Modeling the Scaling Law for Error Field (EF) Penetration by Using TM1

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Simple error field penetration scalings set the tolerances & correction-coil designs for new machines like ITER

Successes

- Scaling done using simplest possible 0D parameters: n_e, B_T, R₀, β_N/ℓ_i
- Robust perturbation metric, δ, incorporates plasma response

$$b_{\rm r} \propto n_e^{0.5} B_{\rm t}^{-1.0} R_0^{0.1} (\beta_{\rm N}/l_i)^{-0.2} f_0$$



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Challenges

- Profile effects not captured by 0D parameters
- Theoretical prediction isn't enough to address the scaling
- Biases & gaps in database cause, residual EFs

$$b_{\rm r} \propto n_e^{0.5} B_{\rm t}^{-1.0} R_0^{0.1} (\beta_{\rm N}/l_i)^{-0.2} f_0$$



EF scaling studies in experiments are more complicated than expected due to the coupling of plasma parameters



The coupling of plasma parameters makes EF scaling complicated

N.C. Logan, et al., Challenges projecting EF correction tolerance 24th MHD workshop, 2019
 B.A. Grierson, et al., Phys. Plasmas 26, 042304 (2019)

Analytical theory is not enough to address the EF scaling

1-fluid scaling from Fitzpatrick's theory [1]

- $b_r/B_t \propto n_e^{3/5} \tau_V^{-3/5} T_e^{3/5} f_0$ Rutherford regime
- $b_r/B_{\rm t} \propto n_e^{7/12} \tau_{\rm V}^{-7/12} T_e^{5/8} f_0$
- $b_r/B_t \propto n_e^{1/2} \tau_V^{-1/2} T_e^{11/20} f_0^{4/5}$ Transition regime

Visco-resistive regime

 $b_r/B_{\rm t} \propto n_e^{7/16} \tau_{\rm V}^{-7/16} T_e^{9/32} f_0^{5/8}$ Waelbroeck regime

No density dependence according to Neo-Alcator scaling [2]

$$\tau_{\rm V} \propto \tau_{\rm E} \propto n_{\rm e} \implies b_r / B_{\rm t} \propto n_e^0$$

[1] R. Fitzpatrick, PPOP**5**, 3325 (1998)[2] W. Pfeiffer and R.E. Waltz, NF **19**, 51 (1979)

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1-fluid scaling from Fitzpatrick's theory [1]

$$\begin{split} b_r/B_{\rm t} &\propto n_e^{3/5} \tau_{\rm V}^{-3/5} T_e^{3/5} f_0 \\ b_r/B_{\rm t} &\propto n_e^{7/12} \tau_{\rm V}^{-7/12} T_e^{5/8} f_0 \\ b_r/B_{\rm t} &\propto n_e^{1/2} \tau_{\rm V}^{-1/2} T_e^{11/20} f_0^{4/5} \\ b_r/B_{\rm t} &\propto n_e^{7/16} \tau_{\rm V}^{-7/16} T_e^{9/32} f_0^{5/8} \end{split}$$

No density dependence according to **Neo-Alcator scaling** [2]

 $\tau_{\rm V} \propto \tau_{\rm E} \propto n_{\rm e} \implies b_r / B_{\rm t} \propto n_e^0$

$b_r/B_t \propto T_e^{1/6} B_t^{-1} R_0^{-7/6}$

 $b_r/B_t \propto n_e^{1/4} T_e^{1/8} B_t^{-5/4} R_0^{-1}$ SC regime

Nonlinear 2-fluid scaling [4]

Linear 2-fluid scaling [3]

Polarization $b_r/B_t \propto n_e B_t^{-9/5} R_0^{-1/4}$ regime

Inconsistent with observed n^{0.5}, no rotation scaling

[1] R. Fitzpatrick, PPOP**5**, 3325 (1998) [2] W. Pfeiffer and R.E. Waltz, NF 19, 51 (1979) [3] A. Cole and R. Fitzpatrick, POP 13, 032503 (2006) [4] R. Fitzpatrick, PPCF 54, 094002 (2012)

VR regime

Analytical theory is not enough to address the EF scaling

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Linear 2-fluid scaling [3]

 $b_r/B_t \propto T_e^{1/6} B_t^{-1} R_0^{-7/6}$ VR regime

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Motivation:

- Examine EF scaling law under single-fluid and two-fluid conditions
- Examine the scaling difference in core and edge (pedestal) penetration
- ✓ Predict the level of penetration threshold in ITER

 [1] R. Fitzpatrick, PPOP**5**, 3325 (1998)
 [3] A. Cole and R. Fitz

 [2] W. Pfeiffer and R.E. Waltz, NF **19**, 51 (1979)
 [4] R. Fitzpatrick, PPCI

[3] A. Cole and R. Fitzpatrick, POP 13, 032503 (2006)
[4] R. Fitzpatrick, PPCF 54, 094002 (2012)

Outline

- TM1 modeling of 3/2 EF threshold scaling
 - \rightarrow Single-fluid modeling: well reproduced Fitzpatrick's theory
 - \rightarrow Two-fluid modeling: sensitive scaling on plasma rotation
- TM1 modeling pedestal-top n=2 RMP threshold scaling
 - \rightarrow Two-fluid modeling: similar with core scaling
- Prediction for ITER
- Summary

Nonlinear MHD Model TM1 is Used to Simulate EF penetration

- Cylindrical geometry, circular cross-section
- Nonlinear, resistive, two-fluid model [1]:

 - Able to perform modeling under single-fluid or two-fluid conditions
 - Two-fluid condition includes diamagnetic drift effect, and ion polarization current in transport
 - Long time-dependent modeling with > 1 s evolution

[1] Q. Yu, et al., POP 10, 797 (2004); NF 51, 073030 (2011)
 S. Gunter, et al., JCP 209, 354 (2005)

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• TM1 modeling pedestal-top n= $\frac{d\psi}{dt} = E - \eta j + \Omega(\nabla_{\mu} \mathbf{B}_{e^{-1}} - \nabla_{\mu} T_{e})$ Diama Diamagnetic → Two-fluid modeling: simil $\frac{du}{dt} = -C_s^2 \nabla_{\parallel} P / n_e + \mu_{\perp} \nabla_{\perp}^2 u$ $\rho \frac{\mathrm{d}}{\mathrm{dt}} \nabla^2 \phi = \vec{\mathbf{e}}_{\varphi} \cdot (\nabla \psi \times \nabla \mathbf{j}) + \rho \mu \nabla^4 \phi + \mathbf{S}_{\mathrm{m}}$ Prediction for ITER $\frac{\mathrm{dn}_{\mathrm{e}}}{\mathrm{dt}} = \frac{\omega_{\mathrm{ce}}}{v_{\mathrm{e}}} \nabla_{\parallel} \mathbf{j} - \nabla_{\parallel} (\mathbf{n}_{\mathrm{e}} \mathbf{u}) + \nabla \cdot (\mathbf{D}_{\perp} \nabla \mathbf{n}_{\mathrm{e}}) + \mathbf{S}_{\mathrm{n}}$ Summary $\left|\frac{3}{2}n_{e}\frac{dT_{e}}{dt} = \frac{\omega_{ce}}{\nu_{e}}T_{e}\nabla_{\parallel}j - T_{e}n_{e}\nabla_{\parallel}u + n_{e}\nabla\cdot(\chi_{\parallel}\nabla_{\parallel}T_{e})\right|$ $+ n_e \nabla \cdot (\chi_{\perp} \nabla_{\perp} T_e) + S_e$

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Input Parameters for TM1 Modeling

- Input parameters
 - Equilibrium and profiles from DIII-D EF L-mode database
 - Transport coefficients derived from measured profiles $\Rightarrow \mu = \chi_{\perp} = 2D_{\perp} = 0.5m^2/s$ are used

- m/n=3/2 EF



TM1 modeling scans RMP strength to determine the m/n=3/2 EF penetration threshold



• EF penetration: phase shift jump, rotation braking, and island growth

TM1 single-fluid modeling shows EF threshold positively depends on plasma density

- EF threshold scales as n_e^{0.56} from TM1 modeling
 - Higher density
 → higher inertia
 → stronger EF threshold



TM1 single-fluid modeling shows EF threshold positively depends on electron temperature

- EF threshold scales as T_e^{0.6} from TM1 modeling
 - Higher temperature
 → lower resistivity
 → stronger screening
 → stronger EF threshold
 - Most experimental scaling ignored temperature effect



TM1 single-fluid modeling shows EF threshold positively depends on plasma viscosity



Scaling laws from TM1 single-fluid modeling agree with Fitzpatrick's analytical theory



[1] R. Fitzpatrick, Phys. Plasmas 5, 3325-3341 (1998)

TM1 single-fluid modeling shows EF threshold negatively depends on toroidal magnetic field

 EF threshold scales as B_t^{-1.15} from TM1 modeling



TM1 single-fluid modeling shows EF threshold negatively depends on toroidal magnetic field

 EF threshold scales as B_t-1.15 from TM1 modeling

- Hard to obtain the accurate scaling in narrow B_t region
 - Fast damping in low B_t region
 - 15% error from residual EF or measurement error can lead to B_t⁻²



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$$\frac{d\mathbf{u}}{dt} = E - \eta \mathbf{j} + \mathbf{Q} (\mathbf{v}_{\parallel} \mathbf{n}_{e} + \mathbf{v}_{\parallel} \mathbf{1}_{e}) \mathbf{j} \text{ effect}$$

$$\frac{d\mathbf{u}}{dt} = -C_{s}^{2} \nabla_{\parallel} \mathbf{P} / \mathbf{n}_{e} + \mu_{\perp} \nabla_{\perp}^{2} \mathbf{u}$$

$$\text{Momentum, } \rho \frac{d}{dt} \nabla^{2} \phi = \vec{e}_{\varphi} \cdot (\nabla \psi \times \nabla \mathbf{j}) + \rho \mu \nabla^{4} \phi + \mathbf{S}_{m}$$

$$particle, \quad \frac{d\mathbf{n}_{e}}{dt} = \frac{\omega_{ce}}{v_{e}} \nabla_{\parallel} \mathbf{j} - \nabla_{\parallel} (\mathbf{n}_{e} \mathbf{u}) + \nabla \cdot (\mathbf{D}_{\perp} \nabla \mathbf{n}_{e}) + \mathbf{S}_{n}$$

$$\frac{energy}{transport} \quad \frac{3}{2} \mathbf{n}_{e} \frac{dT_{e}}{dt} = \frac{\omega_{ce}}{v_{e}} T_{e} \nabla_{\parallel} \mathbf{j} - T_{e} \mathbf{n}_{e} \nabla_{\parallel} \mathbf{u} + \mathbf{n}_{e} \nabla \cdot (\chi_{\parallel} \nabla_{\parallel} T_{e}) + \mathbf{n}_{e} \nabla \cdot (\chi_{\perp} \nabla_{\perp} T_{e}) + \mathbf{S}_{e}$$

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TM1 two-fluid modeling shows EF threshold scaling law on density depends on plasma rotation



- Two-fluid effect affects α_n when $|\omega_E| \sim |\omega_{*_e}|$
 - Two-fluid effect becomes important when $|\omega_{E}| \sim |\omega_{*e}|$
 - Two-fluid effect is negligible when $|\omega_{E}| >> |\omega_{*e}|$

TM1 two-fluid modeling shows EF threshold scaling law on density depends on plasma rotation



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TM1 two-fluid modeling shows EF threshold scaling law on temperature depends on plasma rotation



TM1 two-fluid modeling shows EF threshold scaling law on temperature depends on plasma rotation



- Two-fluid effect affects α_T when $|\omega_E| >> |\omega_{*_e}|$
 - Two-fluid effect becomes important when $|\omega_{E}| >> |\omega_{*e}|$
 - Two-fluid effect is negligible when $|\omega_{E}| \sim |\omega_{*e}|$

TM1 two-fluid modeling shows EF threshold scaling law has weaker dependence on visvosity



• Two-fluid effect affects α_v and leads to a weaker dependence on viscosity compared to single-fluid \rightarrow can't cancel the density dependence

TM1 two-fluid modeling shows linear dependence of EF threshold on plasma rotation

- 3/2 EF penetration threshold linearly depends on plasma rotation
 - Diamagnetic drift cancels rotation (minimum threshold) when |ω_E| ~ |ω_{*e}|
 → perpendicular flow
 - Almost linear growth of island width vs. RMP strength when $\omega_{\rm E}$ + $\omega_{*\rm e}$ =0



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TM1 two-fluid modeling shows that RMP usually triggers pedestaltop and -foot field penetration in the ELM control experiments



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TM1 simulated density and rotation dependence for pedestaltop penetration

2D scaling power law obtained

$$B_{th}^{}/B_{t}^{}=3.5\times10^{-2}n_{e}^{0.7}|\omega_{\perp e}^{}|^{0.94}B_{t}^{-1}$$

 $n_{\rm e}$ in unit of $10^{19} m^{\text{-}3},$ rotation in krad/s, $B_{\rm t}$ in T

- Similar to core EF scaling
- Lower n_e and higher rotation makes penetration easier



TM1 simulated density and rotation dependence agree with DIII-D experiment

2D scaling power law obtained

$$B_{th}^{}/B_{t}^{}=3.5\times10^{-2}n_{e}^{0.7}|\omega_{\perp e}^{}|^{0.94}B_{t}^{-1}$$

 $n_{\rm e}$ in unit of $10^{19} m^{\text{-}3},$ rotation in krad/s, $B_{\rm t}$ in T

- Similar to core LM scaling
- Lower n_e and higher rotation makes penetration easier
- Consistent with experiment [1]

[1] C. Paz-Soldan, et al., NF 59, 056012 (2019)



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If we make reasonable estimates for ITER profiles, direct TM1 predictions fall within typically observed thresholds

- TM1 predicts threshold in DIII-D is close to the experiments

 T_e=0.4keV, n_e=2.5×10¹⁹ m⁻³, ω_E=10 krad/s
- TM1 predicts a lower threshold for ITER using DIII-D IBS profiles
 - Scaled to $T_e=1$ keV, $n_e=5\times10^{19}$ m⁻³, $\omega_E=2-8$ krad/s
- If rotation in ITER is more than one order lower than DIII-D [1], then much lower threshold

[1] A.M. Garofalo et al Nucl. Fusion 51, 083018 (2011)



Pedestal-top penetration threshold in ITER may be also one order lower than DIII-D

ITER parameters

$$B_{t} = 5.15 \text{ T}, R = 6.38 \text{ m}$$

 $a = 1.98 \text{ m}, q_{95} = 3.1$

 $\omega_{\rm E,q=3} \approx \omega_{\rm *e} \approx -3 \,\rm krad/s$

 The penetration threshold for ITER n=3 RMP will be an order lower than DIII-D





- TM1 single-fluid modeling agrees with Fitzpatrick's analytical theory
- TM1 two-fluid modeling shows that the scaling coefficients are strongly affected due to two-fluid effect
- TM1 predicted penetration in both the core and pedestal of ITER will be weaker than DIII-D due to the slower flow frequency
- Next step: compare with DIII-D experiments and perform detail ITER prediction

Backup slides

TM1 single-fluid modeling shows EF threshold scaling law on major radius depends on plasma rotation

- EF threshold scales as R₀^{0.78} for constant angular frequency
 - Stronger velocity for larger R_0

 EF threshold scales as R₀^{-0.18} for constant velocity

- More like this case [1]

[1] A.M. Garofalo et al Nucl. Fusion 51, 083018 (2011)

