

# A Tutorial on Bayesian Analysis for (Fusion) Science

Lisa Reusch  
Daniel Den Hartog



*Monday Physics meeting • NSTX, PPPL • Aug 15<sup>th</sup>, 2016*

- Motivation: Integrated Data Analysis (IDA) collaboration project
- Introduction to Bayesian Analysis
  - Fundamentals of Bayesian analysis
  - Example application of Te measurement using double-filter SXR diagnostic
- Application of Bayesian Analysis to IDA



# We aim to improve $T_e$ and $Z_{eff}$ measurement on NSTX-U using integrated data analysis (IDA).



- Over the next three years, we will concentrate on
  - increasing the accuracy, precision, and resolution (both spatial and temporal) of  $T_e$  and  $Z_{eff}$ 
    - Integrate Thomson scattering, Multi-color soft x-ray, charge-exchange recombination spectroscopy, and other diagnostics as appropriate and available
    - Initial priority is  $Z_{eff}$
- This project will also develop IDA expertise, with emphasis on new methods of multi-diagnostic and multi-parameter analysis.



# As fusion experiments become more complex, maximum scientific value must be extracted from data.



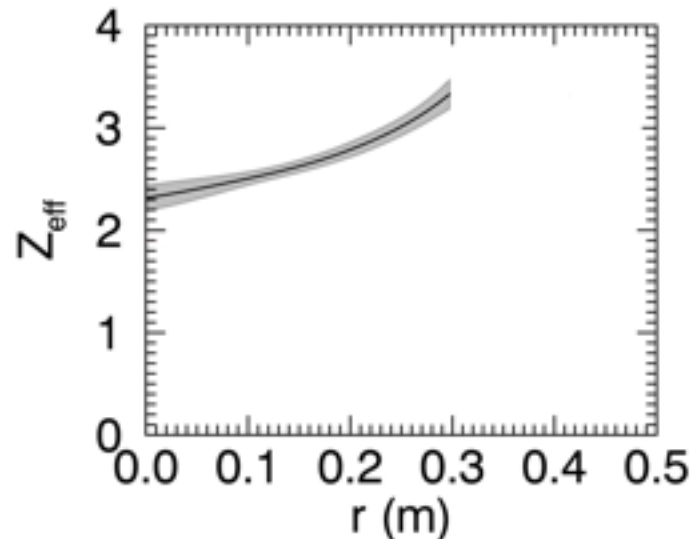
- As we transition to fusion experiments that are full nuclear environments
  - severe limitations will be imposed on diagnostics
- A representative example from the ITPA Diagnostics group of the measurement challenges on ITER:
  - Action Item 20a353, “Can we get  $Z_{eff}$  from other measurements?”
    - No dedicated single-chord visible bremsstrahlung measurement is currently planned for installation on ITER



# Integrated Data Analysis (IDA) provides a framework to deal with measurement limitations.



- The goal of IDA is to
  - combine data from heterogeneous and complementary diagnostics
  - consider all dependencies within and between diagnostics
  - obtain the most reliable results in a transparent and standardized way.
- Increased measurement precision/resolution is a typical result of IDA.
- IDA additionally enables formation of “meta-diagnostics,” which combine information from various instruments to produce unique measurements.
  - $Z_{eff}$  on MST obtained by combining information from CHERS and SXR:



# Integrated Data Analysis is often accomplished using a Bayesian statistical framework.



- Highly modular
- Consistent and automatic error analysis
- Can include background/physics information into the analysis quantitatively



- Motivation: Integrated Data Analysis (IDA) collaboration project
- **Introduction to Bayesian Analysis**
  - Fundamentals of Bayesian analysis
  - Example application of Te measurement using double-filter SXR diagnostic
- Application of Bayesian Analysis to IDA



# Good sources for learning more about Bayesian Analysis



- Sivia D.S. and Skilling J., *Data Analysis: a Bayesian Tutorial 2nd edn* (Oxford: Oxford University), 2006
- Von Toussaint, U., “Bayesian Inference in physics,” *Rev. Mod. Phys.* **83**





# Bayesian analysis has an alternate view of data interpretation



- In a classical approach to data analysis
  - An objective Truth exists (i.e. a single right answer)
  - Measurements sample that Truth imperfectly.
  - Repeated measurements reveal the underlying Truth.
- A Bayesian approach
  - Has is a truth, but it is more subjective. (For example, the data itself is the truth—it's the physical entity that can be measured.)
  - Attempts to determine what we can learn from a single measurement or a limited number of measurements.



# The foundations of Bayesian Analysis are Bayes' Rule and Marginalization



Bayes' Rule:

$$P(x | y, I) = \frac{P(y | x, I)P(x | I)}{P(y | I)}$$

Marginalization:

$$P(x | y, I) = \int P(x, \alpha | y, I) d\alpha$$



# Estimation of electron temperature takes the form



$$\underbrace{P(T_e | D, \sigma)}_{\textit{Posterior}} = \frac{\overbrace{P(D | T_e, \sigma)}^{\textit{Likelihood}} \overbrace{P(T_e | \sigma)}^{\textit{Prior}}}{\underbrace{P(D | \sigma)}_{\textit{evidence}}}$$

- $T_e$  is electron temperature, the desired parameter
- $D$  is the diagnostic data, i.e. the actual measurement made
- $\sigma$  is the uncertainty of the system



# The posterior is the desired result



$$\underbrace{P(T_e | D, \sigma)}_{\text{Posterior}} = \frac{\overbrace{P(D | T_e, \sigma)}^{\text{Likelihood}} \overbrace{P(T_e | \sigma)}^{\text{Prior}}}{\underbrace{P(D | \sigma)}_{\text{evidence}}}$$

- Can be interpreted as the result and error bar.
- Can be calculated directly
  - Often involves inversions or fitting routines
  - Often lacks uncertainty information



The Likelihood Function relates the measurement to the parameter of interest through modeling.



$$\underbrace{P(T_e | D, \sigma)}_{\textit{Posterior}} = \frac{\overbrace{P(D | T_e, \sigma)}^{\textit{Likelihood}} \overbrace{P(T_e | \sigma)}^{\textit{Prior}}}{\underbrace{P(D | \sigma)}_{\textit{evidence}}}$$

- Involves forward models of the system
  - Physical processes generating signal
  - Instrumentation effects
- Is often easier to calculate than the posterior probability
- Can incorporate systematic and statistical uncertainties in a straightforward way



# The Prior probability reflects our background knowledge about the system



$$\underbrace{P(T_e | D, \sigma)}_{\textit{Posterior}} = \frac{\overbrace{P(D | T_e, \sigma)}^{\textit{Likelihood}} \overbrace{P(T_e | \sigma)}^{\textit{Prior}}}{\underbrace{P(D | \sigma)}_{\textit{evidence}}}$$

- Often this is a range of values in which we expect the answer to lie.
- Often informed by physical constraints
  - $T_e$  must be positive
  - Must be within the measurement range of the diagnostic



# The evidence is a normalization factor



$$\underbrace{P(T_e | D, \sigma)}_{\textit{Posterior}} = \frac{\overbrace{P(D | T_e, \sigma)}^{\textit{Likelihood}} \overbrace{P(T_e | \sigma)}^{\textit{Prior}}}{\underbrace{P(D | \sigma)}_{\textit{evidence}}}$$

- Can be ignored for parameter estimation problems
- Often important when choosing between 2 or more models
- Bayes' Rule becomes:

$$\underbrace{P(T_e | D, \sigma)}_{\textit{Posterior}} \propto \overbrace{P(D | T_e, \sigma)}^{\textit{Likelihood}} \overbrace{P(T_e | \sigma)}^{\textit{Prior}}$$



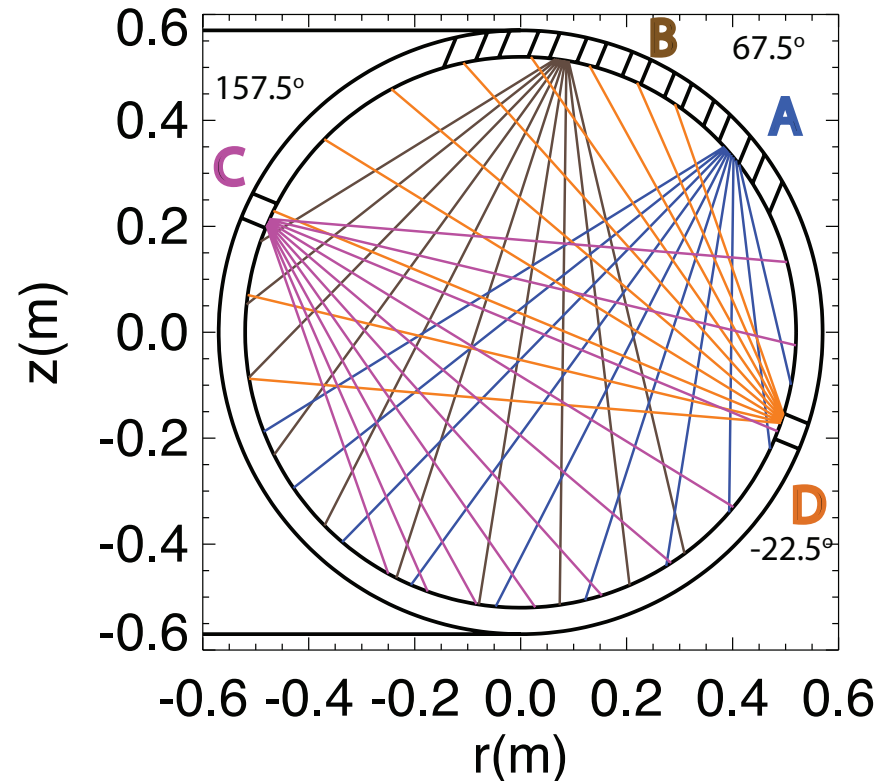
- Motivation: Integrated Data Analysis (IDA) collaboration project
- Introduction to Bayesian Analysis
  - Fundamentals of Bayesian analysis
  - **Example application of Te measurement using double-filter SXR diagnostic**
- Application of Bayesian Analysis to IDA





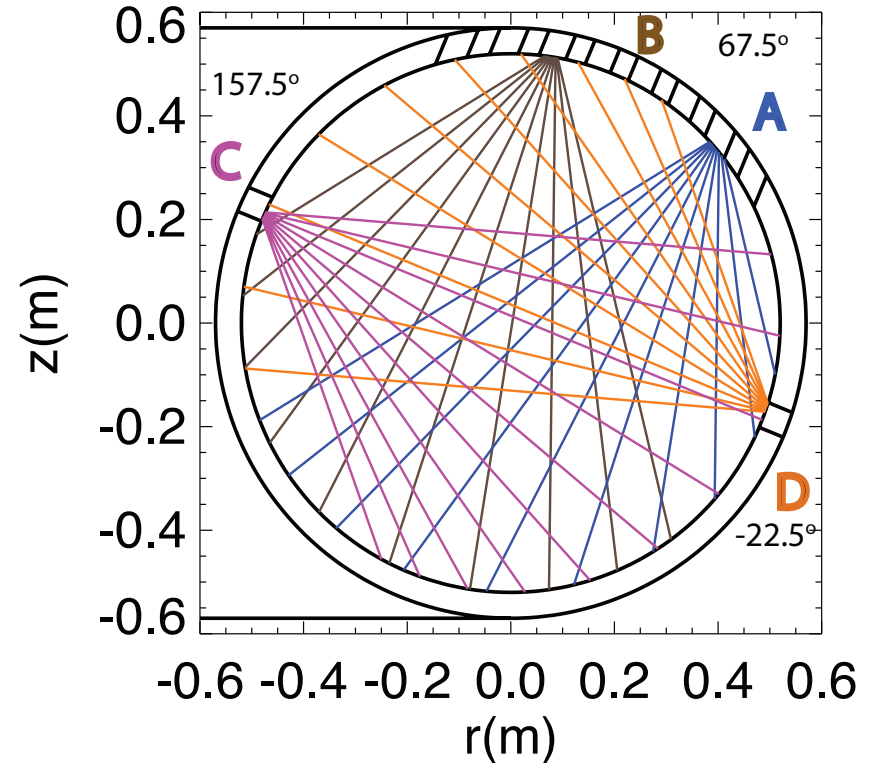
# The two-color SXR tomography system contains $T_e$ information in a poloidal cross-section.

- 40 unique lines of sight at one toroidal location
  - Two detectors: 425  $\mu\text{m}$  and 800  $\mu\text{m}$  Be filters
- Thicknesses chosen to block high energy emission lines
- Different thickness filters allow estimation of x-ray spectrum slope



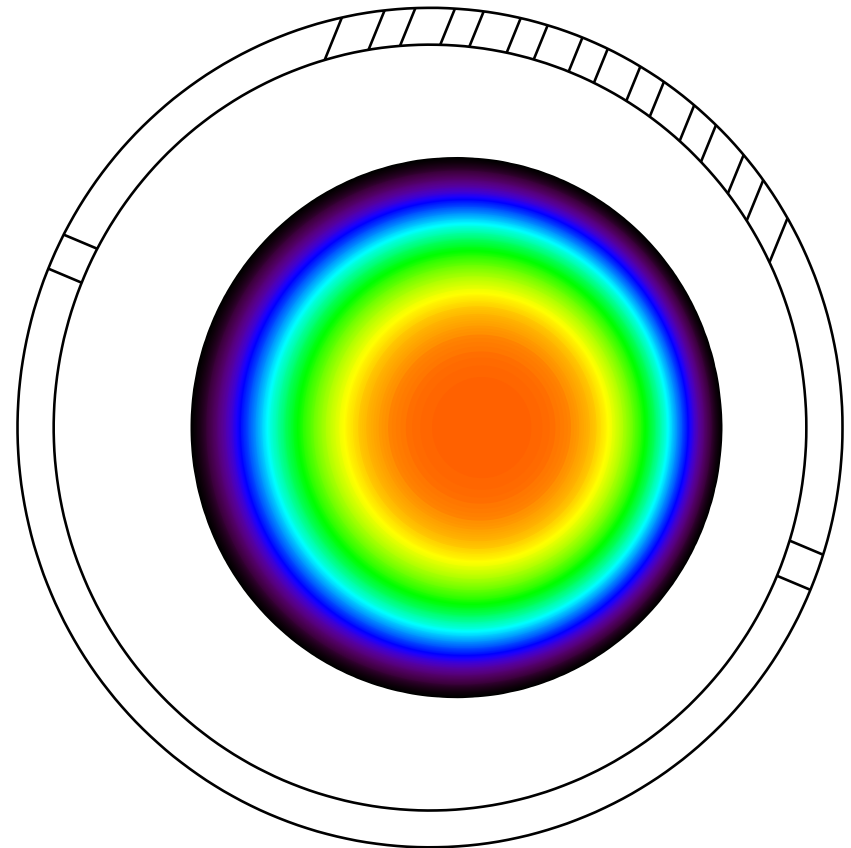
# Two-color SXR tomography system is capable of measuring $T_e$ .

- $f \sim n_e Z_{\text{eff}} T_e^{-1/2} e^{-E/T_e}$   
+ *recomb*
- Detectors that share a line of sight have same  $n_e$ ,  $Z_{\text{eff}}$ , and recombination.
- $\frac{f_{\text{thin}}}{f_{\text{thick}}} \sim T_e$
- The relationship of the measured ratio to  $T_e$  is not straightforward.



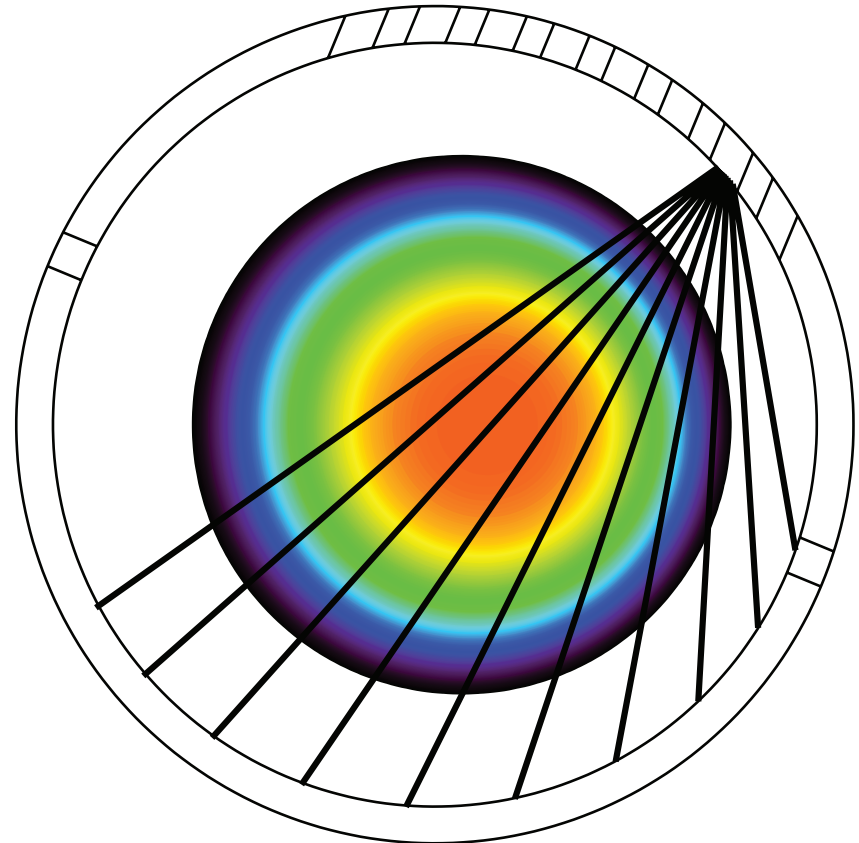
# SXR forward model predicts x-ray emissivity on a 2-dimensional grid.

- Three parameter function for  $T_e$  profile used (axisymmetric)  
$$T_e(r) = T_{e0}(1 - (r/a)^\alpha)^\beta$$
- Ansatz profiles for density and  $Z_{\text{eff}}$  used.



# Predicted brightness based on x-ray emissivity calculated for each detector

- Predicted brightness takes into account:
  - Geometry of line of sight
  - Detector effects
  - Be filter effects
- Predicted ratio,  $R_p$ , calculated from predicted brightness



# Likelihoods follow a Gaussian distribution.



- SXR detection relies on sensing photons → Poisson distributions
- In the limit of large numbers of photons, they are Gaussian distributions.

$$P(D_{SXR} | T_e(r), \sigma) = \frac{1}{\sqrt{2\sigma^2}} e^{-\chi^2}$$

$$\chi^2 = \frac{(R_m - R_p)^2}{2\sigma^2}$$

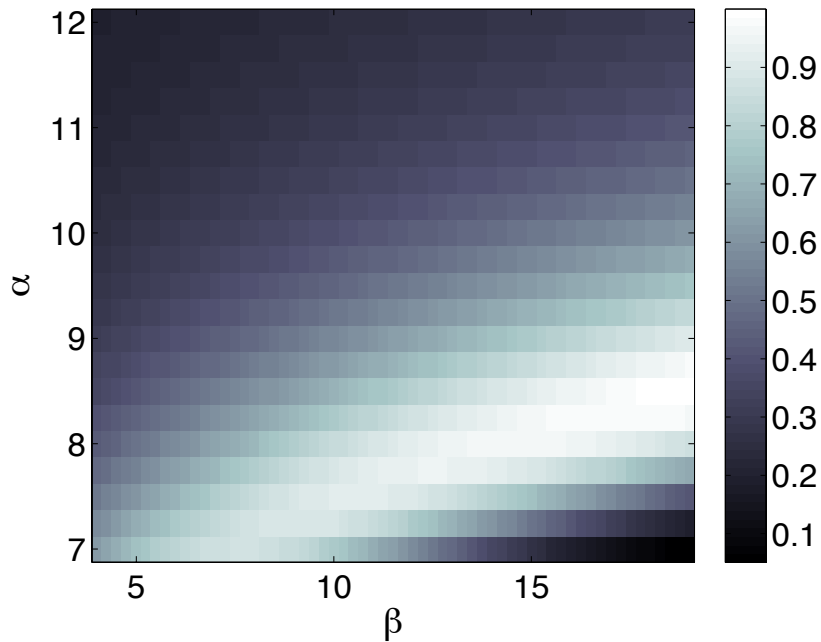
- $\sigma$  contains both the statistical and systematic sources of uncertainty
- Systematic uncertainties estimated from:
  - Tolerances and Machining precision
  - Filter thickness measurements
  - Filter calibrations



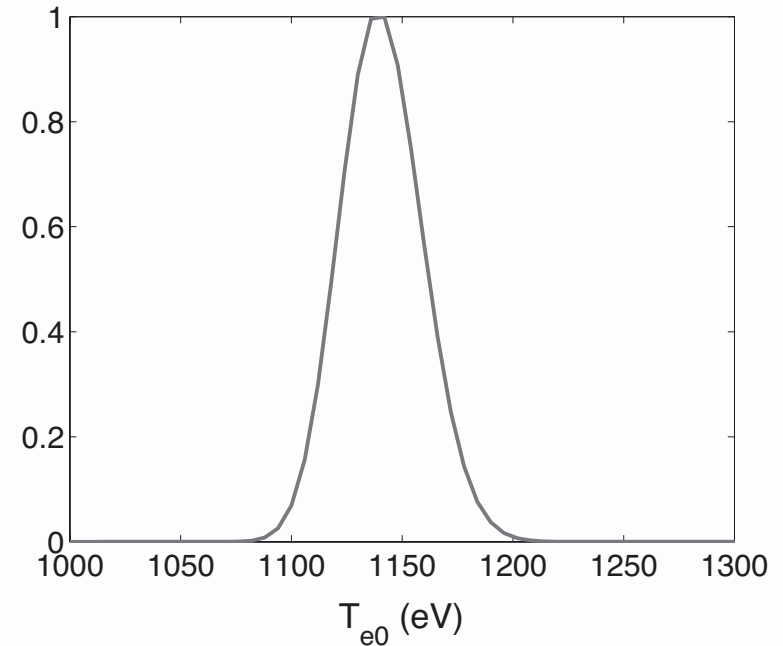
# Likelihood function are often multidimensional



$$P(D_{SXR} | T_e(r), \sigma) \rightarrow P(D_{SXR} | T_{e0}, \alpha, \beta, \sigma)$$



Marginalized core  $T_e$   
( $T_{e0}$ )



Marginalized edge gradient  
( $\alpha$  and  $\beta$ )



# Prior distributions can be uniform PDFs over a range informed by experiment

Parameter	Range
$T_{e0}$	500-2300 eV
$\alpha$	7-12
$\beta$	4-19

$$P(T_{e0}) = \begin{cases} \frac{1}{2300 - 500} & \text{for } 500 \leq T_{e0} \leq 2300 \\ 0 & \text{otherwise} \end{cases}$$

$$P(\alpha) = \begin{cases} \frac{1}{12 - 7} & \text{for } 7 \leq \alpha \leq 12 \\ 0 & \text{otherwise} \end{cases}$$

$$P(\beta) = \begin{cases} \frac{1}{19 - 4} & \text{for } 4 \leq \beta \leq 19 \\ 0 & \text{otherwise} \end{cases}$$

- Likelihood functions calculated on uniform grid of points covering these ranges



The posterior probability is the answer desired



$$P(T_e(r) | D_{SXR}, \sigma) \propto \underbrace{P(D_{SXR} | T_{e0}, \alpha, \beta, \sigma)}_{\text{Likelihood function}} \underbrace{P(T_{e0})P(\alpha)P(\beta)}_{\text{Priors}}$$

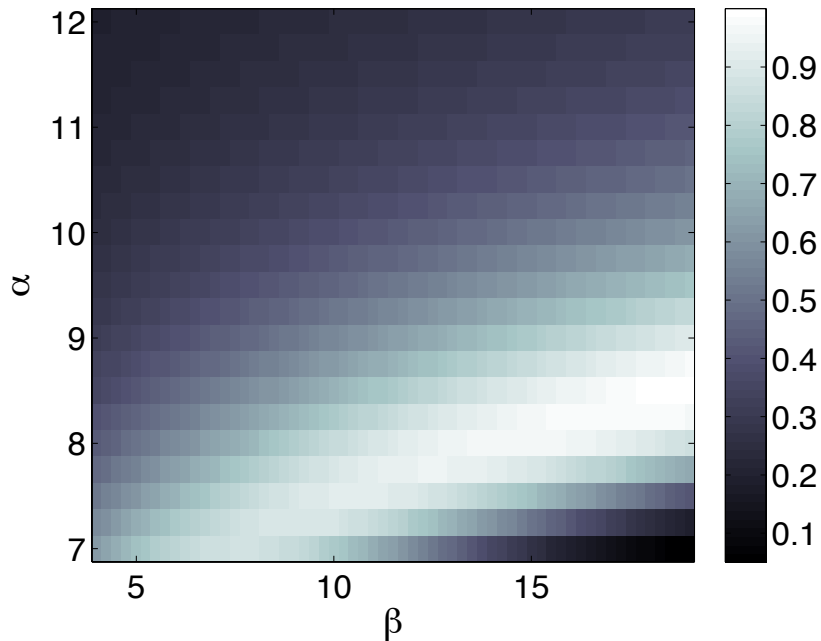




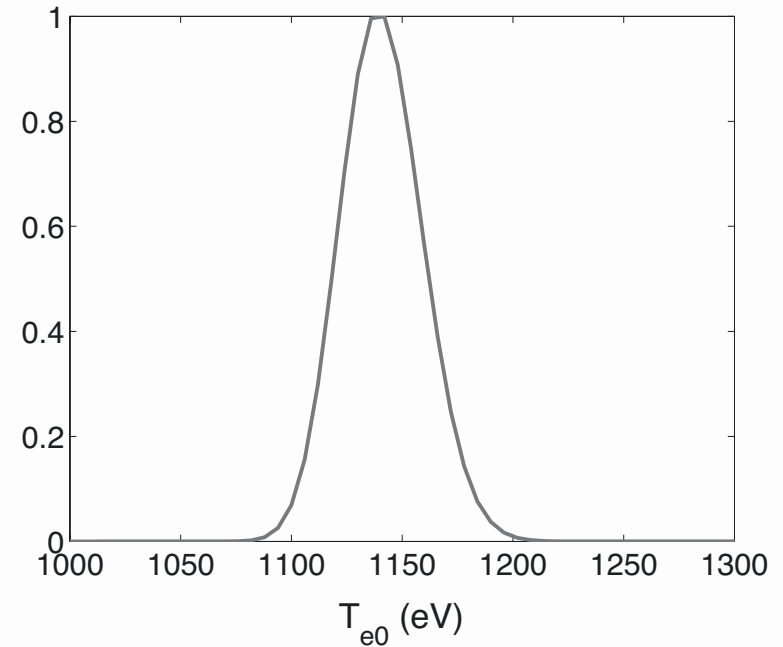
# The posterior probability is the answer desired



$$P(T_e(r) | D_{SXR}, \sigma) \propto \underbrace{P(D_{SXR} | T_{e0}, \alpha, \beta, \sigma)}_{\text{Likelihood function}} \underbrace{P(T_{e0})P(\alpha)P(\beta)}_{\text{Priors}}$$



Marginalized core  $T_e$



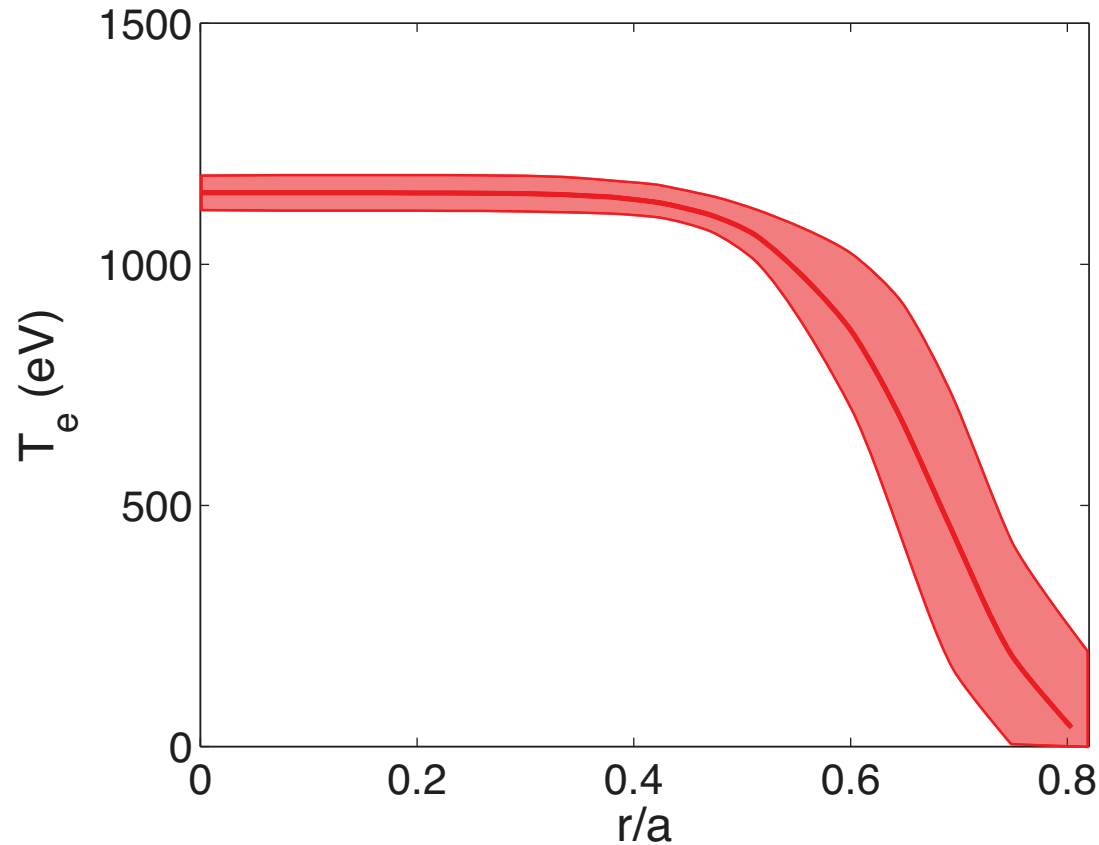
Marginalized edge gradient



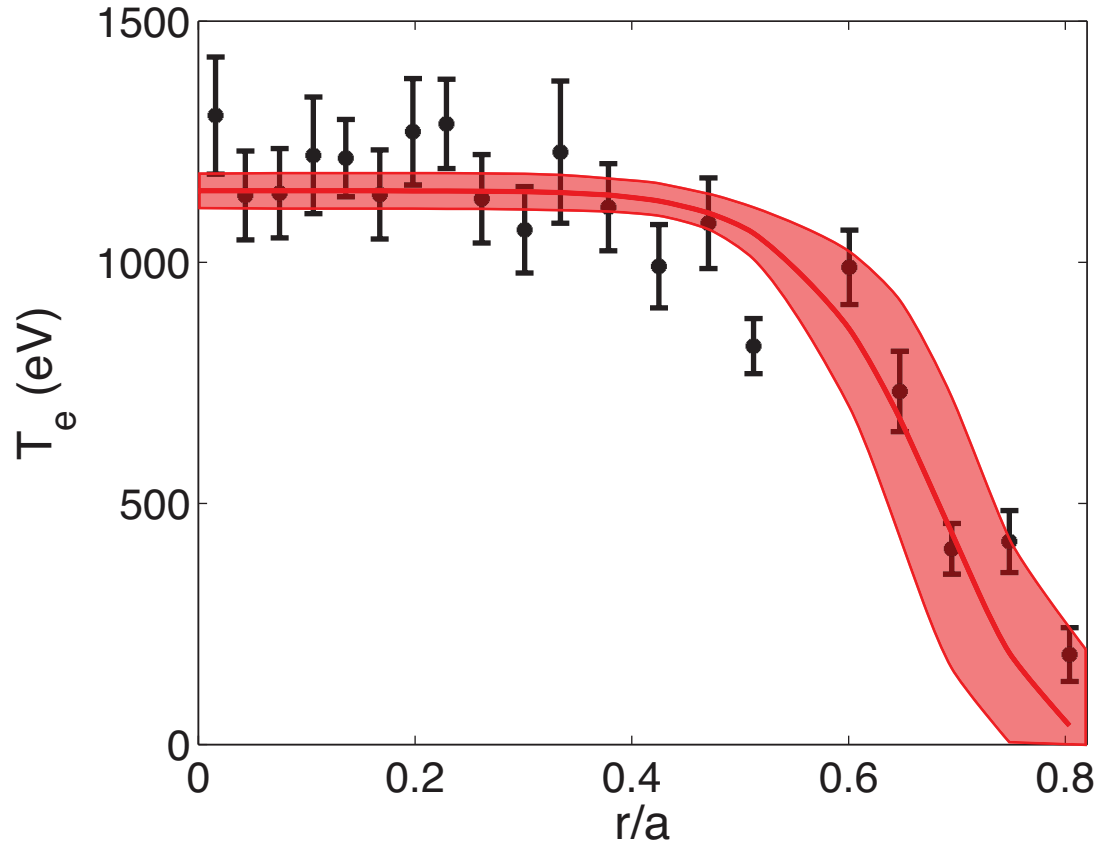
# The result is the most likely $T_e$ profile



$$P(T_e(r) | D_{SXR}, \sigma) \propto \underbrace{P(D_{SXR} | T_{e0}, \alpha, \beta, \sigma)}_{\text{Likelihood function}} \underbrace{P(T_{e0})P(\alpha)P(\beta)}_{\text{Priors}}$$



The most likely  $T_e$  profile agrees well with TS.

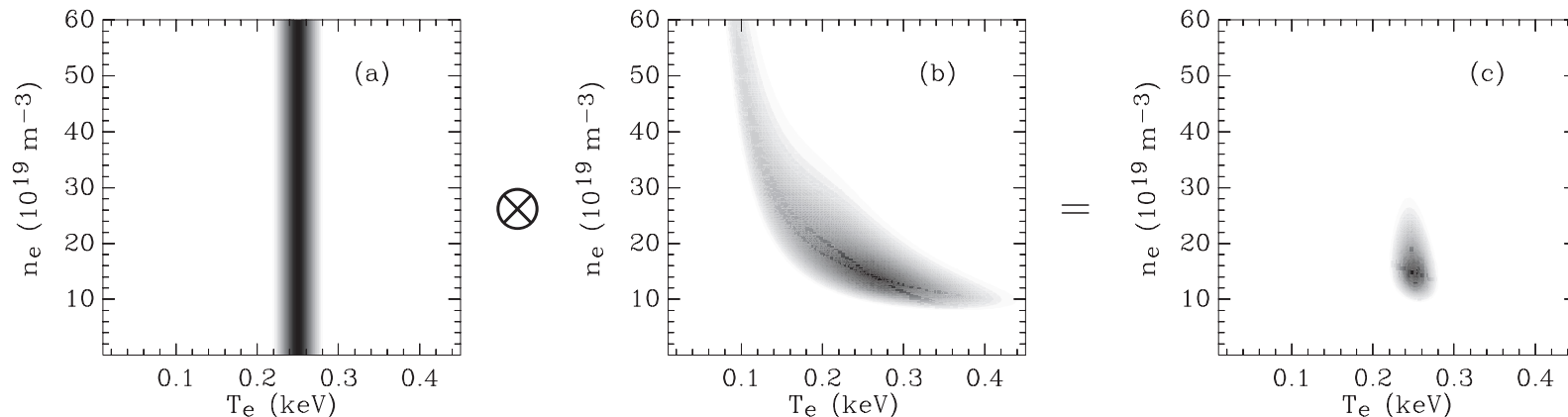


This is the most likely profile assuming the plasma is axisymmetric



- Motivation: Integrated Data Analysis (IDA) collaboration project
- Introduction to Bayesian Analysis
  - Fundamentals of Bayesian analysis
  - Example application of Te measurement using double-filter SXR diagnostic
- **Application of Bayesian Analysis to IDA**

# Integrated Data Analysis in a Bayesian framework proceeds with a series of steps:



- Identify uncertainties and quantify with probability distribution functions (PDF)
- Combine all relevant information within a probabilistic framework
  - include diagnostic models and prior knowledge
  - develop a forward model for measurement
  - marginalize out nuisance parameters such as systematic effects
- Search parameter space, which is often high-dimensional
- Final result is the posterior PDF of the quantity of interest

R. Fischer, A. Dinklage, and E. Pasch, “Bayesian modelling of fusion diagnostics,” *Plasma Phys. Control. Fusion* **45**, 1095–1111 (2003).



- Many Diagnostics are sensitive to  $Z_{\text{eff}}$ 
  - Near infrared / Visible Bremsstrahlung
  - Charge exchange recombination spectroscopy (CHERS)
  - Soft x-ray (SXR)
  - Neutral beam attenuation
  - Thomson Scattering background light
  - Loop voltage
  - ...etc.

$$P(Z_{\text{eff}} | SXR, \text{CHERS}, \dots) \propto L_{SXR} \times L_{\text{CHERS}} \times \dots \times \text{Priors}$$

$$e.g. L_{SXR} \sim P(SXR | Z_{\text{eff}})$$



- We have started developing an IDA technique using a Bayesian probability framework to improve  $T_e$  and  $Z_{\text{eff}}$  measurements on NSTX-U
- The fundamental ideas in Bayesian Analysis are:
  - Bayes' Rule: 
$$P(x | y, I) = \frac{P(y | x, I)P(x | I)}{P(y | I)}$$
  - Marginalization: 
$$P(x | y, I) = \int P(x, \alpha | y, I) d\alpha$$
- Consideration of all assumptions, background physical knowledge and uncertainties are necessary when developing a Bayesian approach to the analysis of a diagnostic.
- Bayesian Analysis is a natural framework in which to develop IDA due its
  - Modularity
  - Automatic error analysis
  - Ability to include background information in the analysis

