

Interface Control Document MAGNETS : DIAGNOSTICS

Interface Document: NSTXU_1-1-3_IC_102

REVISION 0

November 6, 2019

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National Spherical Torus eXperiment Upgrade

National Spherical Torus Experiment Upgrade

Interface Control Document

MAGNETS: DIAGNOSTICS

NSTX-U-ICD-MAG-DIA-0

**Revision 0
May 15, 2019**

Change Record

| Revision | Date | Description of Change |
|----------|--------------|-----------------------|
| 0 | May 15, 2019 | Initial Release |
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References

[1] GENERAL REQUIREMENTS DOCUMENT, NSTX-U-RQMT-GRD-001-01.

[2] SYSTEM REQUIREMENTS DOCUMENT, MAGNET SYSTEMS, NSTX-U-RQMT-SRD-002-02.

[3] SYSTEM REQUIREMENTS DOCUMENT, Diagnostics, NSTX-U-RQMT-SRD-011-01.

[4] CS Air-Side Diagnostics, NSTX-U-RQMT-RD-005-01

[5] Inner-PF Coil Interfaces to Coil Support Designs and Cooling Systems

1. Purpose

This document describes the various interfaces between the following subsystems: Magnets and the Diagnostics. The interface locations and boundaries that connect the Magnets to the Diagnostics are identified based on different interface types.

2. Scope

The Magnets address the TF Coils, OH Solenoid, Resistive Wall Mode, Outer PF coils, PF-1a coils, PF-1b Coils, and PF-1c Coils. The Diagnostics system consists of Thermocouples, Mirnov sensors, Halo and Plasma Current Rogowski coils, Langmuir probes, Neutron measurements, Magnetics Multi-pulse Thompson Scattering (MPTS), Plasma TV, CHERS, spectroscopy, FIDA, BES, MSE, High-K Scattering, and microwave diagnostics, among other instrumentation and diagnostics. The scope of this document addresses any defined interfaces between these identified system elements.

3. Responsibilities

The interfaces are managed between the following organizations:

- Magnets
- Diagnostics
- Systems Engineering and Integration

4. Interfaces

Interface requirements in the following sections are identified with a requirement number, ICD, followed by a number [ICD-MAG-DIA-X] where “X” is a sequential count beginning with 001, MAG represents Magnets, and DIA represents Diagnostics. There is also a unique identifier for all interfaces in the format [#####-#####-X]. The identifier is a concatenation of two level 5 WBS values and the interface type. This is followed by an interface description and a list of references. References provide evidence pertaining to interfaces include but are not limited to drawings, calculations, or specifications. References also include a reference to a paragraph that identifies the set of interface definitions.

4.1. Interface Types

The top-level interface types are defined in Table 1. Within each heading, there are sub-headings to address any special sub-elements that need consideration. For example, the Mechanical has four sub-elements that need to be addressed: Structural, Spatial, Location, and Wall/Floor Penetration. For those interface types with sub-interfaces there are corresponding sub-sections.

Table 1. Interface Types.

| Heading | Abbreviation | Name |
|---------|--------------|--------------------------|
| 4.2 | Me | Mechanical |
| 4.3 | Ep | Electrical Power |
| 4.4 | Si | Signal |
| 4.5 | Di | Diagnostics |
| 4.6 | Gf | Gas/Fluid |
| 4.7 | Va | Vacuum |
| 4.8 | Sw | Software |
| 4.9 | Th | Thermal |
| 4.10 | Pe | Plasma/Eddy/Halo Current |

Table 2 provides the N2 Diagram identifying all the interfaces for NSTX-U while Table 3 provides the specific details of the interface.

Table 2. N2 Diagram Interface types.

| | | | | | | | | | | | | | | | | |
|--------------------------|---------------------|-------------------------|-----------------------|---------|-----------------|-----------------------|----------------|----------------|--------------------------|-------|-------------|---------------|---|-------------------------------|-----------------------------|------------------------------|
| Plasma Facing Components | Me,Th,Pe | | Me,Th,Va,Pe | | | | | | Me | Me | Me,Pe | | Me | | | |
| | In-Vessel Structure | Me,Di,Pe | | | Th | | | Me,Th,Pe | Me | | Me,Di,Pe | | | Di | | |
| | | Vacuum Vessel Structure | | | Me,Va | Me,Va | Me | Me,Th,Pe | Me | Me,Va | Me,Di,Va | | Si | Di,Si | | |
| | | Va | Centerstack Structure | | | Va,Th | Me,Gf | Me | Me | Me | | | | Di | | |
| | | Me | Me,Th,Ep | Magnets | | | | Me | | | Di | | Si | Di | | |
| Si | | Me,Va | | | Heating Systems | | Gf | Th | | Me | | Gf,Si | Si | Si | Si | |
| | | | | | Si,Va,Me,Sw,Gf | Vacuum Pumping System | | Si | Si | Gf,Si | Si | | Si,Va | Si | Si | |
| | | | | Gf,Si | | | Coolant System | Gf | | | | Gf,Sw | Si,Sw | Si | | |
| | Th,Gf | Ep,Di,Th,Va | Ep,Gf,Th,Pe | | Si | | Si | Bakeout System | | | | | | Me | Si,Me | |
| | | | Gf,Va | Gf,Va | Ep | Gf,Si | | | Gas Delivery System | Me | Va | | Si,Sw | Si | Si | |
| | | Gf | Si | | | Si,Gf,Va | | Gf | Wall Conditioning System | | | | Si,Sw | Si | Si | |
| | | Me,Va | Me,Va | Me | Me | Gf,Si | Gf | | | Va,Ep | Diagnostics | | Si,Sw | Si | Si | Si |
| | | | | Ep | Ep | Ep | Ep | Ep | Ep | Ep | Ep | Power Systems | Si | Ep,Si | Ep,Si,Di,Gf | Ep |
| | | | | | Si | | | | | Me,Si | Si | | Centralized Instrumentation and Control | Si,Me | | |
| | | | | | | | | | | Sw | | Si | Si,Sw | Integrated Machine Operations | | |
| | | | | | | | | Ep | | | | | | | Operations & Safety Systems | |
| Me | | Me | Me | Me | Me | Me | | Me | Me | Me | Me | Me | Me | Me | Me,Ep | D-Site Locations (Test Cell) |

Table 3. Callout.

| | |
|---------|-------------|
| Magnets | Di |
| Me | Diagnostics |

The remainder of this document addresses each of the interfaces. Note the template includes a paragraph heading for each interface and a table for each interface type. In the event there is no interface, the table will remain blank with a blank row.

The following paragraphs in Section 4 address each of the interfaces, and Section 5 addresses any off-project interfaces. Off-project interfaces are those external interfaces that interact with the NSTX-U system.

4.2. Mechanical Interfaces

This paragraph addresses any type of mechanical interfaces that include a structural, spatial, location dependent interfaces or areas where penetrations into a wall or floor are required. These are identified independently as interface parameters will likely be different.

4.2.1. Structural Interfaces

This identifies any interfaces between system elements that require a structural interface. This could be based on various forces placed on the system and by the system.

| Identifier | Interface | References |
|---------------------------|---|-------------------------------|
| 1.4.1.2.4- 1.1.3.2-S | A Rogowski coil is mounted to the outer TF leg , for use in the diamagnetic flux measurement. | See Paragraph 4.2.1.1, DC1947 |
| 1.4.1.2.1- 1.1.3.3.2-S | Plasma Current Rogowski coils mounted on the OH solenoid under the microtherm insulation | See Paragraph 4.2.2.2, Ref 4 |

4.2.1.1. Rogowski Coil – Outer TF

Interface Notes:

- Drawing 9D1095 Sheet 16 provides the CWD for the Rogowski Coil

ICD-MAG-DIA-001: The TF Rogowski coil is mounted to the TF-Outer Leg as shown In Figure 1. The interface uses G-10 base clamps to secure to the TF leg. There are eight 316 SS cap screws that secure the assembly. The Rogowski coil assembly is identified by the red cylinder, and Green and Yellow components

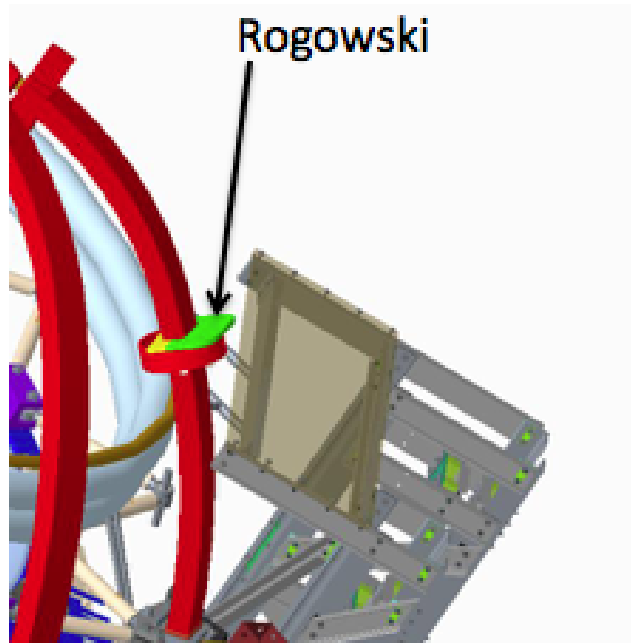


Figure 1. TF Rogowski Mounted on TF Leg

4.2.1.2. Plasma Current Rogowski Coils – OH solenoid

ICD-MAG-DIA-002: Figure 2 shows that the Rogowski Coil is held against the OH coil by the Microtherm blanket, until the Rogowski Coil enters the angled section. The micro-therm insulation is, in-turn, held in place by tightly wrapping Kapton tape around the insulation. Figure 2 shows the Plasma Current Rogowski coil (brown) mounted between the OH Coil (green) and the Microtherm (white) until the Rogowski coil enters the angled section of the Center Stack Casing. Note that there are 3 Plasma current Rogowski coils as defined in Ref 4.

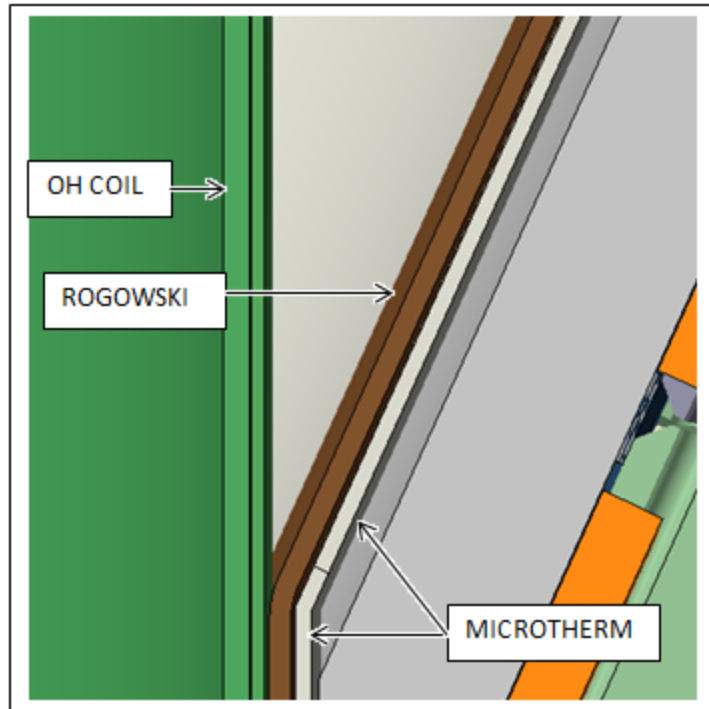


Figure 2. Plasma Current Rogowski

4.2.2. Spatial Interface

This identifies any interfaces between the system elements pertaining to spatial restrictions or constraints.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.2.3. Location Interfaces

This identifies any interfaces between the system elements that have any particular dependencies on element location or location constraints.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.2.4. Wall/Floor Penetration Interfaces

This identifies any interfaces between the system elements any penetrations or modifications to the wall or floor of the D-Site building.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.3. Electrical Power Interfaces

This identifies any interfaces between the system elements requiring AC, DC, rectification or power conditioning.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.4. Signal Interfaces

This identifies any interfaces between the system elements and signals that are used to either send or receive control information or data. It explicitly includes the type of physical interface such as Ethernet or Fiber Optic or any specific protocols.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.5. Diagnostic Interfaces

This identifies any interfaces between the system elements with any instrumentation or diagnostic equipment to collect performance data.

| Identifier | Interface | References |
|---------------------------|--|--|
| 1.1.3.3.2- 1.4.1.2.2-D | Poloidal Flux Loops mounted on the Ohmic Heating Solenoid | See Paragraph 4.5.1, Drawing 9D1095, Ref 4 |
| 1.1.3.3.3- 1.4.1.2.2-D | Poloidal Flux Loops mounted on Inner Poloidal Field 1a Coils | See Paragraph 4.5.2, Drawing 9D1095, Ref 4 |
| 1.1.3.3.4- 1.4.1.2.2-D | Poloidal Flux Loops mounted on Inner Poloidal Field 1b Coils | See Paragraph 4.5.3, Drawing 9D1095, Ref 4 |
| 1.1.3.3.5- 1.4.1.2.2-D | Poloidal Flux Loops mounted on Inner Poloidal Field 1c Coils | See Paragraph 4.5.4, Ref 4 |

Interface Notes:

- Ref 4 provides the locations for all the Airside diagnostics specifically Flux Loops.

4.5.1. Poloidal Flux Loops – OH Solenoid

ICD-MAG-DIA-003: The Flux Loops (0.037”) are wrapped horizontally around the OH coil. The OH consists of nine Flux Loops: one along the midplane, four upper coils and four lower coils

ICD-MAG-DIA-004: The Flux Loops are identified in the CWD, Drawing, 9D1095 Sheets 25, 30.

4.5.2. Poloidal Flux Loops – PF-1a

ICD-MAG-DIA-005: The Flux Loops (0.046” thick) are wrapped horizontally around the PF1a coil and fit between the coils and the slings that holds the coil in place. Figure 2 shows the location of the four flux loops in the OD in yellow.

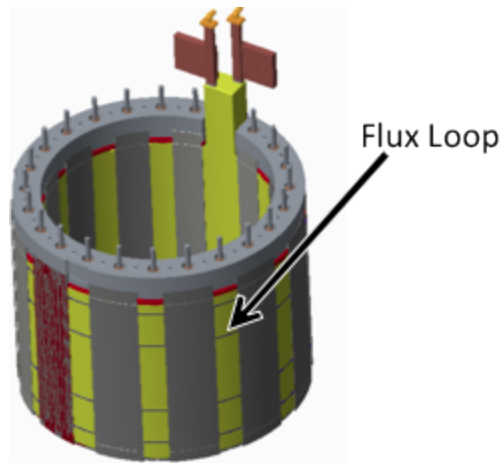


Figure 2. PF-1a Flux loop Diagnostics

ICD-MAG-DIA-006: The Flux Loops are identified in the CWD, Drawing, 9D1095 Sheets 10, 25.30.

4.5.3. Poloidal Flux Loops – PF-1b

ICD-MAG-DIA-007: The Flux Loops (0.046" thick) are wrapped horizontally around the PF-1b coil, and fit between the coils , and the slings that holds the coil in place. Figure 3 shows the location of the two flux loops in the OD in yellow.

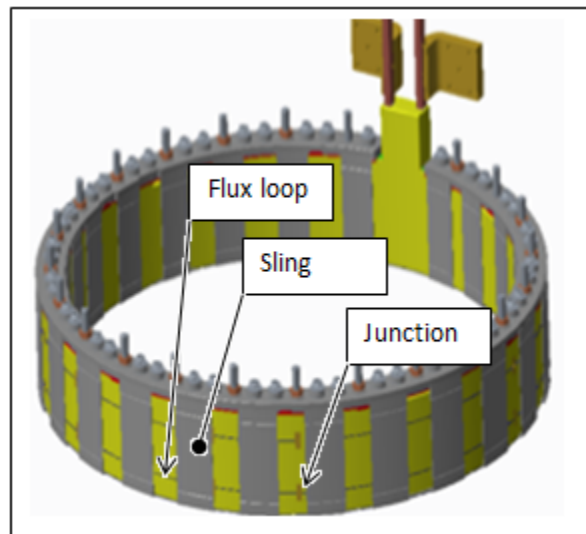


Figure 3.PF-1b Flux loop Diagnostics

ICD-MAG-DIA-008: The Flux Loops are identified in the CWD 9D1095 Sheets 10, 46

4.5.4. Poloidal Flux Loops – PF-1c

ICD-MAG-DIA-009: The two Flux Loops (0.046” thick) are wrapped horizontally around the PF-1c coil, and fit between the coils, and the slings that holds the coil in place. Electrical junctions can be made between the slings,

ICD-MAG-DIA-010: The Flux Loops are not identified in the CWD. Drawing 9D1095 requires updating.

4.6. Gas/Fluid Interfaces

This paragraph has two different types of interfaces: Gas and Fluid.

4.6.1. Gas Interfaces

This identifies any interfaces between the system elements that use any type of gas (e.g., He).

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.6.2. Fluid Interfaces

This identifies any interfaces between the system elements that use any type of fluid (e.g., ionized water).

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.7. Vacuum Interfaces

This identifies any interfaces between the system elements that pertain to the Vacuum.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.8. Software Interfaces

This identifies any interfaces between the system elements that use software that may exchange interfaces with other software components. This includes application programming interfaces (APIs) or any other exchange of information between different software applications.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.9. Thermal Interfaces

This identifies any interfaces between the system elements that pertain to Thermal characteristics.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.10. Plasma Interfaces

This paragraph has two different types of interfaces: Plasma and Eddy/Halo Current.

4.10.1. Plasma Interfaces

This identifies any interfaces between the system elements with the Plasma.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

4.10.2. Eddy/Halo Current Interfaces

This identifies any interfaces between the system elements with the Eddy/Halo Currents.

| Identifier | Interface | References |
|------------|-----------|------------|
| N/A | | |

5. Off-Project Interfaces

The off-project interfaces are components that are not specifically part of the NSTX-U system. They may include external systems and interfaces where the program has little control over part of the interface. They are provided for completeness.

There are no external interfaces.