

Vacuum Vessel System - Integrated Machine Operations Interface C

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National Spherical Torus Experiment Upgrade

Interface Control Document

VACUUM VESSEL SYSTEM: INTEGRATED MACHINE OPERATIONS

NSTX-U-VVS-IMO-ICD-0

Revision 0
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Change Record

Revision	Date	Description of Change
0	October 25, 2019	Initial Release

References

- [1] GENERAL REQUIREMENTS DOCUMENT, NSTX-U-RQMT-GRD-001-01
- [2] SYSTEM REQUIREMENTS DOCUMENT, VACUUM VESSEL AND INTERNAL HARDWARE, NSTX-U-RQMT-SRD-004-01.
- [3] SYSTEM REQUIREMENTS DOCUMENT, Diagnostics, NSTX-U-RQMT-SRD-011-01.
- [4] NSTX-U Machine Instrumentation, NSTX-U-RQMT-RD-008-03.

1. Purpose

This document describes the various interfaces between the following subsystems: Vacuum Vessel Structures and the Integrated Machine Operations. The interface locations and boundaries that connect the Vacuum Vessel Structures to the Integrated Machine Operations are identified based on different interface types.

2. Scope

The Vacuum Vessel Structures consist of the Vacuum Vessel and the Umbrella Structures. The Integrated Machine Operations consists of the Machine Instrumentation and Real-Time Control and Protection Systems such as the Digital Coil Protection System, and the Shorted Turn Protection System. The scope of this ICD focuses on Machine Instrumentation and this document addresses any defined interfaces between these identified system elements.

3. Responsibilities

The interfaces are managed between the following organizations:

- VVIH
- Diagnostics
- Systems Engineering and Integration

4. Interfaces

Interface requirements in the following sections are identified with a requirement number, ICD followed by a number [ICD-VVS-IMO-X] where X is a sequential count beginning with 001, VVS represents Vacuum Vessel Structures and IMO represents Integrated Machine Operations. There is also a unique identifier for all interfaces in the format [#####-#####-X]. The identifier is a concatenation of two level 5 SBS values and the interface type. This is followed by an interface description and a list of references. References provide evidence pertaining to interfaces include but are not limited to drawings, calculations, or specifications. Reference also include a reference to a paragraph that identifies the set of interface definitions.

4.1. Interface Types

The top-level interface types are defined in Table 1. Within each heading there are sub-headings to address any special sub-elements that need consideration. For example, the Mechanical has four sub-

elements that need to be addressed: Structural, Spatial, Location, and Wall/Floor Penetration. For those interface types with sub-interfaces there are corresponding sub-sections.

Table 1. Interface Types

Heading	Abbreviation	Name
4.2	Me	Mechanical
4.3	Ep	Electrical Power
4.4	Si	Signal
4.5	Di	Diagnostics
4.6	Gf	Gas/Fluid
4.7	Va	Vacuum
4.8	Sw	Software
4.9	Th	Thermal
4.10	Pe	Plasma/Eddy/Halo Current

Table 2 provides the N2 Diagram identifying all the interfaces for NSTX-U while Table 3 provides the specific details of the interface.

Table 2. N2 Diagram Interface types

Plasma Facing Components	Me,Th,Pe		Me,Th,Va,Pe						Me	Me	Me,Pe		Me			
	In-Vessel Structures	Me,Di,Pe			Th			Me,Th,Pe	Me		Me,Pe			Di		
		Vacuum Vessel Structure			Me,Va	Me,Va	Me	Me,Th,Pe	Me	Me,Va	Me,Di,Va		Si	Di,Si		
		Va	Centerstack Structures			Va,Th	Me,Gf	Me	Me					Di		
		Me	Me,Th,Ep	Magnets				Me			Di		Si	Di	Me	
Si		Me,Va			Heating Systems		Gf	Th		Me		Si	Si	Si	Si	
					Si,Va,Me,Sw,Gf	Vacuum Pumping System		Si	Si	Si	Si		Si,Va	Si	Si	
				Gf,Si			Coolant System	Gf				Gf,Sw	Si,Sw	Si	Si	
	Th,Gf	Ep,Di,Th,Va	Ep,Gf,Th,Pe		Si		Si	Bakeout System							Si,Me	
			Gf,Va			Me,Gf,Si		Gas Delivery System	Gf	Va			Si,Sw		Si	
		Gf				Si,Gf,Va		Me	Wall Conditioning System				Si,Sw		Si	
		Me,Va	Me,Va	Me	Me	Gf,Si	Gf		Va,Ep	Diagnostics			Si,Sw	Si	Si,Me	Si
				Ep	Ep	Ep	Ep	Ep	Ep	Ep	Power Systems	Ep,Si	Ep,Si	Me,Ep,Si,Di,Gf	Ep	
					Si				Me,Si	Si		Centralized Instrumentation and Control	Si,Me			
												Si	Si,Sw	Integrated Machine Operations		
								Ep							Operations & Safety Systems	
Me		Me	Me	Me	Me	Me		Me	Me	Me	Me	Me	Me	Me	Me,Ep	O-Site Locations (Test Cell)

Table 3. Callout

Vacuum Vessel Structures	Di
	Integrated Machine Operations

The remainder of this document addresses each of the interfaces. Note the template includes a paragraph heading for each interface and a table for each interface type. In the event there is no interface, the table will remain blank with a blank row.

The following paragraphs in Section 4 address each of the interfaces, and Section 5 addresses any off-project interfaces. Off-project interfaces are those external interfaces that interact with the NSTX-U system.

4.2. Mechanical Interfaces

This paragraph addresses any type of mechanical interfaces that include a structural, spatial, location dependent interfaces or areas where penetrations into a wall or floor are required. These are identified independently as interface parameters will likely be different.

4.2.1. Structural Interfaces

This identifies any interfaces between system elements that require a structural interface. This could be based on various forces placed on the system and by the system.

Identifier	Interface	References
1.1.2.1.2- 1.7.3.4.5-S	The mirror is aligned and weld to the top of the Umbrella	See Paragraph 4.2.1.1

4.2.1.1. Laser Instrumentation - Umbrella

User Notes: This design has not yet completed FDR.

ICD-VVS-IMO-001: A commercial mirror is welded to the top of the Umbrella Structure. Figure 1 provides the approximate location of the mirror.

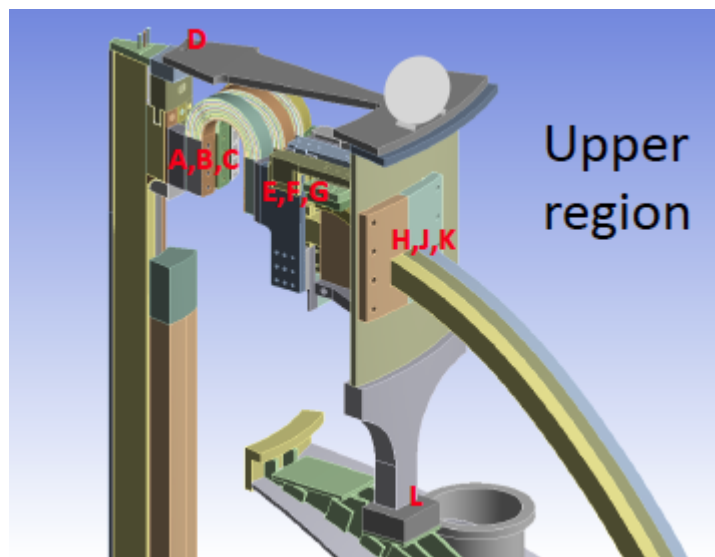


Figure 1. Notional Location of Mirror

4.2.2. Spatial Interface

This identifies any interfaces between the system elements pertaining to spatial restrictions or constraints.

Identifier	Interface	References
N/A		

4.2.3. Location Interfaces

This identifies any interfaces between the system elements that have any particular dependencies on element location or location constraints.

Identifier	Interface	References
N/A		

4.2.4. Wall/Floor Penetration Interfaces

This identifies any interfaces between the system elements any penetrations or modifications to the wall or floor of the D-Site building.

Identifier	Interface	References
N/A		

4.3. Electrical Power Interfaces

This identifies any interfaces between the system elements requiring AC, DC, rectification or power conditioning.

Identifier	Interface	References

N/A		
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4.4. Signal Interfaces

This identifies any interfaces between the system elements and signals that are used to either send or receive control information or data. It explicitly includes the type of physical interface such as Ethernet or Fiber Optic or any specific protocols.

Identifier	Interface	References
N/A		

4.5. Diagnostic Interfaces

This identifies any interfaces between the system elements with any instrumentation or diagnostic equipment to collect performance data.

Identifier	Interface	References
1.1.2.3.1- 1.7.3.4.1-D	Sensors measure strain in the TF trusses	See Paragraph 4.5.1, Drawing 9D11557
1.1.2.1.2- 1.7.3.4.1-D	Sensors measure strain in the spoked lids	See Paragraph 4.5.2, Drawing 9D11535
1.1.2.3.2- 1.7.3.4.1-D	Sensors measure displacements of the radial slides.	See Paragraph 4.5.3, Drawing 9D11558

Interface Notes:

- While the Vacuum Vessel Thermocouples are only Vacuum Vessel scope the drawing reference is included for clarity. Drawing DC-1244 provides details on location and mounting method for the installation of thermocouples on the vacuum vessel.

4.5.1. Strain Gauge -TF Trusses

ICD-VVS-IMO-002: The strain gauges are attached to the underside of the TF trusses using epoxy as shown in Figure 2. Drawing 9D11557 provides the details of the implementation.

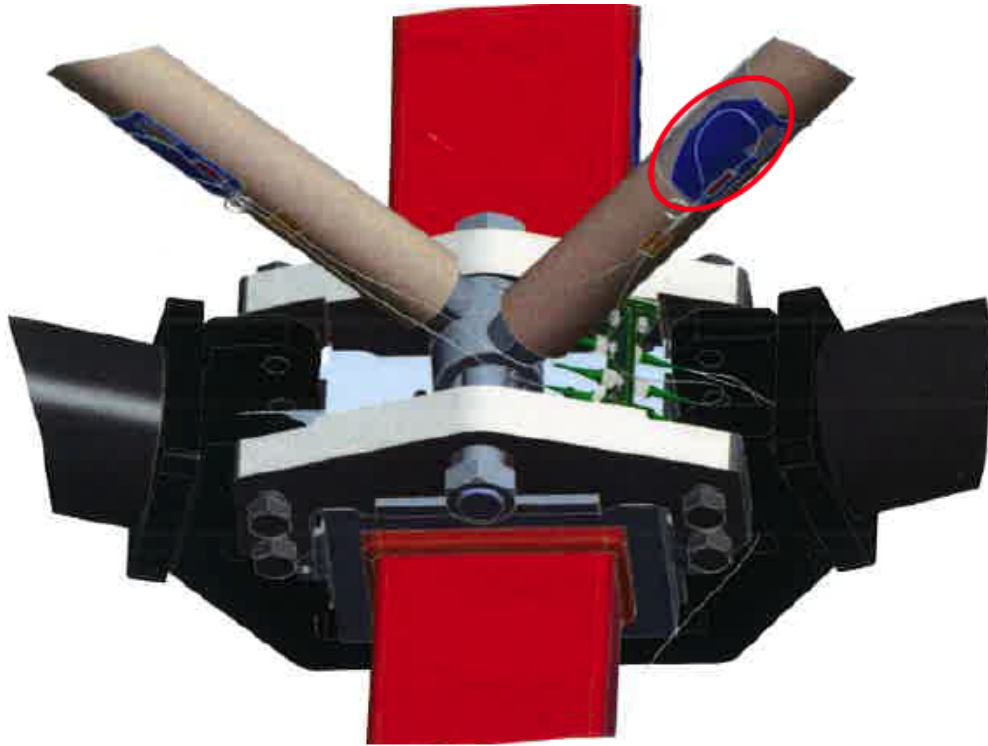


Figure 2. Strain Gauges on TF Trusses

ICD-VVS-IMO-003: The strain gauges are attached between the TF support structures using silicone as shown in Figure 3. Drawing 9D11557 provides the details of the implementation.

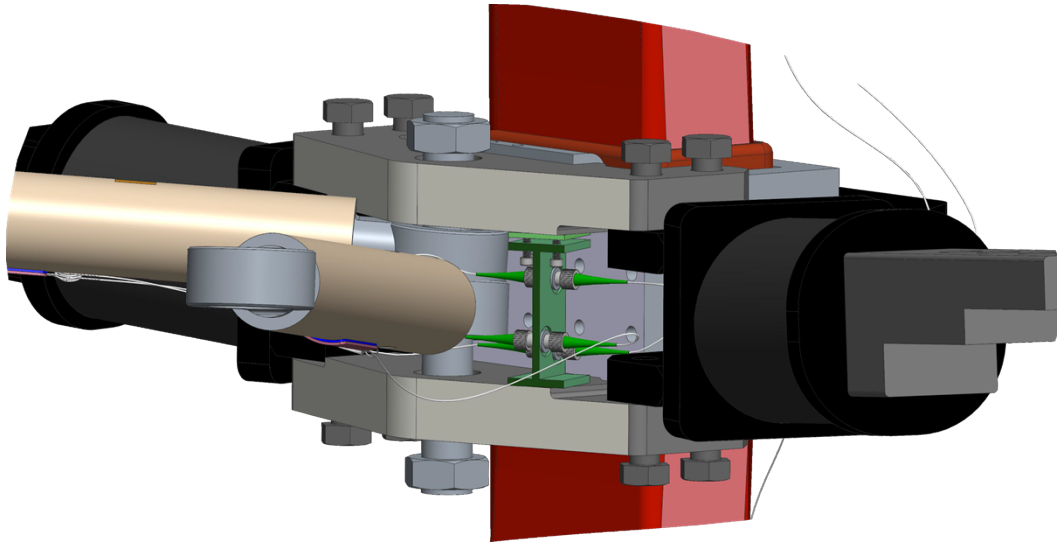


Figure 3. Sensors are mounted between the structures

4.5.2. Sensor – Spoked Lid

ICD-VVS-IMO-004: Strain and Temperature sensors are mounted in a bus on each of the spokes as shown in Figure 3. Drawing 9D11535 provides the details on these sensors.

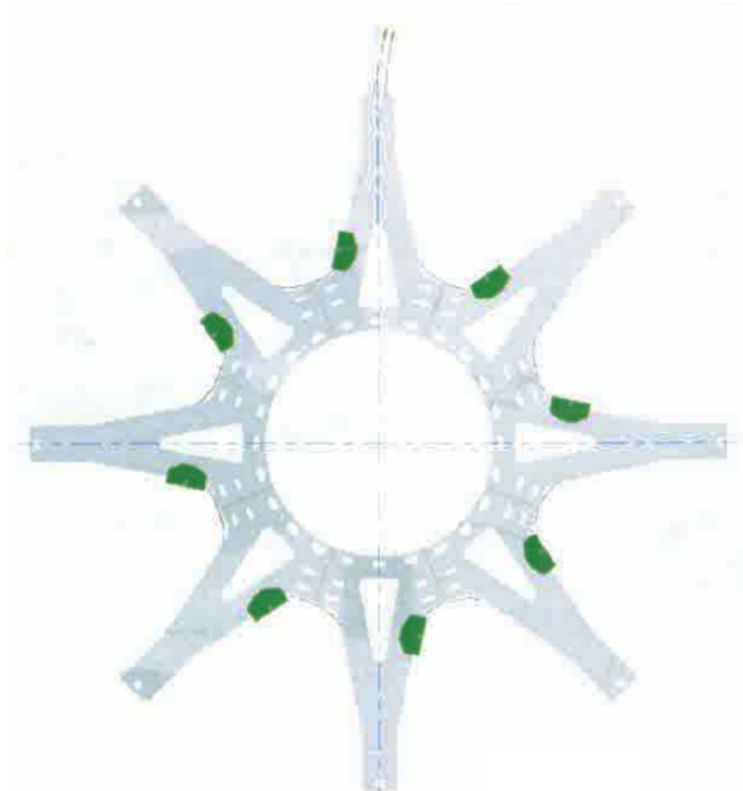


Figure 3. Sensor Locations on Spoked Lid

ICD-VVS-IMO-003: Fiber optic cables interconnect these components in a ring as shown in Figure 4.

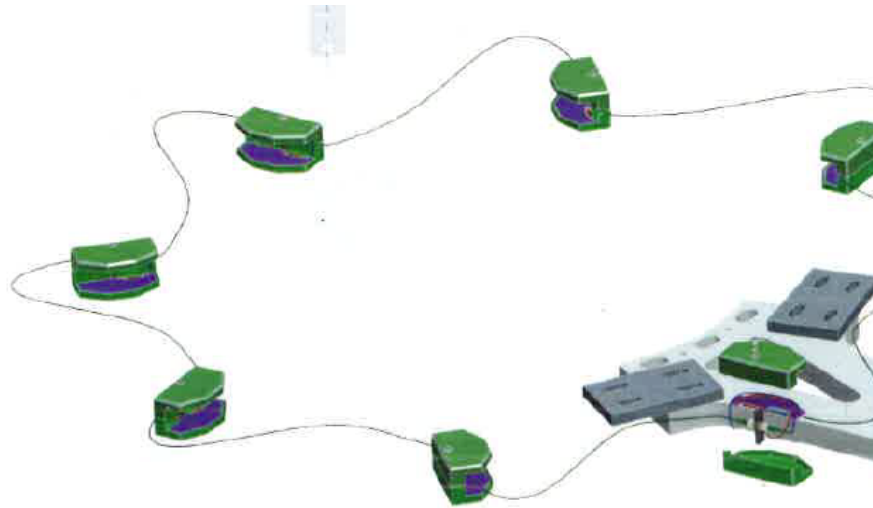


Figure 4. Sensor connections via Fiber Optic Bus

4.5.3. Displacement Sensors - Outer PF Supports

ICD-VVS-IMO-004: The Fabret-Perot displacement sensors are bolted to the welded stud using #10-32UNC-2B HEX NUTon brackets (green) that are installed on the PF-4 supports as shown in Figure 4. Drawing 9D11558 provides the sensor and mounting details.

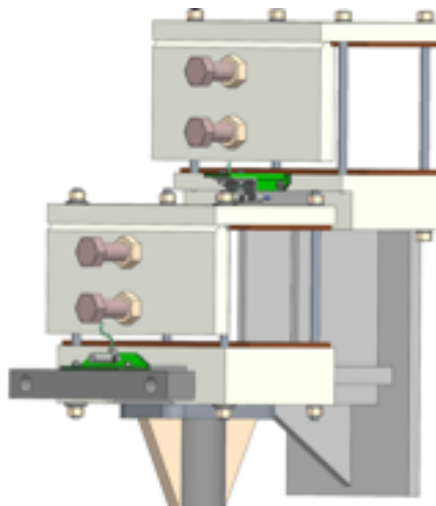


Figure 4. PF-4/5 Displacement sensors

ICD-VVS-IMO-005: The sensors are connected using fiber optic cables.

4.6. Gas/Fluid Interfaces

This paragraph has two different types of interfaces: Gas and Fluid.

4.6.1. Gas Interfaces

This identifies any interfaces between the system elements that use any type of gas (e.g., He).

Identifier	Interface	References
N/A		

4.6.2. Fluid Interfaces

This identifies any interfaces between the system elements that use any type of fluid (e.g., ionized water).

Identifier	Interface	References
N/A		

4.7. Vacuum Interfaces

This identifies any interfaces between the system elements that pertain to the Vacuum.

Identifier	Interface	References
N/A		

4.8. Software Interfaces

This identifies any interfaces between the system elements that use software that may exchange interfaces with other software components. This includes application programming interfaces (APIs) or any other exchange of information between different software applications.

Identifier	Interface	References
N/A		

4.9. Thermal Interfaces

This identifies any interfaces between the system elements that pertain to Thermal characteristics.

Identifier	Interface	References
N/A		

4.10. Plasma Interfaces

This paragraph has two different types of interfaces: Plasma and Eddy/Halo Current.

4.10.1. Plasma Interfaces

This identifies any interfaces between the system elements with the Plasma.

Identifier	Interface	References
N/A		

4.10.2. Eddy/Halo Current Interfaces

This identifies any interfaces between the system elements with the Eddy/Halo Currents.

Identifier	Interface	References

N/A		
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5. Off-Project Interfaces

The off-project interfaces are components that are not specifically part of the NSTX-U system. They may include external systems and interfaces where the program has little control on part of the interface. They are provided for completeness.

There are no external interfaces.