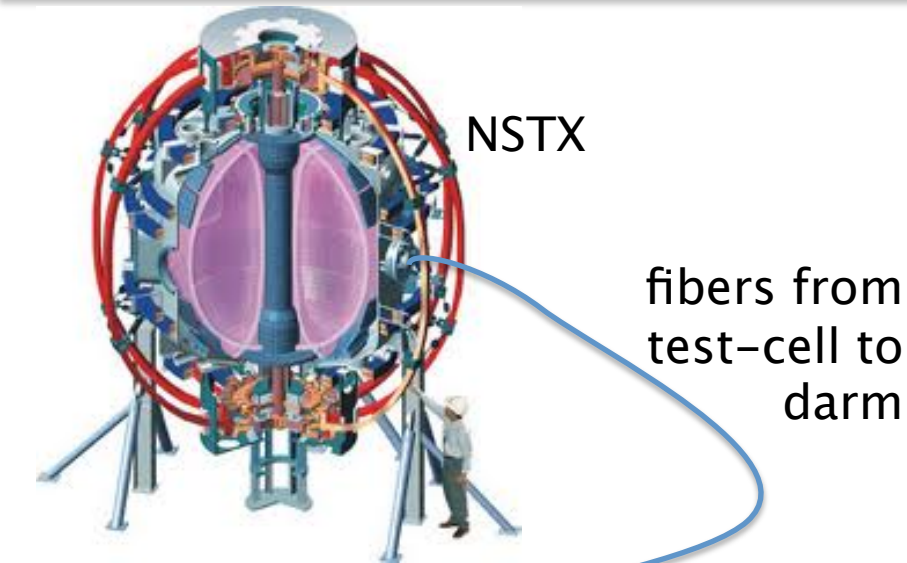

RTV diagnostic

Layout and Current status

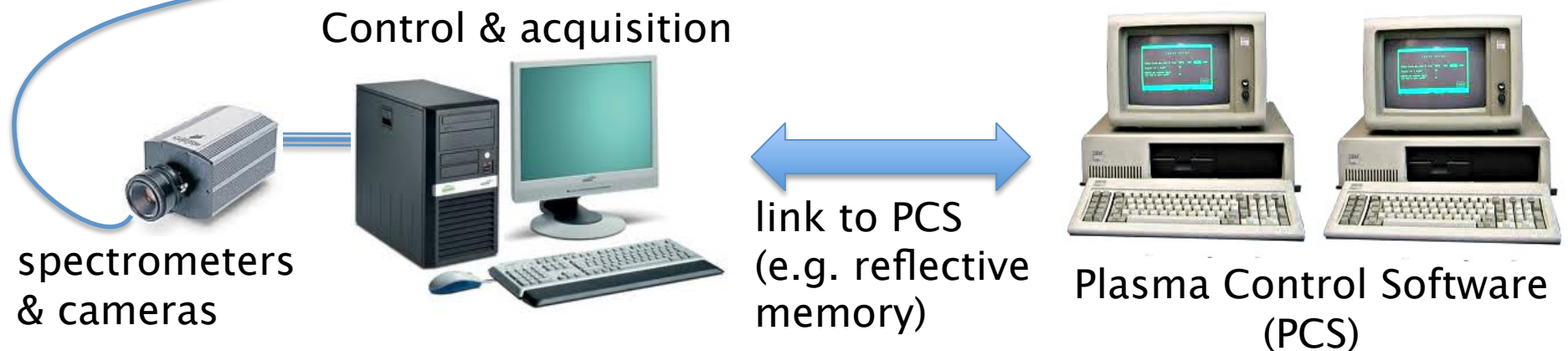
M. Podestà, PPPL
Feb. 2011

RTV systems: stand-alone diagnostic or *input* for PCS



Goal: *fast* measurements of toroidal rotation

- Up to 5kHz (limited by SNR)
- 2 systems, 4 channels
 - Active + background pairs



Basic parameters

parameter	value, min/max
Spectrometer	KOSI with HD grating
Camera	2x Cascade 128+
	max 5kHz sampling
	4 views/camera
	8 fibers/view
	16bit resolution
Target ops	1kHz sampling
	real-time analysis: v_{tor}
	<5% error on v_{tor}

Control & Acquisition PCs

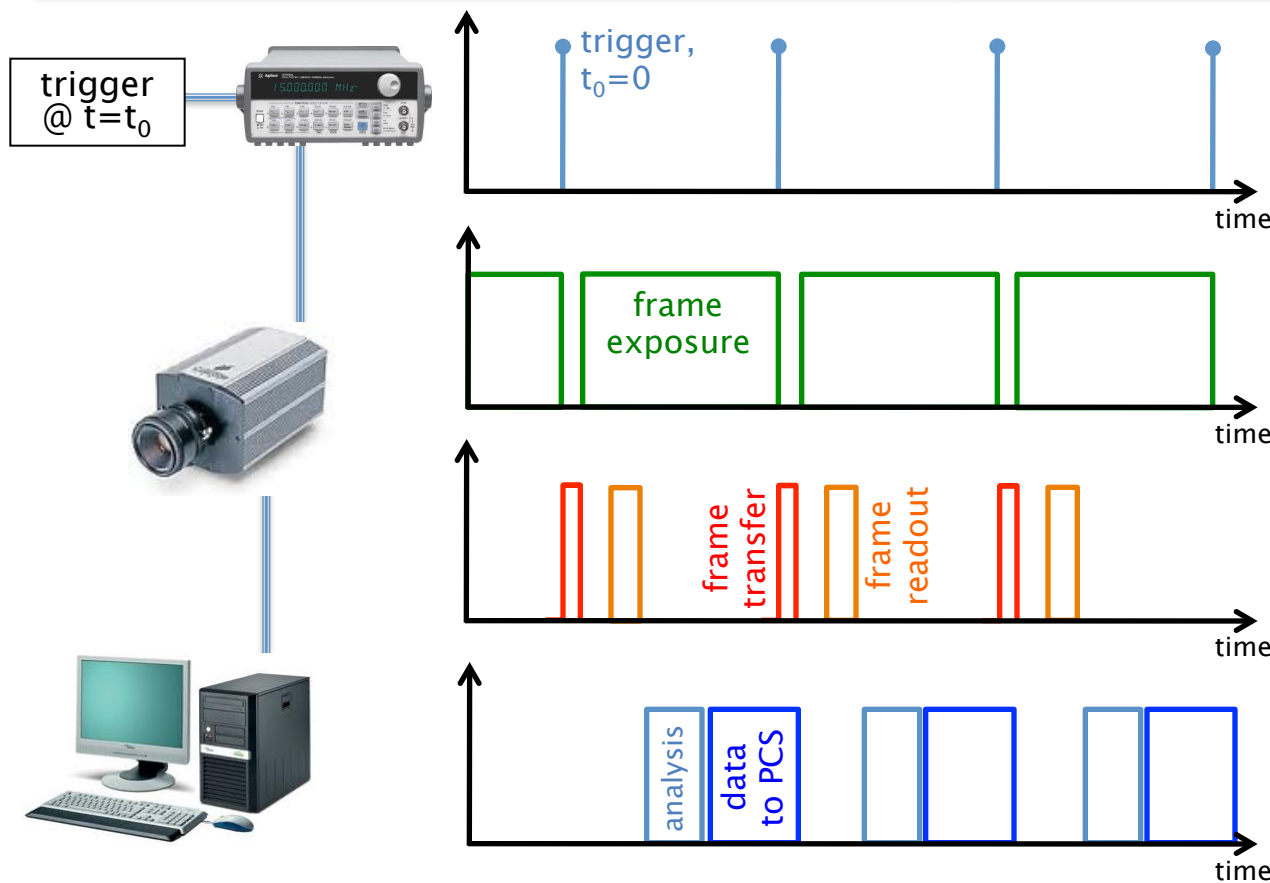
4U; QuadCore-XEON 3400
2xPCI-E x16
4xPCI 32bit/33MHZ
150GB/1TB drives
4:USB3.0

Description	Mfgr	Model	Qty
Processor	Intel	X3440 Lynnfield 2.53GHz 8MB L3	1
Motherboard	Asus	ASUS P7F-C/4L LGA 1156 Intel 3420 ATX	1
Memory	Kingston	2GB 1333MHZ DDR3 ECC CL9DIMM KIT3 TS Intel	2
Power Supply	Seasonic	SS-560KM Active PFC, 560W, 80Plus	1
DVD Burner	LG	DVD SATA Burner	1
CPU Heatsink	Dynatron	K985	1
1TB RE3 Drive	Western Dig	WD1002FBYS 1TB 7200 RPM SATA 3.0	1
150GB VelociRaptor Drive	Western Dig	VelociRaptor 150GB 10K SATA 3.0	1
92mm PWM Fan	Arctic Cooling	AF9 PWM 92mm Case Fan	3
4U Rackmount Case	AIC	EJ-RMC4S	1
4U Rack Rails	AIC	20" Rack Mount Rails	1
LCD Monitor	Samsung	EX2220X Glossy Black 21.5" 5ms LED	1
Keyboard w/GlidePoint	Adesso	ACK-730PB PS/2 Keyboard with Touchpad	1

Current status of control/ acquisition software

- Developed C++ prototype control software
 - Use standard libraries, open source only
 - PVCAM from camera manufacturer, LEVMAR for curve fitting
 - MDS events supported
 - Acquisition up to 5kHz achieved
 - 4 bins, 2 spectra/bin
 - Frame acquired and analyzed in $<200\mu\text{s}$
 - Real-time fitting w/ gaussian+linear background demonstrated in $<100\mu\text{s}$, multiple bins
 - Most time-consuming step in v_{tor} analysis
 - Excellent comparison w/ off-line fit (IDL)
- Used Windows XP so far, plan to move to Unix soon

Expected timing and data format



exposure	$\sim 1/f_{\text{samp}}$
frame shift	$< 15\mu\text{s}$
readout	$\sim 50\mu\text{s}$, $100\mu\text{s}$ fixed delay wrt t_0
analysis	$< 100\mu\text{s}$
data to PCS	$< 10\mu\text{s}$ (reflective memory*), or t.b.d.

Data to PCS,
16bit resolution:

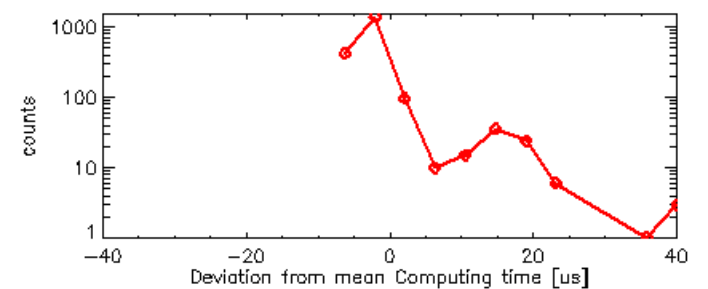
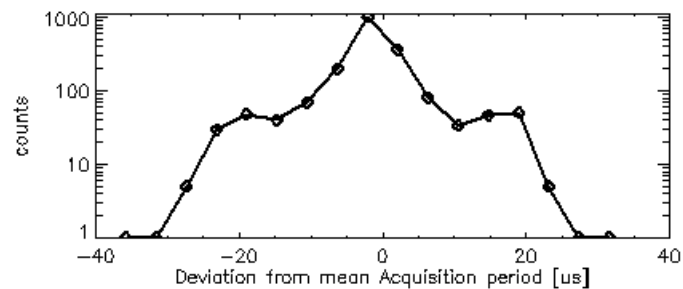
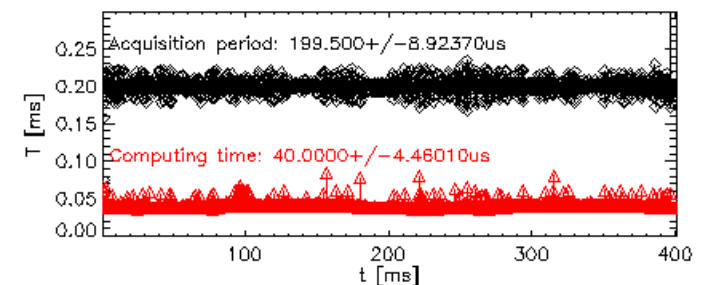
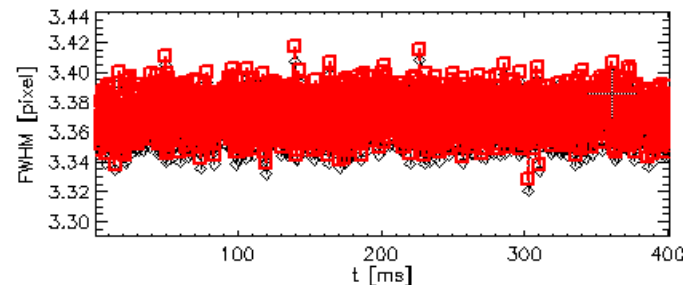
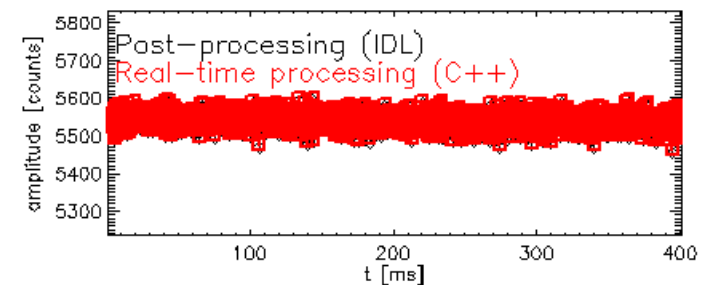
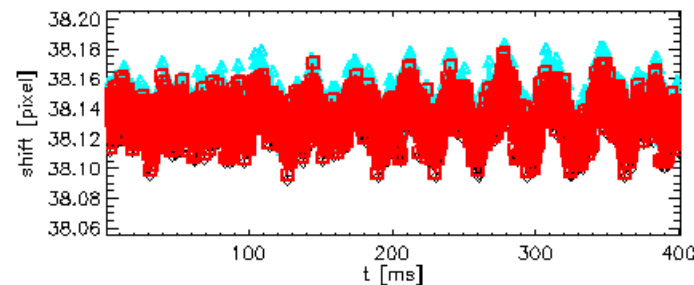
- 4x positions values
- 4x velocity values
- 4x velocity uncertainty values
- 4x "error flags"
- 1 time-stamp

*Fusion Engineering and Design 85 (2010) 561-563

Example of 'real-time' acquisition and analysis; typical performance



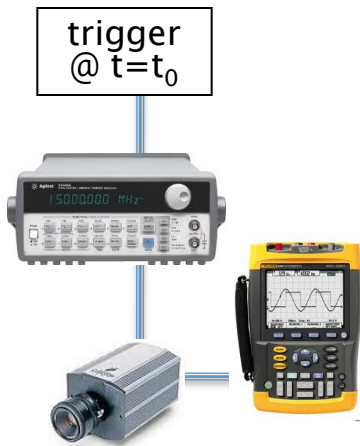
- Use waveform generator as external trigger
- Compare real-time vs. off-line (IDL) fits



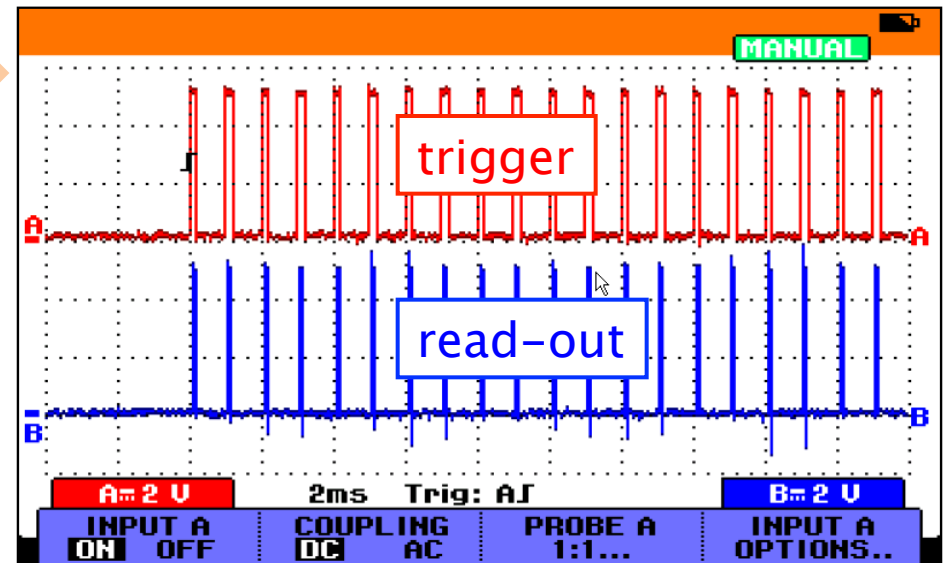
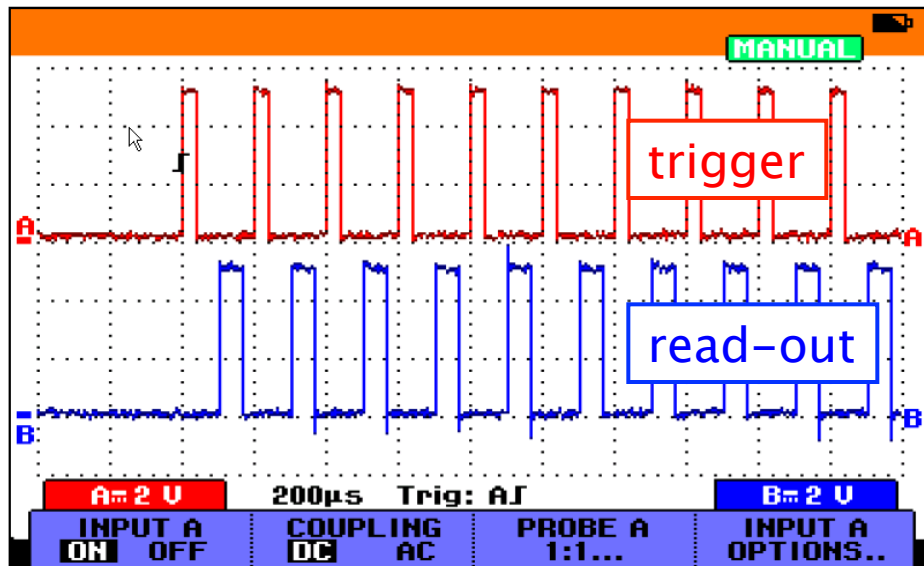
- Time-stamps from C++ software timer
- Compare w/ scope
 - Artifacts (spikes) introduced by Windows timer

No delay observed between initial trigger & start-of-acquisition

- Waveform generator provides precise, controllable trigger/timing
- Reproducible sequence, no 'set-up' delay observed, no missing frames, ...



Acquisition @ 1kHz



Acquisition @ 5kHz