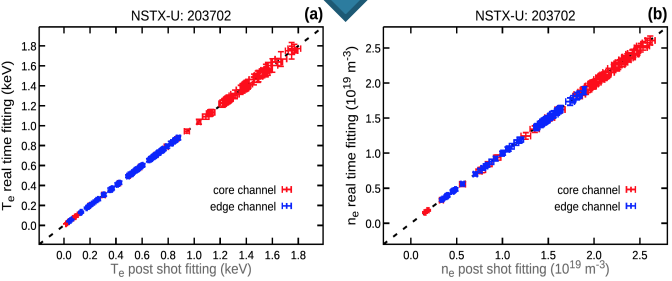
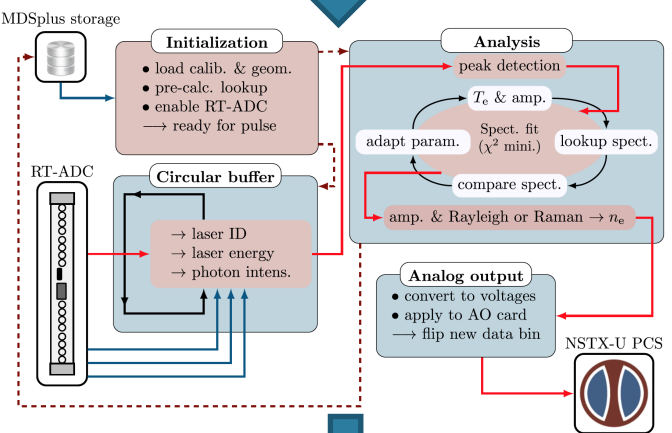
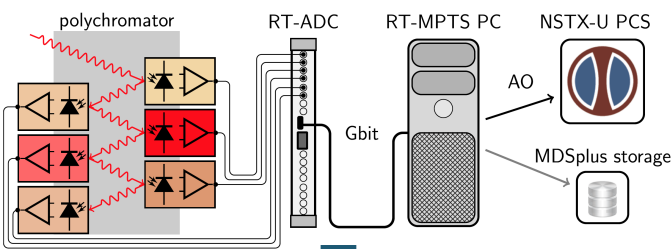


NSTX-U modeling and control

J.T. Wai, M. Kaur, F. Laggner, G. Tchilinguirian,
R. Rozenblat, P.J. Vail, M.D. Boyer, A.
Welander, A.O. Nelson, Z.A. Xing, C.
Lasnier, T.K. Gray, O. Izacard, E. Kolemen

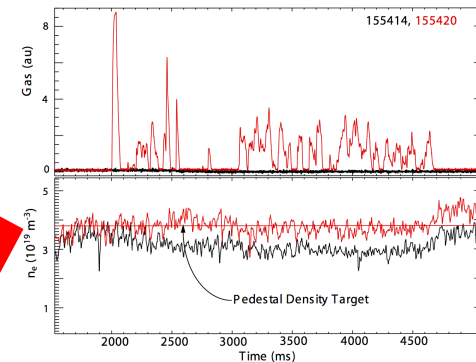
0. RT-MPTS Diagnostics (M. Kaur, F. Laggner, G. Tchilinguirian, R. Rozenblat)

Rt-MPTS for Control and Rt-Kinetic-EFIT

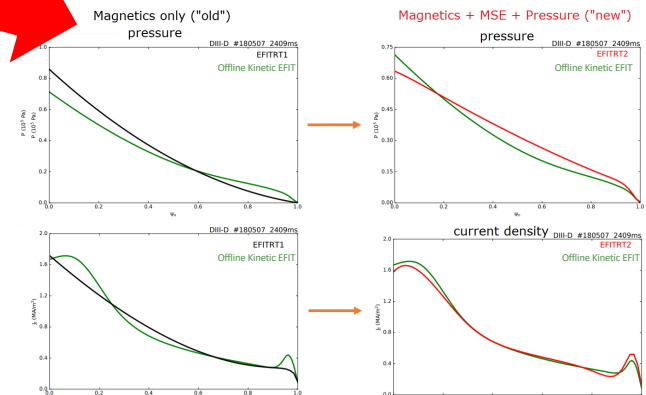


Project Objectives:

- Compute n_e and T_e profiles in real-time (2021)
- Share this information with PCS (2021)
- Enhance rt-EFIT with rt-MPTS data (2022)
- Develop control algorithms to achieve and stabilize scenarios with prescribed edge and core structures (2022-2023)
- Improved disruption avoidance (2023-2025)

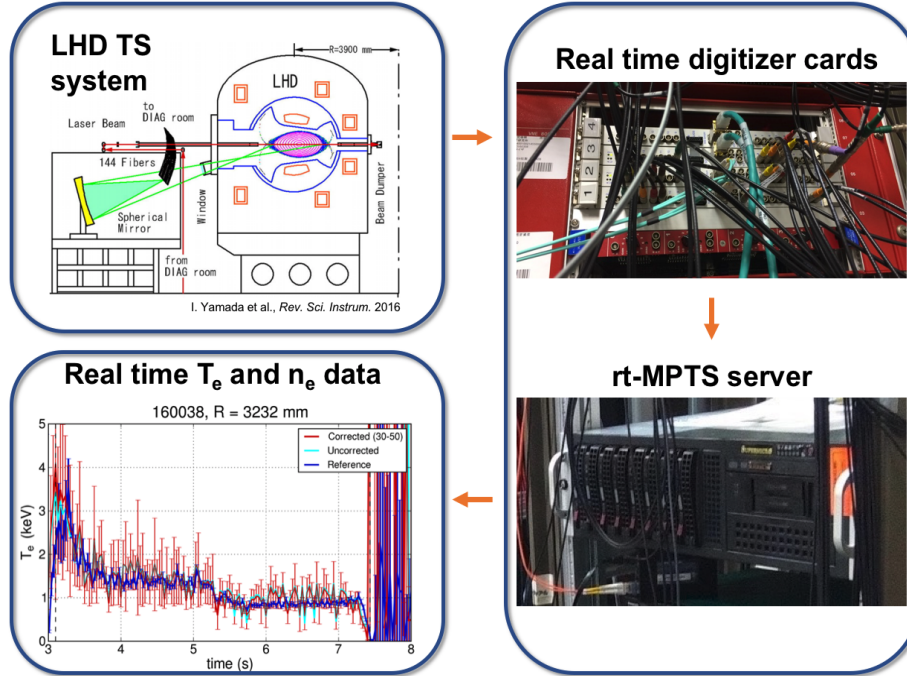


Control Example: Pedestal Density (DIII-D)



Rt-Kinetic EFIT (DIII-D)

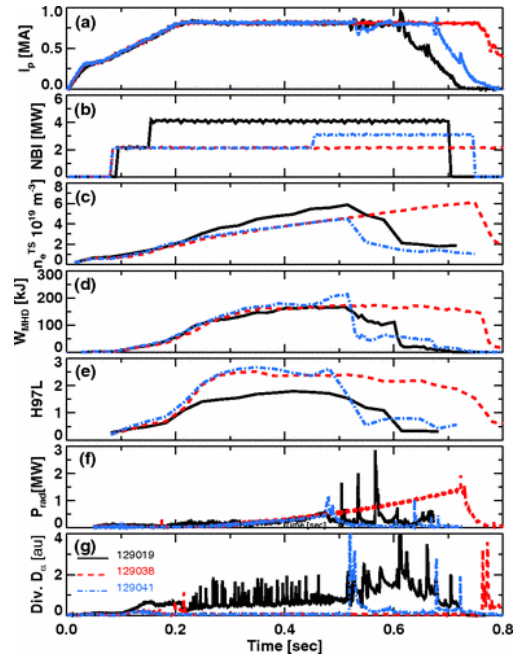
NSTX-U RT-MPTS Copy Running at LHD System



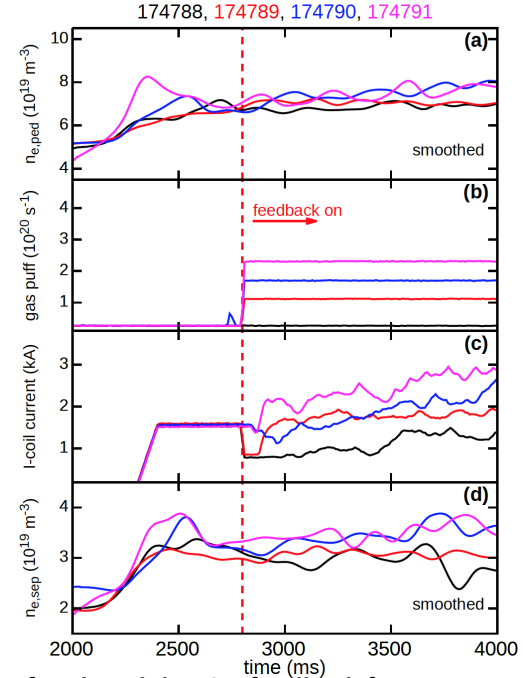
The digitizer cards and the real time server (right) as implemented at LHD. The rt-MPTS T_e result is compared with the offline TS system (bottom left), with the rt-MPTS system in red and reference in blue.



NSTX-U RT-Thomson: Help Advanced Scenarios



Comparison of pre-lithium ELMy discharge (black), and two post-lithium discharges with different NBI power (blue, red)



Demonstration of pedestal density feedback for super H-mode. As the gas is increased from discharge to discharge (feed-forward), the MP coil current is feedback controlled such that a constant pedestal top electron density ($n_{e,ped}$) is achieved.



Control/Physics Overview

1. Snowflake divertor (SFD) feedback control
2. Optimization of SFD power and particle exhaust
3. Improving SFD reconstruction via infrared thermography
4. Shape control model validation
5. Optimization of rampup feedforward trajectories
6. Neural networks for fast shape reconstruction and modeling

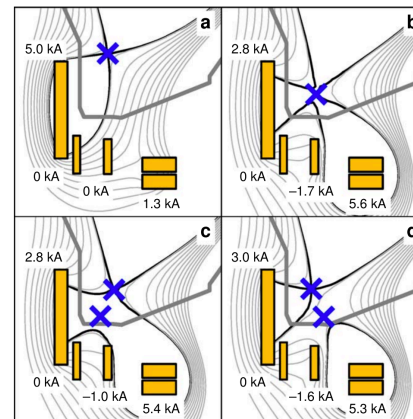


1. Snowflake divertor feedback control

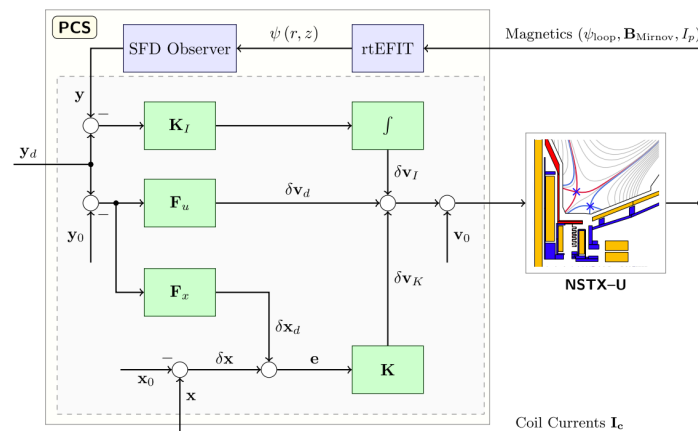
Snowflake divertor control – (Vail)

- *Snowflake divertor:*
 - *Second order null*
 - *High flux expansion, heat flux splitting phenomenon, detachment access*
- *Control algorithm:*
 - *Proportional control for isoflux shape targets*
 - *LQI for snowflake targets ($dr, d\theta$)*

<https://doi.org/10.1088/1361-6587/aaf94a>

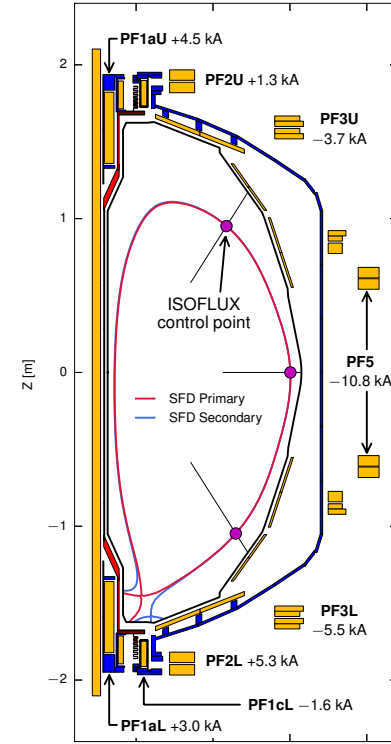
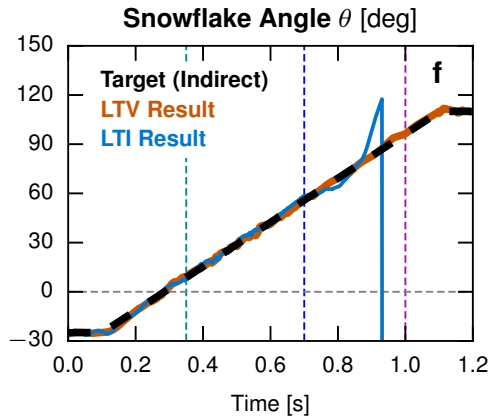
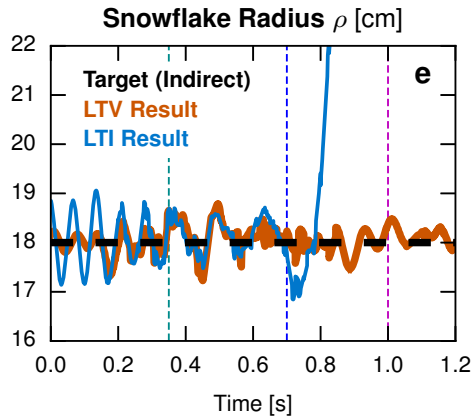


a. Standard divertor
b. Perfect snowflake
c. Snowflake plus
d. Snowflake Minus



High-fidelity closed loop simulation indicates need for time-varying model in control

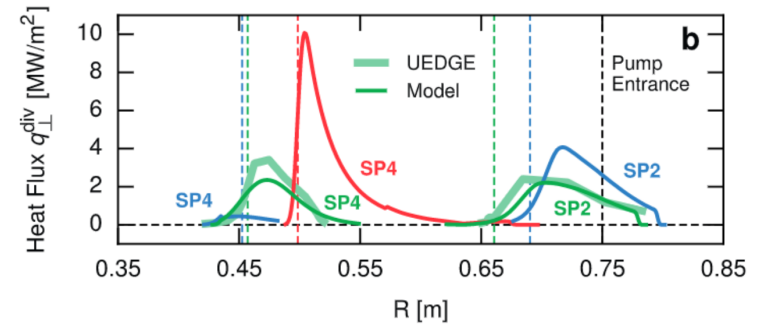
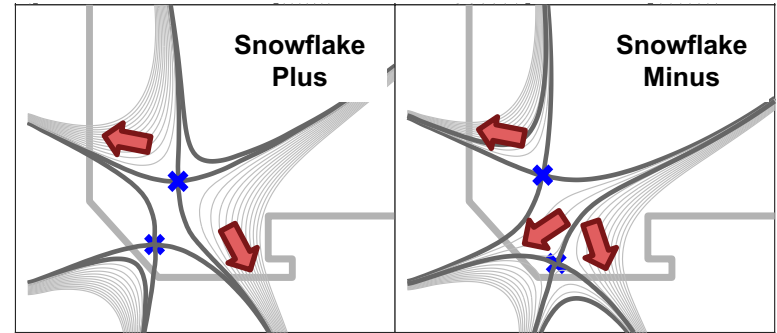
- *Developed and tested with nonlinear closed loop simulation environment.*
- *Linear time-invariant (LTI) system insufficient for moderate-large changes. Must use time-varying (LTV) model*



2. Optimization of SFD power and particle exhaust (Vail, Izacard)

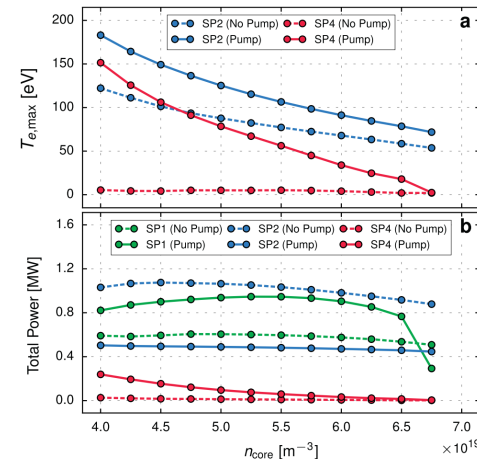
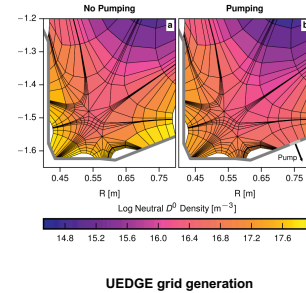
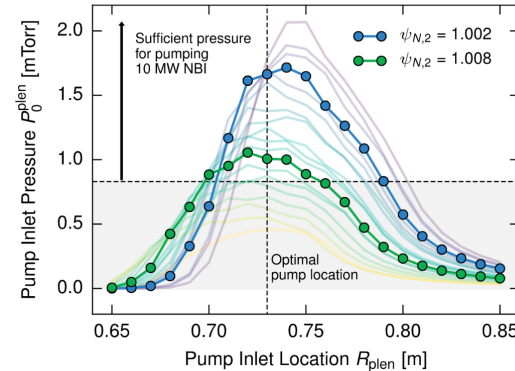
Snowflake divertor heat exhaust

- Study of power and particle exhaust capabilities using in NSTXU using cryopump + snowflake
- Develop simple, fast heat flux diffusion model [Vail, NME] and validated with UEDGE
 - Heat flux diffuses across ψ but in separate domains for SFD-minus



SFD power exhaust with cryopumping

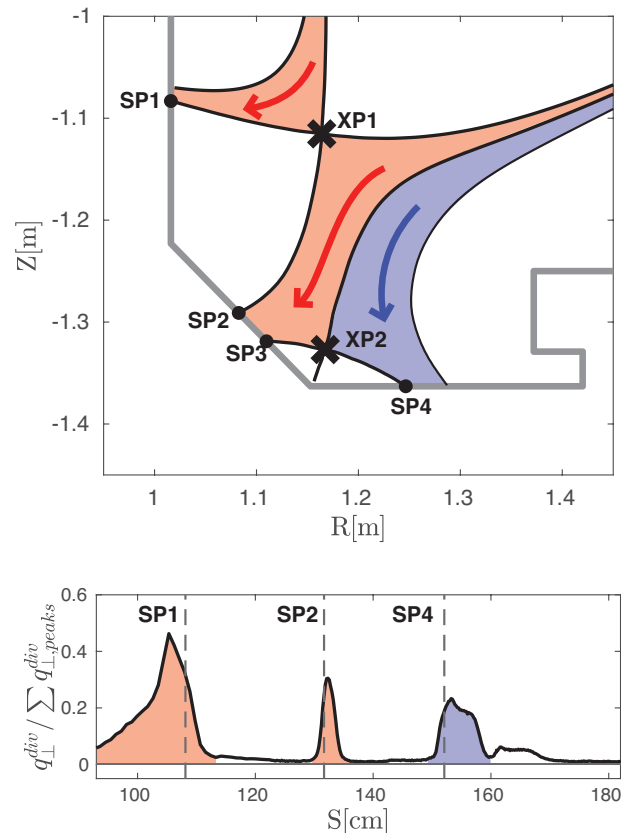
- To pump 10MW NBI power, need $P > 0.83$ mTorr at pump inlet [Vail, NME]
 - Assume 24 kL/s volumetric pump rate for liquid helium cooled cryopump
- At pump optimal location, 83% of SFD equilibria in database meet this condition.
- UEDGE simulation: with pumping
 - T_e rises at strike points due to reduced collisionality
 - SOL power is redistributed among strike points
 → changes the ideal 'power balanced' SFD configuration



3. Improving SFD reconstruction via infrared thermography (Wai, NME, 2020)

Infrared thermography (IRTV) for SFD reconstruction

- **Snowflake plus:** secondary x-point lies in the private flux region. Scrape-off layer (SOL) fieldlines directly intersect divertor in 2 locations \Rightarrow 2 heat flux peaks.
- **Snowflake minus:** secondary x-point lies in the SOL. Fieldlines directly intersect divertor in 3 locations \Rightarrow 3 heat flux peaks.
- **Equilibrium vs. IRTV inconsistencies**
 - Strike point location mismatch
 - Occasionally, incorrect # of heat flux peaks for the snowflake type
 - IRTV used to improve equilibrium
 - Useful for control (feedback on x-point locations [Kolemen, 2018])
 - Geometry sensitive to unmeasured divertor currents. Potential use as diagnostic for bootstrap current.



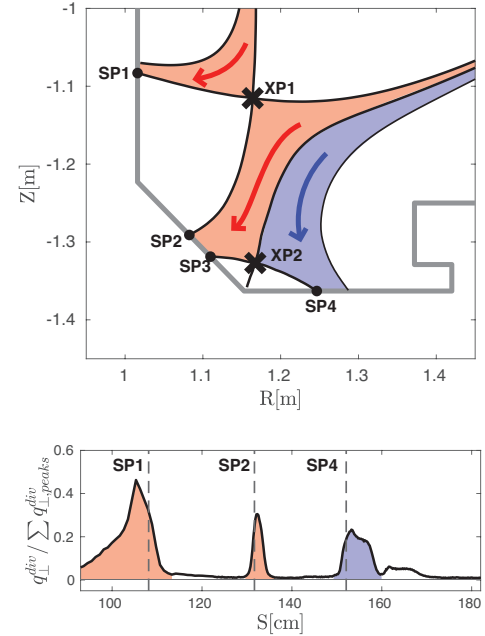
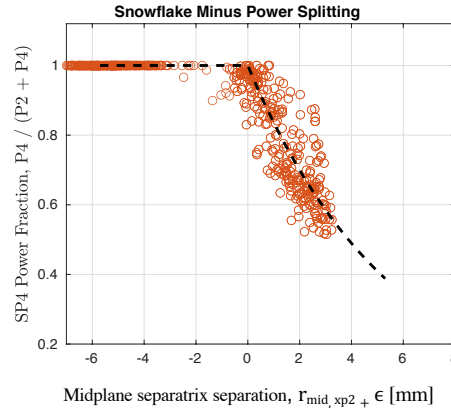
Heat flux power fraction in the SFD

- Power fraction f_{sp4} measured from the divertor heat flux profile. At each peak, $P_{pk} = \int 2\pi R(s)q_{\perp}(s)ds$
- Secondary separatrix position $r_{mid, xp2}$ measured from EFIT equilibrium.
- Data is selected from subset of shots that have wide range of x-point separation and fit to:

$$f_{sp4} := \frac{P_4}{P_2 + P_4}$$

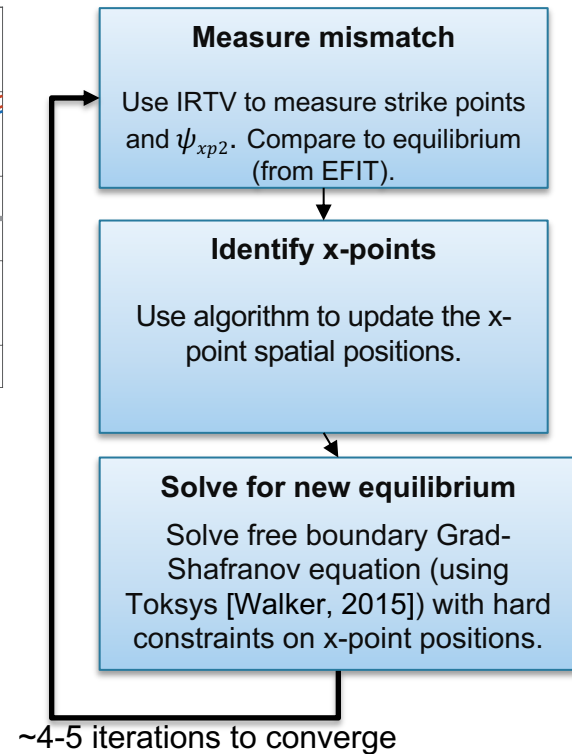
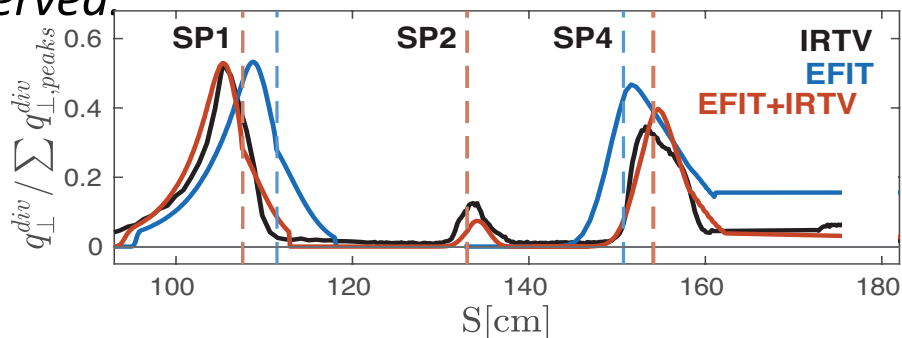
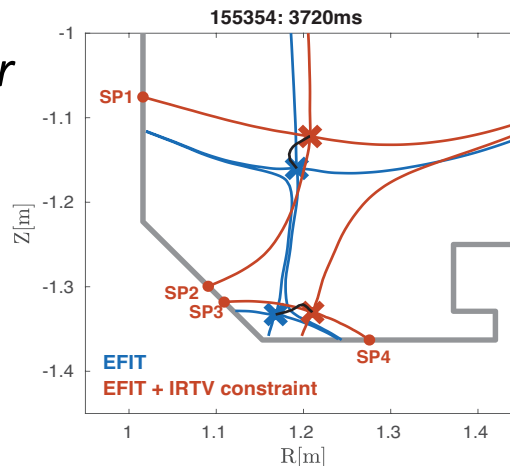
$$= \frac{\int_{r_{mid, xp2}}^{\infty} q_{\perp}^{mid, peak} e^{-r/\lambda_q^{eff}} dr}{\int_0^{\infty} q_{\perp}^{mid, peak} e^{-r/\lambda_q^{eff}} dr}$$

$$= e^{-r_{mid, xp2}/\lambda_q^{eff}}$$



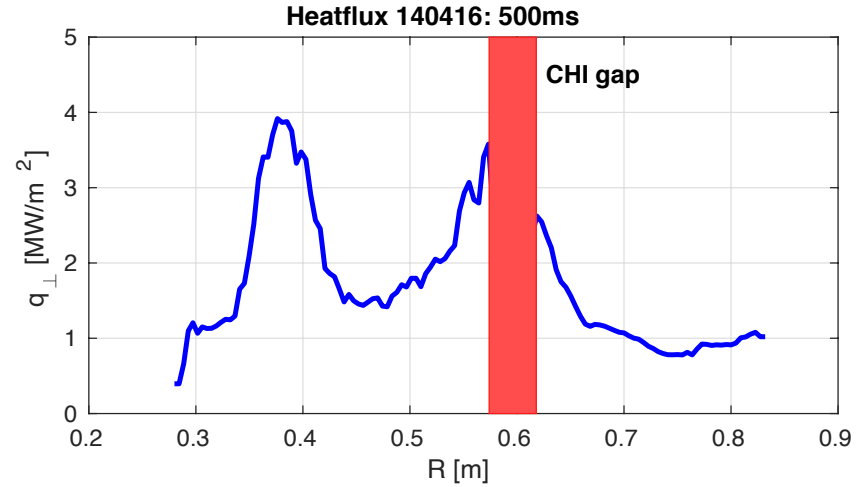
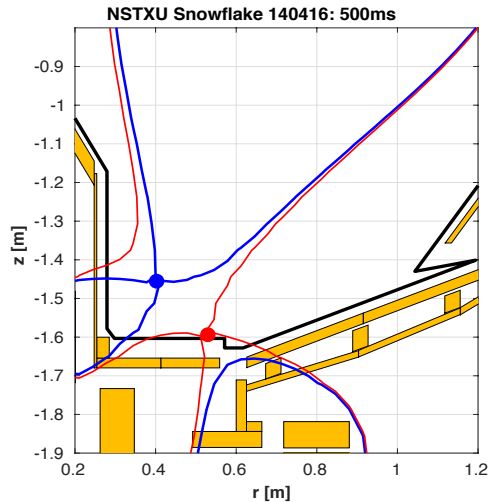
IRTV used to constrain strike points, x-points

- *Strike points and outboard power fraction are mapped to x-point locations [?].*
- *Final heat flux profiles match consistently.*
- *Modification to edge current observed*



Extension to NSTXU

- Technique was developed with DIII-D but principles can extend to NSTXU
 - Fewer constraints available to lack of visibility on inner wall, CHI gap



The 2 observable LFS heat flux peaks. Inner peak not observed, and outermost peak obscured by CHI gap.

4. Shape control model validation (Wai, Boyer)

Model validation for shaping feedforward control

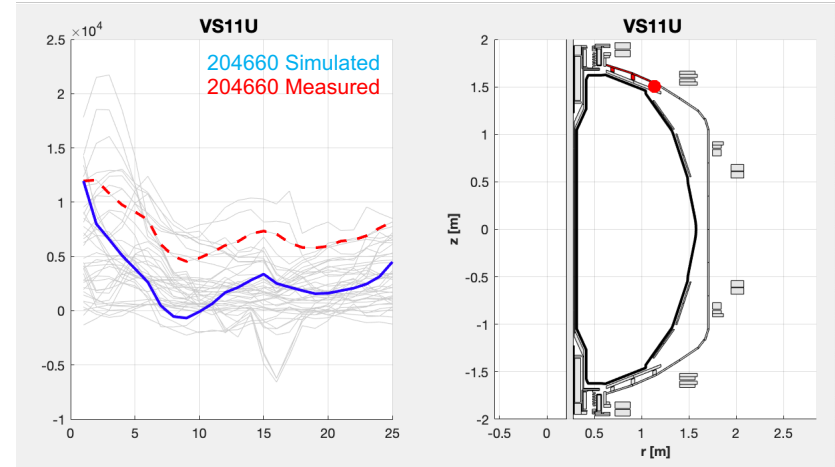
- Shape control based on the toroidal circuit equation which can be transformed to time-varying state-space system.

$$\begin{aligned} v_s &= R_s I_s + M_{ss} \dot{I}_s + \dot{\Psi}_{ss,plasma} \\ \dot{\Psi}_{ss,plasma} &= \frac{\partial \Psi_{s,plasma}}{\partial I_s} \dot{I}_s \end{aligned} \quad \rightarrow \quad \dot{I} = A(t)I + B(t)v$$

- *Shape control algorithm relies entirely on PID feedback with no feedforward.*
- *Large shape errors at startup, and small errors during flattop lead to poor performance.*
- *A design tool that translates a target shape evolution into approximate feedforward current evolution is needed*

Model validation

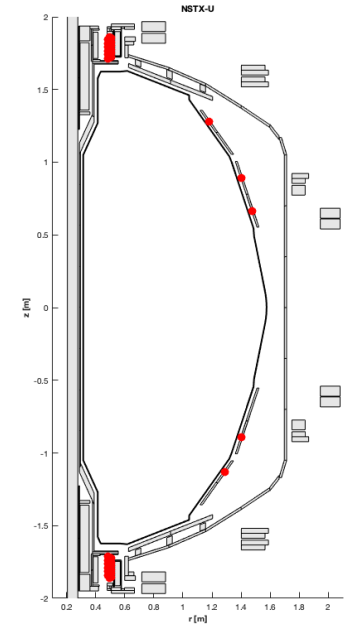
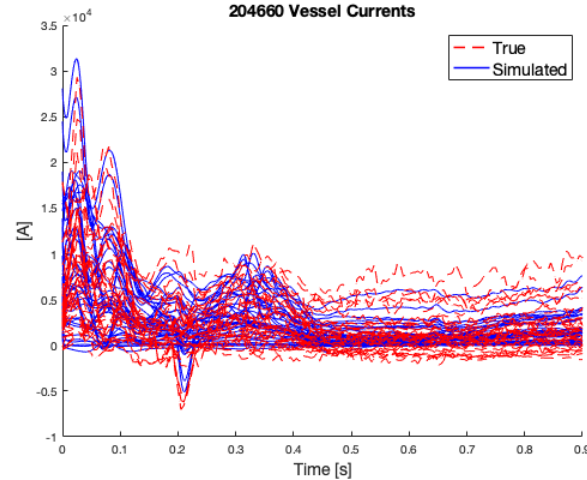
- First step is to validate the model versus experiment, so that current evolution can be simulated.
 - Vessel currents play a strong role on equilibrium, especially with NSTXU short pulse length
- Use a greybox fitting procedure to identify: coil power supply internal inductances, vacuum vessel resistances, plasma resistance $R_p(t)$.



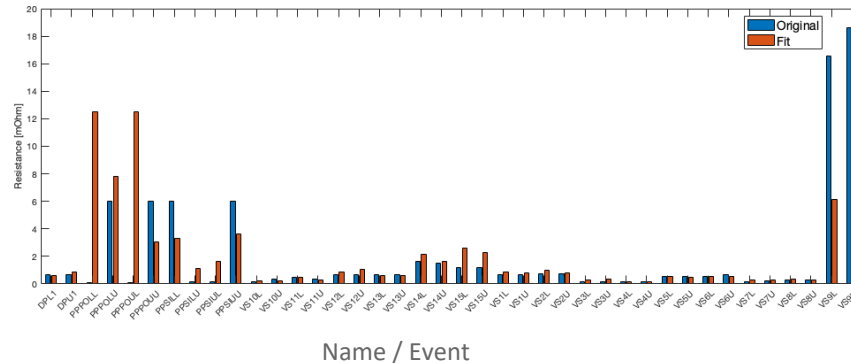
Vacuum vessel currents show inconsistency with measured.

Vessel fitting results modify resistance in bellows, passive plates

- Fitted model parameters give much better match to vessel currents, plasma current.
- Resistances that changed the most with fitting are consistent with expectations
 - Bellows
 - Passive plates, 'effective' resistances difficult to measure because of nontoroidal eddy currents



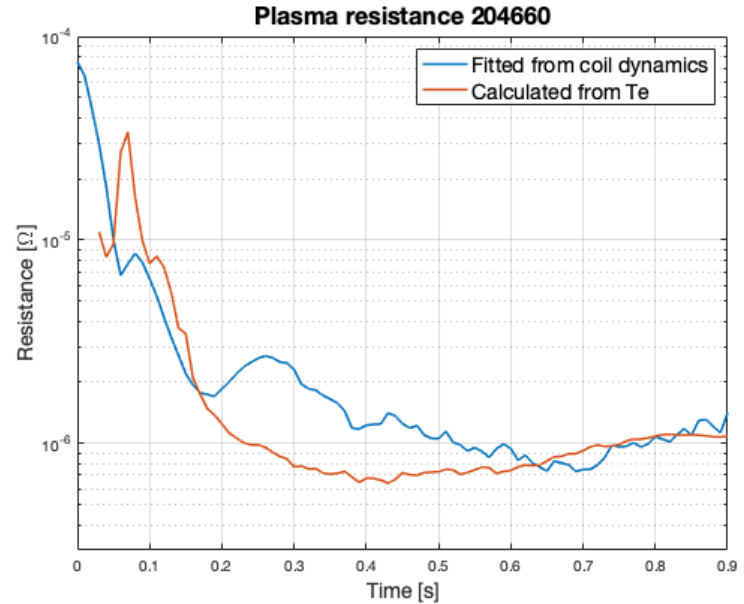
Bellows and passive plate locations



Identify plasma resistance Rp(t)

- Plasma resistance an important time-varying parameter to identify
- Sets the trajectory for OH coil
- Currently, using values fit from the dynamics model.
 - In future, could couple with evolution predictors (Nubeam net, current profile evolution, Te/ne modelling)
 - Fitted values not far from simple Te modeling with Spitzer resistivity

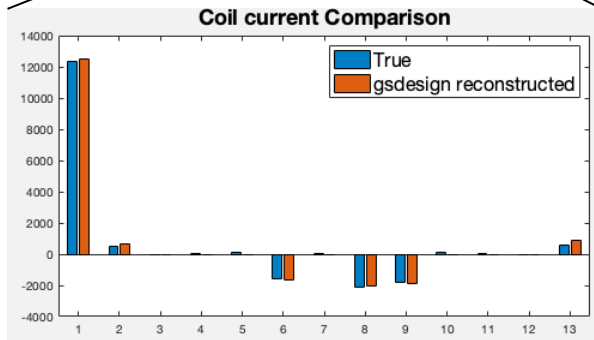
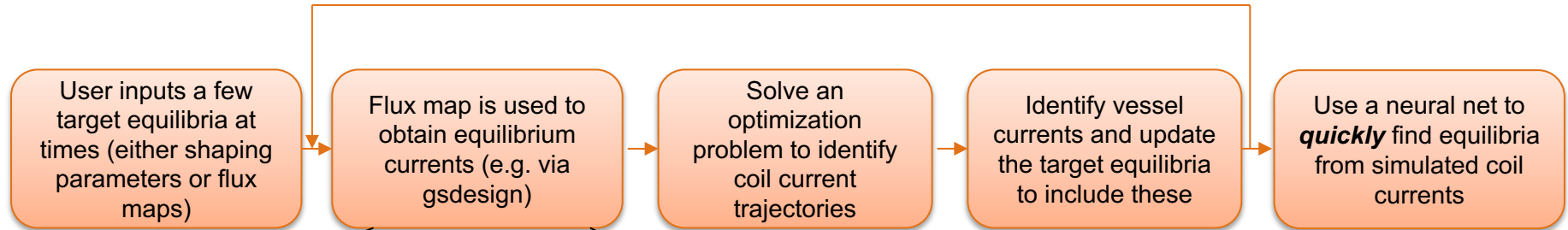
$$Res = \frac{2\pi R_0 \eta}{\pi \kappa a^2} \quad \eta \approx \frac{\pi e^2 m^{1/2}}{(4\pi \epsilon_0)^2 (KT_e)^{3/2}} \ln \Lambda$$



5. Optimization of rampup feedforward trajectories (Wai, Boyer)

Optimization of feedforward trajectories -

Iterative time slice algorithm:



Optimization to find feedforward trajectories

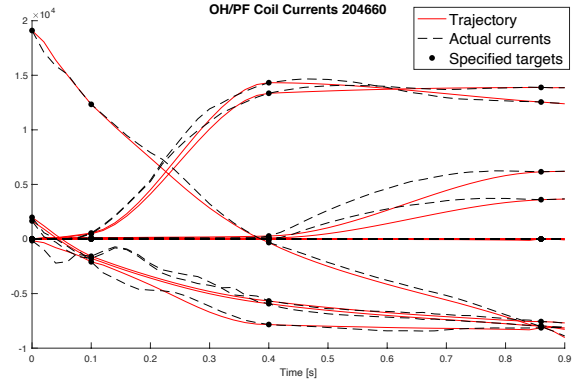
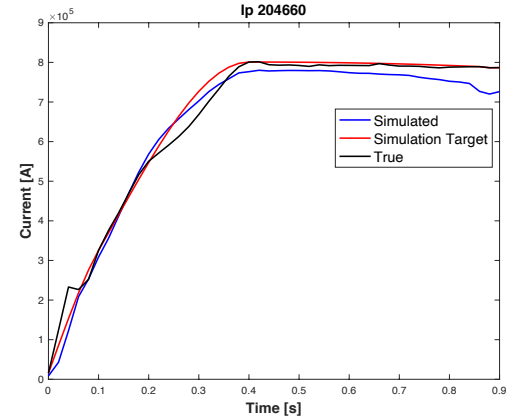
- Define a cost function of the form

$$J = \sum_{i=1}^N (I_{k+i} - r_{k+i})^T Q (I_{k+i} - r_{k+i}) + \Delta I_{k+i}^T Q_v \Delta I_{k+i}$$

Subject to: (dynamics constraint)

$$\dot{I} = A(t)I + B(t)v$$

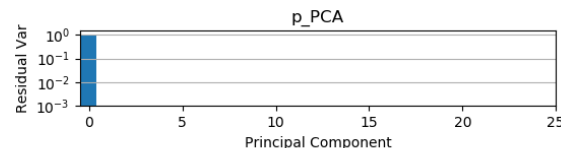
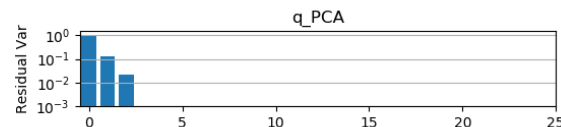
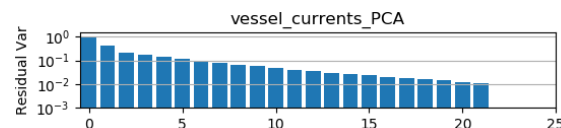
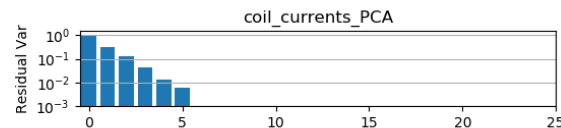
- The reference trajectory r depends on vessel currents, and $A(t)/B(t)$ depend on the equilibrium, so this problem should be solved iteratively.



6. Neural networks for fast shape reconstruction and modeling (Boyer, Wai)

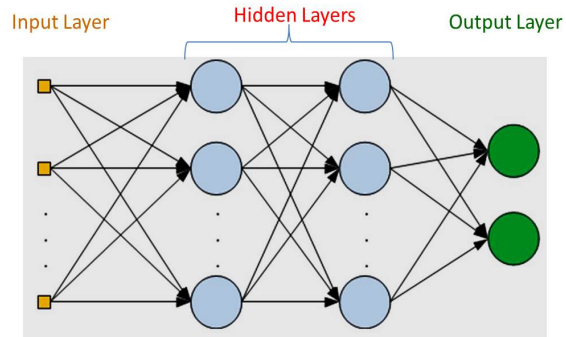
Eqnet finds equilibrium from coil currents

- Feedforward trajectory planner could be useful as an operator tool, especially if results can be obtained quickly! ~1 min
- Several steps currently in optimization take ~1hour
 - Free boundary GS solutions for all equilibria timeslices
 - Identify plasma flux response for all times
- **Eqnet:** finds approximate flux map based on coil currents, vessel currents, q and p profiles.
 - Use PCA reduction of inputs, n_components selected for 99% explained variance

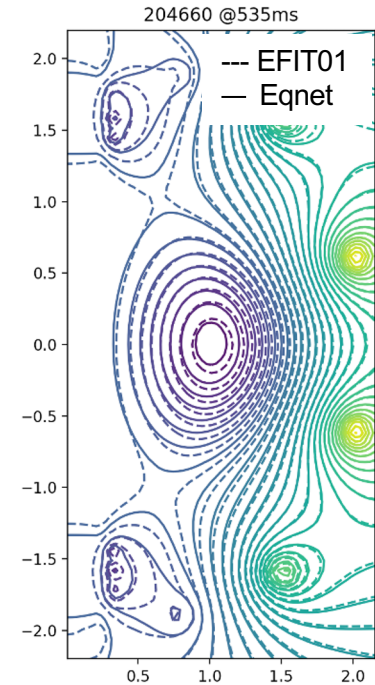
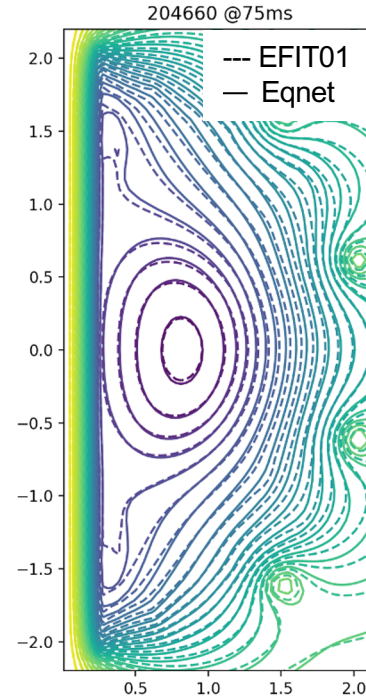


Eqnet

- Uses separate PCA components for rampup and flattop
 - Allows accurate for accurate estimation during rampup ($\sim t < 300\text{ms}$) since rampup samples under-represented in database
- Eqnet has standard multi-layer perceptron (MLP) framework.

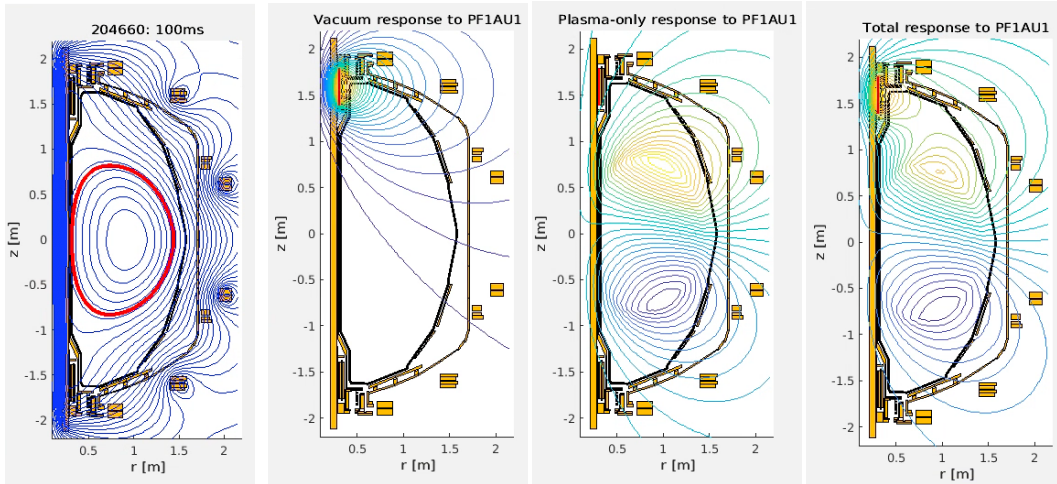


Generic MLP network



Future extensions to include estimation of response

- Future extension
 - Train NN to identify the plasma response
 - In theory, identifying plasma response does not require much more representation capacity than estimating the equilibrium
 - Targets could be identified from code (gspert) or from actual data (derivative of the equilibrium wrt time, minus the vacuum response)



Plasma response calculated from the gspert code

References

P.J. Vail, et al. "Design and simulation of the snowflake divertor control for NSTX-U", PPCF, 2019.

P. Vail, et al., "Optimization of the snowflake divertor for power and particle exhaust on NSTX-U", NME, 2019.

J.T. Wai, et al., "Infrared constrained equilibrium reconstruction and application to snowflake divertor studies", NME, 2020.

