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Theory Improvements

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X Science LLC

Kinetic terms in the RWM dispersion relation enable stabilization; theory consistent with experimental results



[🔘] NSTX-U

NSTX-U will have lower collisionality and second, off-axis neutral beam



[J. Menard et al., submitted to Nucl. Fusion (2011)]



EPs have a generally stabilizing effect that is independent of rotation; Anisotropic distribution impacts stability

$$\delta W_{F} = \frac{1}{2} \int \left\{ \left(\frac{|B_{L}|^{2}}{p_{0}} - \frac{B^{2}}{m_{0}} |\nabla \cdot \xi_{\perp} + 2\xi_{\perp} \cdot \kappa|^{2} + j_{\beta} \left(\xi_{\perp}^{\perp} \times \delta \right) \cdot B_{\perp} \right) + 2 \left(\kappa \cdot \xi_{\perp}^{*} \right) \left(\xi_{\perp} \cdot \nabla p_{ong} \right) \right\} dV.$$

$$siscatAlfvén fast magneto-aconstie kink ballooning (16) ballo$$

D NSTX-U

Rochester – Theory Improvements (Berkery)

 $\omega_{\phi}/\omega_{\phi}^{exp}$ (marginally stable)

March 15, 2012

[J.W. Berkery et al., Phys. Plasmas 17, 082504 (2010)]

0.5

χ

1.0

Reduced collisionality (v) is stabilizing for RWMs, but only near kinetic resonances

(



- NSTX-tested kinetic RWM stability theory: 2 competing effects at lower v
 - Stabilizing collisional dissipation reduced (expected from early theory)
 - Stabilizing resonant kinetic effects enhanced (contrasts early RWM theory)

[J. Berkery et al., Phys. Rev. Lett. 106, 075004 (2011)]

MISK currently uses an energy-dependent collisionality, MARS-K uses a constant.

Possible improvements:

Particle, momentum, and energy conserving Krook operator for like-particle collisions (suggested by G. Hammett):

$$C(\tilde{f}_j) = -\nu_{\text{eff}} \tilde{f}_j + \nu_{\text{eff}} f_j \left[\frac{\tilde{n}_j}{n_j} + \frac{m_j u_{\parallel} v_{\parallel}}{T_j} + \frac{\tilde{T}_j}{T_j} \left(\hat{\varepsilon} - \frac{3}{2} \right) \right]$$

Lorentz operator with pitch angle dependence:

$$\nu_{3}(\varepsilon,\chi,\Psi) = \frac{1}{2}\nu_{2}\epsilon_{r}\left[Z_{\text{eff}} + \frac{1}{\sqrt{\pi\hat{\varepsilon}}}e^{-\hat{\varepsilon}} + \frac{1}{\sqrt{\pi}}\left(2 - \hat{\varepsilon}^{-1}\right)\int_{0}^{\sqrt{\hat{\varepsilon}}}e^{-t^{2}}dt\right]\frac{\partial}{\partial\chi}\left(1 - \chi^{2}\right)\frac{\partial}{\partial\chi}$$

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Further exploration of the effect of plasma rotation

- Effect on equilibrium
- Including poloidal rotation
- Eigenfunction modification (next slide)





[N. Aiba et al., Phys. Plasmas 18, 022503 (2011)]



Figure 26. (*a*) Comparison of plasma ω_E profiles versus *q* for the RWM-unstable plasma excluding (black) and including (other colours) the carbon impurity diamagnetic rotation in the radial force balance equation for the calculation of the electrostatic potential profile $\Phi(\psi)$. (*b*) Comparison of growth rates of the *n* = 1 RWM computed with the MARS-F code plotted versus ω_E using the generalized-geometry analytic fit to the particle orbit times and including the neoclassical parallel resistivity profile for the plasma resistivity.

[J. Menard, APS 2010 and 2011]

[J. Menard *et al.*, Nucl. Fusion **50**, 045008 (2010)]

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The RWM eigenfunction may be modified by several factors



The importance of eigenfunction modification and Alfven resonances at rational surfaces will come out of code benchmarking.

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How can we approximate eigenfunction modification in MISK with an iterative approach?

- 1) We take the eigenfunction from the PEST marginally-stable eigenfunction: $\gamma \rightarrow 0$, $\delta I \rightarrow 0$, $\delta W_F = -\delta W_V$ (at the marginal wall position).
- 2) We can calculate a fluid growth rate with that fixed eigenfunction, the true wall position, and the assumption that the inertial term is still negligible.

$$\gamma_F \tau_w = -\delta W_\infty / \delta W_b$$

3) We can calculate a kinetic growth rate and mode rotation frequency by including kinetic effects and anisotropy corrections, but still assuming a fixed eigenfunction and negligible inertial term. $\delta W_{\infty} + \delta W_{K}$

$$(\gamma - i\omega_r)\tau_w = -\frac{\delta W_\infty + \delta W_K}{\delta W_b + \delta W_K}$$

- 4) We can even iterate for corrected γ and ω_r , and solve for multiple roots. [J. Berkery et al., Phys. Plasmas **18**, 072501 (2011)]
- 5) Keeping the eigenfunction fixed, we could additionally try to include the inertial term (which actually involves multiple roots as well): $\delta W = \delta W_{ee} + \delta U$

$$(\gamma - i\omega_r)\tau_w = -\frac{\delta W_\infty + \delta W_K + \delta I}{\delta W_b + \delta W_K + \delta I}$$
$$\delta I = \frac{1}{2} \sum_j \int \rho_0 (\gamma + i(n\omega_\phi - \omega_r))(\gamma + i(n\omega_\phi - \omega_r) + i\omega_{*j}) \left| \boldsymbol{\xi}_\perp \right|^2 d\mathbf{V}$$

6) Now, if the eigenfunction is allowed to change, how do we solve for a new one?

Rotation and kinetic damping may also affect the ideal no-wall stability limit





[J. Menard and Y.Q. Liu, EPS 2012]





[I. Chapman *et al.*, Plasma Phys. Control. Fusion **53** 125002 (2011)]

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Important Physics Is Given by the Evaluation of the Orbit Integral.

The general solution of the linearized Vlasov equation including zeroth and first order gyrophase-dependent terms is written as

$$\begin{split} \tilde{f} &= -\tilde{\boldsymbol{\xi}}_{\perp} \cdot \nabla f + Z_{j} e \frac{\partial f}{\partial \mathscr{E}} \tilde{\boldsymbol{\zeta}} + i m_{j} \left(\omega \frac{\partial f}{\partial \mathscr{E}} - \frac{\partial f}{\partial P_{\phi}} \right) \left[\tilde{\boldsymbol{\xi}}_{\perp} \cdot \boldsymbol{v} - \tilde{\eta} \right] + \frac{\partial f}{\partial \mu} \left(\tilde{\boldsymbol{\xi}}_{\perp} \cdot \nabla \mu - \frac{M(\tilde{\boldsymbol{\xi}}_{\perp})}{B} \right) \\ \tilde{\eta} &= -\frac{\upsilon_{\parallel}}{\Omega_{cj}} [\hat{b} \times \boldsymbol{v}_{\perp} \cdot (\hat{b} \cdot \nabla) \tilde{\boldsymbol{\xi}}_{\perp} + \hat{b} \cdot (\hat{b} \times \boldsymbol{v}_{\perp}) \cdot \nabla \tilde{\boldsymbol{\xi}}_{\perp}] \\ &+ \frac{1}{4\Omega_{cj}} [\boldsymbol{v}_{\perp} \times \hat{b} \cdot \boldsymbol{v}_{\perp} \cdot \nabla \tilde{\boldsymbol{\xi}}_{\perp} + \boldsymbol{v}_{\perp} \cdot (\boldsymbol{v}_{\perp} \times \hat{b}) \cdot \nabla \tilde{\boldsymbol{\xi}}_{\perp}] - \frac{\upsilon_{\perp}^{2}}{2\Omega_{cj}} \mathbf{B} \cdot \nabla \times \left(\frac{\tilde{\boldsymbol{\xi}}_{\perp}}{B} \right) \\ &+ \int_{-\infty}^{t} dt' \left\{ \left(\frac{\upsilon_{\perp}^{2}}{2} - \upsilon_{\parallel}^{2} \right) \boldsymbol{\kappa} \cdot \tilde{\boldsymbol{\xi}}_{\perp} + \frac{\upsilon_{\perp}^{2}}{2} \nabla \cdot \tilde{\boldsymbol{\xi}}_{\perp} - \frac{Z_{j} e}{m_{j}} \tilde{\boldsymbol{\zeta}} \\ &+ \frac{\upsilon_{\parallel} \upsilon_{\perp}^{2}}{2\Omega_{cj}} \nabla \cdot \left[\frac{1}{2} (\hat{b} \cdot \nabla \ln B) (\hat{b} \times \tilde{\boldsymbol{\xi}}_{\perp}) - \tilde{\boldsymbol{\xi}}_{\perp} \times \hat{b} \cdot \nabla \hat{b} \right] \right\} \end{split}$$

FLR effects large for MHD modes at rational surfaces





Finite Orbit Width Kinetic damping of RWMs

- Orbit widths can be very important for fast ions
- Use guiding-centre following code to capture this physics



- RWM passively stable in ITER Advanced Scenario due to kinetic damping
- Only capture these effects by including orbit widths
- Sensitive to rotation, so should not be relied upon!



Ian Chapman email:

"I need to talk to YQ and Jon Graves who probably have insight from the algebraic formulation with FOW included that they're working on."

IOP PUBLISHING

PLASMA PHYSICS AND CONTROLLED FUSION

Plasma Phys. Control. Fusion 52 (2010) 055004 (19pp)

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Neoclassical ion heat flux and poloidal flow in a tokamak pedestal

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