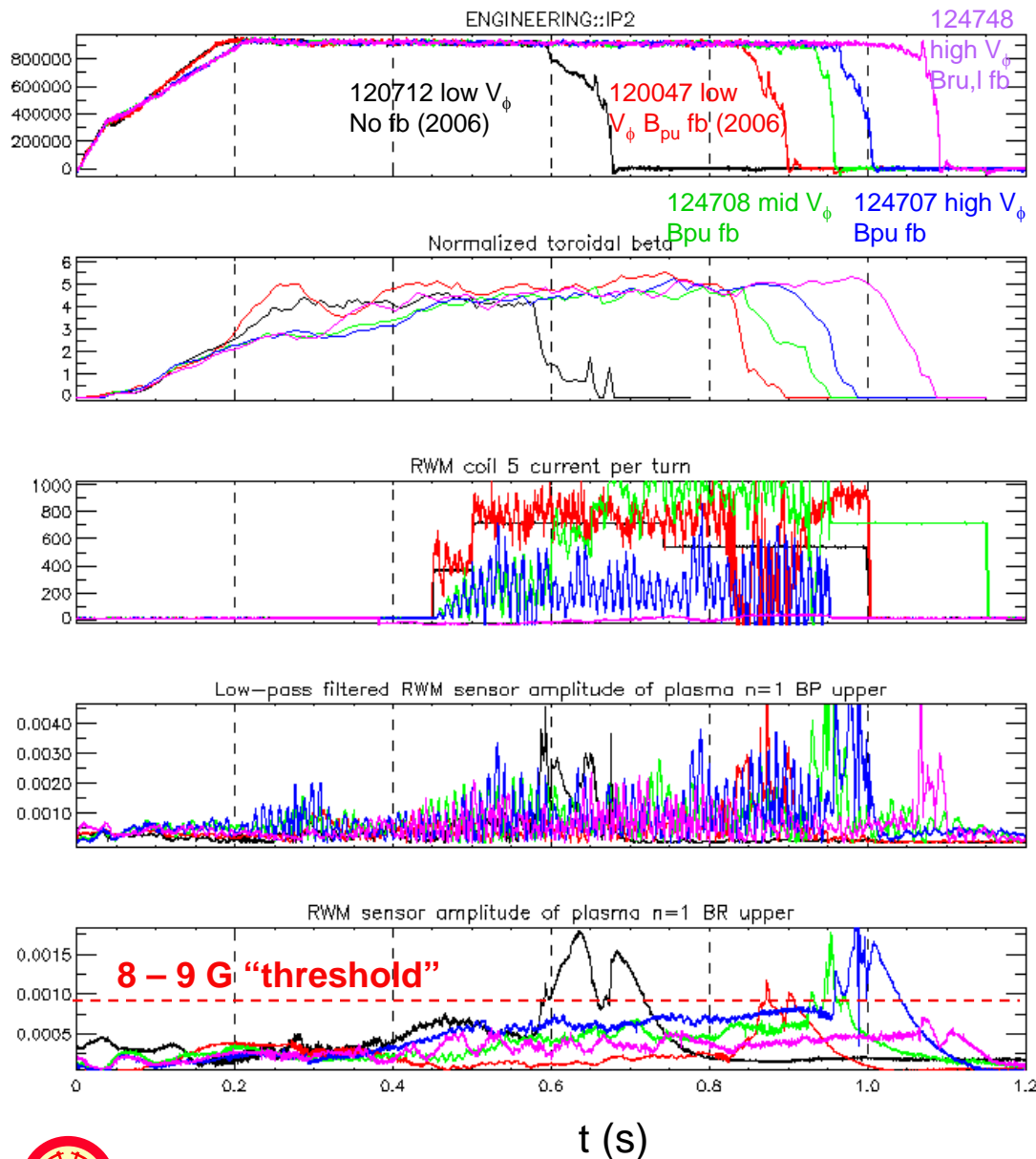
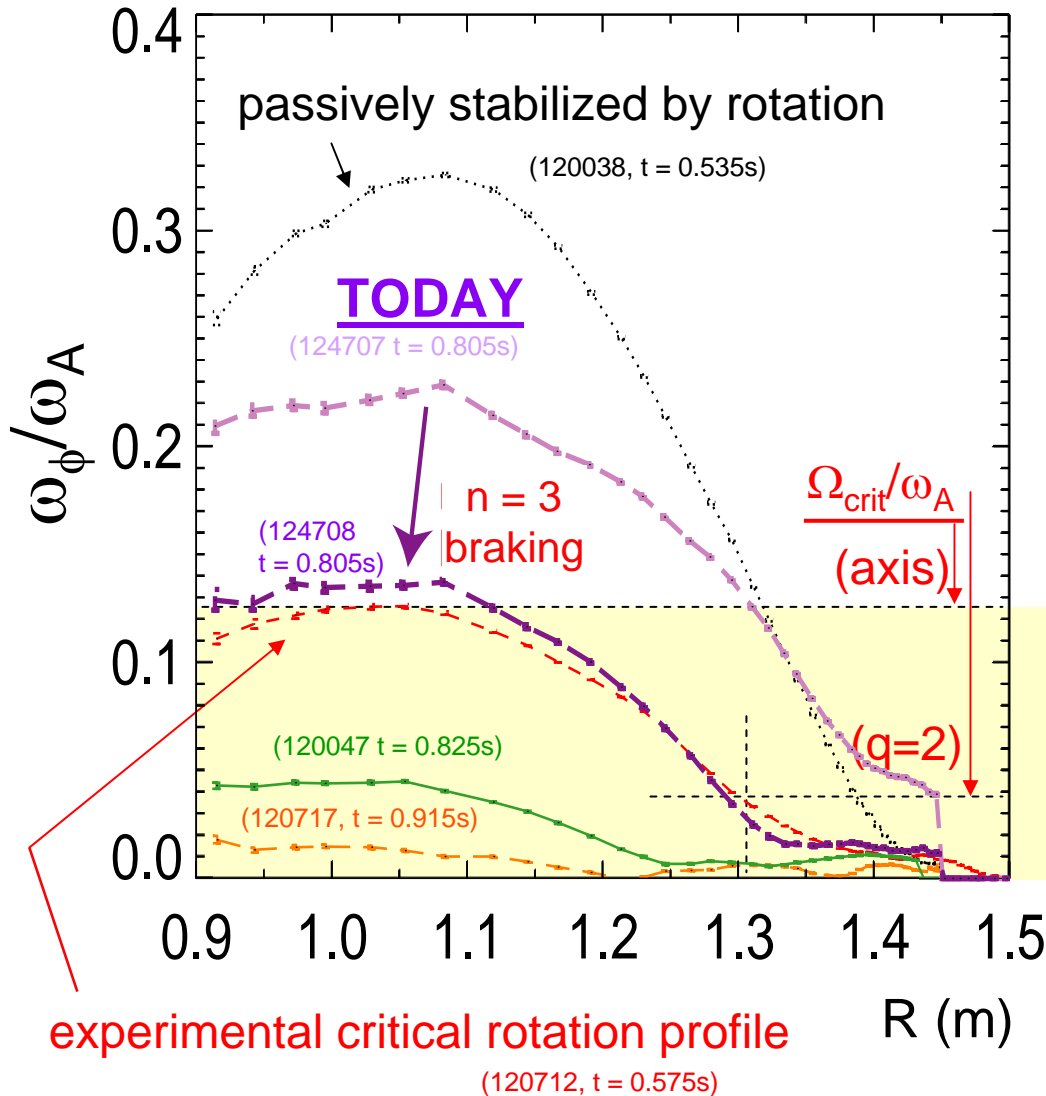


# XP728: RWM active stabilization – used $B_r$ sensors for feedback



- ❑ Completed phase scan for feedback with  $B_p^{\text{lower}}$  +  $B_p^{\text{upper}}$  sensors
- ❑ Determined feedback phase for best response with  $B_r^{\text{upper}}$  +  $B_r^{\text{lower}}$  sensors
  - ❑ Detailed feedback dynamics, apparent mode deformation
- ❑ Started second part of XP – dependence on  $V_\phi$ 
  - ❑ Feedback successful at high rotation
    - ~ 200A  $B_r$  correction
  - ❑ Reduced rotation profile to 2006 “critical rotation profile”
- ❑ Feedback using  $B_r^{\text{upper}}$  +  $B_r^{\text{lower}}$  sensors at high rotation available as tool for other XPs

# Rotation profiles produced during RWM feedback – XP728



- Produced broad, high rotation profiles with feedback

- $B_p, B_r$  feedback

- On last shot reduced rotation profile with n = 3 braking to “critical rotation profile”

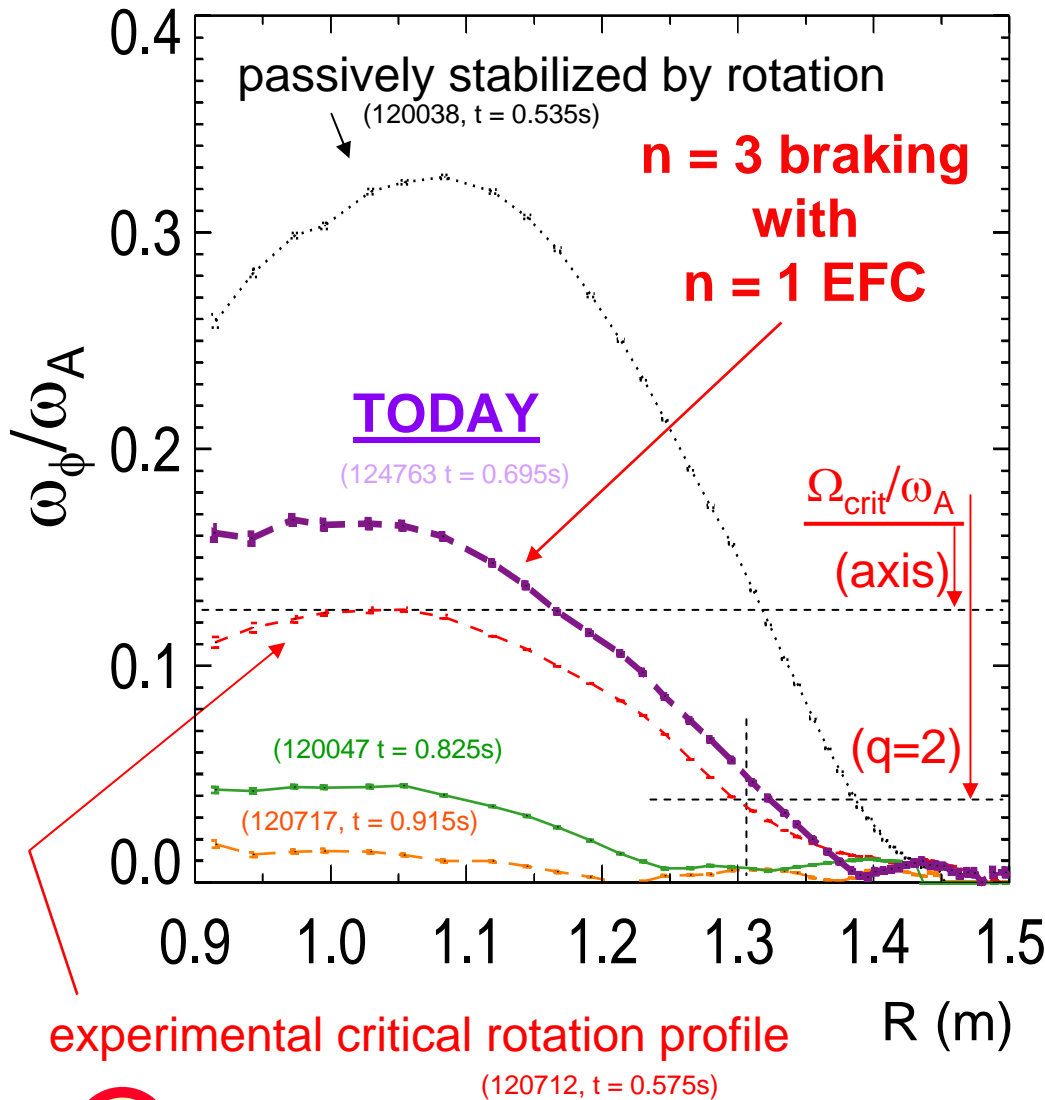
- To complete XP:

- Need to increase n = 3 braking to get KEY data at low rotation; vary phase

- Need to gate on/off feedback at low rotation < “critical profile”

# n = 1 error field correction applied to n = 3 braking – XP729

(A. Garofalo, et al.)



- n = 1 “optimal” error field correction currents found
  - Using Bpu sensors (iteration converged)
  - Using Bru + BrI sensors (diverged)
- Started n = 3 braking on last few shots
  - Reduced rotation to near “critical” rotation profile
- To complete XP:
  - Several shots with stronger n = 3 current
    - Will braking effect saturate?
    - Will  $\Omega_{crit}(\psi)$  change?