

Tokamak Disruption Event Characterization and Forecasting Research and First Real-time Application on KSTAR

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Disruption Event Characterization and Forecasting Research (DECAF) continues to expand, including first real-time application on KSTAR

□ DECAF (very brief) overview ← see Jan 24, 2022 talk for more detail

Recent automated large database analysis capability

Real-time DECAF implementation

Real-time DECAF hardware update



Continued DECAF development builds from an extrapolable approach with strong initial success – now expanded to real-time in KSTAR

- Fully automated, physics-based analysis of existing tokamak databases from multiple devices (e.g. KSTAR, NSTX, MAST/-U, AUG)
- Analyzing all plasma states, continuous and asynchronous events
 - "<u>Critical</u>": (Level 3) event chains leading to disruption if no action taken
 - "Proximity": (Level 2) paths to "critical" events
 - "<u>Safe</u>": (Level 1) events indicate steady operation (e.g. L-mode / H-mode determination, steady ELMing, benign confinement transitions)
- "Forecaster events": give earliest warnings

K STA

- High quantitative success found (recently improved)
 - □ > 91% true positive, ~ 8% false positive (~1e4 shots, ~1e6 samples)
- Research <u>continues</u> focused on improving forecasting to needed accuracy (98%+ goal for ITER, w/low false positives)



Data / analysis is desired in real time to reproduce offline analysis DECAF is structured to ease parallel development of disruption characterization, event criteria, and forecasting





r/t DECAF initial deployment: four real-time software elements were installed, some tested in 2021, running in 2022 + more being added



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Island rotation dynamics model is used to compute the critical frequency to forecast disruption

- Cylindrical, rigid body model
- Possible model of drag for both a "slip" and a "no slip" condition:

$$\frac{d(I\Omega)}{dt} = T_{aux} - T_{mode} - \frac{(I\Omega)}{\tau_{2D}}$$

LTM-f

Utilize DECAF realtime MHD system to determine mode, critical frequency



LTM forecaster on KSTAR leaves ample time for potential NTM control before disruption

JTM-fsignals

- Plots show summary of **DECAF** results for characterization and forecaster in a disrupting **KSTAR** shot
- Bifurcation frequency is crossed at ~4.5 s
 - Locking occurs at ~ 5.8 s
 - Disruption happens at ~ 6.1 s
- Significant time period of 1.6 s between forecasting and disruption

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LTM Forecaster

LTM Characterization

condition

DECAF development attention to real-time system design and implementation on KSTAR, DECAF code analysis processing

Real-time DECAF on KSTAR

several key diagnostics now acquired in real-time as part of the KSTAR PCS
initial implementation real-time DECAF software as part of KSTAR PCS

DECAF analysis capability (several development goals recently achieved)

Parallel processing over high performance clusters

- PPPL private (~30 CPUs) and open SLURM queues (~1,000 CPUs)
- Next step to utilize Princeton Stellar cluster (over 50,000 CPUs)

Analysis persistence

- Automated interaction with the DECAF database
- 200 TB dedicated storage, funded for further expansion

Analysis chunking

 Standard DECAF analyses are now "one-button" capable to process an *entire run year of data*, or the <u>entire database of a device(</u>!) for iterated analysis of DECAF forecasting models, etc.

NSTX DECAF run: 30 CPU SLURM

Following

slides

- 20 shots, 16 DECAF events
- 30 seconds computation time

NSTX run year ~ 3,000 shots - extrapolation: 0.8 hours computation

NSTX database ~ 25,000 shots (40 TB) - extrapolation: 7 hours computation

True positive rate for disruption forecasting found to be very high in large database analysis (ex: NSTX 2009 run campaign)







- Key analysis step: Determining causality vs. correlation between warnings and the disruption
 - critical for all disruption prediction algorithms!
 - significant analysis focus now

MP2022-03-01-015: Real-time DECAF event validation at high non-inductive current, control development, and disruption mitigation actuation – MAIN GOALS





31404: MGI fired – offline DECAF shows LTM-F, LTM events reach Level 3 – 100% accuracy in r/t prediction on dedicated run days



KSTAR

- 100% accuracy in real-time DECAF Level 3 events (6/9/22)
 - 18 shots; 3 MGI
 - 7 true positives
 - □ 11 true negatives
- 100% accuracy in real-time DECAF Level 3 events (6/15/22 + 6/22/22)
 - 22 shots
 - 12 true positives
 - 10 true negatives
- Excellent distinction between true positives and negatives

DECAF Model: KSTAR-MDL061222sas2 (version: Vv1)

MP2022-03-01-015 1st day: Offline DECAF analysis for shots taken



Examination of DECAF False positives (31391, 31392, 31397, 31400)



LTM-F Level 3 spike causes false positive

(ZHX) Level 3 LTMf LTM DIS > CQS(+0.021s) (2.493s) (+0.672s) (+0.675s) (+0.678s)IPR ≳50 40 30 20 10 Level 2 LTM LTMf 11:11 LTMf --- Threshold 0.6 1.0 1.5 2.0 2.5 3.0 4 P time (s) I_p (MA) n kstar 31397 Warning 0.2 31397 0.0 0.0 0.5 1.0 1.5 2.0 2.5 3.0 3.5 4.0 t (s)

LTM-F is not a false positive in this shot (- 0.5s FP time margin insufficient)

LOQ Level 3 approaching lp flat-top – check q95 calculation; increase threshold



KSTA

LTM-F is not a false positive in this shot (- 0.5s FP time margin insufficient)





BRIEF review of real-time DECAF results from 6/15/22

DECAF warning levels examined for LTM-F and LTM event warnings

- □ LTM-F forecasted TM accurately (Level 3)
- LTM frequency warning reached Level 3 after the LTM-F warning (correct)
- LTM stored energy warning reached Level 3 after LTM frequency warning (correct)
- Repeated 100% accuracy in forecasting

New IPR software was enabled and ran, not yet completed

□ The real-time Ip current target waveform was correct, but the Ip waveform comes up with 0 right now

- □ The timing demonstration of the disruption avoidance worked, but actuator didn't stop the mode lock yesterday (request more run time to complete this → happening 7/6/22 KST)
 - □ Just need to add software that connects real-time DECAF warning with disruption avoidance actuator
 - With some more shots (requested) can add toroidal rotation to n = 1 disruption avoidance actuator, also can attempt ECCD as disruption avoidance actuator



Real-time DECAF warnings show early LTM forecast of disruption, and additional LTM warnings for mode locking



KSTAR

Pre-programmed n = 1 field applied at same time as critical rtDECAF LTM-F forecast was made to "simulate" disruption avoidance



Forecast worked, but n=1 AC field did not prevent TM mode lock

> Such an activation was successful in 2021 "NTM entrainment" experiment

Two differences this year regarding TM lock prevention attempt

- n = 1 applied AC field did not rotate toroidally (patch panel setting different)
- target plasma different

rtDECAF disruption avoidance attempt possible in 2022 run

> alter rtDECAF software to trigger key actuator

> > • n = 1 field, ECCD, etc.

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NSTX-U real-time MHD system implementation, part of our present grant research, will enable similar capability for NSTX-U

KSTAR rtMHD system



KSTAR real-time MHD computer, DAQ

<u>KSTAR buffer chassis</u> (diagnostic interface box)

Started discussions on NSTX-U system design

- Diagnostic discussion with Eric F. and Stefano M.
- Initial implementation / PCS interfacing discussion with Greg. T. and Frank H.
- Discussion with Dan B. of incommon interfacing

LEMO cables from high-n array mag probes

NSTX-U High-n system



KSTAR

MP2022-03-01-015: Real-time DECAF event validation at high non-inductive current, control development, and disruption mitigation actuation – address GOAL 4 tonight



NOTE: Detailed shot plan provided next, target plasmas from 2021, 2022

New disruption avoidance actuator: applied entrainment field successful in preventing naturally-occurring 2/1 NTM locking (2021 KSTAR experiment)



<u>NOTE</u>: applied AC field frequency is << mode rotation (due to boundary value field alteration? analysis continues)</p>

KSTAR

MP2022-03-01-015: Real-time DECAF event validation at high non-inductive current, control development, and disruption mitigation actuation – 7/6/22 **Goal 4)**: Test auxiliary system actuation by rtDECAF events for several target plasmas as an initial demonstration of disruption avoidance Task Number of Shots (0) SET-UP: IVCC Patch panel: STD-N1A; MGI available: YES; rtDECAF analysis ON at t = 1.5s (1) n = 1 toroidally rotating field actuator: Darget plasma: "I-mode \rightarrow H-mode": (NO n = 1 field) 29204; (WITH n = 1 field) 29207 (1a) Run target plasma to get mode; rtDECAF disruption avoidance turned ON to actuate n = 1 field 2 (1b) If (1a) is successful, turn OFF AC field, turn OFF DECAF disruption avoidance actuation (leave rtDECAF analysis ON) (2) <u>NBI actuator</u>: Darget plasma: "delayed H-mode": 25331 ($B_T = 1.8T$ better reproducibility); 31747 $B_T = 1.6T$ (2a) Run target plasma 25331 to get mode; rtDECAF disruption avoidance turns ON extra NBI sources (from NBI-2) 2 (2b) If (2a) is successful, turn OFF extra NBI, turn OFF DECAF disruption avoidance actuation (leave rtDECAF analysis ON) 1 (3) ECCD actuator: both pre-programmed and rtDECAF actuated ECCD) Target plasma: "ECCD TM": 31445; 31444 (3a) Run target plasma to get mode; when rtDECAF disruption avoidance triggers turn EC5 on, extra ECCD power add EC3 2 (3b) If (3a) is successful, turn OFF ECCD, DECAF disruption avoidance actuation OFF (leave rtDECAF analysis ON) (4) <u>Disruption mitigation</u>, low delay: produce rtDECAF-induced MGI disruption mitigation with least delay 1 (5) Produce high poloidal beta ~ 3, high non-inductive plasma (Target: 29033 high $\beta_p = 3$), rtDECAF disruption avoidance ON (6) Produce high poloidal beta ~ 3, high non-inductive plasma (Target: 29033 high $\beta_p = 3$), rtDECAF disruption avoidance OFF, but rtDECAF analysis ON _____

Total number of shots:

shots: 12

New real-time diagnostic acquisition in the KSTAR PCS enabling an integrated, world-class r/t DECAF analysis



KSTAR

The first real-time DECAF module in KSTAR PCS measuring T_e profile (started during 2021 run campaign)



Initial real-time toroidal velocity (rtV₀) diagnostic shows very good agreement with KSTAR CES system



 $\hfill\square$ rtV $_{\phi}$ and offline CES system share sightlines

KSTAR

Y.S. Park (CU), W.H. Ko (KFE)

100 Hz

NEW real-time toroidal velocity diagnostic (rtV_o) delivered to KSTAR, now being installed (this week!)

Spectrometer



Fiber bundle



Real-time computer and DAQ



Switch from Windows 10 to Linux system, more compatible with other r/t systems

M. Podesta, K. Erickson, J. Yoo (PPPL), Y.S. Park (CU), W.H. Ko (KFE)



DECAF disruption prediction and avoidance research continues and has expanded to real-time operation on KSTAR

- Multi-device, integrated approach to disruption prediction and avoidance that meets disruption predictor requirement metrics (D. Humphreys, et al., PoP 22 (2015) 021806)
 - Physics-based "event chain" yields key <u>understanding</u> of evolution toward disruptions needed for confident extrapolation of forecasting, control
 - □ Full multi-machine databases. Recent performance for NSTX: > 99% true positive rate
 - Supporting physics analysis, experiments run to create, validate models, expand operating space
- DECAF producing early warning disruption forecasts
 - \Box On transport timescales: \rightarrow guide disruption avoidance by profile control
- DECAF expanded to real-time operation on KSTAR
 - \Box LTM and LTM forecaster used as critical warnings \rightarrow LTM-f \rightarrow
 - Controlled shutdown, disruption mitigation by MGI triggered in real-time by DECAF warnings
 - 100% success rate in controlled experiments (40 shots)
 - Moving ahead to test initial disruption avoidance for the first time (tonight EDT!)

We are hiring researchers+ -> Email: sabbagh@pppl.gov

