Towards a Predictive Capability for Local Helicity Injection Startup

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University of Wisconsin-Madison 56<sup>th</sup> American Physical Society Division of Plasma Physics Meeting

> New Orleans, LA Oct. 28<sup>th</sup>, 2014



PEGASUS Toroidal Experiment



#### Local Helicity Injection (LHI) is a Promising Non-Solenoidal Startup Technique



- Unstable current streams form tokamak-like state via Taylor relaxation
- Appears scalable to MA-class startup





#### A Hierarchy of Predictive Models Being Developed for LHI Startup

1. Maximum I<sub>p</sub> limits\*

Helicity Conservation

 $I_p \leq I_{TL} \sim \sqrt{\frac{I_{TF}I_{inj}}{W}}$ 



2. 0-D power-balance  $I_p(t)$ 

$$I_p \left[ V_{LHI} + V_{IR} + V_{IND} \right] = 0; \ I_p \le I_{TL}$$

Simulated current stream

- 3. 3D Resistive MHD (NIMROD)\*\*
  - See Sovinec, GP8.00047



\*D.J. Battaglia, et al. Nucl. Fusion **51** (2011) 073029. \*N.W. Eidietis, Ph.D. Thesis, UW-Madison, 2007. \*\*J. O'Bryan, Ph.D. Thesis, UW-Madison, 2014. \*\*J. O'Bryan, C.R. Sovinec, Plasma Phys. Control. Fusion **56** 064005 (2014)



## 2. 0-D Power-Balance: Lumped-Parameter Model for Predictive I<sub>p</sub>(t)

- Model elements:
  - Inputs:  $R_0(t)$ , shape(t),  $V_{LHI}(t)$ ,  $\eta(t)$ ,  $\ell_i(t)$
  - Low-A inductance, force-balance
- Reasonable agreement between calculated  $I_{\rm p}(t)$  and measurement

 High-I<sub>p</sub>: current drive dominated by PF induction, geometry evolution 0-D model predictions vs data



#### Physics Test for MA Startup on NSTX-U Requires Increased Helicity Injection Drive



• Confinement when  $V_{LHI} \gtrsim V_{IND}$  is a critical issue

- At  $I_p \sim 0.2$ -0.3 MA in PEGASUS



#### Knowledge of Confinement an Important Question for Predictability

•  $I_p(t)$  model depends critically on  $\eta$ 





• Dual confinement regimes?

Warm Core	Cool Edge
OH-like	Stochastic
Inductive drive	Reconnection
Low $\tilde{B}/B$	Large $\tilde{B}/B$





## 3. NIMROD Simulations Show I<sub>p</sub> Growth Resulting from Reconnection in Edge

- Resistive MHD modeling (NIMROD)
- Divertor injection
  - Coherent current streams reconnect
  - Inject current rings

- Qualitative agreement to experiment:
  - Injector-localized MHD
  - Intermittent MHD bursts
  - $\quad \Delta I_p \sim I_{inj} \ jumps$
  - Reconnection driven anomalous ion heating observed (M.G. Burke, PP8.00095)







\*\*J. O'Bryan, PhD. Thesis, UW Madison 2014



#### Understanding Injector Physics Enables High V<sub>ini</sub> Operation

- High-power, low-PMI while immersed in scrape-off plasma
  - Cathode shaping mitigates cathode spots
  - Shield rings, local limiter prevent arc-back
- $I_p$  increases with  $V_{inj}$
- J<sub>inj</sub>, V<sub>inj</sub> depend on tokamak scrape-off density
  - Space-charge neutralization of streams

$$J_{INJ} = n_{edge} e_{\sqrt{\frac{2e}{m_e}}} \sqrt{V_{INJ}}$$

Advanced injectors with quiescent operation









## Technology & Science Challenges for NSTX-U & Beyond

- Long-pulse startup (0.1 s)
  - Injector heat load
  - Edge density control
  - Plasma control
- High B<sub>TF</sub>
  - Confinement scaling
  - Effective injector size
  - Initial tokamak formation
  - Reconnection with high guide field
- Plasma size scaling
- Close fitting wall
  - Potentially complicates relaxation

Injector technology evolving to meet physics challenges

**Concave cathode** 

Frustum cathode, local limiter





High heatflux cathode, shield rings







## PEGASUS-U to Address Physics, Technology for Scalable LHI Startup

- Long pulse startup (0.1 s)
- New central column (A~1.2)
  - Increased  $B_{TF}(5x)$
  - New OH solenoid, PPPL (6x V-s)
- Enhanced divertor coils
- Upgraded High-V<sub>LHI</sub> Injectors
  - Remotely insertable
- Core diagnostics:
  - Multipoint TS
  - CHERS via DNB
- Supporting the 5 year plan for NSTX-U

#### PEGASUS-U







#### Moving Towards Predictable, MA-Class, Non-Solenoidal Startup

- A hierarchy of models is being developed for LHI startup:
  - Max I<sub>p</sub>: helicity conservation, Taylor relaxation
  - $I_p(t)$ : 0-D power-balance (future: TSC)
  - Detailed dynamics: resistive MHD (NIMROD)
- Outstanding issues:
  - Scaling to high toroidal field, longer-pulse, large size
  - Confinement, stability in LHI drive dominant regime
  - Edge density, J<sub>inj</sub> control strategies
  - Advanced injector development
- PEGASUS-U will address critical LHI physics issues for NSTX-U

K.E. Thome talk: next this session, GO3 PEGASUS group posters: session PP8





#### Outboard LHI Provides Robust Startup on the PEGASUS ST





## Controlling Plasma-Material Interaction is Enabling High V<sub>INJ</sub> Operation

- Injector requirements include
  - $\ Large \ A_{inj}, \ J_{inj}$
  - V<sub>inj</sub> > 1 kV
  - $\Delta t_{pulse} \sim 10\text{--}100 \text{ ms}$
  - Minimize PMI
  - ...all adjacent to tokamak LCFS
- Advanced injector design enables high V<sub>inj</sub>
  - Cathode shaping to mitigate cathode spots
  - Shielding of cathode, insulators to prevent injector breakdown
  - 3x improvement in  $V_{inj}$ ,  $\Delta t_{pulse}$









*Voltage of quiescently operating injectors (red) and voltage after breakdown of overdriven injectors (black)* 





## Technology & Science Challenges for NSTX-U & Beyond

- Long-pulse startup (100ms)
  - Injector heat load
  - Edge density control
  - Plasma control
- High B<sub>TF</sub>
  - Confinement scaling
  - Effective injector size
  - Initial tokamak formation
  - Reconnection with high guide field
- Close fitting wall
  - Potentially complicates relaxation

## Injector technology evolving to meet physics challenges

Concave cathode: Cathode spots near BN  $\rightarrow$  PMI



Frustum cathode,

local limiter:





Cathode spot control, but arc-back







Stepped shielding: Mitigate spots & arc-back, but heat-load cracking









## Tests of Various Injector Concepts Favor Smaller A<sub>INJ</sub>, High V<sub>INJ</sub>

- Tests of large-area passive electrodes show reduced effective A<sub>INJ</sub>
  - Integrated metallic electrode surface
    - Cathode spot emission



Above: integrated electrode injector assembly

- Large area gas-effused Mo Plate
  - Hollow cathode emission
  - Non-uniform  $J_{INJ}$ , effective  $A_{INJ} = 0.15 A_{GEOMETRIC}$
- Conclusion: Arc-based injector system most effective path to maximize HI rate







#### LHI Injects Current Streams that Relax, Form Tokamak-Like Plasma





\*\*D

#### Helicity Balance, Taylor Relaxation Criteria Set Max Achievable I<sub>p</sub> from LHI

Helicity balance in a Tokamak geometry:

$$\frac{dK}{dt} = -2\int_{V} \eta \mathbf{J} \cdot \mathbf{B} \, \mathrm{d}^{3} \mathrm{x} - 2\frac{\partial \Psi}{\partial t} \Psi - 2\int_{A} \Phi \mathbf{B} \cdot \mathrm{d} \mathbf{s} \quad \Longrightarrow \quad \mathbf{I}_{p}$$

• Helicity injection provides an effective loop voltage<sup>\*,\*\*</sup>:

#### Taylor relaxation of a force-free equilibrium:



 $\leq \frac{A_p}{2\pi R_0 \langle \eta \rangle} \left( V_{ind} + V_{eff} \right)$ 



#### Global Helicity Balance, Taylor Relaxation Limits Confirmed



D.J. Battaglia, et al. *Nucl. Fusion* **51** (2011) 073029. N.W. Eidietis. *Non-inductive startup of the Pegasus Spherical Torus using Localized washer-gun current source*, Ph.D. Thesis, UW-Madison, 2007. THE UNIVERSITY

MADISO



# Experiments demonstrate dependence on the width of the driven current layer

- Relaxation current limit scales as  $w^{-1/2}$
- One-gun discharges had higher limits than corresponding three-gun cases, indicating the gun array was misaligned:





#### Internal Measurements Show Null Formation, J(R,t) Throughout LHI Discharge Evolution

- Initial relaxation to tokamak-like topology coincident with inboard null formation
  - Injected current filaments perturb vacuum **B**
  - $B_z$  must be sufficiently low and/or  $I_{inj}$  sufficiently high for null to form
- Hall probe<sup>\*</sup>  $B_Z(R)$  provides  $J_{\phi}(R)$  evolution

- Predicted field null observed



<sup>2-</sup>D force free current model



\*: Bongard et al., Rev. Sci. Instrum. 81, 10E105 (2010)





#### 2. When I<sub>p</sub>(t) < Taylor Limit 0-D Power Balance Model Predicts I<sub>p</sub>(t)

• Lumped parameter model + helicity conservation:

$$I_p \left[ V_{eff} + V_R + V_{PF} + V_{Lp} \right] = 0$$

- V<sub>eff</sub>: From helicity injection
- $V_R$ : Resistive dissipation from assumed flat Spitzer  $T_e(R,t) = 70eV$
- V<sub>PF</sub>: Poloidal induction voltage
- V<sub>Lp</sub>: Voltage due to plasma self-inductance
- Inputs:  $R_0(t)$ , a(t),  $Ip(t_0)$ ,  $<\eta_0>$ ,  $\kappa(t)$ ,  $\ell_i(t)$ 
  - Analytic low-A descriptions of  $L_p$ ,  $B_z$ , plasma shape
- Differential equation in  $I_p(t)$  solved when  $I_p(t) < I_{Taylor}(t)$





Poynting's Theorem Applied at Plasma Boundary Defines Current Sources & Sinks

$$\underline{I_p V_s} = \iiint \frac{\partial}{\partial t} \left( \frac{B_{\theta}^2}{2\mu_0} \right) dV + \underline{I_p^2 R_p} - \underline{I_p V_{NICD}}$$

#### Plasma surface voltage

- Inductive drive from OH, PF-ramping
- Self-inductance: contribution from *external* fields

#### Internal magnetic energy

Self-inductance: contribution from *internal* fields, static boundary

#### **Resistive dissipation**

- Uniform, constant Spitzer resistivity assumed

#### Non-inductive current drive

- Local helicity injection

$$V_{s} = -\frac{\partial}{\partial t} \left( \psi_{OH} + \sum_{i} \psi_{PF,i} + L_{e} I_{p} \right)$$

$$\frac{1}{I_p} \frac{\partial}{\partial t} \left( W_{B,p} \right) = \frac{1}{I_p} \frac{\partial}{\partial t} \left( \frac{1}{2} L_i I_p^2 \right)$$

$$V_{R} = I_{p}R_{p} = I_{p}\left(\frac{\left\langle \eta_{p}\right\rangle 2\pi R_{0}}{A_{p}}\right)$$

$$V_{NICD} = V_{eff} \approx \frac{A_{inj}B_{\phi,inj}}{\Psi_T}V_{inj}$$







#### Plasma Self-Inductance Modeled with Analytic, Low-A Approximations

• Plasma self-inductance is partitioned into internal, external components:

$$L_p = \underline{L_i} + \underline{L_e}$$

• External component L<sub>e</sub> is heavily aspect-ratio dependent:

$$\underline{L_e} = \mu_0 R_0 \frac{a(\varepsilon)(1-\varepsilon)}{1-\varepsilon+\kappa b(\varepsilon)} \qquad a(\varepsilon) = (1+1.81\sqrt{\varepsilon}+2.05\varepsilon)\ln\left(\frac{8}{\varepsilon}\right) - (2.0+9.25\sqrt{\varepsilon}+1.21\varepsilon) \\ b(\varepsilon) = 0.73\sqrt{\varepsilon}(1+2\varepsilon^4-6\varepsilon^5+3.7\varepsilon^6) \\ \text{where} \quad \varepsilon = \frac{1}{A} \qquad \text{*S.P. Hirshman and G.H. Nielson 1986 Phys. Fluids 29 790}$$

• Internal component decreasing in time (typically  $l_i = 0.5 \rightarrow 0.2$ ):

$$W_{B,p} = \iiint_{V_p} \frac{B_{\theta}^2}{2\mu_0} dV = \frac{1}{2} L_i I_p^2 = \frac{1}{2} \left( \frac{\mu_0 V_p}{C_p^2} \ell_i \right) I_p^2$$





#### Plasma Self-Inductance Modeled with Analytic, Low-A Approximations

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- Applied vertical field provides force-balance and inductive loop-voltage
  - $\psi_{PF}$  estimated with Hirshman & Nielson\* mutual inductance-like  $M_v$  equation

$$\frac{V_{PF}}{\partial t} = \frac{\partial}{\partial t} \left( \sum_{i} \psi_{PF,i} \right) \approx \frac{\partial}{\partial t} \left[ M_V \pi R_0^2 B_V \Big|_{R_0} \right] \qquad c(\varepsilon) = 1 + 0.98\varepsilon^2 + 0.49\varepsilon^4 + 1.47\varepsilon^6 
\text{where} \qquad M_V(\varepsilon,\kappa) = \frac{\left(1 - \varepsilon\right)^2}{\left(1 - \varepsilon\right)^2 c(\varepsilon) + d(\varepsilon)\sqrt{\kappa}} \qquad c(\varepsilon) = 0.25\varepsilon \left(1 + 0.84\varepsilon - 1.44\varepsilon^2\right) 
\text{*S.P. Hirshman and G.H. Nielson 1986 Phys. Fluids 29 790}$$

- $B_v$  required for force-balance is aspect-ratio and shape dependent
  - Uses Mitarai & Takase\* formula for  $B_v$  for force-balance at low-A with  $\kappa$ :

$$B_{V} = \frac{\mu_{0}I_{p}}{4\pi R_{0}} \left\{ \frac{1}{\mu_{0}} \frac{\partial L_{e}}{\partial R} + \frac{\ell_{i}}{2} + \beta_{p} - \frac{1}{2} \right\}$$

\*O. Mitarai and Y. Takase 2003 Fusion Sci. Technol.



# Low-A, Analytic Models Approximate V<sub>PF</sub>

- Applied vertical field provides force-balance and inductive loop-voltage
  - $\psi_{PF}$  estimated with Hirshman & Nielson\* mutual inductance-like  $M_v$  equation



- B<sub>v</sub> required for force-balance is aspect-ratio and shape dependent
  - Uses Mitarai & Takase\* formula for  $B_v$  for force-balance at low-A with  $\kappa$ :

$$B_{V} = \frac{\mu_{0}I_{p}}{4\pi R_{0}} \left\{ \frac{1}{\mu_{0}} \frac{\partial L_{e}}{\partial R} + \frac{\ell_{i}}{2} + \beta_{p} - \frac{1}{2} \right\}$$

\*O. Mitarai and Y. Takase 2003 Fusion Sci. Technol.



# System Represented by ODE Initial Value Problem

$$\frac{\partial I_{p}}{\partial t} = -\frac{\frac{1}{2}\frac{\partial L_{i}}{\partial t} + \frac{\partial L_{e}}{\partial t} + R_{p} + \frac{\partial}{\partial t}\left[M_{V}\pi R_{0}^{2}\left(\frac{B_{v}}{I_{p}}\right)\right]}{L_{p} + M_{V}\pi R_{0}^{2}\left(\frac{B_{v}}{I_{p}}\right)}I_{p} + \frac{V_{OH} + V_{eff}}{L_{p} + M_{V}\pi R_{0}^{2}\left(\frac{B_{v}}{I_{p}}\right)}$$

• At initial relaxation to tokamak-like state:

– Initial value from Taylor limit

- If I<sub>p, Pow. Bal.</sub> > I<sub>p, Taylor</sub>: follow Taylor limit
- Else: follow power-balance





#### Plasma Parameters Constitute Power-Balance Inputs

- $I_{p}(t_{0})$ 
  - Initial condition to DE solver
- Shape
  - $R_0(t), a(t), \kappa(t), \delta(t)$
- Plasma parameters
  - $< \eta >$  assumed constant, Spitzer
  - $-\beta_p=0$
  - −  $l_i: 0.5 \rightarrow 0.2$
- LHI parameters

 $- A_{inj}(t), V_{inj}(t)$ 



Time [ms]



# $\bigcirc$ LHI Plasmas Undergo Two-Phase I<sub>p</sub>(t) Evolutions



- Low I<sub>p</sub>: Taylor limited
  - Set by plasma geometry, I<sub>inj</sub>

- Higher I<sub>p</sub>: power-balance
  - Balance of LHI, inductive effects, resistive losses





#### Using 0-D Model as Interpretive Tool Gives Insight into LHI Current Dynamics



 Inductive voltages dominated by geometric evolution

- Geometry evolution ~ 3 V
- PF ramping ~ 1 V
- Inductive reactance ~ 4 V





#### Testing and Calibration of the Model Proceeding on Multiple Fronts

$$I_{p}V_{s} = \frac{\partial}{\partial t} (W_{B,p}) + I_{p}^{2}R_{p} - I_{p}V_{NICD}$$

Plasma surface voltage

 $V_{s} = -\frac{\partial}{\partial t} \left( \psi_{OH} + \sum_{i} \psi_{PF,i} + L_{e} I_{p} \right)$ 

Internal magnetic energy

Non-inductive current drive

 $\frac{1}{I_p}\frac{\partial}{\partial t}\left(W_{B,p}\right) = \frac{1}{I_p}\frac{\partial}{\partial t}\left(\frac{1}{2}L_iI_p^2\right)$ 

**Resistive Dissipation** 

 $V_{R} = I_{p}R_{p} = I_{p}\left(\frac{\eta_{p}2\pi R_{0}}{A_{r}}\right)$ 

I<sub>p</sub>(t) compared for various plasma evolutions

Approximations for ψ<sub>s</sub>(t), W<sub>m</sub>(t), L<sub>i</sub>(t) calibrated to experiment

Thomson Scattering

TF variations

Upgraded injector systems to vary V<sub>eff</sub>



J.L. Barr, APS DPP 2014

 $V_{NICD} = V_{eff}$ 



#### Model Applied to NSTX-U Geometry for Initial $I_p \sim 1$ MA Start-up Scenario Prediction



\*C. Neumeyer et all (2009) 23rd IEEE/NPSS Symposium on Fusion Engineering

\*\*C. Neumeyer (2001) "NSTX Internal Hardware Dimensions" http://nstx.pppl.gov/nstx/Engineering/NSTX\_Eng\_Site/Technical/Machine/NSTX\_Engr\_Machine\_Dims\_cm.html





#### Current Growth During LHI Correlated with Bursts of MHD Activity

#### Measured burst properties include

- Two primary spectral components
  - $n=1 \Longrightarrow 10-20 \text{kHz} \textcircled{a} R_{inj}$ , line-tied
  - n=0 rightarrow <5 kHz, plasma motion
- Typically correlates with sharp I<sub>p</sub> increase

#### NIMROD simulations produce bursty MHD

- Bursts from transient reconnection events
- Qualitative agreement with experiment





## Bursts show n=1

- Current multiplication, transport accompanied by MHD activity
- Two common spectral features
  - High-frequency 10-20 kHz n = 1
  - Low-frequency < 5 kHz n = 0
- n = 1 mode consistent with line tying
  - Activity localized near injector radius
  - Toroidal asymmetry in
- n = 0 localized to plasma interior
  - Inward radial motion





- NIMROD shows magnetic reconnection during LHI
  - Ion heating commonly observed in reconnection experiments\*

- Consistent with ion cyclotron heating mechanism\*\*
  - Pegasus LHI MHD spectra show significant power in IC resonance region



Predictive Understanding of Plasma Impedance Required for Projecting to Higher Ip

- Determines feasible V<sub>INJ</sub>, A<sub>INJ</sub>, I<sub>INJ</sub>
   and demands on power system
- Governed by plasma physics of arc source and tokamak edge
  - Low  $I_{INJ}$ : Double layer  $J_{INJ} \sim V_{INJ}^{3/2}$
  - High  $I_{INJ}$ : Space charge neutralization 10 of e-beam by edge plasma

$$J_{INJ} = n_{edge} e_{\sqrt{\frac{2e}{m_e}}} \sqrt{V_{INJ}}$$

- n<sub>edge</sub> dependence to be validated
  - Assuming  $n_{edge} \sim fill pressure$

Ramp-up I-V characteristics for Pegasus injectors agrees with 2-parameter model across wide range of fill pressures



