

# XP1023: Optimized RWM control for high $\langle \beta_N \rangle_{\text{pulse}}$ at low collisionality and $I_i$

S.A. Sabbagh, J.M. Bialek, S.P. Gerhardt, R.E.

Bell, J.W. Berkery, B. LeBlanc, J.E. Menard, et al.

*Department of Applied Physics and Applied Mathematics,  
Columbia University, New York, NY, USA*

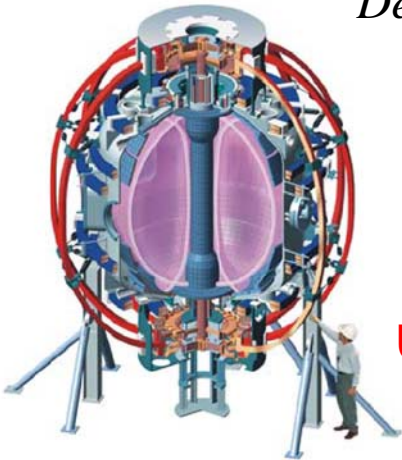
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**UPDATE on RWM  $B_R$ , and  $B_p + B_R$  sensor feedback**

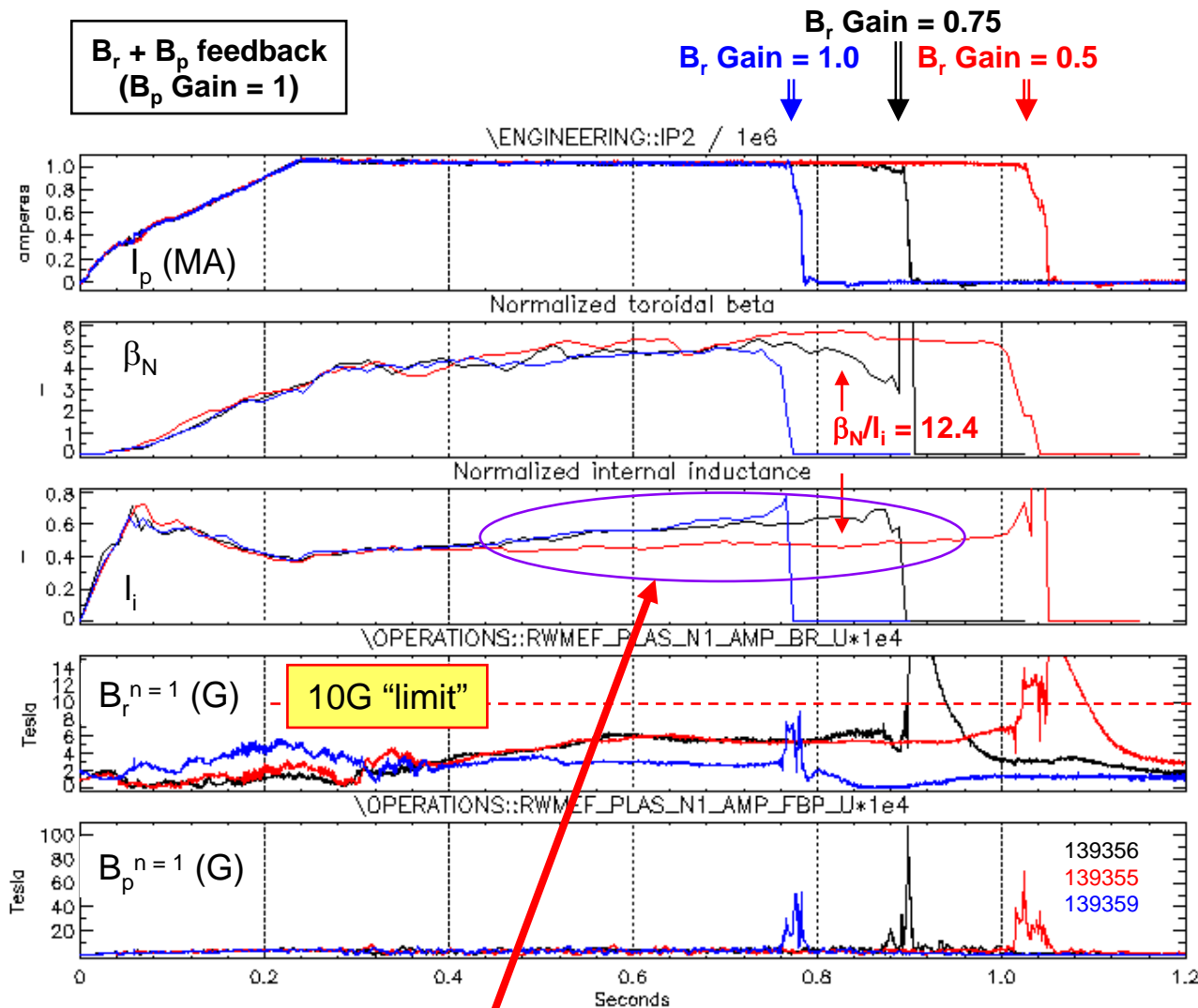
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# Original three point $B_r$ sensor feedback gain scan taken was invalid – due to radiated power excursions ( $I_i$ increases)

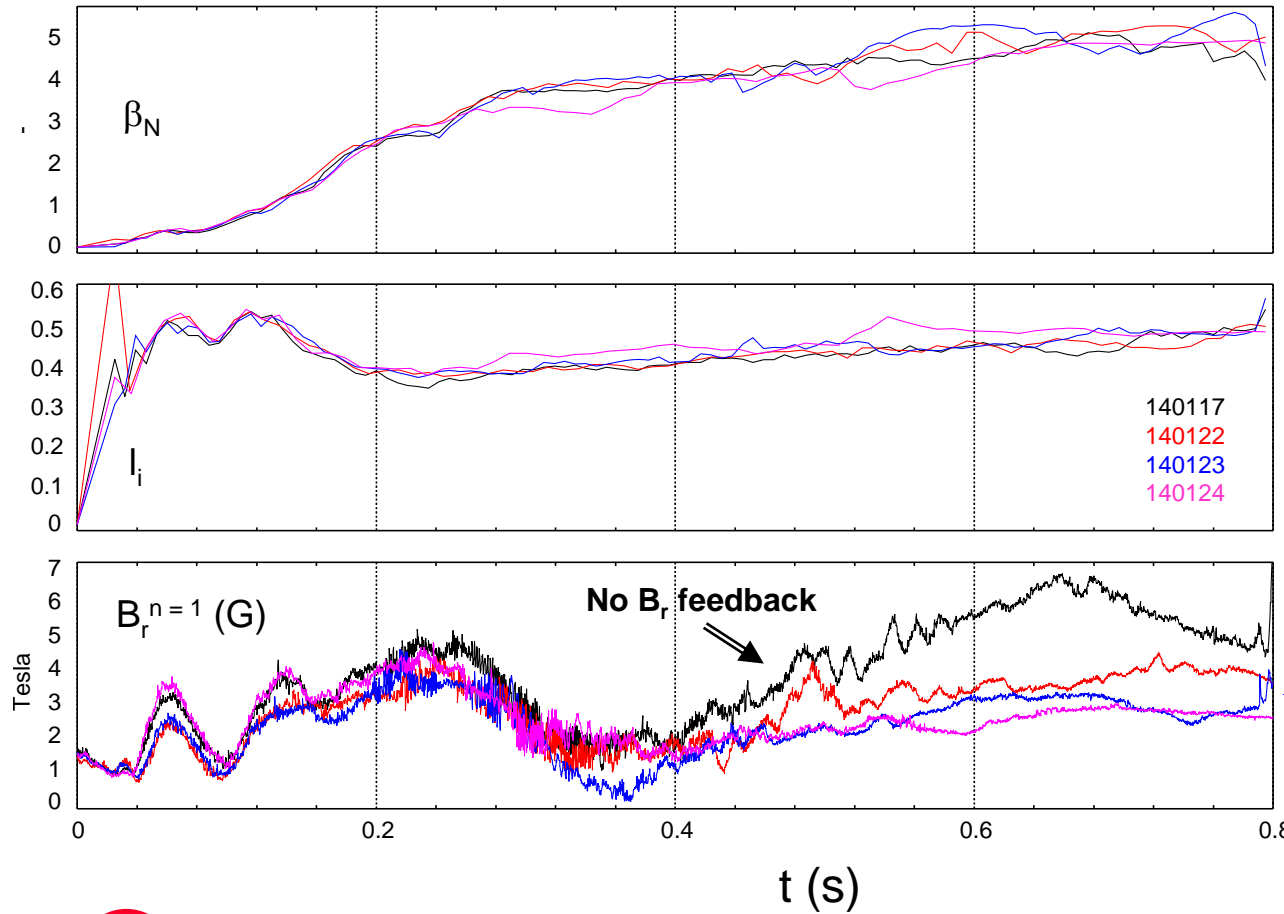


- Highest  $\beta_N/I_i$  of the day, long pulse length
  - $\beta_N/I_i = 12.4$  reached
    - NSTX highest value = 13
- Increased  $B_r$  sensor FB gain showed shorter pulse
  - $B_r$  feedback spatial phase may be optimized with  $B_p$  sensor FB
    - Further analysis needed
  - Results not yet optimized
    - Need to complete scans

# RWM $B_R$ sensor feedback reduces $n=1$ radial error field significantly

- New  $B_r$  sensor feedback gain scan taken on low  $I_i$  target plasmas

$B_R + B_p$  feedback  
( $B_p$  Gain = 1)



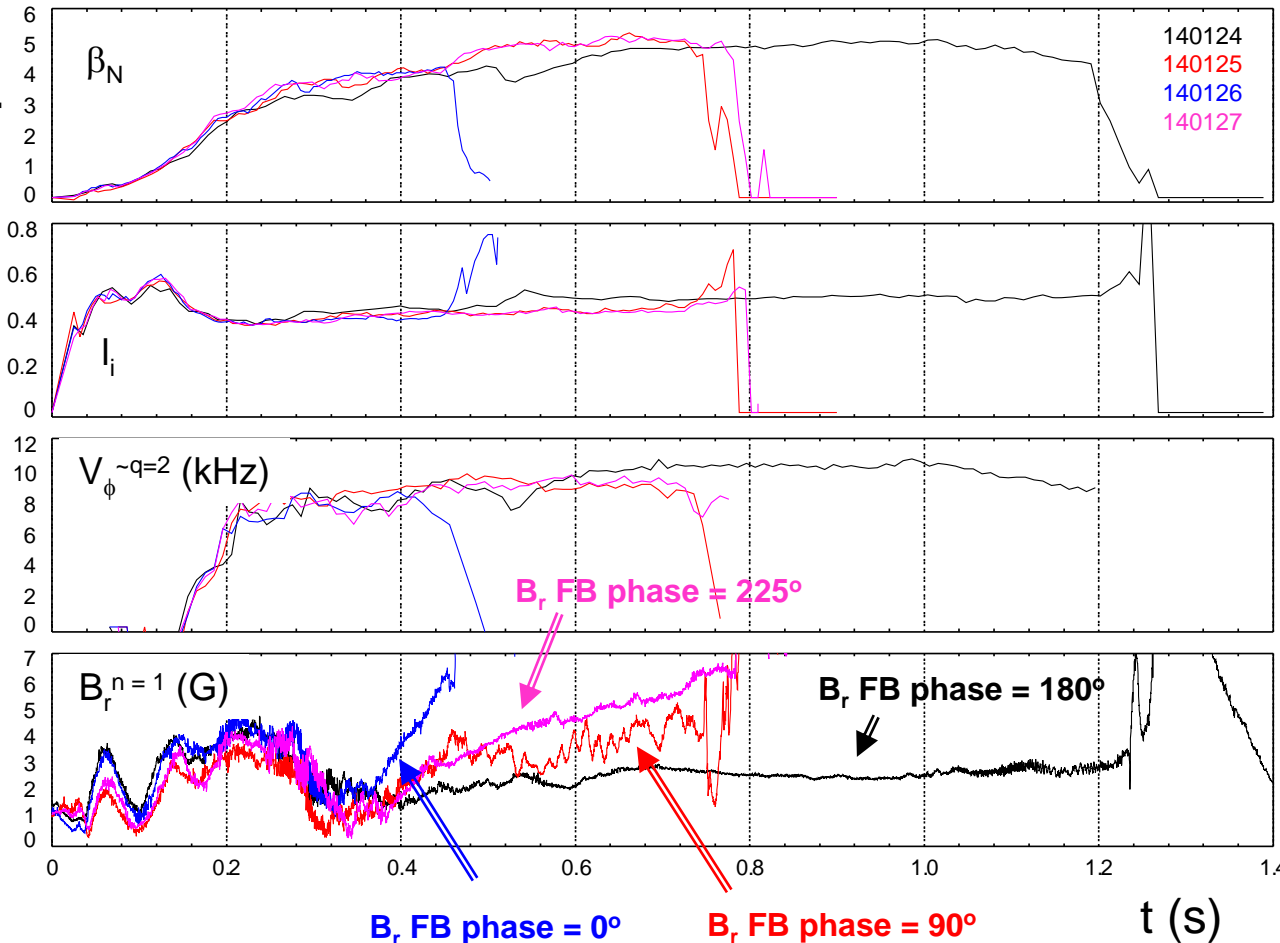
- Highest gain attempted (1.5) most favorable
- $B_r$  feedback constrains slow ( $\sim 10$  ms)  $n=1$  radial field growth
- $B_r^{n=1} = 9G$  consistently disrupts plasma

←  $B_r$  Gain = 1.0  
←  $B_r$  Gain = 1.25  
←  $B_r$  Gain = 1.50



# RWM $B_R$ sensor $n=1$ feedback phase variation shows clear settings for positive/negative feedback

$B_R + B_p$  feedback  
( $B_p$  Gain = 1,  $B_R$  Gain = 1.5)



- $B_r$  sensor feedback phase scan shows superior settings

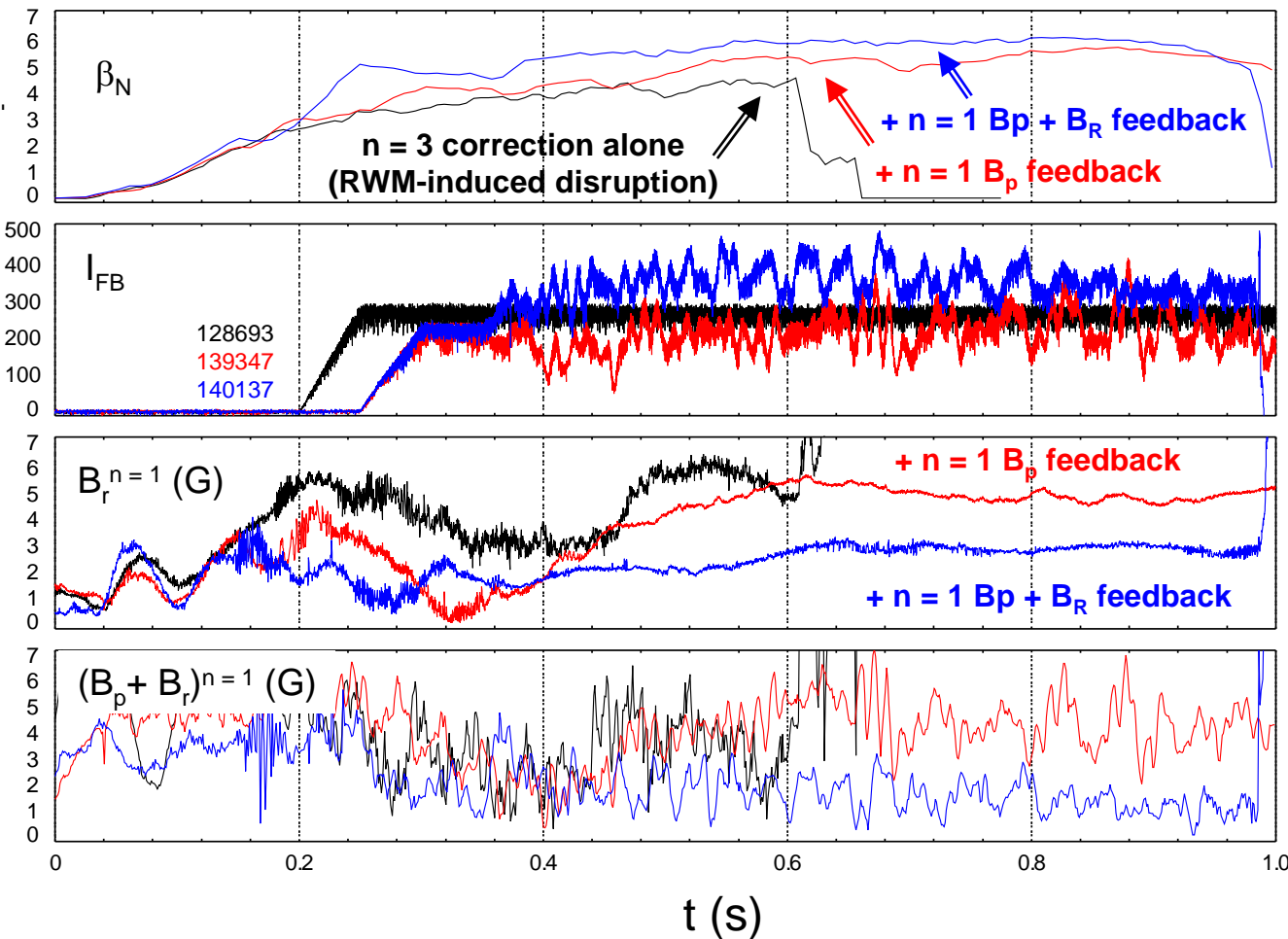
- Result clarified significantly by new MIU algorithm OHxTF compensation

- Positive/negative feedback produced at expected phase values

- 180° negative FB
  - 0° positive FB
  - $n=1$  growth/decay of other settings bracketed by 0°, 180° settings



# Use of combined RWM sensor $n=1$ feedback yields best reduction of $n=1$ fields / improved stability



- Varied levels of  $n > 1$  field correction

- $n = 3$  DC error field correction alone more subject to RWM instability
- $n = 1$   $B_p$  sensor fast feedback sustains plasma
- Addition of  $n = 1$   $B_R$  sensor FB prevents disruptions when amplitude reaches  $\sim 9$  G, better sustains rotation