

Gaussian process regression for profile fitting

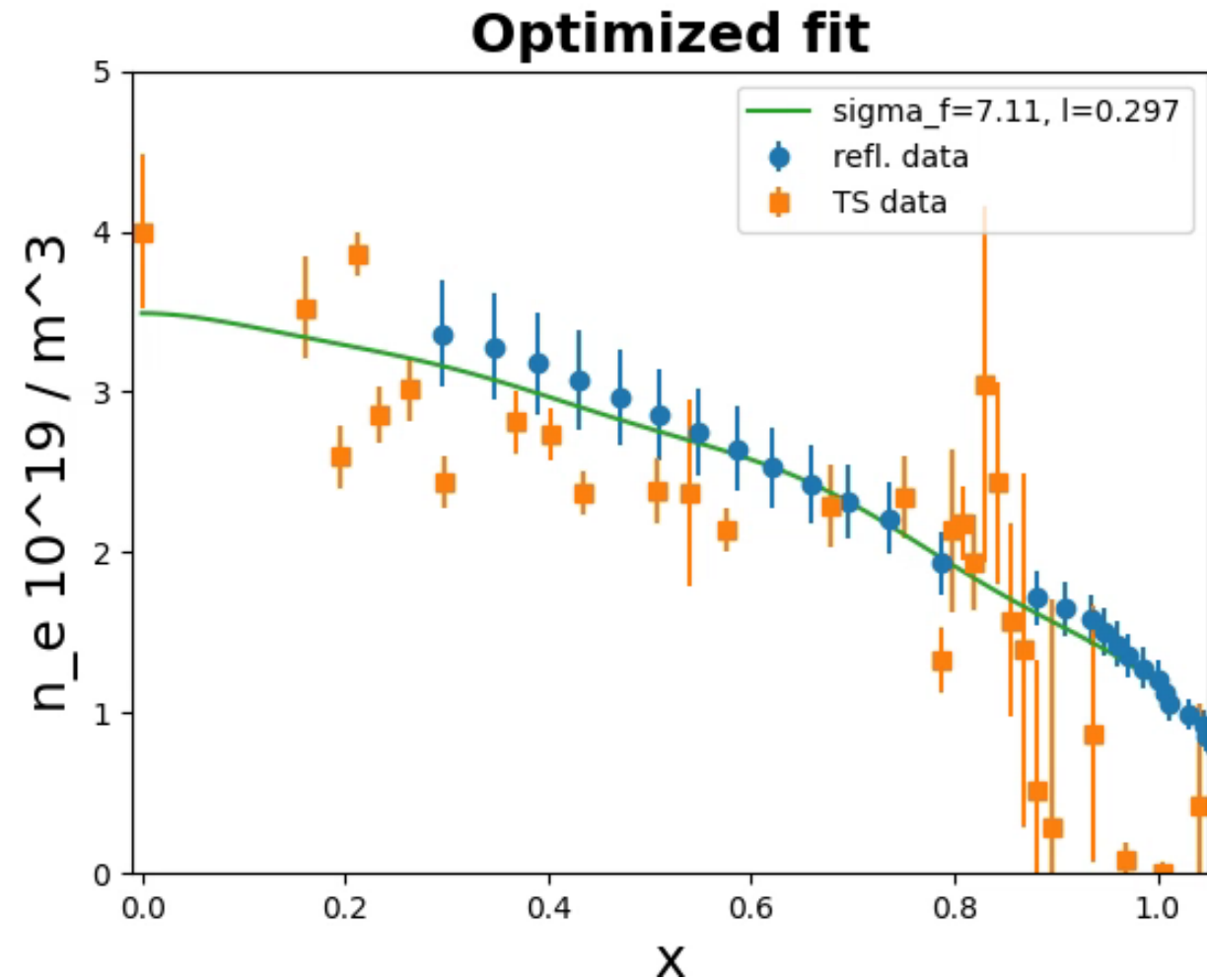
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Problem: combining TS and refl. data for EAST

- EAST's Thomson scattering system has low time resolution and can often be noisy
- Reflectometer data is fast and smooth, but does not reach the core
- For the most accurate profile (required for LH propagation), measured data from both sources are combined



Gaussian process regression improves profile fitting

- Gaussian process regression (GPR) technique uses statistics to allow profile fitting to be more easily automated, with better results
 - [[M.A. Chilenski et al 2015 Nucl. Fusion 55 023012](#)]
- Given a set of (possibly multi-dimensional) input and output, it can be used to predict new outputs with better spatial and/or temporal resolution
- Open-source Python package: **gptools**
- Symmetry constraints (zero slope at $\rho = 0$) can be easily enforced
- Provides an alternative option than fitting with splines, tanh, polynomial, etc.



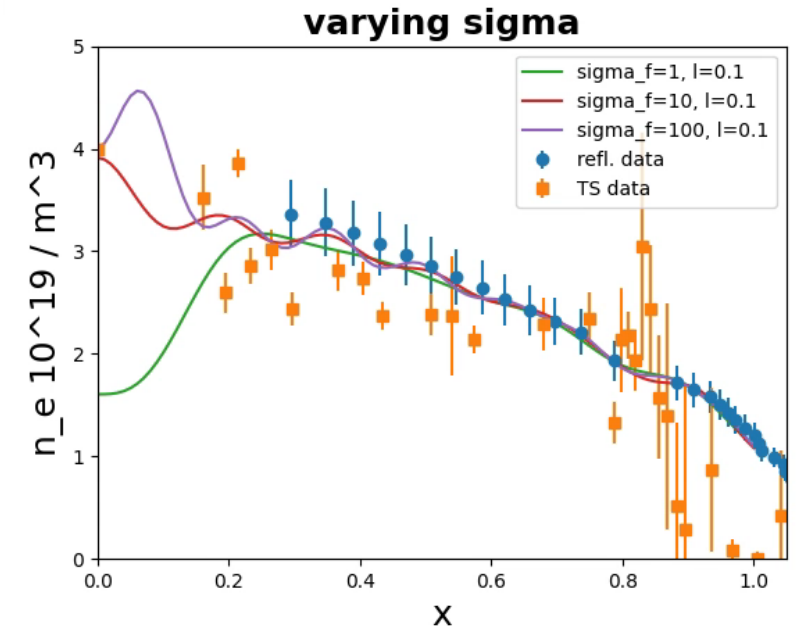
Kernels translate input data to output predictions

- The covariance kernel describes how closely related input/output data should be

- 1D squared exponential kernel:

$$k_{SE}(x, x') = \sigma_f^2 \exp\left(-\frac{|x - x'|^2}{2l^2}\right)$$

- σ_f^2 is the “signal variance”, sets how much the fitted curve can vary in y



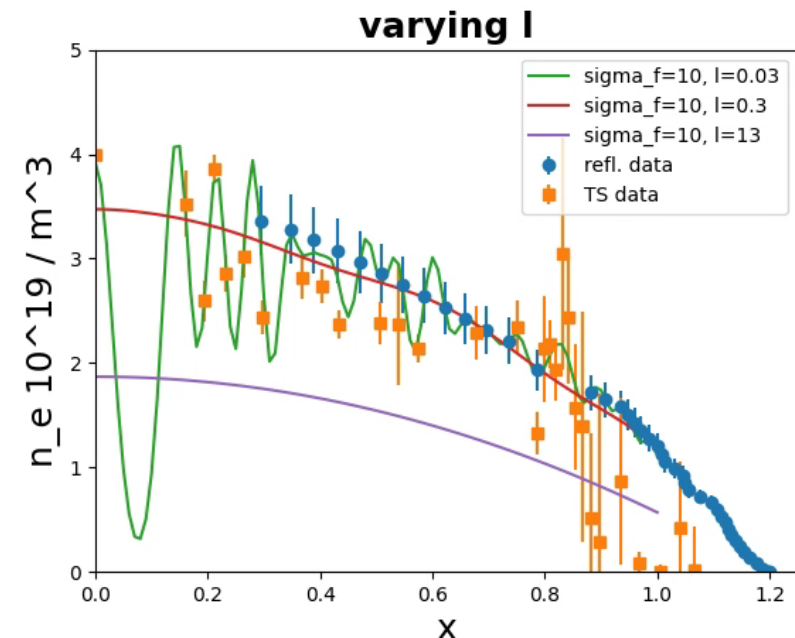
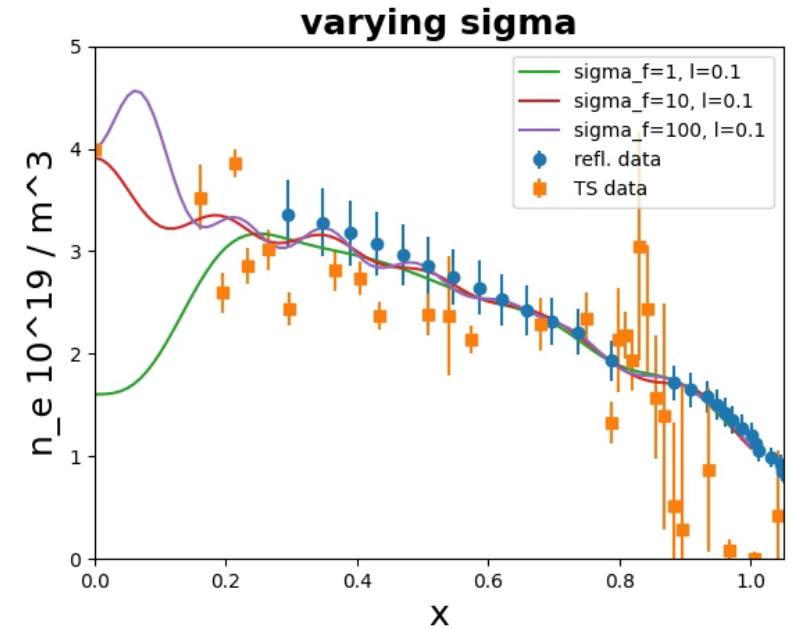
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- σ_f^2 is the “signal variance”, sets how much the fitted curve can vary in y
- l is the “covariance length scale”, sets how much correlation in x is expected
 - Not the same thing as gradient length scale
- For $y(x, t)$, there would be l_x and l_t



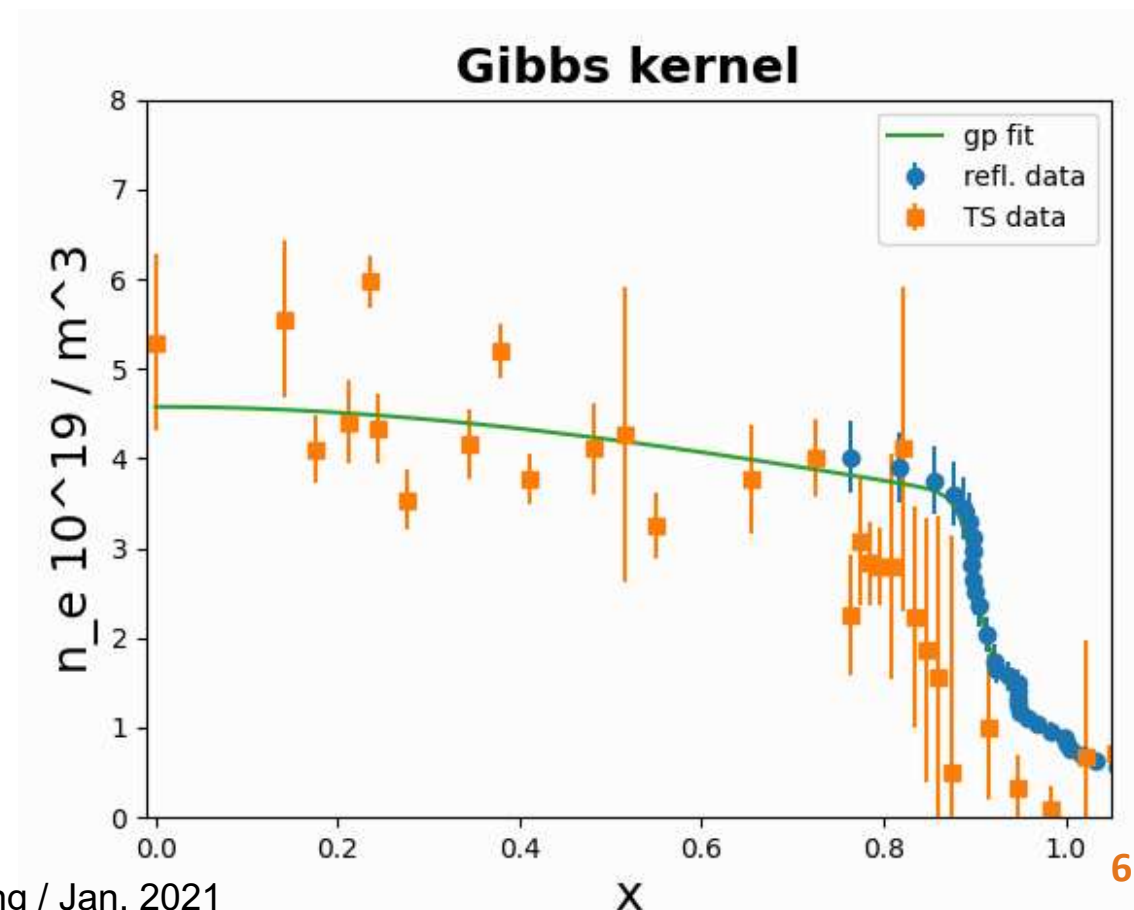
Gibbs kernel allows for varying covariance scale length

- To allow for two different scale lengths in the pedestal vs the core, use Gibbs 1D kernel:

$$k_G(x, x') = \sigma_f^2 \left(\frac{2l(x)l(x')}{l^2(x) + l^2(x')} \right)^{\frac{1}{2}} \exp \left(-\frac{|x - x'|^2}{l^2(x) + l^2(x')} \right)$$

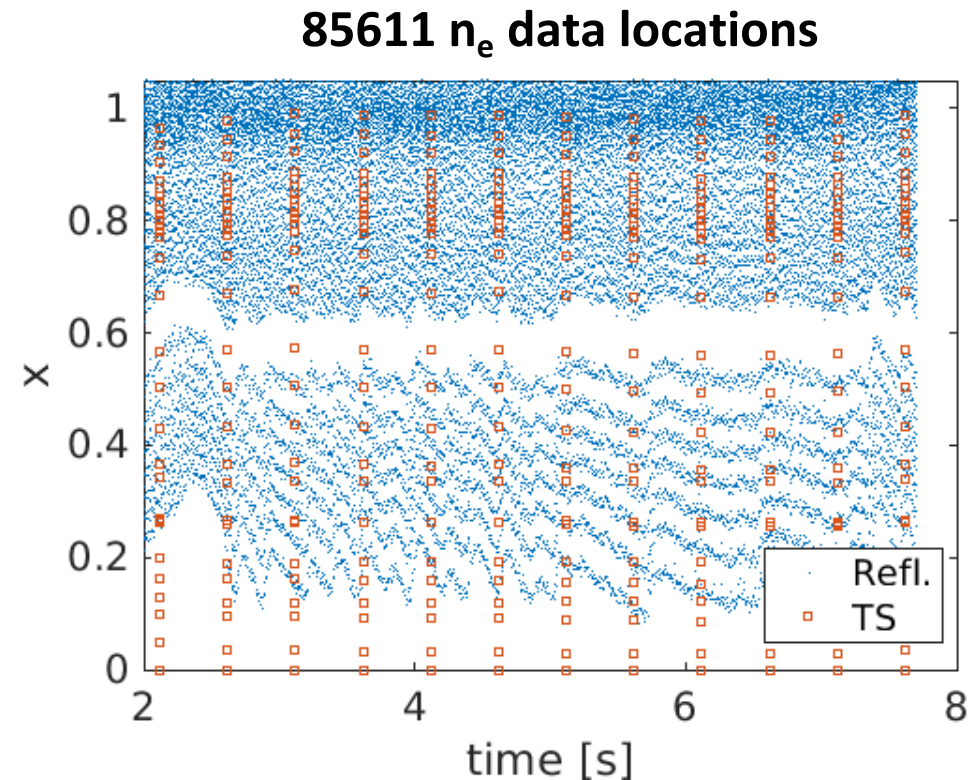
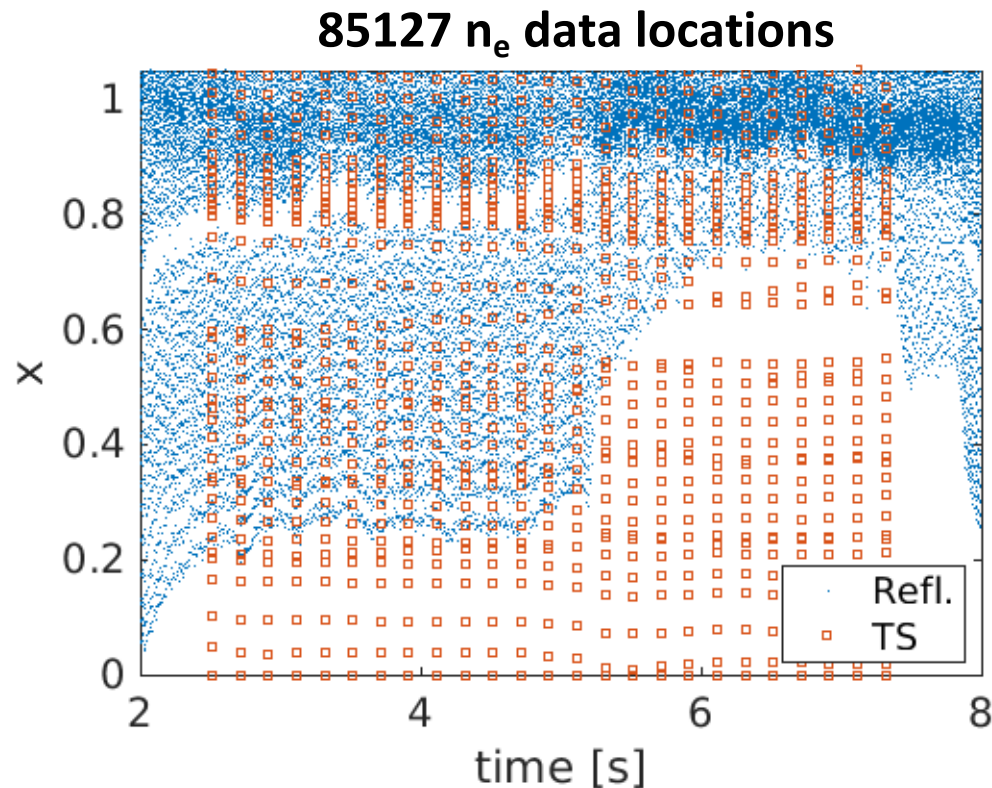
$$l(x) = \frac{l_1 + l_2}{2} - \frac{l_1 - l_2}{2} \tanh \frac{x - x_0}{l_w}$$

where l_1 is the core length scale, l_2 is the edge length scale, and x_0 and l_w are the center and width of the transition



GPR can be used for 2D interpolation

- 2D interpolation can:
 - use TS data when reflectometer data is not available during H-mode
 - use faster refl. to fill in gaps in TS data



Conclusion & Future work

- Gaussian process regression (GPR) is a powerful tool that can automate profile fitting with good accuracy
 - Covariance length scales informed by physics
 - are robust in similar scenarios
- Possible applications with gptools:
 - Incorporate into automated analysis of diagnostics for better resolution or better signal-to-noise
 - Apply *en masse* to a database of pedestal measurements to calculate pedestal height, width, etc. for a semi-empirical model



Additional resources

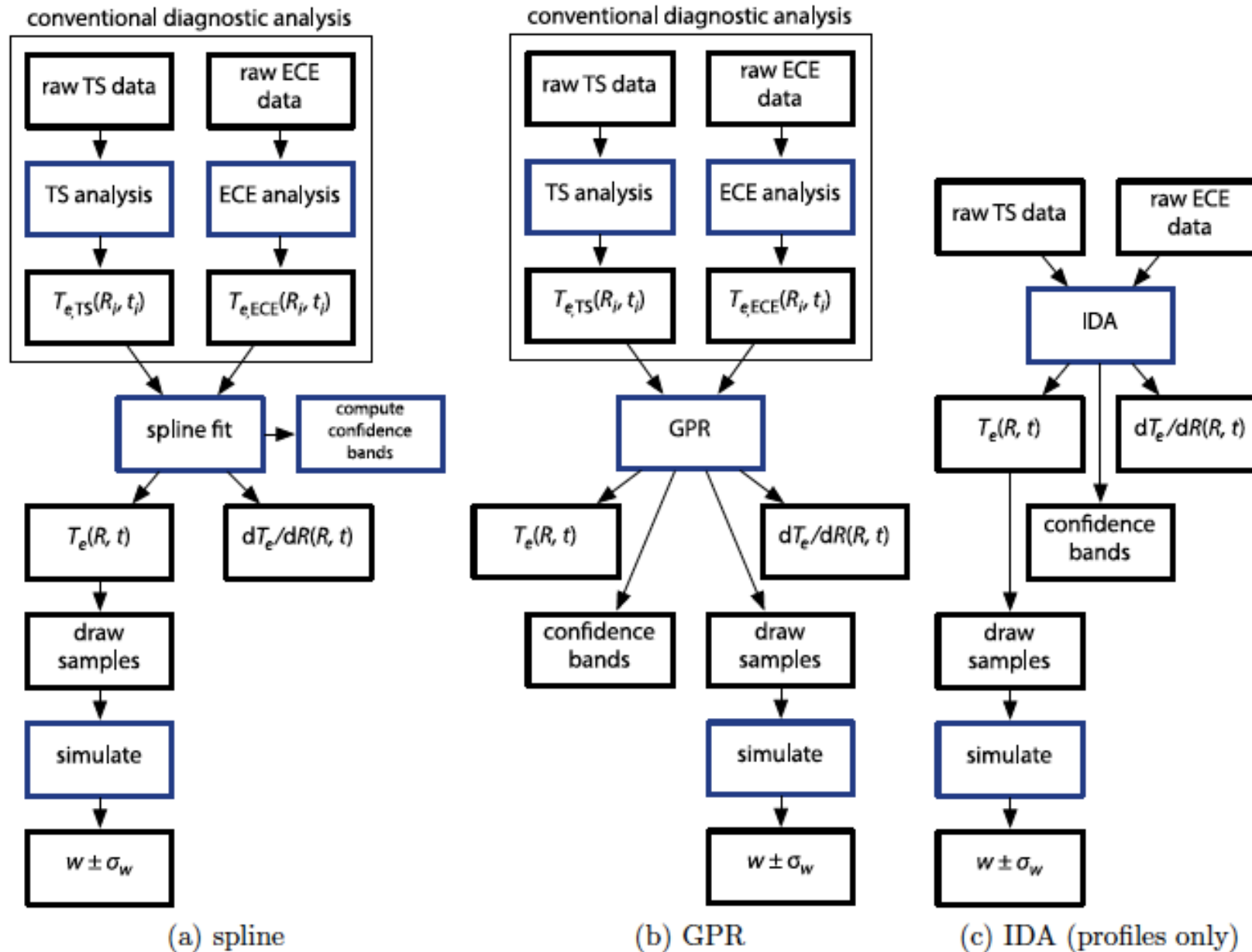
- Paper: M.A. Chilenski *et al* 2015 *Nucl. Fusion* **55** 023012
 - doi: <https://doi.org/10.1088/0029-5515/55/2/023012>
- Python code:
 - Python 2: <https://pypi.org/project/gptools/>
 - Python 3: <https://github.com/wilkiechoi/gptools3>
- User manual:
 - Webpage: <https://gptools.readthedocs.io/en/latest/>
 - PDF:
<https://buildmedia.readthedocs.org/media/pdf/gptools/latest/gptools.pdf>



Backup Slides

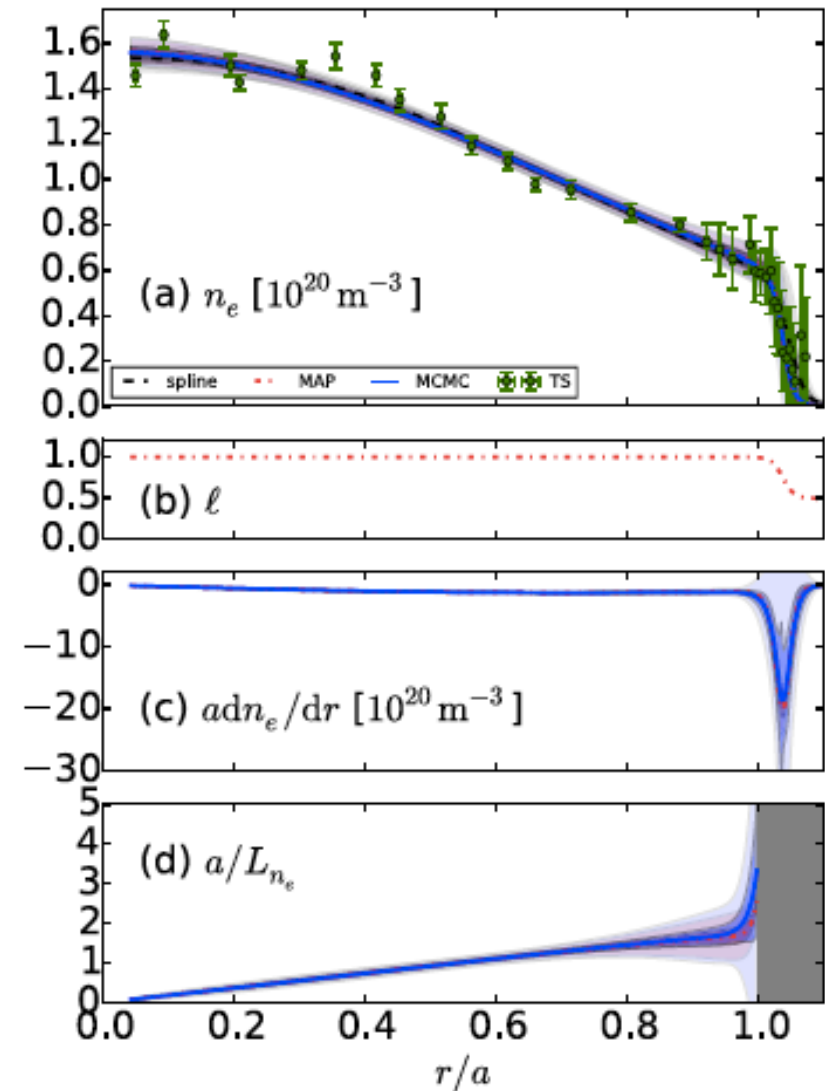


Comparison of workflow, fig. 4 from [Chilenski NF 2015]

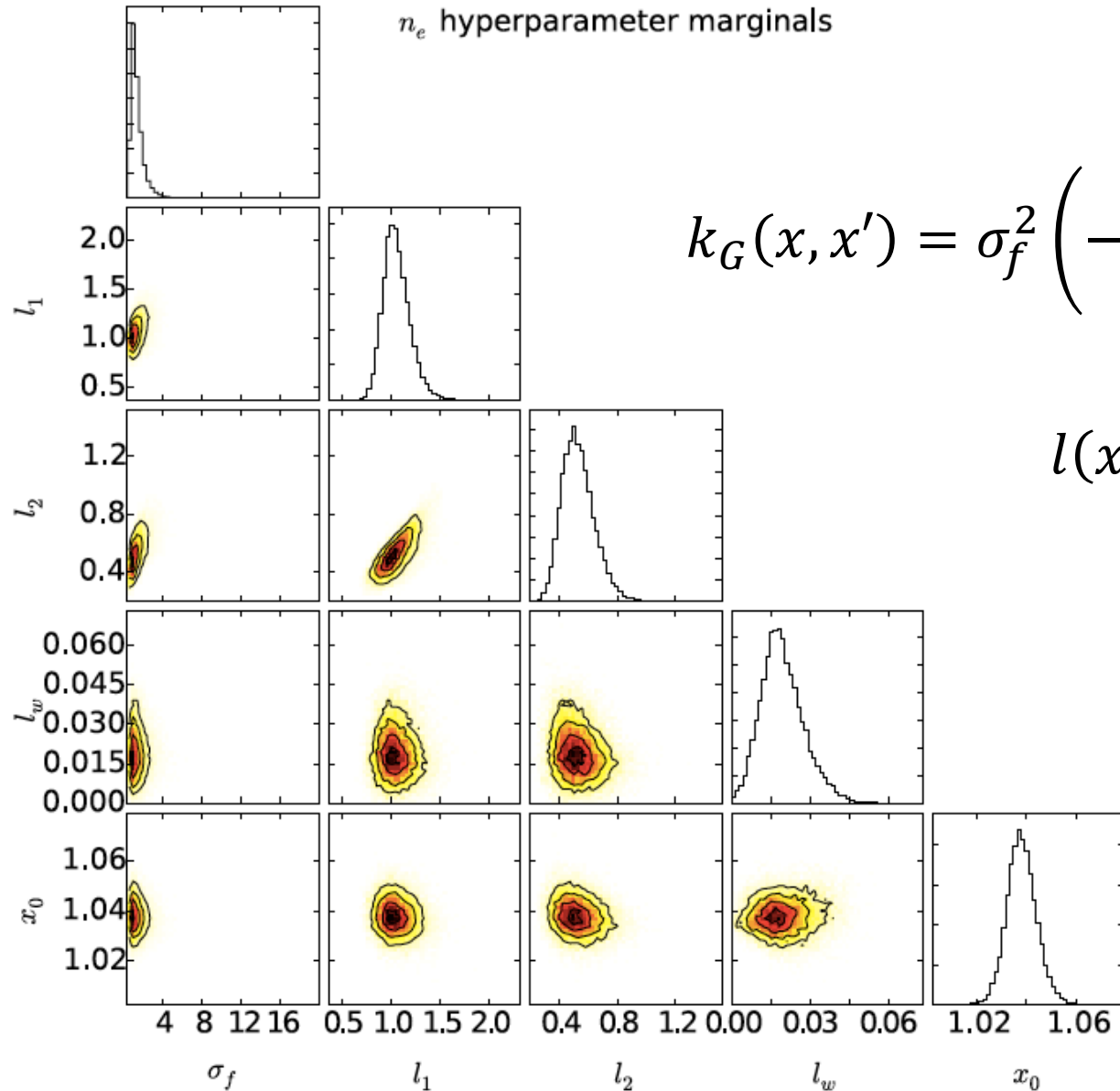


H-mode density profile, fig. 5 from [Chilenski NF 2015]

- Using gptools to fit C-Mod density profile
- Showing long covariance length scale in the core and shorter / at the edge
- Also calculating density gradient of the pedestal, important for transport analysis



Hyperparameters of fit, fig. 7 from [Chilenski NF 2015]



$$k_G(x, x') = \sigma_f^2 \left(-\frac{2l(x)l(x')^2}{l^2(x) + l^2(x')} \right)^{\frac{1}{2}} \exp \left(-\frac{|x - x'|^2}{l^2(x) + l^2(x')} \right)$$

$$l(x) = \frac{l_1 + l_2}{2} - \frac{l_1 - l_2}{2} \tanh \frac{x - x_0}{l_w}$$

- Resultant parameters of Gibbs kernel for density profile on previous slide