

# Development of a prototype infrared imaging bolometer for NSTX-U

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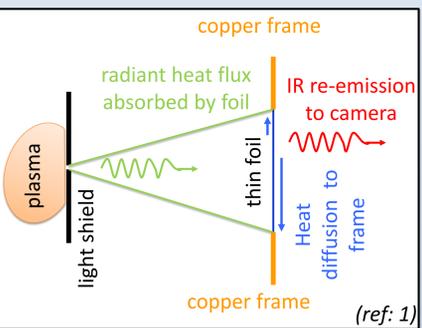
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**ABSTRACT** - Measurements of the radiated power in fusion reactors are of high importance for studying detachment and the overall power balance. A prototype Infrared Video Bolometer (IRVB) system for NSTX-U is being developed for this purpose in addition to the planned resistive bolometer and AXUV diodes on the machine. The IRVB has proven to be a powerful diagnostic on the LHD and JT-60U devices for its 2D imaging quality and reactor environment compatibility. A poloidal view of the lower center stack and inboard divertor are envisaged for the 2015 NSTX-U run campaign. The IRVB measures radiation from the plasma by monitoring the temperature evolution of a 2.5 μm thick 9 x 7 cm<sup>2</sup> calibrated Pt foil using an IR camera (SB focal plane, 2-12 μm, 128x128 pixels, 1.6 kHz). The power incident on the foil is calculated by solving the 2D heat diffusion. Optimizing the camera settings resulted in a sensitivity of 17 mK and a noise equivalent power density of 60.8 μW cm<sup>-2</sup> for 4x20 bolometer pixels and 50 Hz time response. Based on a first estimation of the expected radiated power on the foil, a signal-to-noise ratio of 135 is hence obtained.

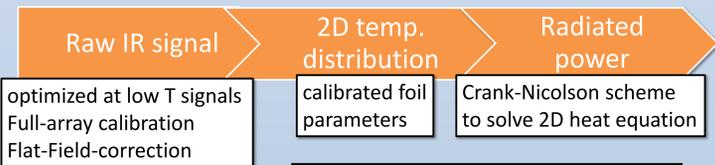
## OBJECTIVES

- Testing feasibility of measuring 2D radiation structures in the NSTX-U divertor using the Infrared Video Bolometer (IRVB) technique (1D detector for prototype)
- Optimizing IRVB time response and sensitivity in comparison to conventional resistive bolometer and AXUV diode systems

## IRVB CONCEPT AND METHOD



- Advantages:**
- 2D radiation measurement
  - Condensing an increased number of bolometer channels on a single detector
  - Absence of vacuum feedthroughs
  - Absence of electrical pickup
- Disadvantages:**
- Previous implementations had limited time response
  - Need for optical path from backside of detector



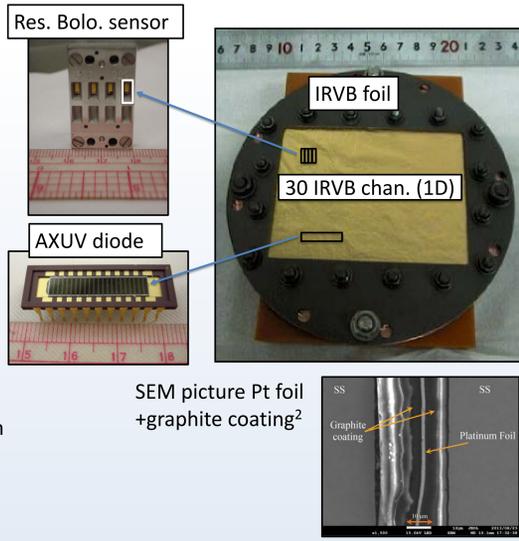
from calibration:  $\Omega_{rad} = \frac{P_{rad}}{kt_f^2}$

from calibration:  $-\Omega_{rad} + \Omega_{bb} + \frac{1}{\kappa} \frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2}$

from calibration:  $\Omega_{bb} = \frac{\epsilon \sigma_{s-b} (T^4 - T_0^4)}{kt_f}$

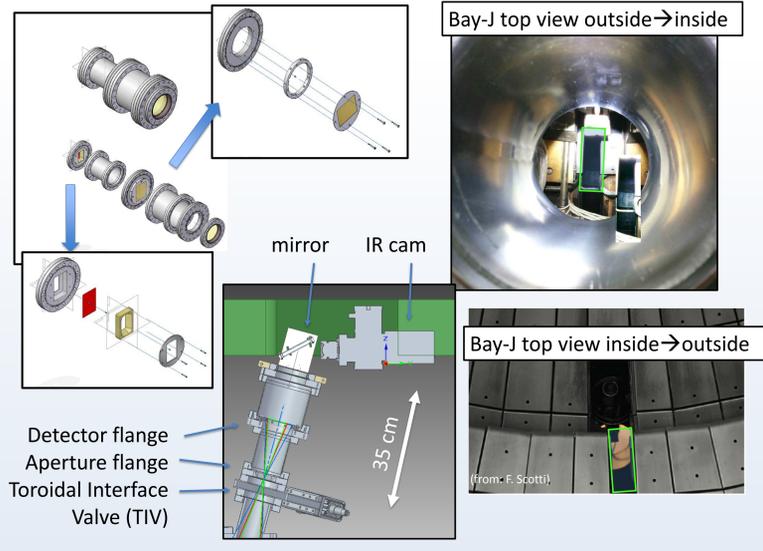
## BOLOMETRIC DIAGNOSTIC METHODS

IRVB offers tremendous increase in channels/cm<sup>2</sup> compared to resistive bolometer and AXUV systems



- Foil calibration<sup>2</sup>:**
- Thickness (spatially resolved) determined from comparison FEM and laser heating
  - Thermal diffusivity (spatially resolved) from thermographic method (expansion rate of heated area by laser pulse yields κ)

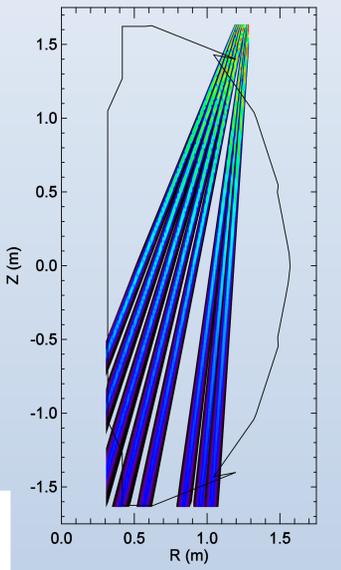
## MECHANICAL DESIGN



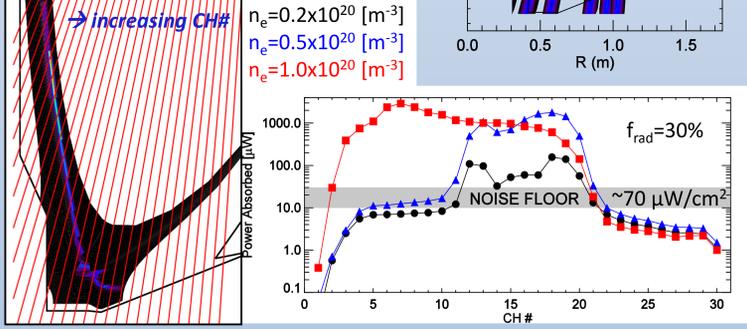
## EXPECTED RADIATION LEVELS

Success of spatially resolving divertor regimes depends on sensitivity and number of channels

- For prototype design: 1D array of bolometer pixels: 30 channels of 7.5x2.11 mm
- Integration along LOS shows overlap of channels
- Spatial resolution versus signal can be changed later in design and analysis; 4, 3, 2 channels combined shown in plot →
- Bolo pixel area: 0.15 cm<sup>2</sup>



Expected radiation levels from SOLPS simulations (J. Lore):

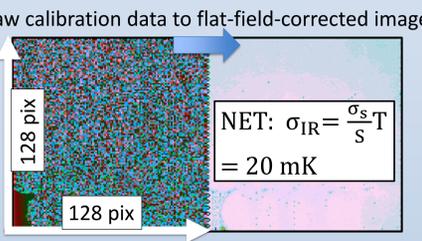


## CAMERA CHARACTERISTICS

Camera performance is critical system component: Sensitivity maximized by minimizing "noise-equivalent-temperature"  $\sigma_{IR} \rightarrow SNR \propto 1/\sigma_{IR}$



- IR Cam: Santa Barbara Focal Plane
- 128x128 pixels
- 1610.31 fps
- Low temperature calibration of full IR detector using BB source
- Near-RT performance optimization:  $\Delta t = 100.875 \mu s$ , gain=3, bias=0



$$SNR = \frac{S_{signal}}{S_{noise}} = \frac{\kappa \cos^4 \theta P_{rad} l_{plasma}}{4\pi k t_f \sigma_{IR} l_{ap-f}^2 V_{plasma}} \sqrt{\frac{f_{IR} N_{IR} A_{bol}^3}{2A_f f_{bol}^3}} = \frac{\kappa \cos^4 \theta P_{rad} l_{plasma} A_{ap}}{4\pi k t_f \sigma_{IR} l_{ap-f}^2 V_{plasma}} \sqrt{\frac{f_{IR} N_{IR}}{2N_{bol} f_{bol}^3}}$$

\*ref 3

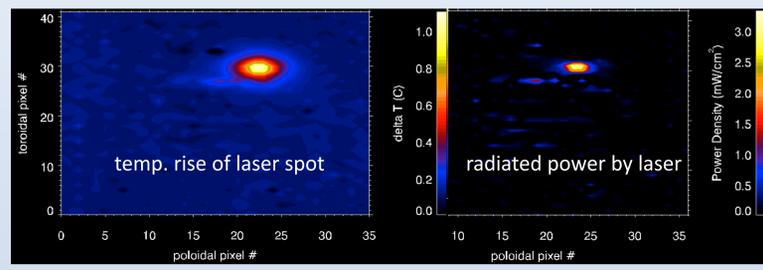
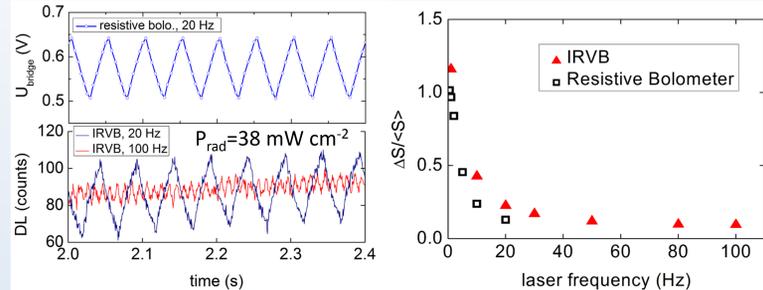
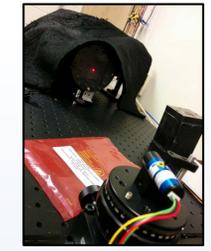
κ – foil thermal conductivity  
 κ – foil thermal diffusivity  
 t<sub>f</sub> = 1.5 - 4 mm – foil thickness  
 A<sub>f</sub> – utilized area of the foil  
 f<sub>IR</sub> – frame rate of IR camera  
 N<sub>IR</sub> – number of IR pixels  
 A<sub>bol</sub> – area of the bolometer pixel

f<sub>bol</sub> – frame rate of IRVB (t.b.d.)  
 N<sub>bol</sub> – number of bolometer pixels (9x7)  
 A<sub>ap</sub> – area of aperture (t.b.d.)  
 l<sub>ap-f</sub> – distance from foil to aperture (16.2 cm)  
 V<sub>plasma</sub> = plasma volume (11 m<sup>3</sup>)  
 θ – angle between sight line and aperture normal  
 l<sub>plasma</sub> – length of sight line through plasma (2.5 m)  
 P<sub>rad</sub> – total power radiated by plasma (~2 MW)

## TIME RESPONSE TESTING ON BENCHTOP

Motivated by assessing time response limit using a (faster) IR cam and allowing for one-to-one comparison to a resistive bolometer

- Foil irradiated by 4mW HeNe laser (λ=635 nm) and arbitrary pulse shape generator
- 2.5 μm Pt foil, irradiated in air (vacuum to be done)
- Power scan: 0.1-4 mW
- Frequency scan: 0.1-150 Hz



## SUMMARY AND FUTURE WORK

- IRVB prototype system for NSTX-U tokamak currently in development
  - Prototype Designed to provide 1D view of NSTX-U divertor radiation
  - IRVB allows for many more detector channels per unit area than resistive bolometer or AXUV systems
  - Installation planned early 2016. Acquiring data for upcoming FY16 campaign.
- future work:**
- Optimization of IRVB time response (laser in vacuum)
  - Studies of IRVB time response and sensitivity in comparison to conventional resistive bolometer systems (ongoing)
  - Finalizing design for multiple IRVB application for tomographic reconstruction purposes (FY16 NSTX-U run campaign)

<sup>1</sup>G.A. Wurden et. al., Rev. Sci. Instr. 68 (1997)  
<sup>2</sup>S.N. Pandya et. al., Rev. Sci. Instr. 85 (2014)  
<sup>3</sup>B.J. Peterson, Rev. Sci. Instr. 71 (2000)