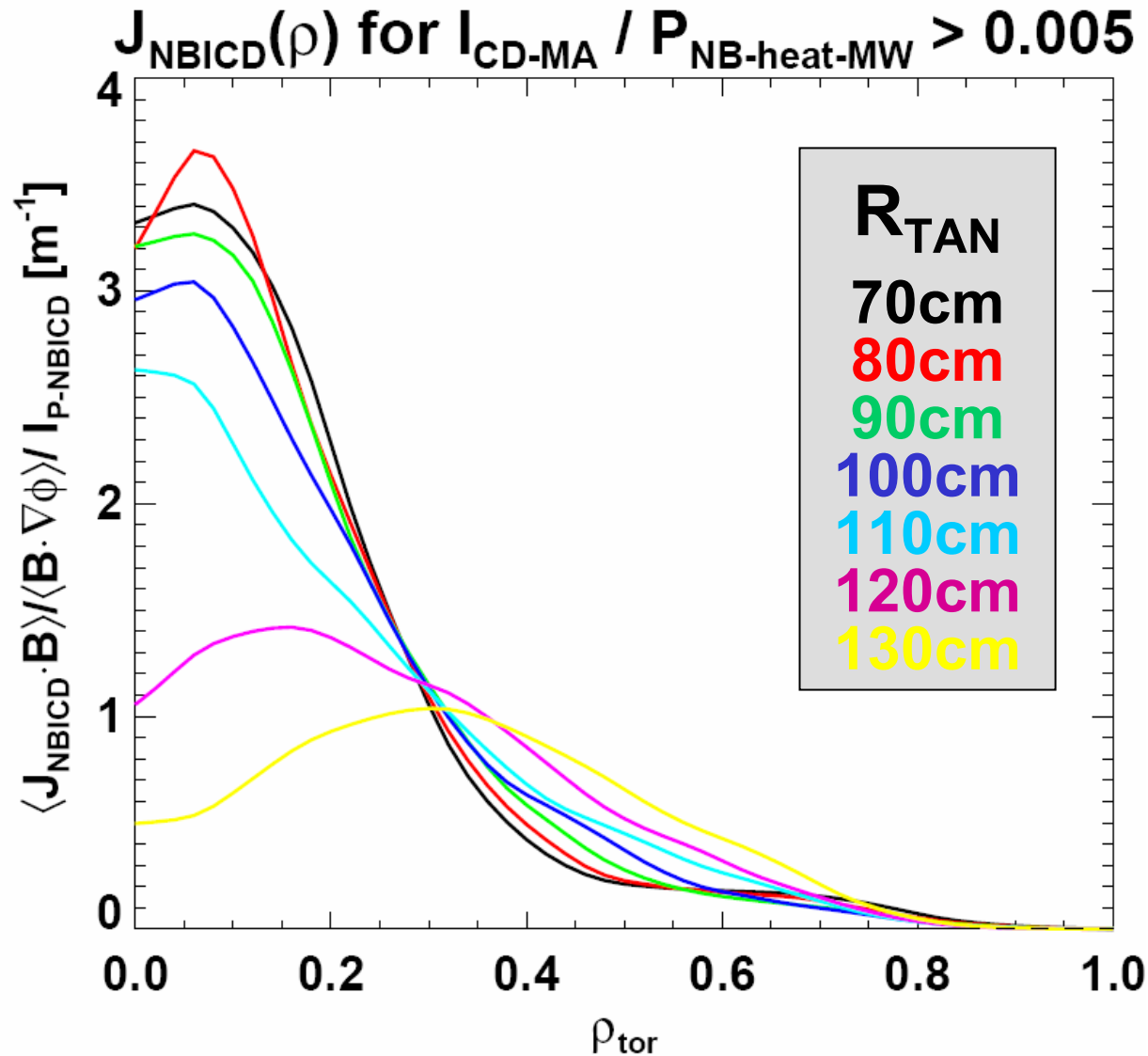
Driven current increases  $\times 3$  for  $R_{\text{TAN}}=0.7 \rightarrow 1.3\text{m}$   
and increases more quickly w/ radius for  $R_{\text{TAN}} > R_0$

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**NBICD for  $\bar{n}_e = 1.4 \times 10^{20} \text{m}^{-3}$ ,  $\bar{T}_e = 4.2 \text{keV}$ ,  $f_{\text{GW}} = 0.43$**



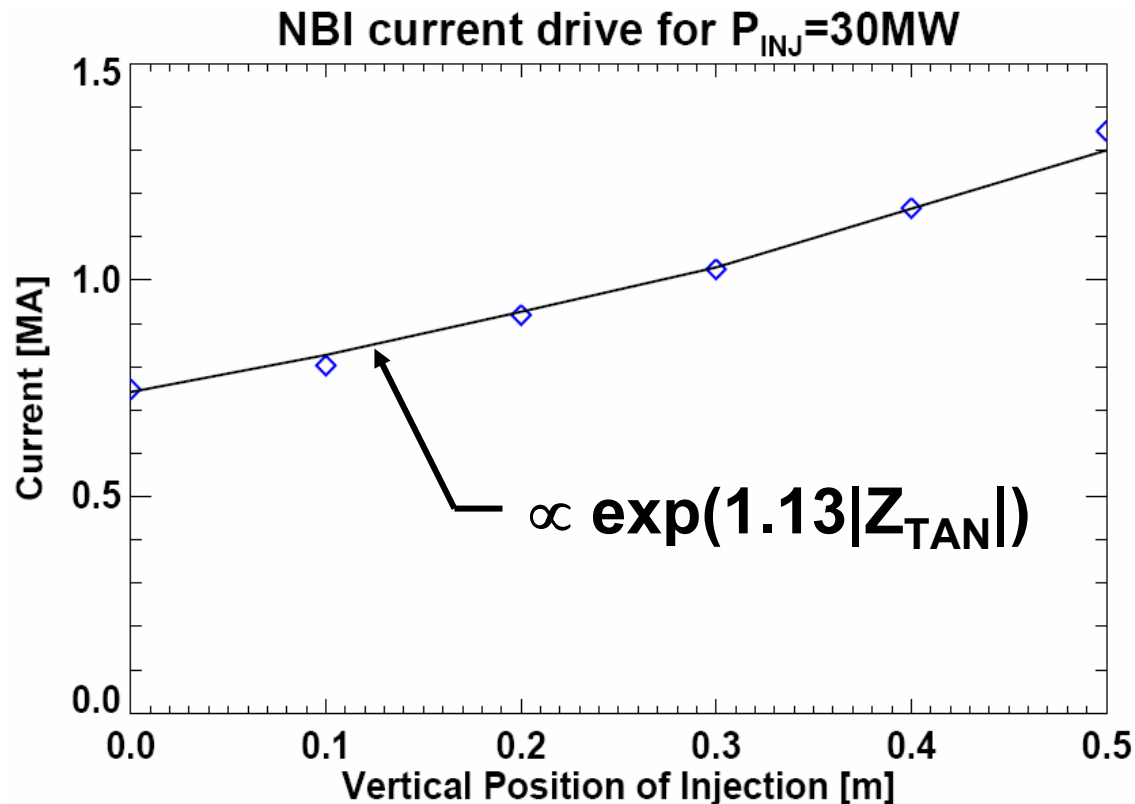
# Beam tangency radius variation would enable control of core current and $q$ profile



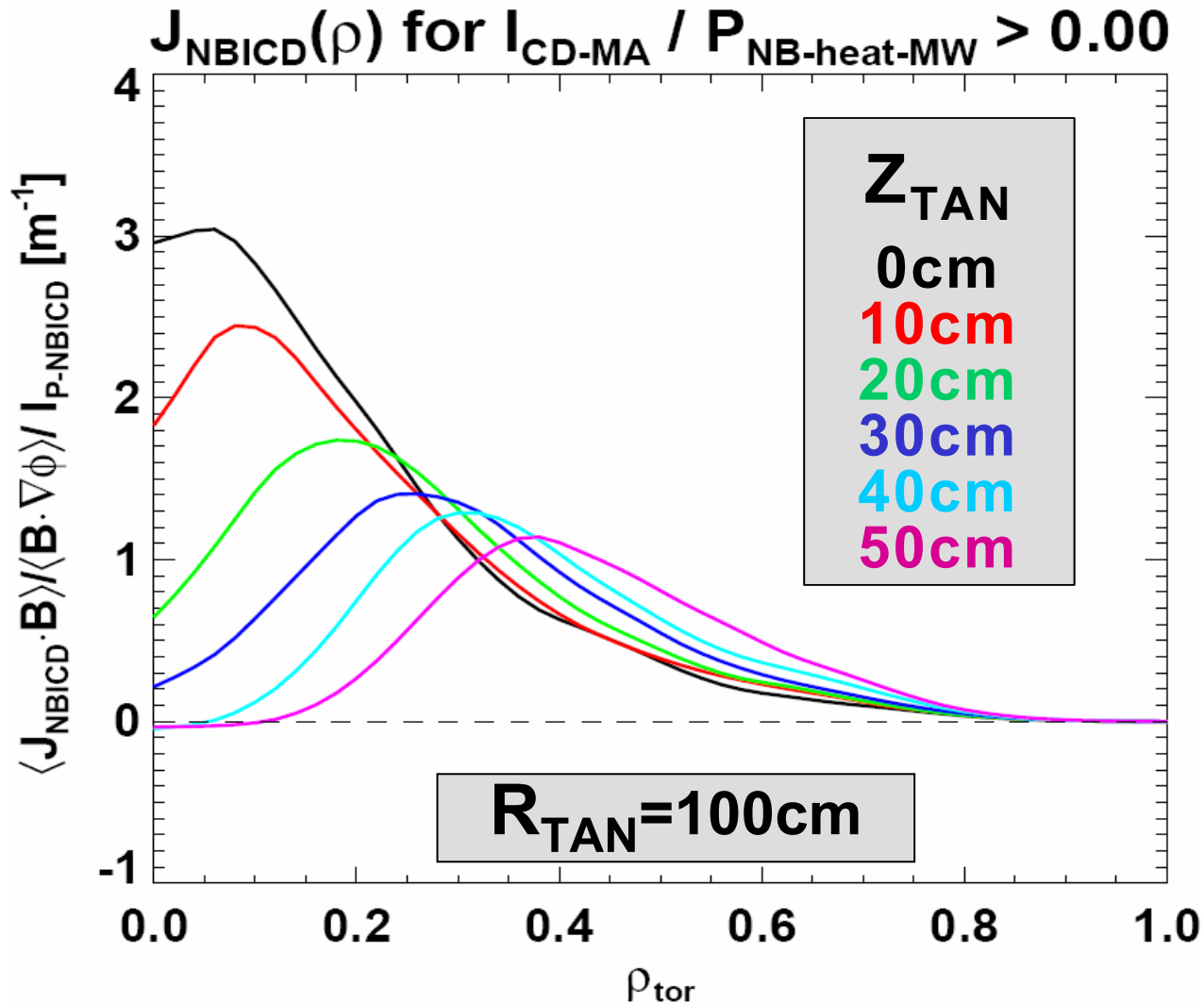
Driven current increases  $\times 1.8$  for  
 $Z_{TAN}=0.0 \rightarrow 0.5m$  for  $R_{TAN} = 1.0m$

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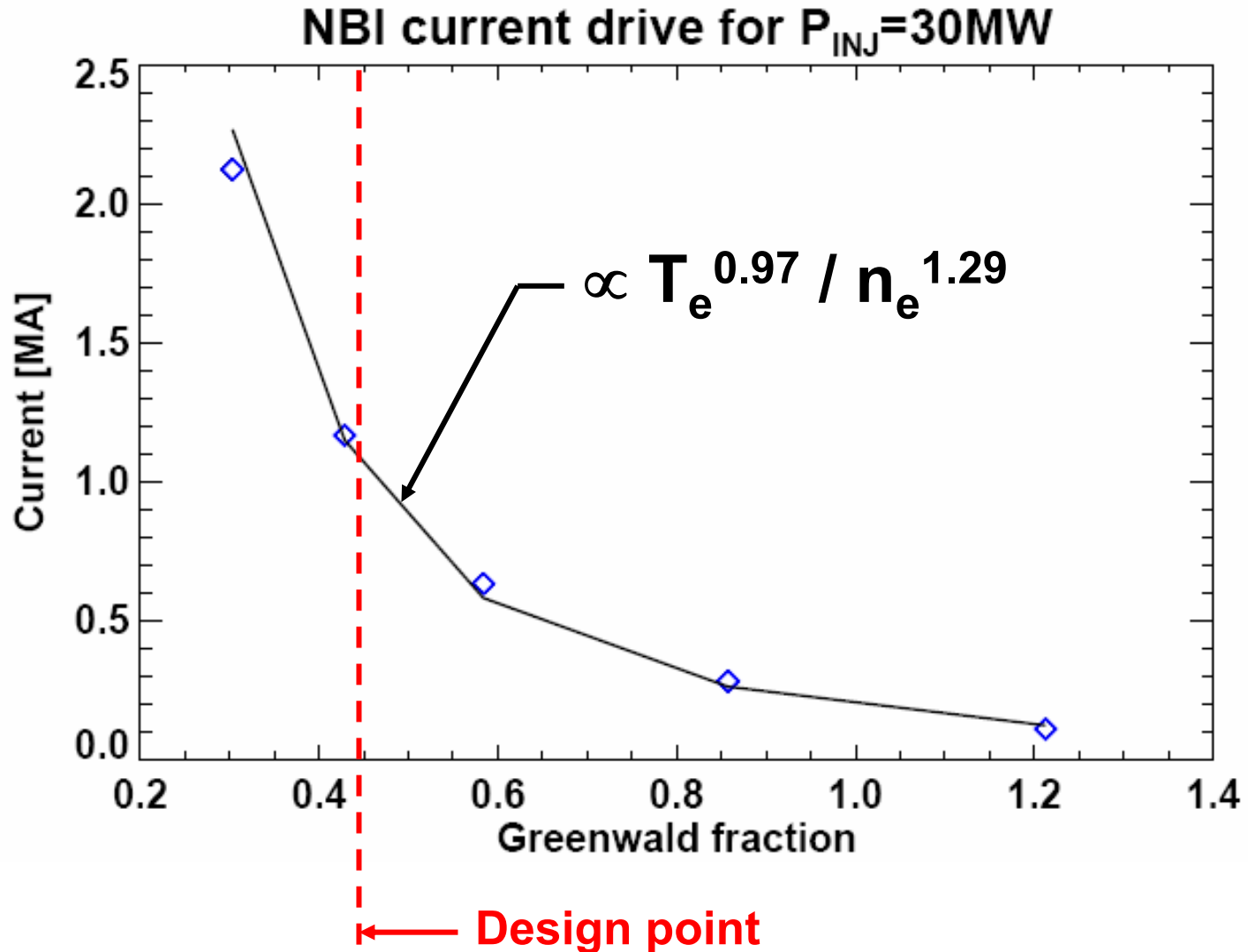
**NBICD for  $\bar{n}_e = 1.4 \times 10^{20} m^{-3}$ ,  $\bar{T}_e = 4.2 keV$ ,  $f_{GW} = 0.43$**



Beam vertical position ( $Z_{TAN}$ ) variation would also enable control of core current and  $q$  profile

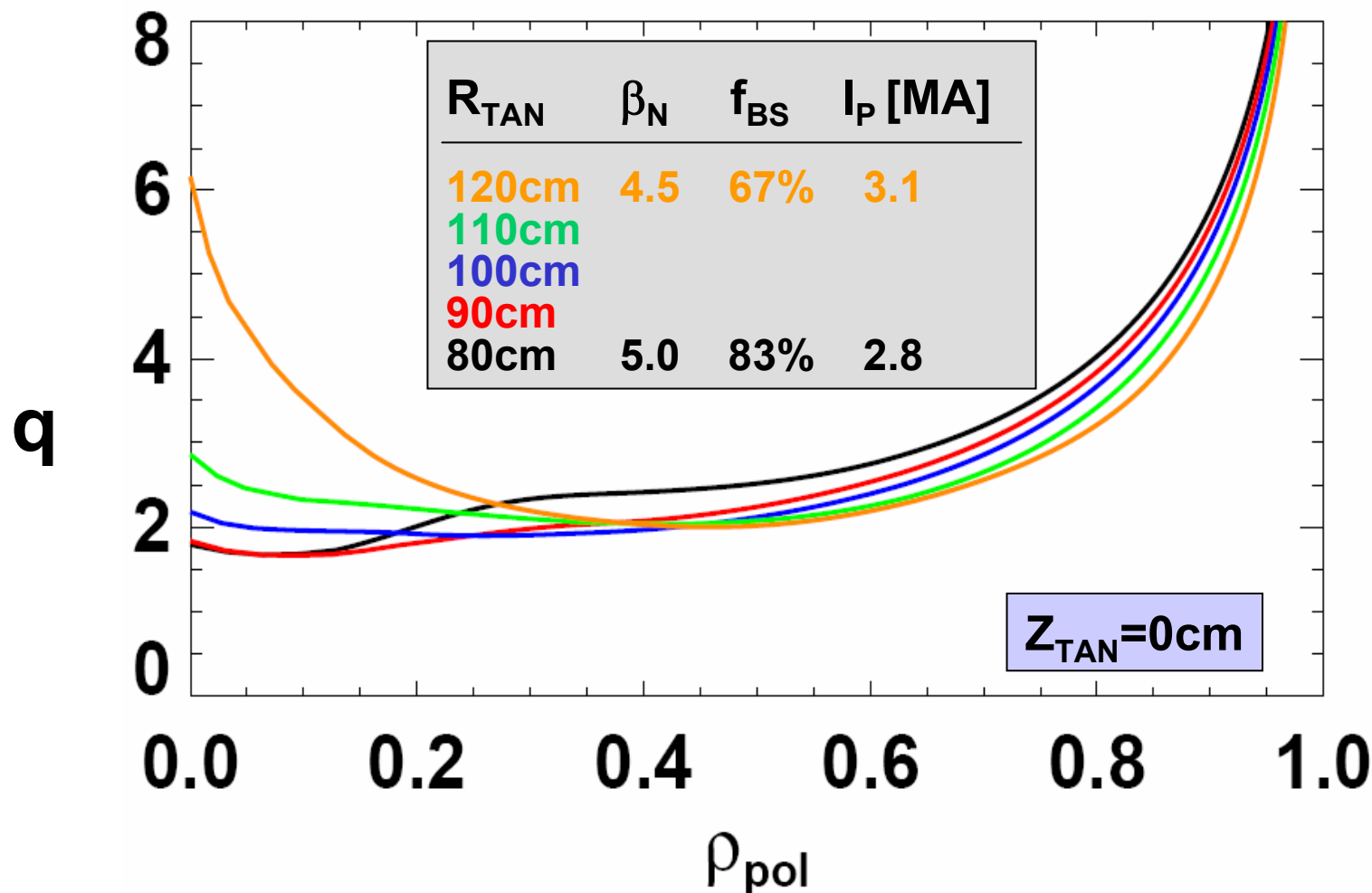


# Ability to control density and operate at $f_{GW} < 0.5$ crucial for high NBICD efficiency



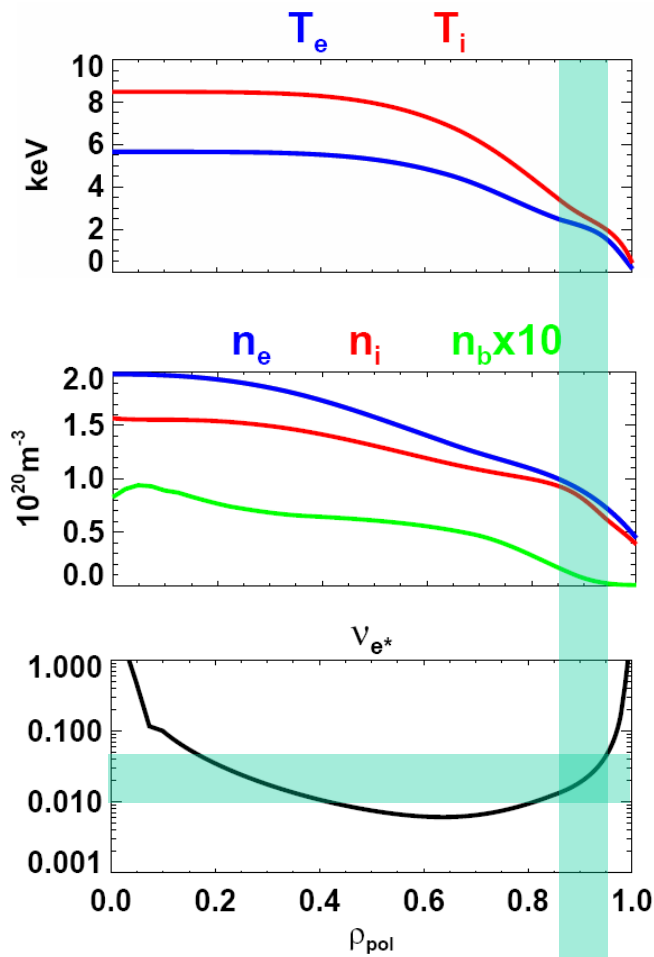
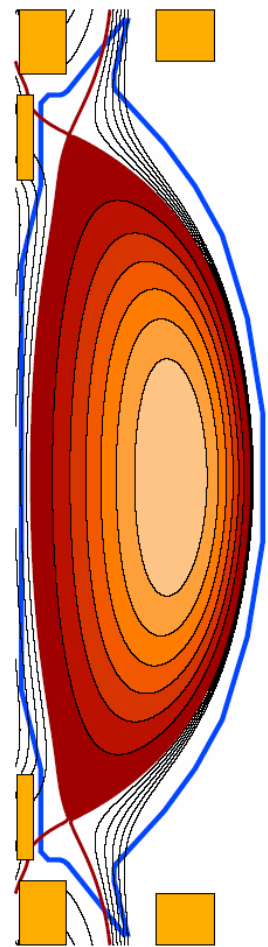
At design point, tangency radius of injection controls degree of shear reversal and radius of  $q_{\text{MIN}}$

$$\bar{n}_e = 1.4 \times 10^{20} \text{m}^{-3}, \bar{T}_e = 4.2 \text{keV}, f_{\text{GW}} = 0.43, \beta_t = 14\%$$

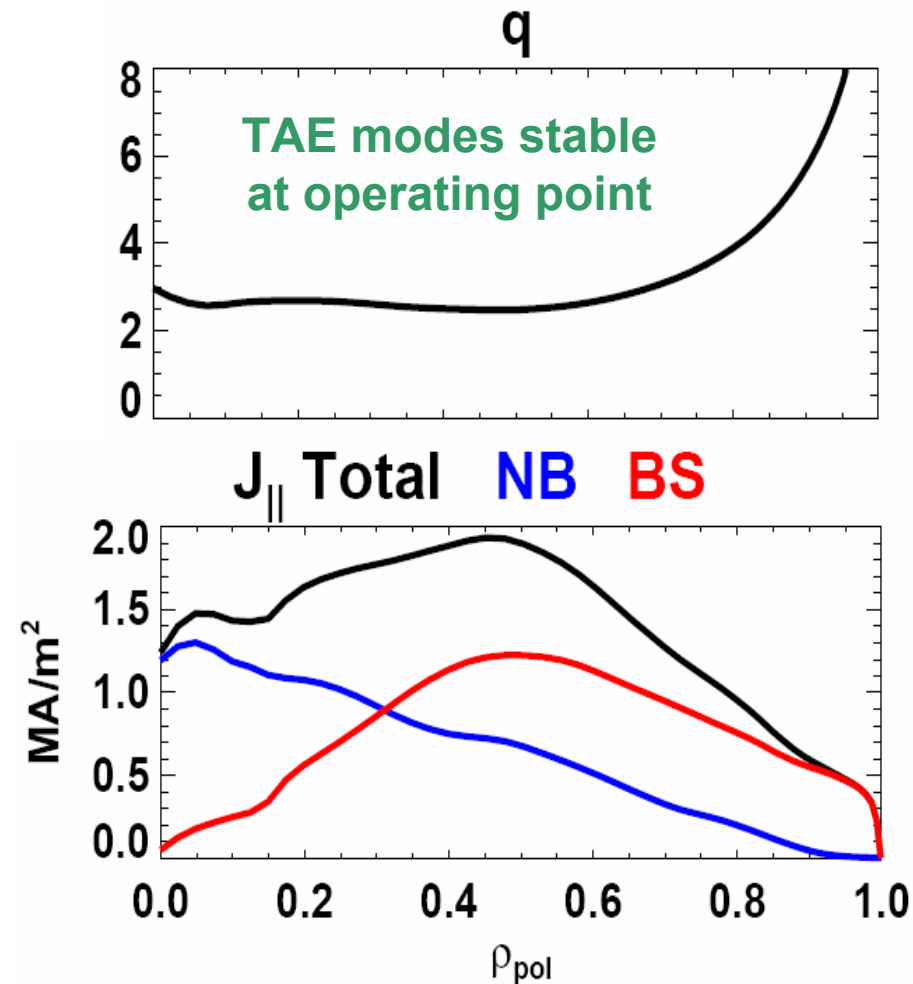




# A=1.8, $\kappa=2.85$ , $I_p=3\text{MA}$ target plasma with self-consistent $J(\rho)$ from NBI and BS with $q_{\text{MIN}} > 2.4$



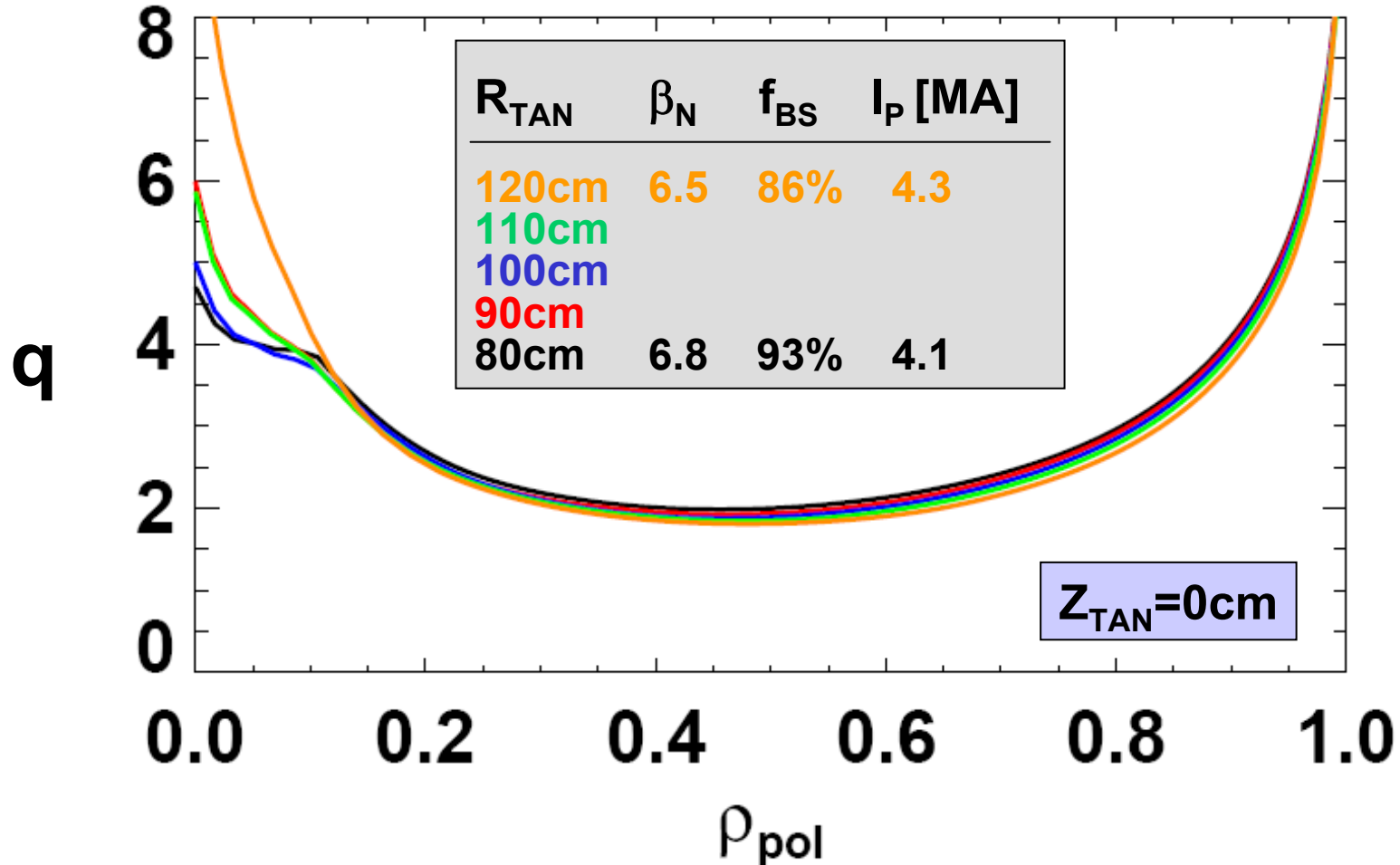
Pedestal  $v_{e^*}$  comparable to ITER



$R_{\text{TAN}} = 115\text{cm}$ ,  $Z_{\text{TAN}} = 0\text{cm}$

If  $\beta_t$  is doubled, bootstrap current dominates NBI-driven current, and  $R_{TAN}$  controls only  $q(0)$

$\bar{n}_e = 2.0 \times 10^{20} \text{m}^{-3}$ ,  $\bar{T}_e = 6.0 \text{eV}$ ,  $f_{GW} = 0.46$ ,  $\beta_t = 28\%$

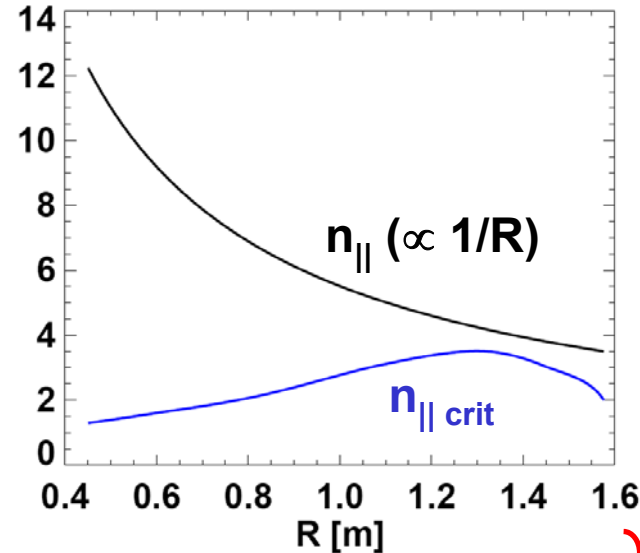


Next step: assess stability and sensitivity to  $n, T$  profile shapes

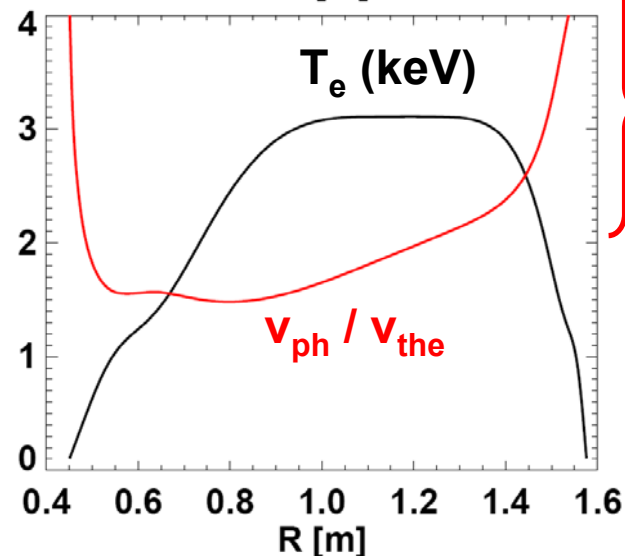
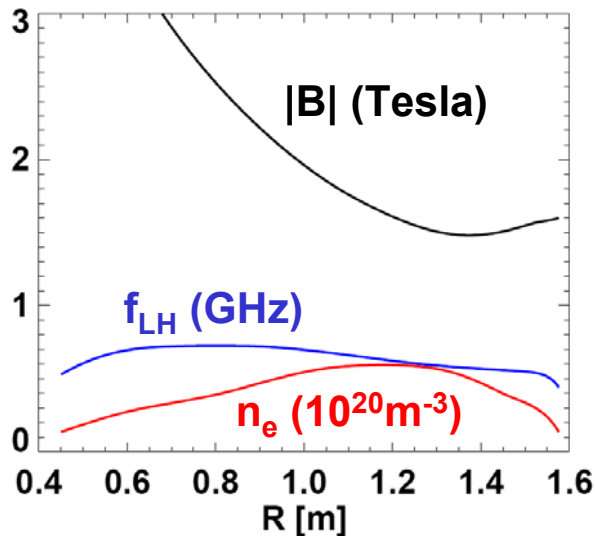
# LHCD for lower-density operating points and current ramp-up appears promising

- Require  $n_{||} > 3.5$  for  $n_e(0) = 6 \times 10^{19} \text{m}^{-3}$
- Find  $v_{ph} / v_{the} = 1.5-3$  for  $T_e(0) = 3 \text{keV}$

**Core LHCD efficiency = 0.1 A/W**  
**1MA of  $I_p$  for 10MW delivered**



$$n_{||\text{crit}} \approx \frac{\omega_{pe}}{|\Omega_e|} + \sqrt{S}$$



$v_{ph} / v_{the}$   
for high  $n_{CD}$

$$\frac{I}{P} \approx \frac{(v_{ph}/v_T)^2}{30} \left[ \frac{T_{10}}{R_1 n_{14}} \right] \text{ A/W}$$

# Summary

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- Systems code has identified favorable design point:
  - $A=1.8-2$ ,  $R_0=1\text{m}$ ,  $I_p=3-4\text{MA}$ ,  $B_T=2\text{T}$ ,  $\kappa=2.7-3$ , full NICD
  - $HH_{98Y} = 1.3$ ,  $\beta_N=4.5$ ,  $\beta_T=15\%$ ,  $f_{BS} \geq 65\%$ ,  $f_{GW}=0.4-0.5$
  - High  $\beta$  possible with  $\Omega_\phi$  & feedback stabilization of RWM
- Favorable coil geometry found for maximum flexibility
  - Divertor flexibility critical element of NHTX mission
- NBI  $Z_{TAN}$  and  $R_{TAN}$  variations allow control of  $J_{NBICD}$ 
  - Analyzing engineering tradeoffs of  $\Delta R$  vs.  $\Delta Z$  beam shift
- Beginning studies of additional heating & CD sources
  - Up to 18MW of additional RF power

# Backup slides

# Systems Code Method

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- XL-based - uses non-linear optimizer (“Solver”)
- Jardin/Kessel algorithms used for NSST were starting point for Systems Code
- Continued evolution with Peng, Rutherford, Kessel for CTF studies
  - See PPPL Report 4165 “Spherical Torus Design Point Studies”
- Engineering & physics algorithms tailored to suit NHTX

# Physics Assumptions in Systems Code

A	1.5-3.0	100% flux surfaces
R0	0.9-1.0m	
kappa	$3.674/\text{SQRT}(A)$	Goldston
delta	0.6	Fixed
qcyl	$4/3*(12.259-13.58*A+6.4286*A^2-1.0417*A^3)$	Multiple of Menard
beta_N	$\leq \text{limit } 6.43-1.02*A$	Fit to Menard no-wall limit
$\alpha_n=\alpha_T$	$(0.64-0.3/A)/2$	Menard model
peaking factor (pf)	$r(1-(r/a)^2)^{\alpha_n}(1-(r/a)^2)^{\alpha_T}$	
kBS	$0.344+0.195*A$	Menard model
fBS	$\text{Beta}_P*kBS*pf^{0.25}/\text{SQRT}(A)$	
Confinement	Ti=Te, HH98=1.3	Also examined Ti .ne. Te w/HHe=0.7-1.3
Solenoid Flux	85% Hirshman-Neilson flux, ramp-up only	85% factor matches formula to Menard data
Non-inductive CD	Bootstrap + NBI (4*8=32MW) @ 110keV	
Paux	32MW (NBI) + 6MW (RF) = 38MW	Beta limited
NBI alignment	Normalized to 90,100,110 cm tangency for R0=0.95m, A=1.8 case	Kaye
PF Currents	Amp-turns scaled from Menard equilibrium @ 3MA (A=1.8)	

# Engineering Assumptions in Systems Code

TF Inner Leg Heating	$J_{cu\_avg} \leq 5.75 \text{ kA/cm}^2$	$dz = \kappa \cdot a + 1.425 \text{ m}$ , packing fraction $f(J_{cu\_avg}, dz)$ based on KCOOL, $v = 10 \text{ m/s}$ , $T_{cu\_max} = 100 \text{ C}$
TF Inner Leg Stress	Radial stress $\leq 138 \text{ MPA}$	Insulation shear stress is tracked
TF Outer Leg Heating	Minimize J but maximizing CSA of outer legs within available space, considering NBI alignment	
TF Outer Leg Stress	Not Modeled	
OH Heating	G-function adiabatic	$dz = f(\kappa \cdot a)$
OH Stress	Hoop stress $\leq 138 \text{ MPA}$	
PF Heating	$J_{cu\_avg} \leq 2.5 \text{ kA/cm}^2$	KCOOL analysis assumes conductor area per turn $1.5 \cdot \text{CSA}$ of existing PF coils, 10 turns per cooling path, 15kA per turn
PF Stress	Not Modeled	
Center Stack Casing (VV) Heating and Radial Build	25% of Paux impinges on CS over $dZ = 2 \cdot \kappa \cdot a$	Radial build based on heat flux, ferritic steel w/15% cooling fraction, 400C, 4MPa He cooling at 150m/s
PFC Heating	Not Modeled	
PFC Stress	Not Modeled	
Transrex Capacity	15kA/PSS, 3.25kA rms	Irms is limiting (Trep~20min)
MG	TF/PF/OH Loads $W \leq 4.5 \text{ GJ}$ , CCV on during pulse	
Grid	NBI/MG/BOP Loads $P \leq 200 \text{ MW}$	Approved by PSE&G for TPX, requires local D-site substation and p.f. correction
Cooling Water Systems	Total flow requirement based on total energy dissipation, rep rate limited by 20MW heat removal	60-10=50C rise typ. $\Delta T$



# Beyond high P/R, NHTX provides high $P/P_{L \rightarrow H}$ required for testing radiative power dispersal techniques

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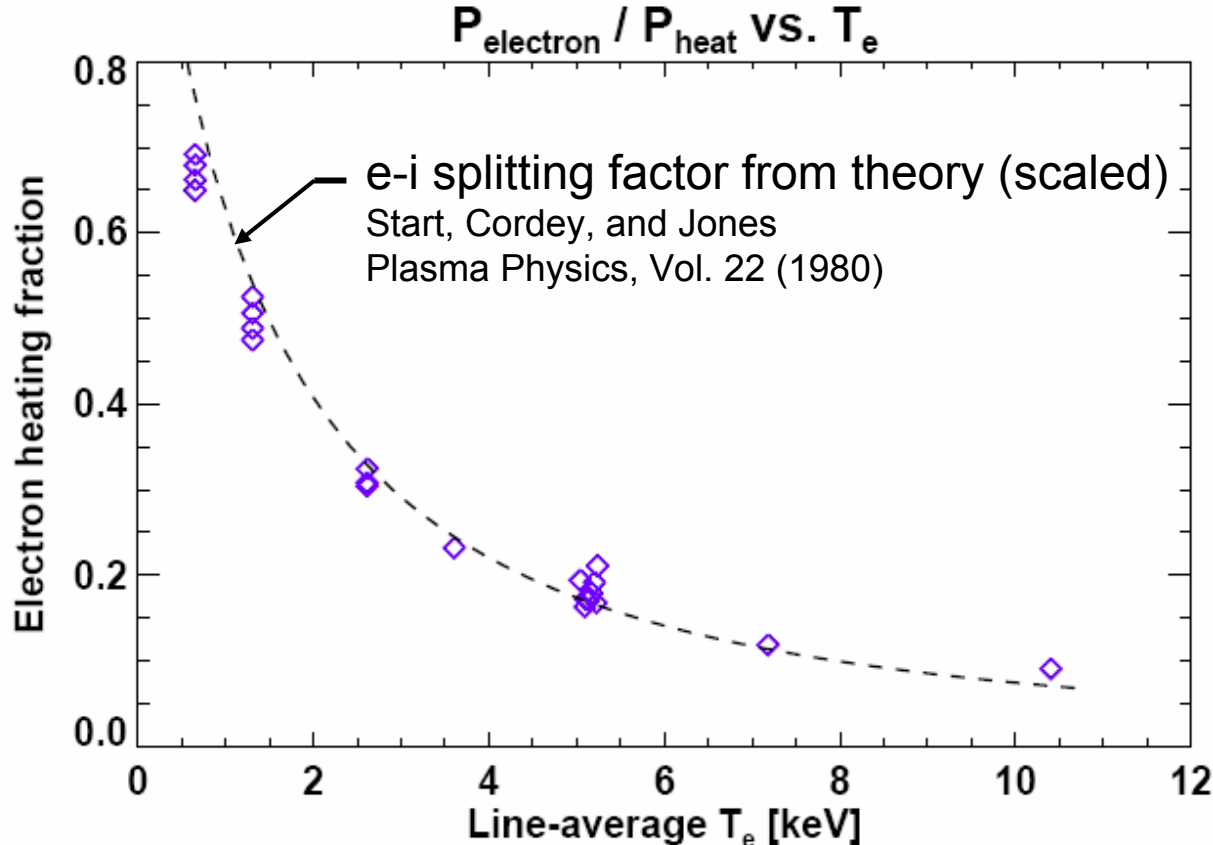
- Can fusion plasmas operate at high  $\tau_E$  and  $\beta$  with 90% core radiated power, to reduce divertor heat flux?
- Physics test requires input power exceeding H-mode threshold power by a very large factor  $\sim 10$ .
- **NHTX has unique capability to test the Demo-relevant physics in this area:**

	$P_{in}/P_{L \rightarrow H} @ 0.85 \times n_{gw}$
<b>ITER</b>	<b>3.6</b>
<b>JT-60SA</b>	<b>4.9</b>
<b>ARIES-AT</b>	<b>11</b>
<b>NHTX</b>	<b>12</b>

**The solution to the power-dispersal problem has order-unity impact on CTF/FDF and Demo design**

# NBICD assessment with TRANSP tests CD efficiency scalings from analytic theory used in 0D optimizations

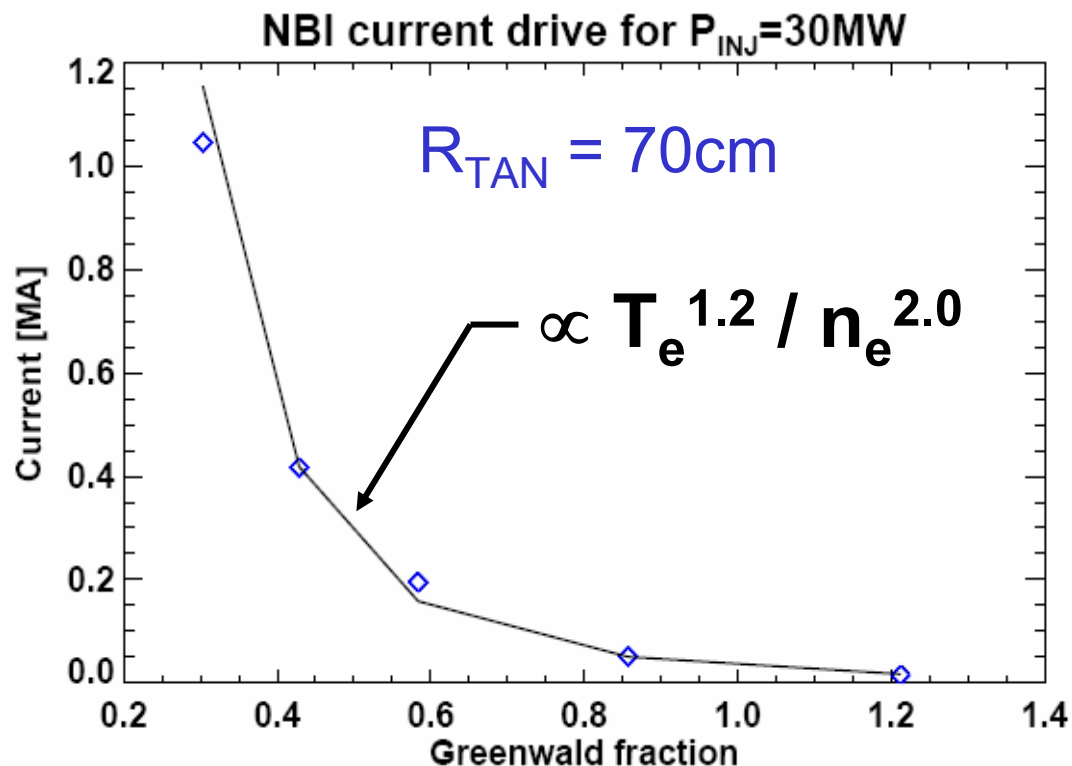
- Expect  $\eta_{CD} \propto I_{NBICD} / P_{heat} \propto T_e^{3/2} / n_e$  (i.e.  $\tau_s$ )  $\times$  e-i splitting factor  $\times$  e-shielding factor
- At high T, fast ions lose energy primarily to thermal ions  $\rightarrow J_{circ}$  should be reduced
- **e-i splitting factor from theory scales like e-heating fraction from TRANSP**



For  $R_{TAN} < R_0$ , TRANSP predicts  $T_e / n_e^2$  CD efficiency scaling when line-averaged  $T_e$ ,  $n_e$  parameters are used:

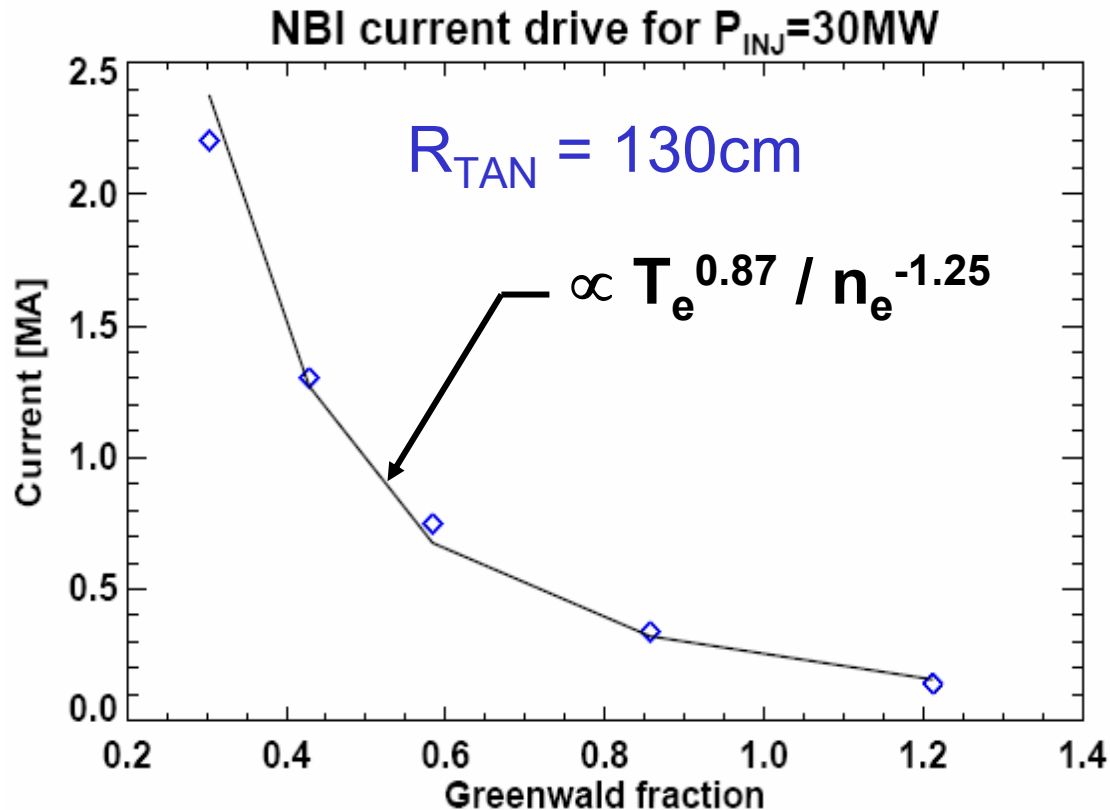
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- Expect faster than  $1/n_e$  scaling from broadened deposition into lower local  $T_e$  when  $n_e$  is increased
- However, NSTX studies w/ ***flat*** core profiles find similar scaling

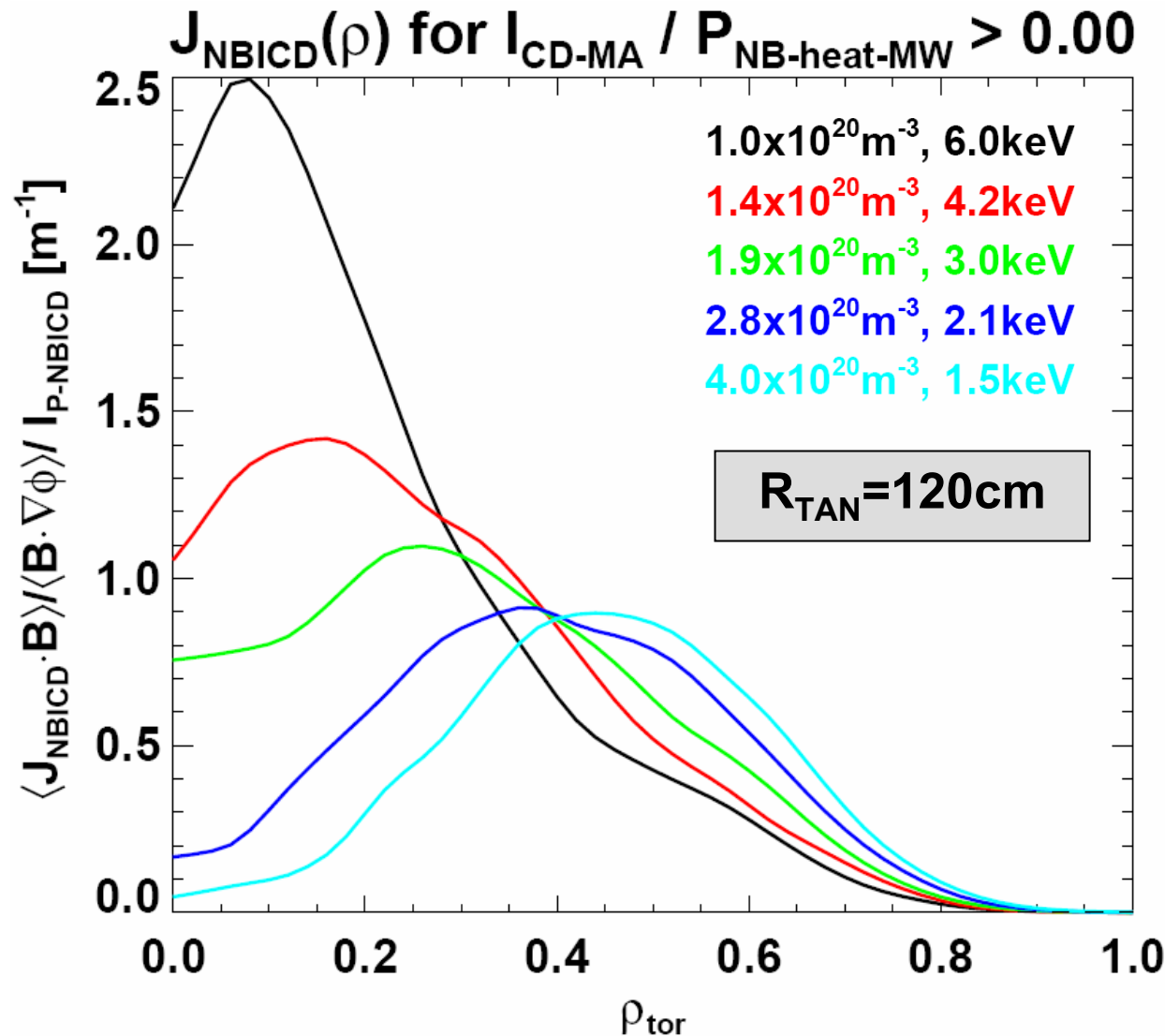


# For $R_{TAN} > R_0$ , TRANSP predicts CD efficiency scaling closer to $T_e / n_e$

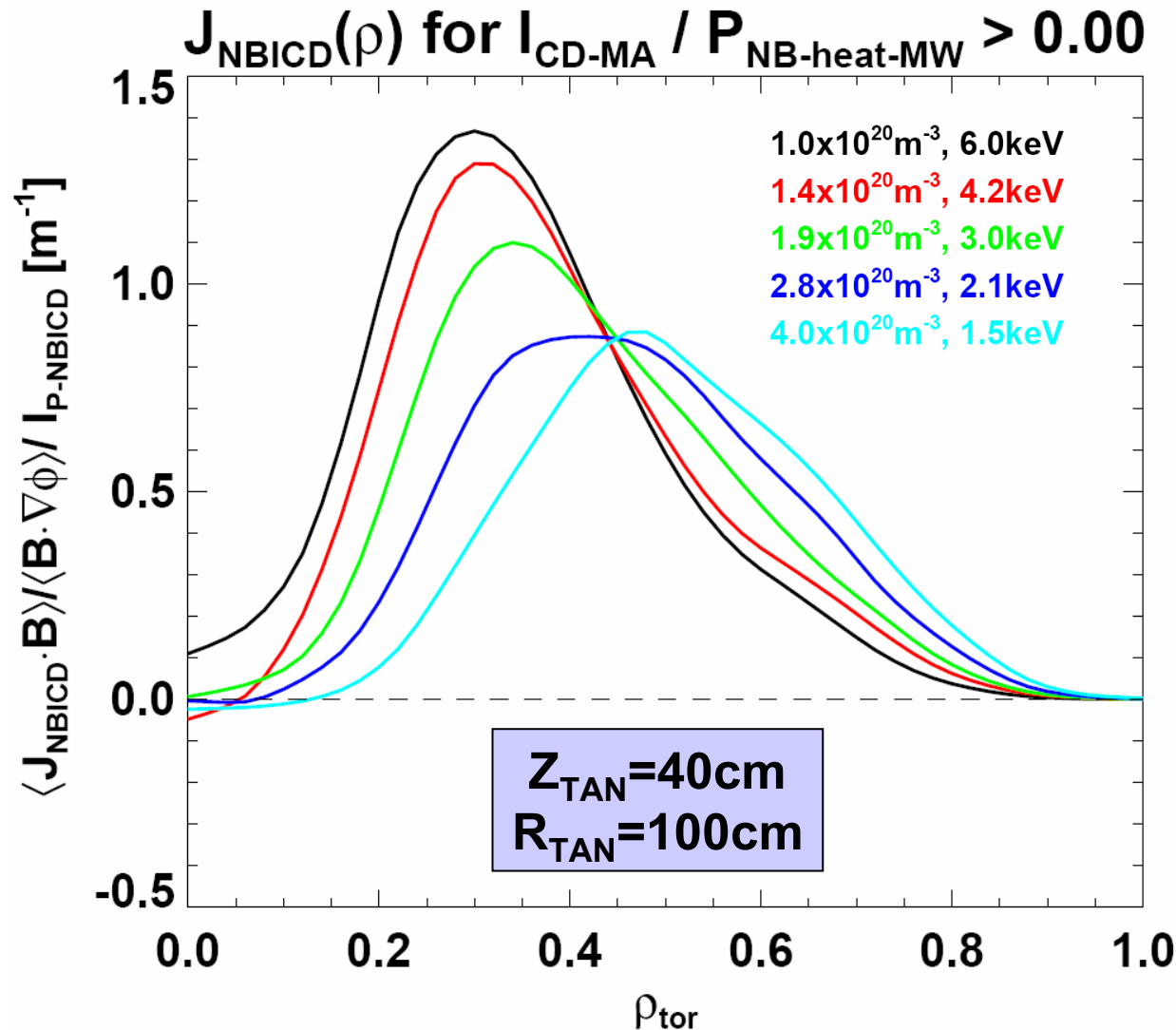
- Implies injection geometry more important than profile effects
- Possible explanation: small  $R_{TAN}$  produces increasingly  $\perp$  fast ions as  $n_e$  increases and deposition profile broadens



# For outboard beam tangency radius, driven current profile broadens significantly at high density



For vertically shifted beams, driven current profile shape is less sensitive to variations in density

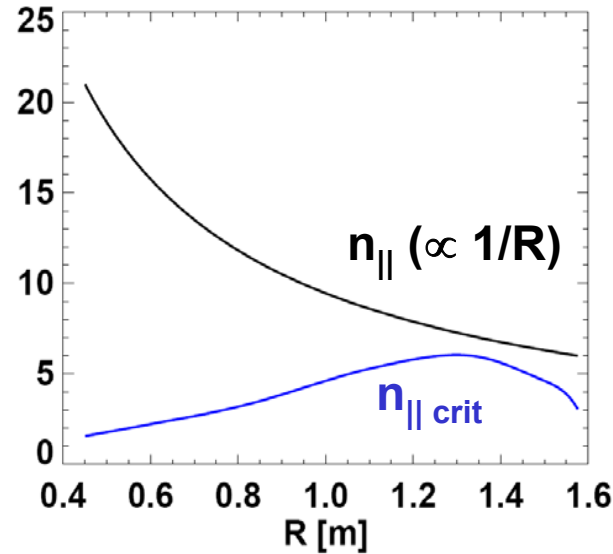


# Additional LHCD at nominal operating point could be challenging due to LFS accessibility requirement

- Require  $n_{||} > 6$  assuming  $k_{||} \propto 1/R$
- Find  $v_{ph} / v_{the} < 1$  inside  $\rho < 0.8$
- Want  $v_{ph} / v_{the} = 2-5$  for high  $\eta_{CD}$

**Core LHCD efficiency = 0.01 A/W**  
**0.1MA of  $I_p$  for 10MW delivered**  
**Use LH for bulk heating w/o torque?**

- Try poloidally directed launch at LFS +  $k_{||}$  downshift at HFS? (need ray-tracing)



$$n_{||crit} \approx \frac{\omega_{pe}}{|\Omega_e|} + \sqrt{S}$$

